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Airfoil Parameters Reverse Engineering Framework for Plot Digitized Blade Sections

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Abstract

A framework to reverse engineer airfoil section parameters using a Turbomachinery Blade Geometry code has been developed and presented. A multivariable single objective optimization is used to reduce the sum of the square difference between the parametric blade shape and the target airfoil blade section to obtain those parameters. The method divides input airfoil into six parts to simplify blade difference calculation. A turbomachine blade section is obtained using the new input files with airfoil parameters: inlet and outlet metal angles, six curvature control points, Leading edge radius, location of maximum thickness, value of maximum thickness, and trailing edge thickness. Key issues of the process are discussed.

A demonstration of the developed method was carried out by first reverse engineering three different airfoils and then reverse engineering E3 transonic compressor blade from its sections. This blade was chosen due to its uniqueness of having a sloped hub. The Airfoil sections were plot digitized from the E3 report which were then run through the method to get Tblade3 parameters. A subsequent 3D simulation of the blade has been carried out to compare the performance of the reverse engineered blade with it's the experimental results of the actual design.

Furthermore, a grid dependence and off design study (full speedline) has been carried out to determine the most appropriate running condition for the comparison. Insights on further directions are suggested that will improve the comparison.

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Nomenclature

E^3 = Energy Efficient Engine

K = Temperature (Kelvin)

Pa = Pascals

u = X component of the normalized airfoil plot with zero stagger

v = Y component of the normalized airfoil plot with zero stagger

TE = Trailing Edge

LE = Leading Edge

tm/c = Maximum Thickness to chord ratio

pss = Part span shroud

Subscripts

r = Radial direction

θ = Tangential direction

z = Axial direction

Chapter 1

Introduction

1.1 Motivation

With the advent of modern jet engines and electric propulsion systems, reverse engineering a turbomachinery blade - in both land and flying gas turbines has gained a renewed interest. While there are many methods in place, throughout the design process a need was recognized for a design framework that could help digitize blades from plot digitized airfoil sections. The idea is to make use of Tblade3 CAD which had the capability to parametrically design airfoil sections and bring in a gradient-based optimizer to minimize the least squared difference between a target and initial airfoil until they are satisfactorily digitized. This framework would also have the advantage of dimensionalising the target airfoil in a given set of parameters instead of the input two-coordinate systems. This is essential because these parameters bring in the benefit of design optimization if the airfoil/blade is to be adopted from one use case to the other. The objective function of the framework has to be twice differentiable easing the calculation of gradient and hessian matrix and should make use of squared distance instead of linear distance for quicker convergence.

1.2 Literature review and previous work

1.2.1 Blade reverse engineering and Tblade3

Though relatively rare, blade reverse engineering methods have been previously explored for easy storage and optimization of existing designs. Chen et al [1] described a conventional approach of 3D

scanning a given turbine blade and then builds on top of it using Modified Adaptive Model-based Digitizing Process (MAMDP) to refine the coordinates obtained into surfaces. Another method described by Mohaghegh et al. [2] is to use reverse engineering to counteract the irregularities that scanner errors produce in extremely delicate designs like those of turbine blades. They suggested implementing design key-points during reverse engineering and demonstrated it on a gas turbine blade.

For our work, we demonstrated the framework using blade design capabilities of an in-house code Tblade3 [3] which is a design tool for 3D blades using a parametric approach. Siddappaji [4] demonstrated its general capabilities to design three use cases - a GE 1.5 MW wind turbine fan design along with carrying out CFD and FEA analysis, a 10-stage high pressure compressor full definition design, and a low-speed centrifugal compressor design. In this thesis, a detailed optimization of Tblade3 coupled with an FEA and a CFD code using a three stage booster's blisk blades is carried out in Siddappaji et al. [5]. AF Nemnem et al.[6] expanded its capabilities to control the meanline curvature with a b-spline to create smooth airfoil surfaces. This resulted in reduced spikes in Mach numbers and pressure distributions. They demonstrated these capabilities over a range of airfoils in various aerodynamic regimes. Balasubramanian et al. [7] added in a novel curvature-based airfoil parameterization feature to tap into the direct proportionality of streamline curvature to pressure gradient using control points for meanline second derivative and a thickness distribution. Sharma et al. [8] integrated Tblade3 into Engineering Sketch Pad (ESP) [9] which is an open-source web-enabled solid modelling system. This integration also enables flends to Tblade3's solid blade models using ESP. The resulting geometry was simulated on a FEM based centrifugal and pressure loads. Furthermore, Sharma et al. [10] added in continuous parameterization instead of discrete for better optimization control.

1.2.2 Energy Efficient Engine Fan and CFD Simulations

To demonstrate the capabilities of the framework, along with standard 2D airfoils from airfoil-tools.com, a jet engine fan from the 1970s was chosen. This fan was part of the Energy Efficient Engine(E3) project from NASA and was selected because of the ease of availability of its three airfoil sections in the form of an E3 report. Initial insights of the geometry were obtained from RW Claus et al. [11]. Their paper helped get a primary understanding of how the fan geometry should

look like. An AIAA meeting paper by Turner M [12] helped underscore the implications of this work in full engine simulations. The design parameters for E3 fan are obtained from NASA-GE STI design report [13], henceforth referred to as the E^3 report. Though this report has the E3 fan with a part span shroud, we will be designing it without one to focus solely on the reverse engineering capabilities of the code. Further insights into GE fan design were obtained from two papers by L.H. Smith. First discusses the evolution of compressor design [14] and second discusses how design methods have evolved to support CFD methods helping make a choice about leading and trailing edge radius values[15]. Turner et al. [16] explored the turbulence modeling of transonic fans while developing an explicit Navier-stokes solver and recommended $k - \epsilon$ solver as a go to solver. Jennions et al. [17] further demonstrated the abilities of a 3-dimensional $k - \epsilon$ solver on three major industrial configurations – NASA Rotor 67, GE/Wennerstrom Rotor 4, and the GE/NASA E^3 fan. Various parameters were considered like tip leakage flow, shock boundary layer interaction, boundary layer growth, and account of internal solid bodies such as part-span shrouds and engine splitters. Barring the E3 fan, there has been many design optimizations carried out from the reports starting with 3D all engine component simulations [18], High Pressure Turbine simulation [19] Low Pressure Turbine simulation [20] a validation study of the Low Pressure Turbine [21], Combustor design [22], Combustor to High Pressure Turbine simulation [23] and High pressure Compressor cavity simulations [24]. Furthermore, losses in the 3D simulations were analyzed using concepts from Denton et al [25].

1.2.3 Multidisciplinary Design Analysis and Optimization

While some of the above optimizations and simulations used other CAD packages to design the turbomachine blades, a major chunk of them were designed using Tblade3. This is attributed to flexibility of Tblade3 and availability of literature in various test cases. Mahmood et al. [26] presented a design process with Tblade3 as the design CAD and Dakota [27] as the optimization driver using Genetic Algorithm to explore the design space. This technique was demonstrated using rotor 6 of the E3 High pressure compressor as a testcase for a single objective optimization to optimize isentropic efficiency.

Mandal et al. [28] developed an optimization process with Dakota for a propulsor design while demonstrating a three blade-row design for NASA BLI fan. The experimental and CFD results

from such a process were contrasted by Sieradzki et al. [29] who demonstrated numerical and design challenges for simulation of BLI fans while using FINE/Turbo. Chen et al. [30] studied flow diagnostics and optimization of transonic compressor/Fan rotor with a single objective function genetic algorithm using Dakota.

While Dakota was initially considered as an optimizer choice given its proven integration with Tblade3, the switch from Dakota was to OpenMDAO [31] as the optimizer was justified with the availability of python scipy's SLSQP [32] module which made both equality and inequality constraints. This was demonstrated in Tom Viars' mini thesis [33] which highlights the use of OpenMDAO to design an optimization using Tblade3. A similar approach was adopted throughout this thesis.

Chapter 2

Methodology

The framework is developed using a combination of python scripts wrapped over Tblade3 and OpenMDAO as shown in Figure 2.3. It allows the input of target airfoil coordinates and initial input files for Tblade3 which are then used to generate reverse-engineered airfoil parameters for the target airfoil. The core of the framework is the development of an airfoil difference calculator which is discussed in the section below, the entire optimization framework is discussed next, followed by an evaluation of the optimum step size for each variable.

2.1 Computing least squared difference

For nomenclature reasons - initial airfoil is generated by Tblade3 during first run before the framework is engaged. Generated airfoil is any airfoil generated by Tblade3 when the framework is being run. Target airfoil is the plot digitized airfoil from 2D sections in reports or from u, v coordinates of standard airfoils.

The least square difference calculator assigns a numerical value to the difference in two airfoil sections - a plot digitized airfoil (target) and the reverse engineered airfoil (initial) section by following these steps:

1. Import target and initial airfoil coordinates
2. Break each airfoil into six parts as shown in Figure 2.1
3. For each part, ensure that initial blade coordinates are a subset of target blade coordinates by

dropping initial blade coordinates whose abscissa is out of the target blade abscissa's range. (Section 2.1.1)

4. Next, abscissa of target blade is interpolated on the subset of initial blade to make sure that both initial and target blade parts have the same abscissa. (Section 2.1.2)
5. The new values of abscissa are used to calculate new u coordinates of each target section. This makes the calculation of least squared differences a one-dimensional calculation along v. (Section 2.1.3)
6. Finally, the difference between each airfoil parts is calculated , the difference is squared and then summed to obtain the total least squared difference value. (Section 2.1.4) The below subsections look at the mathematical equations of the above procedures.

2.1.1 Truncation of target airfoil coordinates

To ensure that the $u_{target_airfoil}$ coordinates are a subset of generated airfoil u coordinates, all the coordinates set values with u values greater than the first coordinate in the generated airfoil are dropped for airfoil sections on the suction side. This is also repeated on the other end of the airfoil part where the cutoff criterion is:

$$\begin{aligned} u_0^{target} &\leq u_0^{generated} \\ u_n^{target} &\geq u_n^{generated} \end{aligned} \tag{2.1}$$

Conversely, for the pressure side, the cut-off criterion is flipped:

$$\begin{aligned} u_0^{target} &\geq u_0^{generated} \\ u_n^{target} &\leq u_n^{generated} \end{aligned} \tag{2.2}$$

2.1.2 Piecewise linear interpolation

u coordinate values of both airfoils need to be equated so that a squared difference can be obtained between each of the v values in a single dimension. To do this, a linear interpolation polynomial function is fit on the target airfoil and is used to obtain values of v from the target airfoil for the corresponding u value from the generated airfoil. This also has the added advantage of easy visual

comparison as the number of coordinates is the same in both airfoils. Mathematically, we fit a piecewise linear interpolation function "f" on initial airfoil coordinates and then use u values from the target airfoil as input to "f" to get their corresponding v values. This will create a new set of coordinates for the generated airfoil whose u values will be equal to the target airfoil.

A piecewise linear interpolant that interpolates using data points $(u_i, v_i)_{i=0}^n$, where $x_0 < x_1 < \dots < x_n$ is given by eq 2.3

$$f_{1,n}(u) = \begin{cases} v_0 \frac{u-u_1}{u_0-u_1} + v_1 \frac{u-u_0}{u_1-u_0}, & u \in [u_0, u_1] \\ v_1 \frac{u-u_2}{u_1-u_2} + v_2 \frac{u-u_1}{u_2-u_1}, & u \in [u_1, u_2] \\ \vdots \\ v_{n-1} \frac{u-u_n}{u_{n-1}-u_n} + v_n \frac{u-u_{n-1}}{u_n-u_{n-1}}, & u \in [u_{n-1}, u_n] \end{cases} \quad (2.3)$$

The i^{th} piece in each subinterval $[u_{i-1}, u_i]$ is given by Lagrange's interpolation formula for first order polynomial (eq. 2.4). These equations are represented here from Xu S[34] and were solved using Numpy interpolate's *interp1d* class.

$$v_{i-1} \frac{u - u_i}{u_{i-1} - u_i} + v_i \frac{u - u_{i-1}}{u_i - u_{i-1}}, u \in [u_{i-1}, u_i] \quad (2.4)$$

2.1.3 Quadratic least squares approximation along v

On the new interpolation generated airfoil and the target airfoil, an order two polynomial is fit on the u, v coordinates to create a pseudo camber line to separate suction and pressure side calculations. Quadratic least-squares approximation was used and the equations from Zubairi et al. [35] are reproduced here. It uses a second-degree polynomial to approximate a given set of data $(u_1, v_1), (u_2, v_2), \dots, (u_n, v_n)$, where $n \geq 3$. We minimize least squares error (Π) in eq 2.5, where a, b , and c are the unknown coefficients for all u_i, v_i data points.

$$\Pi = \sum_{i=1}^n (v_i - (a + bu_i + cu_i^2))^2 \quad (2.5)$$

Partially differentiating Π with respect to a, b , and c and rearranging, we get the linear equations 2.6, 2.7, 2.8. Which are then solved to obtain the value of unknown coefficients.

$$\sum_{i=1}^N v_i = a \sum_{i=1}^N 1 + b \sum_{i=1}^N u_i + c \sum_{i=1}^N u_i^2 \quad (2.6)$$

$$\sum_{i=1}^N u_i v_i = a \sum_{i=1}^N u_i + b \sum_{i=1}^N u_i^2 + c \sum_{i=1}^N u_i^3 \quad (2.7)$$

$$\sum_{i=1}^N u_i^2 v_i = a \sum_{i=1}^N u_i^2 + b \sum_{i=1}^N u_i^3 + c \sum_{i=1}^N u_i^4 \quad (2.8)$$

Python Numpy's *polyfit* class solves for these coefficients. They can be called using *poly1d* class within the same module that stores the fit function (eq. 2.9) which is the mean camber line function for a given airfoil data points set.

$$v_i = \Gamma_{mcl_curve}(u_i) \quad (2.9)$$

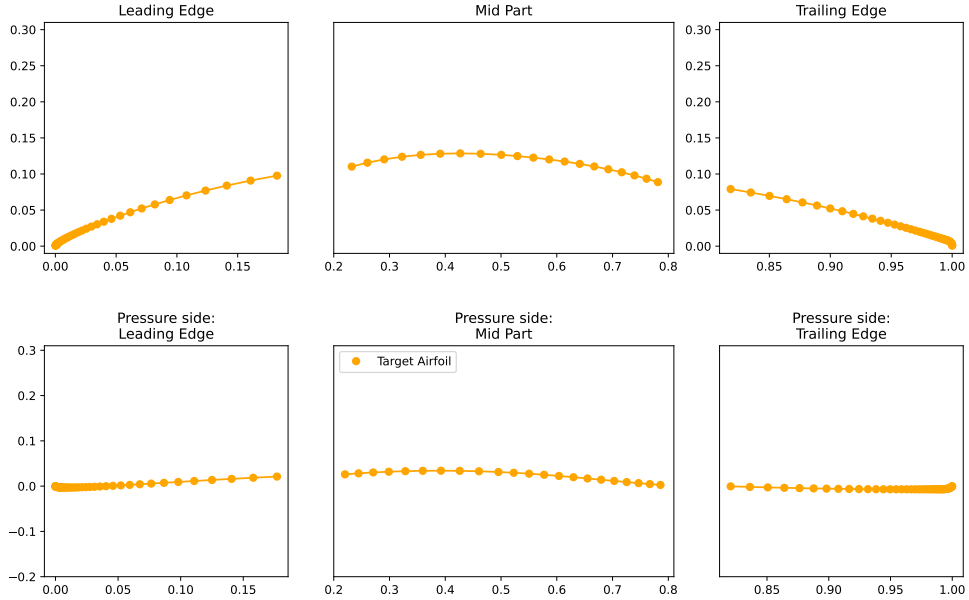


Figure 2.1: Target blade divided into six parts

2.1.4 Squared difference

Differences between each ordinate within an individual part are calculated as shown in eq. 2.10 to 2.15. Once calculated, these differences are then summed up to obtain a single value of squared difference (δ_{sd}) for the entire airfoil - eq 2.16.

$$\delta_{suc_LE} = \sum_{j=1}^{m_{suc_LE}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.10)$$

$$\delta_{suc_mid} = \sum_{j=1}^{m_{suc_mid}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.11)$$

$$\delta_{suc_TE} = \sum_{j=1}^{m_{suc_TE}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.12)$$

$$\delta_{pre_LE} = \sum_{j=1}^{m_{pre_LE}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.13)$$

$$\delta_{pre_mid} = \sum_{j=1}^{m_{pre_mid}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.14)$$

$$\delta_{pre_TE} = \sum_{j=1}^{m_{pre_TE}} (v_j^{rev_engg} - v_j^{target})^2 \quad (2.15)$$

$$\begin{aligned} \delta_{sd} = & \delta_{suc_LE} + \delta_{suc_mid} + \delta_{suc_TE} \\ & + \delta_{pre_LE} + \delta_{pre_mid} + \delta_{pre_TE} \end{aligned} \quad (2.16)$$

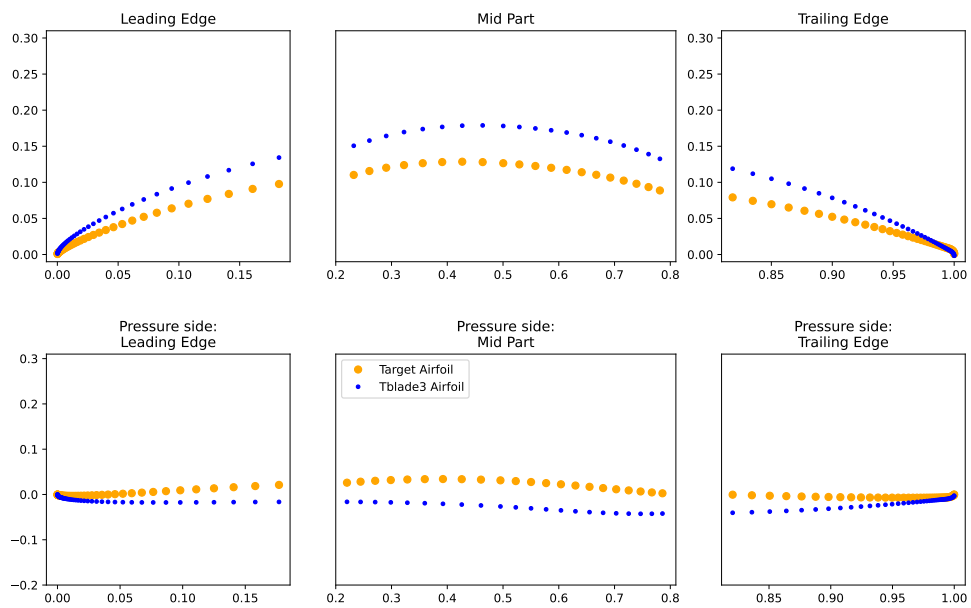


Figure 2.2: Tblade3 airfoil parts after interpolation to calculate least square difference

2.2 Optimization framework

Shown in Figure 2.3 is the overview of airfoil reverse engineering framework. The process begins with preparing the plot-digitized airfoil coordinates and sorting them into Selig airfoil format. This gives us the target coordinates. We prepare TBlade3 input files 3dbginput.1.dat and spancontrolinputs.1.dat and specify them with manual best guess input and output metal angles, curvature control points, LE radius, thickness of max camber, location of max. camber thickness, and TE thickness. Once we have these values, we do a run of Tblade3 to obtain the initial airfoil coordinates of our reverse engineering blade. With the target and initial blade coordinates in a standard format, the OpenMDAO script file is run. The script file then runs Tblade3 on the initial Tblade3 input files to produce the u-v coordinates of the airfoil. Once we have this airfoil, it runs an external python script to calculate squared difference between target and generated airfoil coordinates, then saves the values into a .dat file. The framework also creates a .pdf report of the airfoil sections and writes an image file showing a visual comparison of a generated airfoil with the target airfoil along with the squared difference annotated on the top right corner. Once the script is done, the OpenMDAO script takes over and prints the values of input parameters and squared difference to the screen, it also writes the parameters into the .base, .log, and .dat template files and saves them. It then checks the least squared difference value with the given tolerance, if the tolerance is lower than the specified value or if the value of the least squared difference is stagnating, then the solver exits. Else, it goes back to the beginning and alters values using a minimization algorithm - SLSQP by default, while using the generated blades as the new initial blade. This way it approaches the target blade by minimizing the least squared distance value.

Once the optimization reaches an exit value, we then run the optimization post-processor script, which takes in the log file from the final optimization run and prepares a .pdf report with iteration vs value plots of squared difference and other input variables. It also prints out a table comparing the initial vs target values of the variables.

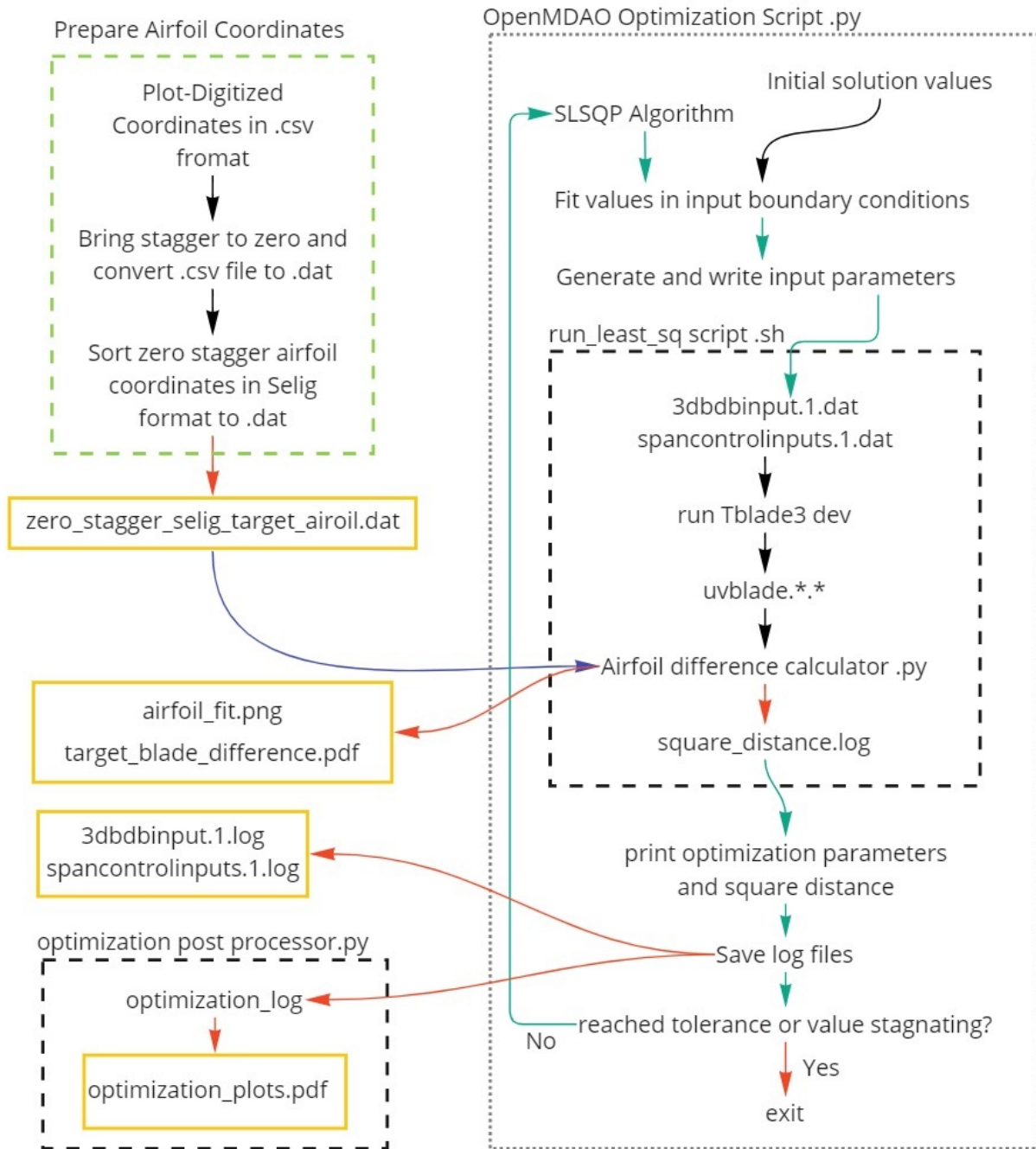


Figure 2.3: Overview of Airfoil parameters reverse engineering framework

2.3 Evaluation of optimum step size for each variable

The structure of optimization variables is described by N2 Model (Figure 2.4) which is visualized below with our squared difference objective function using twelve variables and a constant. To accurately calculate the sensitivities for the objective function using finite difference methods, a step-size study is needed. This is to obtain an efficient calculation of the gradients and hessian matrices while minimizing total error in finite difference methods, which is a combination of truncation and round-off errors.

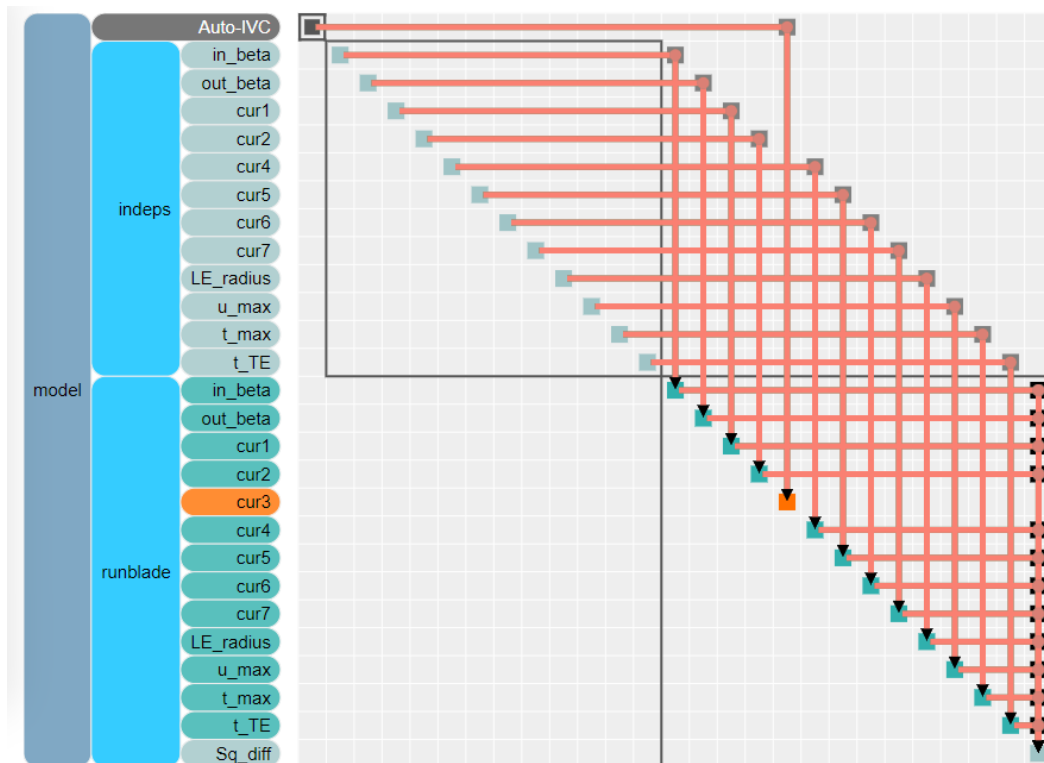
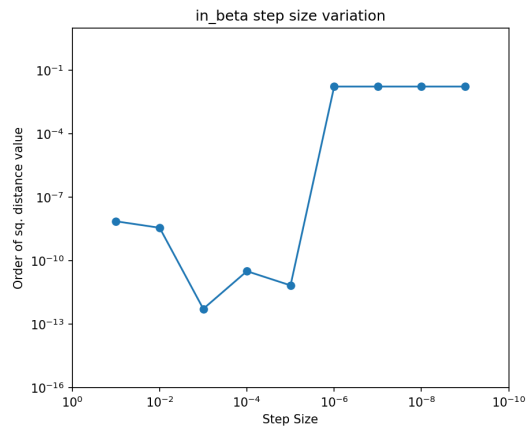


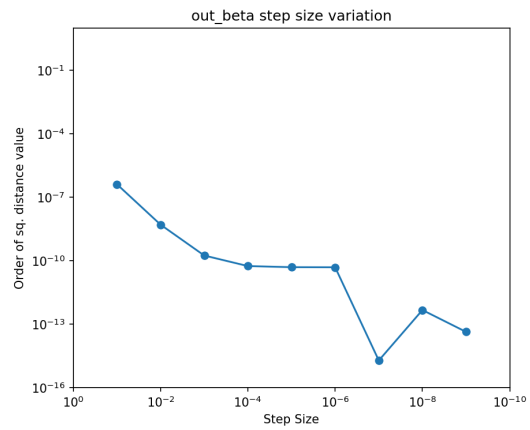
Figure 2.4: N2 model of the optimization framework

In order to perform the step-size study, a template airfoil with known parameters - in this case 0012, is taken and a single variable optimization was run with each initial parameter value increased by 10%. The error tolerance for this optimization was set to $1e-10$ and multiple runs for the same variables were carried out while varying step sizes from 1 to $1e-11$. Once we had the results of all the 11 step sizes for a single variable, a log-log plot of squared distance to step size was plotted for each variable as shown in Figure 2.5. By looking at these plots, we can note that the optimum step sizes for most variables is $1e-3$, except for t_{max} and u_{max} for which it is $1e-4$, and t_{TE} for

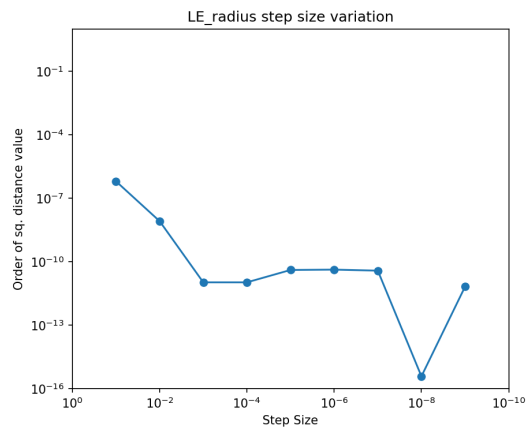
which it is $1e-5$. This helps us define our optimization statement in the next section.



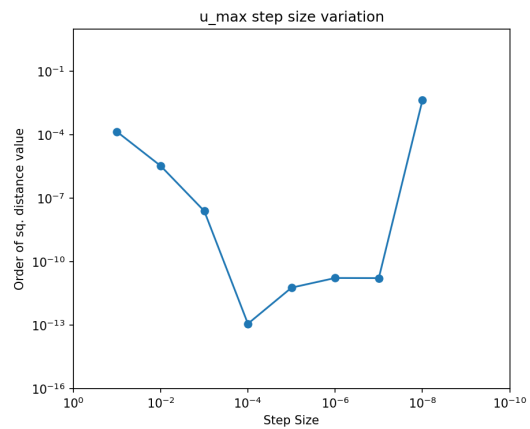
(a) *in_beta*



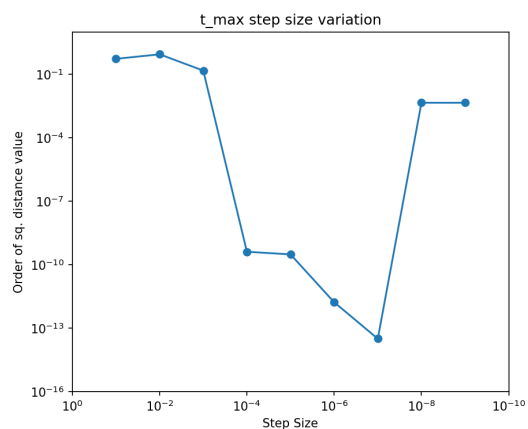
(b) *out_beta*



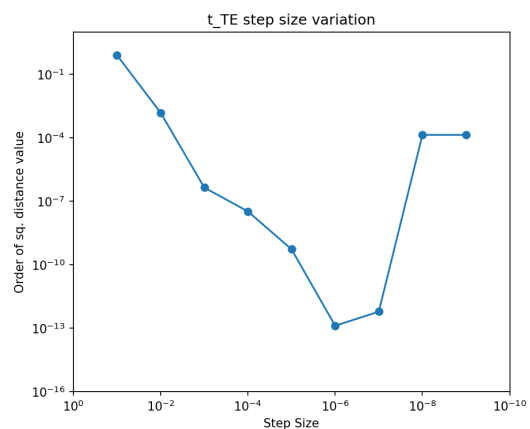
(c) *LERadius*



(d) *u_max*

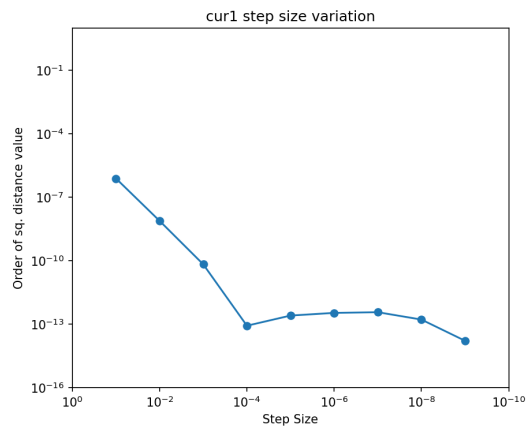


(e) *t_max*

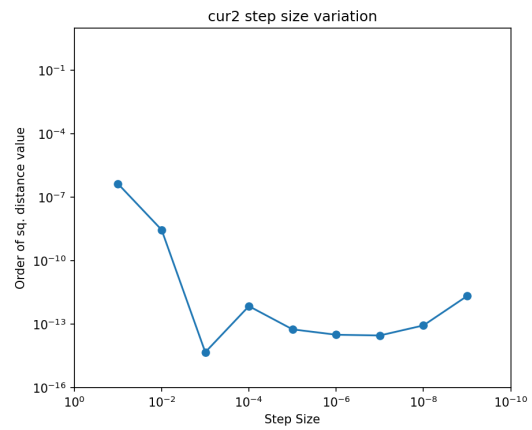


(f) *t_TE*

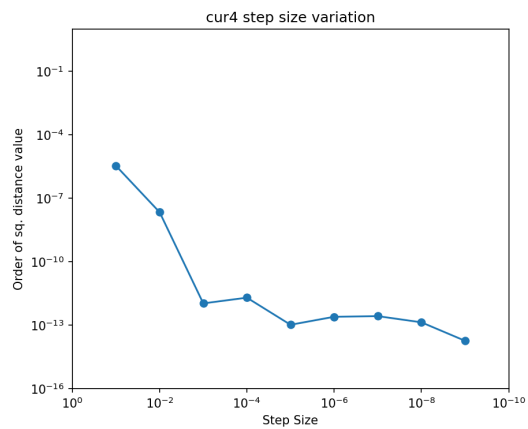
Figure 2.5: sq. distance v/s step size



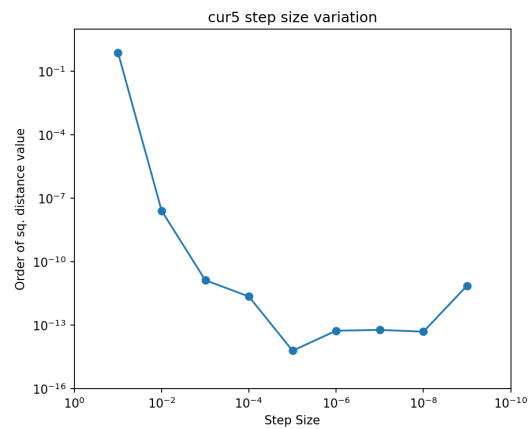
(g) cur1



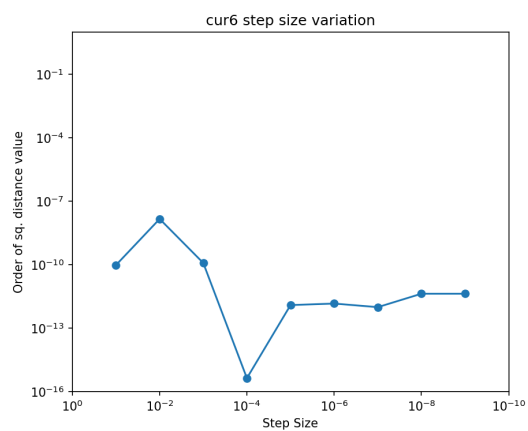
(h) cur2



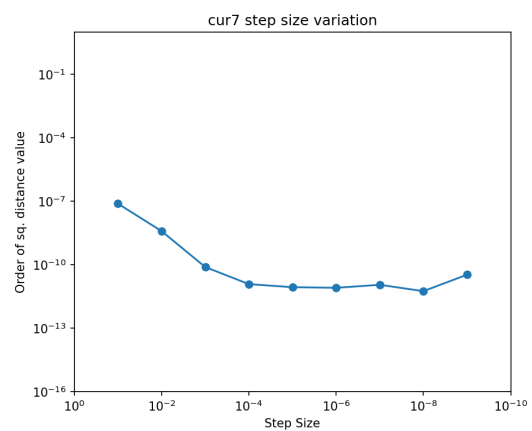
(i) cur4



(j) cur5



(k) cur6



(l) cur7

Figure 2.5: sq. distance v/s step size (contd.)

2.4 Optimization Statement

2.4.1 Minimize

Squared distance between points of a plot digitized airfoil and Tblade3 generated airfoil.

2.4.2 Design Variables

A total of 12 variables - two variables from 3dbginput file: *in_beta*, *out_beta*, and ten variables from spancontrolinput file: *cur1* to 7 except *cur3*, *LE_radius*, *u_max*, *t_max*, and *t_TE* were considered.

2.4.3 SLSQP Algorithm Parameters

A tolerance of $1e-3$ was set for Squared difference and maximum number of gradient evaluations was set to 400. Using inferences from step size study, the optimum step sizes were taken to be $1e-3$ for all the variables except *t_max* and *u_max* for which it is $1e-4$ and *t_TE* for which it is $1e-5$.

2.4.4 Range of design variables

- *in_beta* ranges between -35.10 and 55.50
- *out_beta* ranges between -30.00 and 20.45
- *cur* points 1 to 7 values range between -10.5 to 10.5 and are located at 0.00 , 0.15 , 0.25 , 0.50 , 0.75 , 0.95 , and 1.00 span respectively.
- *LE_radius* ranges between 2.0 and 5.5
- *u_max* ranges between 0.05 and 0.8
- *t_max* ranges between 0.01 and 0.4
- *t_TE* ranges between $1e-6$ and 0.1

2.4.5 Constants

Even though it can range between -10.5 to 10.5 , to obtain a unique solution case, *cur3* is kept constant at 2.31.

The optimization statement forms the basis for all the reverse engineering iterations, and we can next move on the demonstration of standard 2D airfoils in the next section.

Chapter 3

Airfoil demonstration cases

For 2D demonstration cases, we look at three types of airfoils: one with no camber, second with a camber, and lastly a wind turbine airfoil with a near-zero tip radius. The plot digitized target airfoil coordinates were all obtained from airfoiltools website and the stopping criterion for all these airfoil runs were set to $1e^{-03}$ with an initial condition of a generic zero camber airfoil.

3.1 NACA 0012

The NACA 0012 airfoil is a zero camber airfoil with a max thickness of 12% at 30% chord. There were 63 unit chord coordinates obtained from airfoiltools website and it took around 300 gradient evaluations of the objective function to reach a least squared difference value of $3.2659e-4$ as shown in Figure 3.1. Looking at the individual sections in Figure 3.2, the squared difference between the points is focused on the leading edge of both suction and pressure side. The optimization progression is shown in Figure 3.3, a quick stepped descent until 100th iteration with steep steps in the beginning after which the optimization slope reduces to a stagnant slope before resuming the step decline from 175th run. This continues until 250th iteration before stopping at 300th iteration. Figure 3.4 contains the initial and final values of each of the twelve parameters from the optimization, the camber - which is the difference between in_beta and out_beta angles is near zero with the maximum thickness value being 0.12336033. The plotted graph values of each variable are in Figures 3.5 and 3.6.

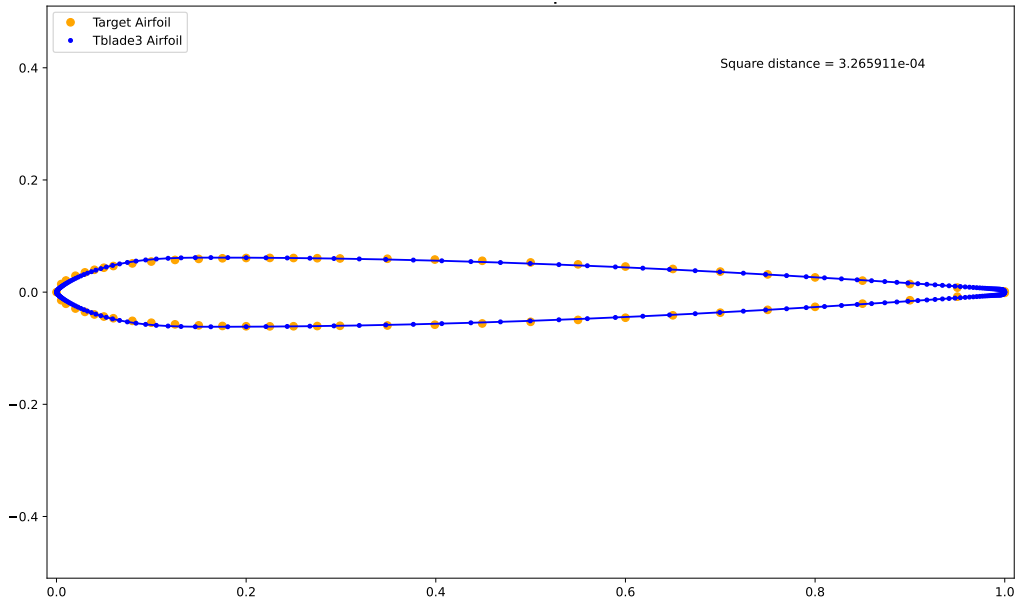


Figure 3.1: Least square difference between NACA 0012 airfoil and reverse engineered airfoil

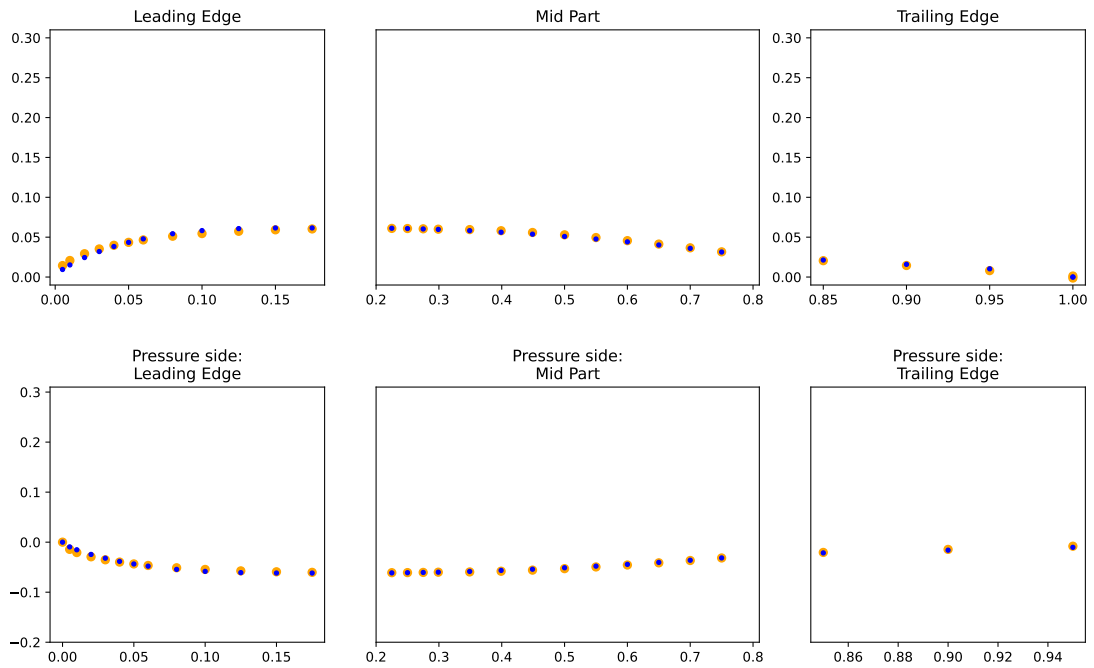


Figure 3.2: Tblade3 airfoil parts after interpolation to calculate least square difference - NACA 0012

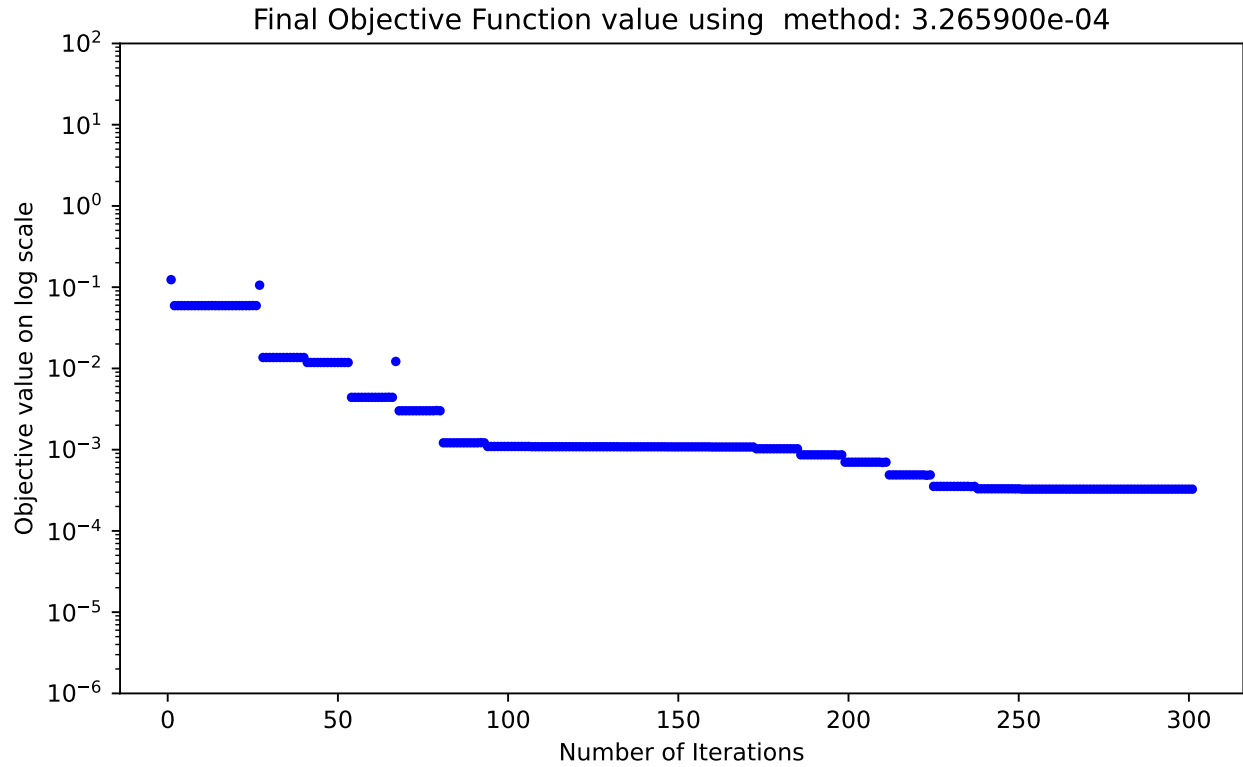


Figure 3.3: Least square difference between target airfoil and Tblade3 generated airfoil - NACA 0012

	Initial input values	Final input values
in_beta	3.0	1.46808322
out_beta	0.0	1.53708203
cur1	1.909	2.04102991
cur2	3.6695	3.71353521
cur4	1.458	1.21376261
cur5	0.8	0.79993379
cur6	0.82	0.98226726
cur7	0.81	0.90412942
LE_radius	2.5	2.78562328
u_max	0.55	0.16346221
t_max	0.246	0.12336033
t_TE	0.01548	0.0098933

Figure 3.4: Initial and Final parameter values - NACA 0012

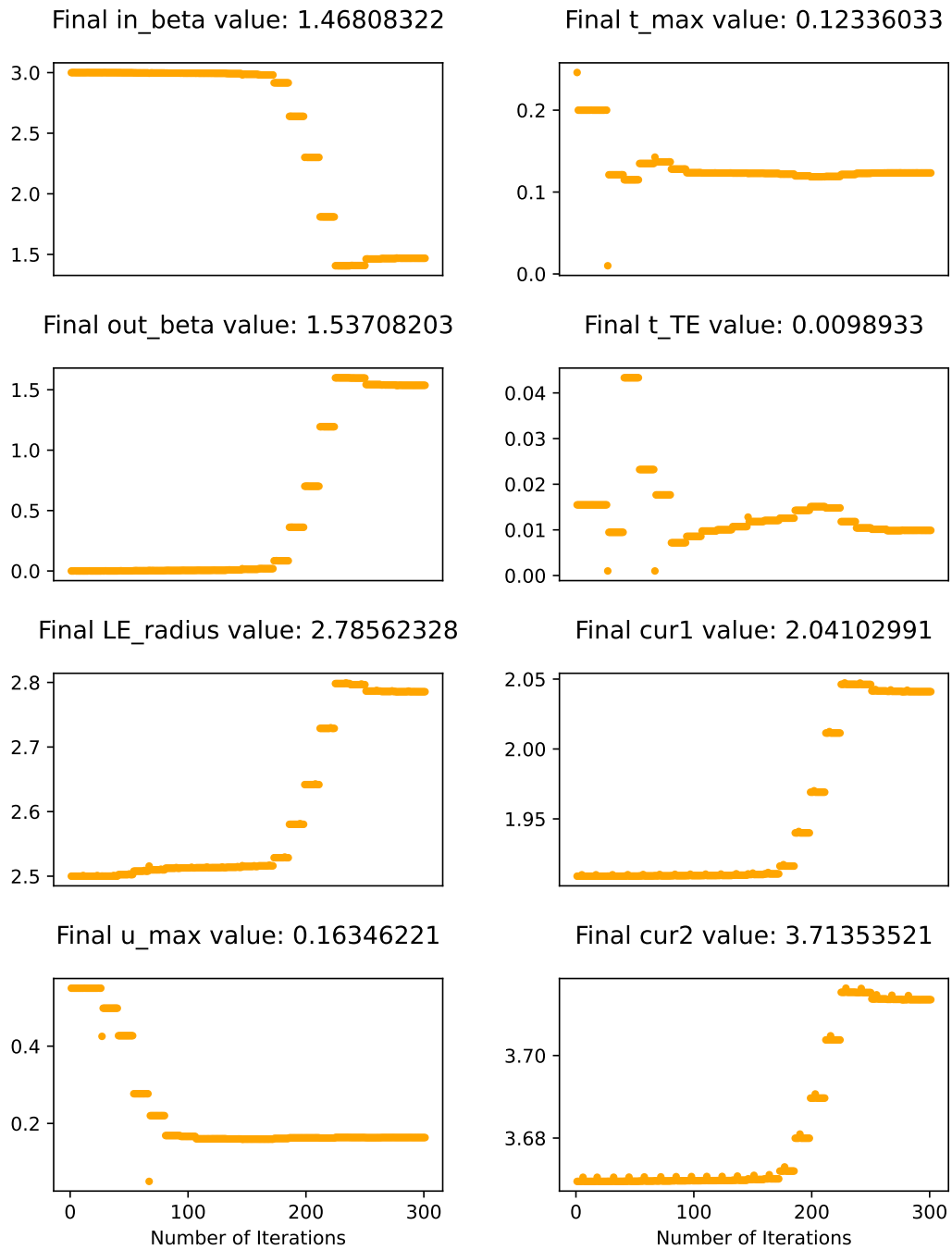


Figure 3.5: Initial and Final parameter plots - NACA 0012

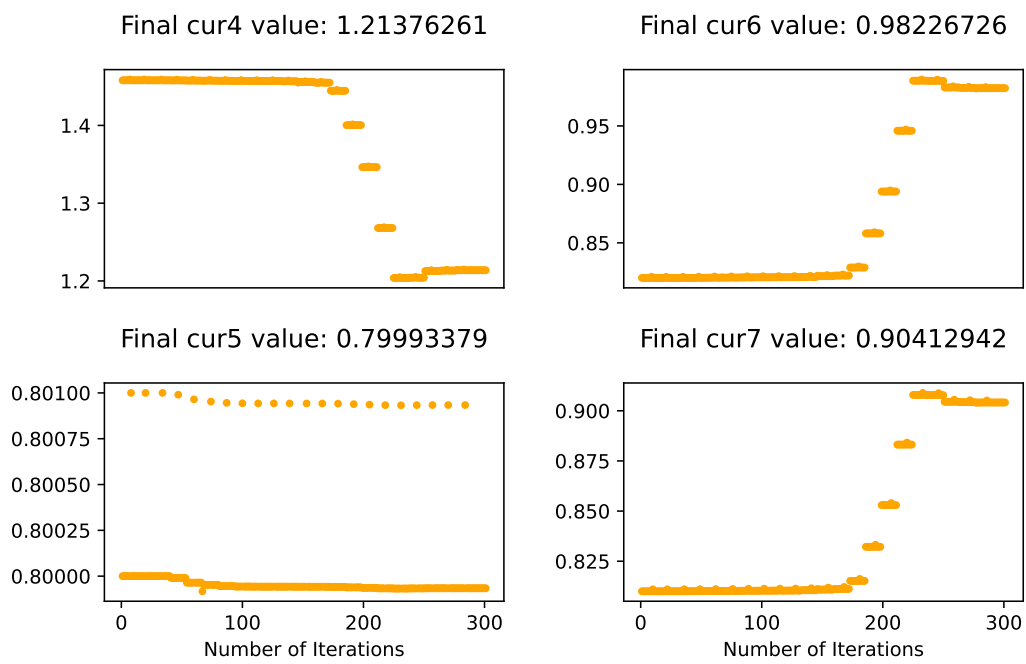


Figure 3.6: Initial and Final parameter plots - NACA 0012 (contd.)

3.2 NACA 2412

The NACA 2412 airfoil is a 2% camber airfoil at 40% chord with a max thickness of 12% at 30% chord. There were 63 unit chord coordinates obtained from airfoiltools website and it took around 450 gradient evaluations of the objective function to reach a least squared difference value of $1.5624e - 04$ as shown in Figure 3.7. Looking at the individual sections in Figure 3.8, the squared difference between the points is focused on the leading edge of pressure side. The optimization progression is shown in Figure 3.9, a quick stepped descent before 50th, 200th, and 350th iterations with other areas having a dull slope. Figure 3.10 contains the initial and final values of each of the twelve parameters from the optimization, the camber is about 11.2 degrees with the maximum thickness value being 0.11943561. The plotted graph values of each variable are in Figures 3.12 and 3.11.

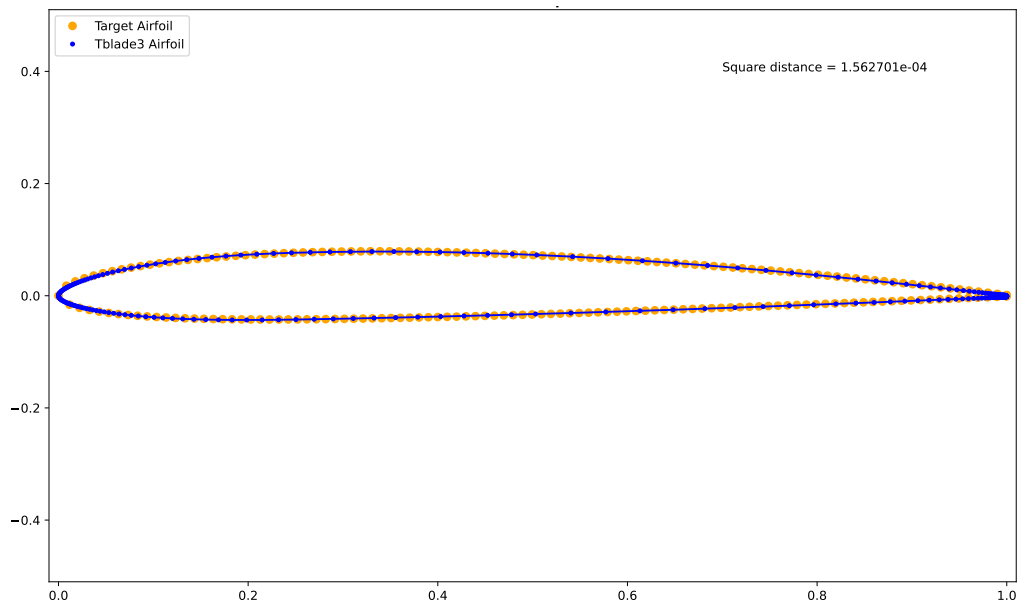


Figure 3.7: Least square difference between NACA 2412 airfoil and reverse-engineered airfoil

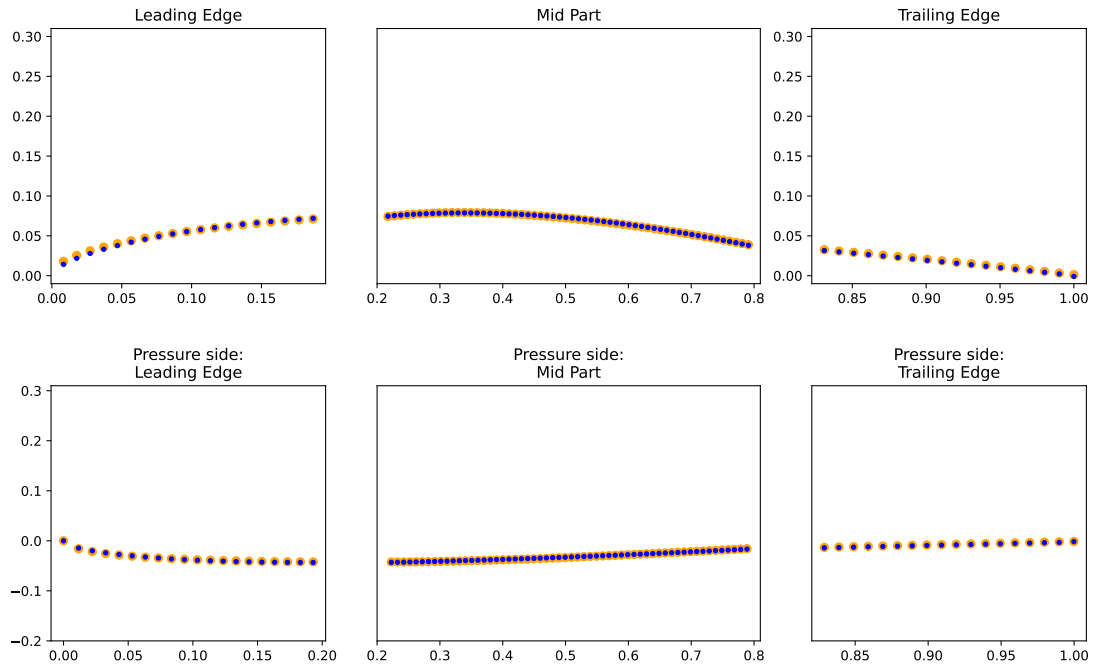


Figure 3.8: Tblade3 airfoil parts after interpolation to calculate least square difference - NACA 2412

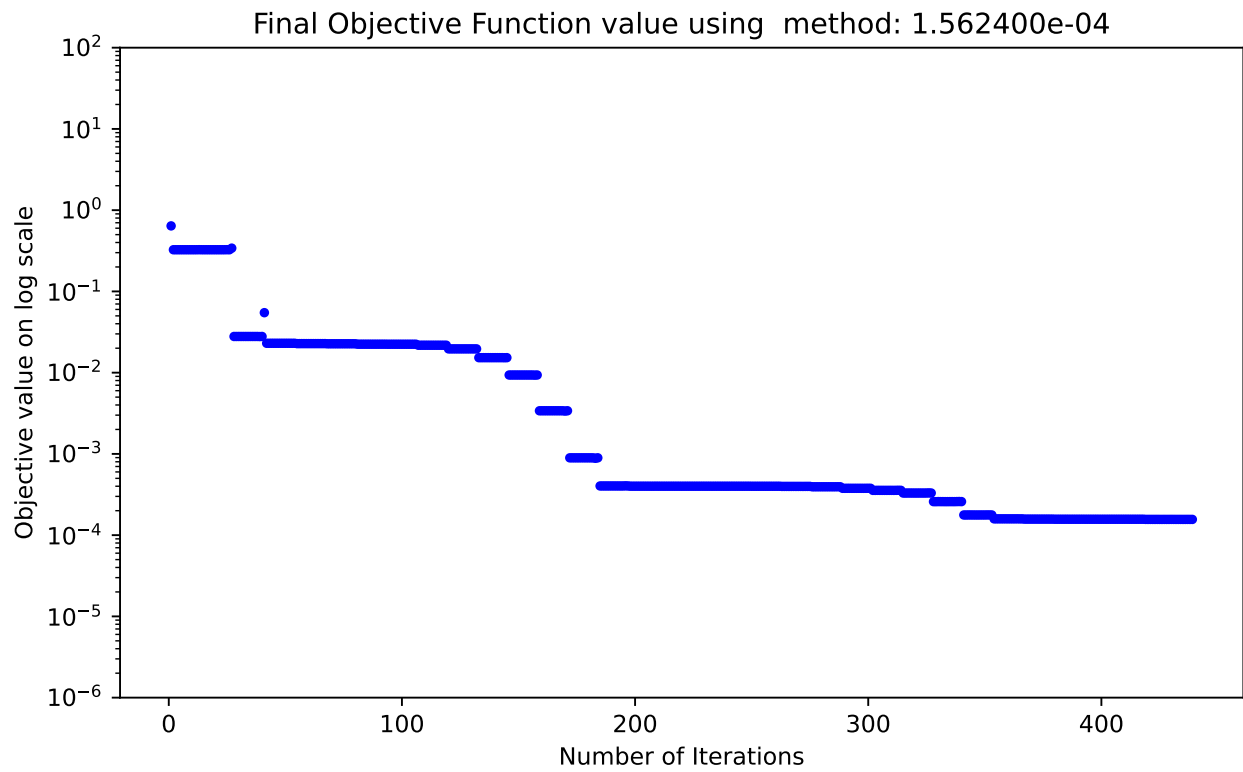


Figure 3.9: Least square difference between target airfoil and Tblade3 generated airfoil - NACA 2412

	Initial input values	Final input values
in_beta	3.0	7.10609787
out_beta	0.0	-4.14327427
cur1	1.909	1.55859773
cur2	3.6695	3.66767226
cur4	1.458	1.84772265
cur5	0.8	0.93696776
cur6	0.82	0.60758513
cur7	0.81	0.58956322
LE radius	2.5	4.5
u_max	0.55	0.27822828
t_max	0.246	0.11943561
t_TE	0.01548	0.00302627

Figure 3.10: Initial and Final parameter values - NACA 2412

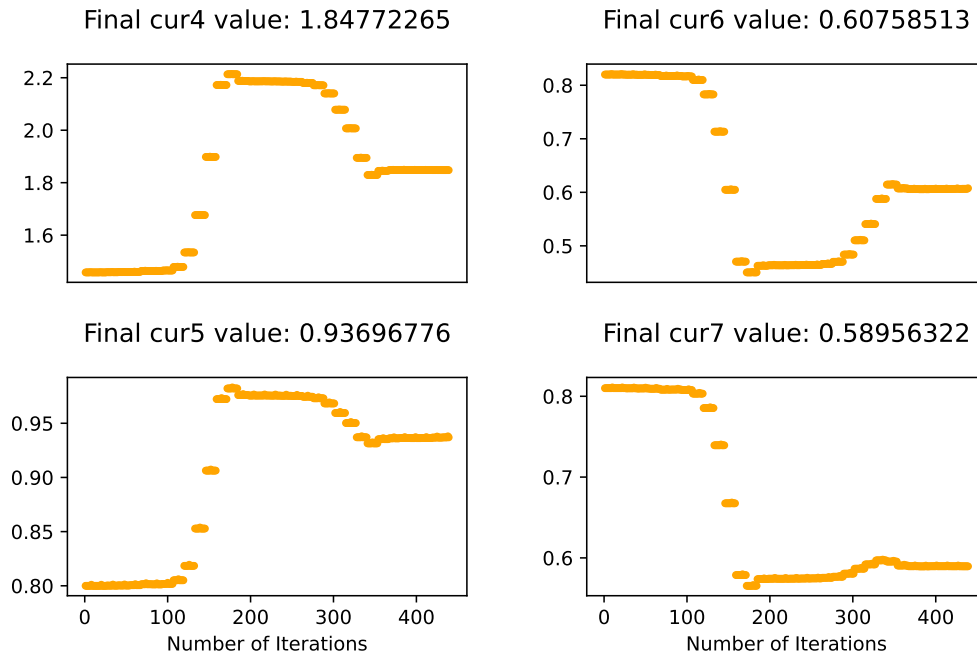


Figure 3.11: Initial and Final parameter plots - NACA 2412

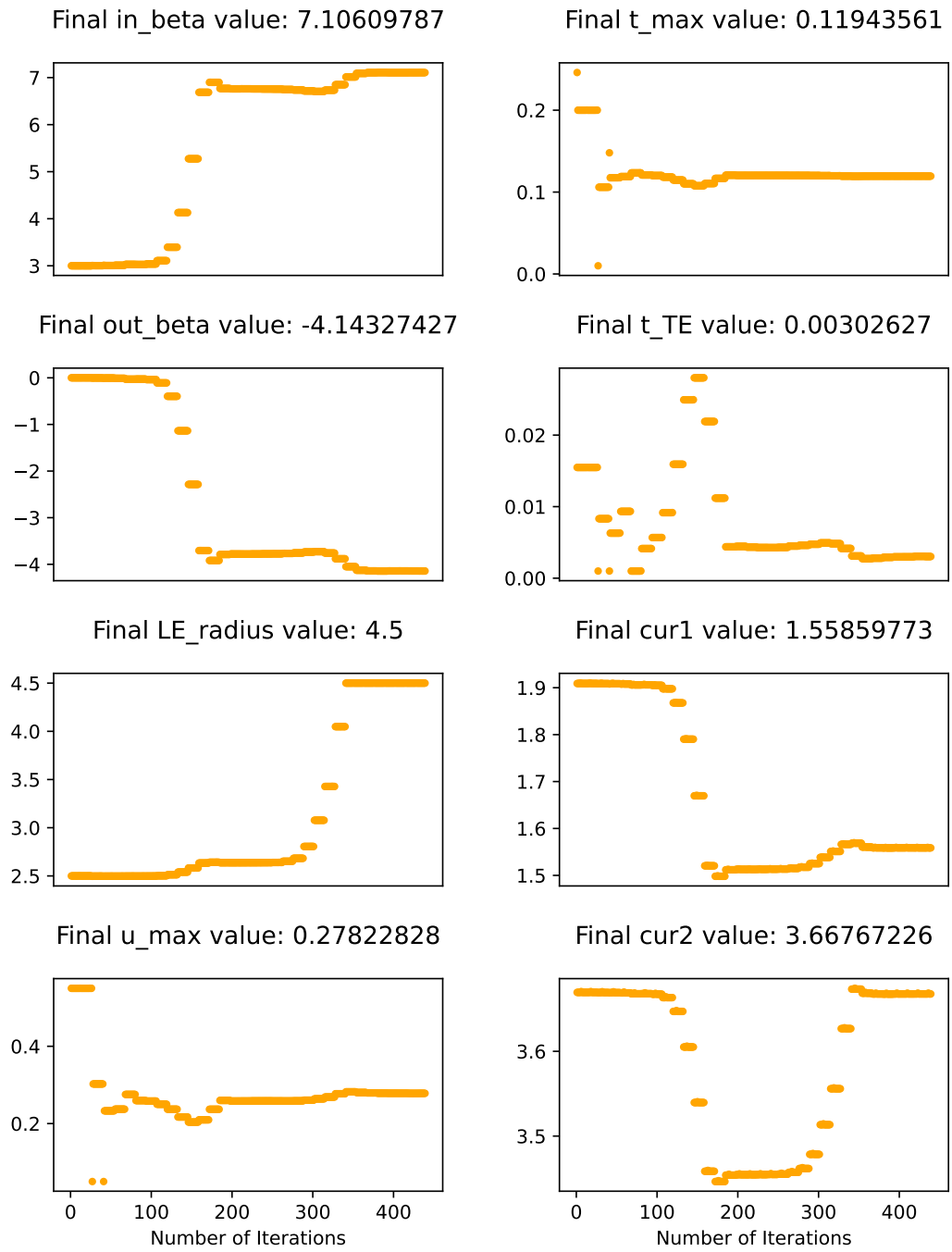


Figure 3.12: Initial and Final parameter values - NACA 2412

3.3 NREL s809

The NREL s809 airfoil is a wind turbine airfoil with Max thickness of 21% at 39.5% chord and max camber of 1% at 82.3% chord. There were 66 unit chord coordinates obtained from airfoiltools website and it took around 600 gradient evaluations of the objective function to reach a least squared difference value of $6.6977e - 04$ as shown in Figure 3.13. Looking at the individual sections in Figure 3.14, the squared difference between the points is focused on the mid sections of both the suction and pressure side along with the trailing edge pressure side. The optimization progression is shown in Figure 3.15, a quick stepped descent until 100th iteration with steep steps in the beginning after which the optimization slope reduces to a stagnant slope which continues until end of the simulation, this stagnation is attributed to the near-zero tip value. Figure 3.16 contains the initial and final values of each of the twelve parameters from the optimization, the camber is near zero with the maximum thickness value being 0.21034362. The plotted graph values of each variable are in Figures 3.18 and 3.17.

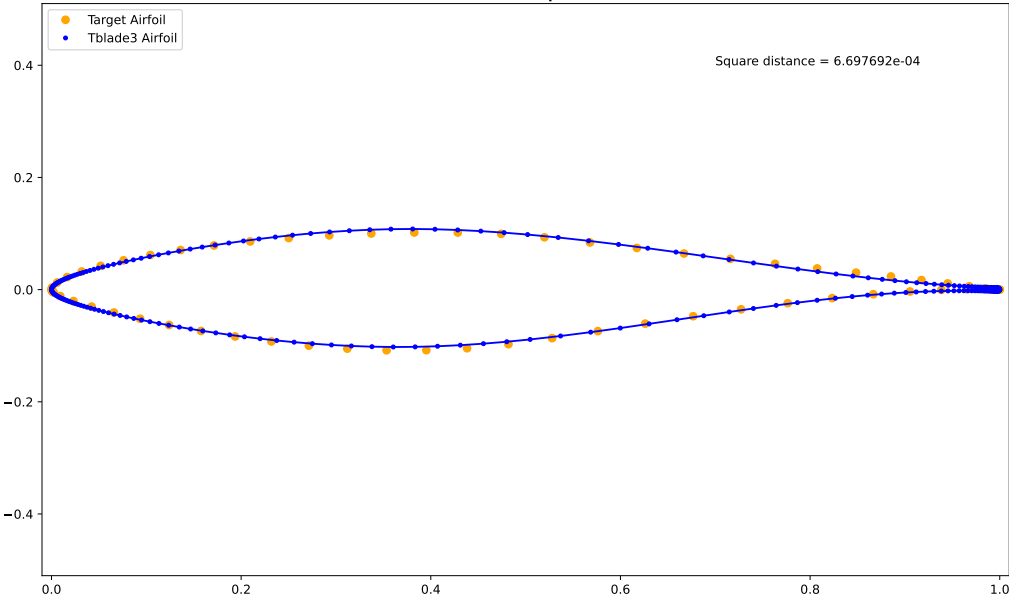


Figure 3.13: Least square difference between NREL s809 airfoil and reverse engineered airfoil

With the three types of 2D airfoil cases demonstrated we can move on to 3D airfoil demonstration cases, where we compare the traditional blade design method and look at why our reverse engineering method is needed.

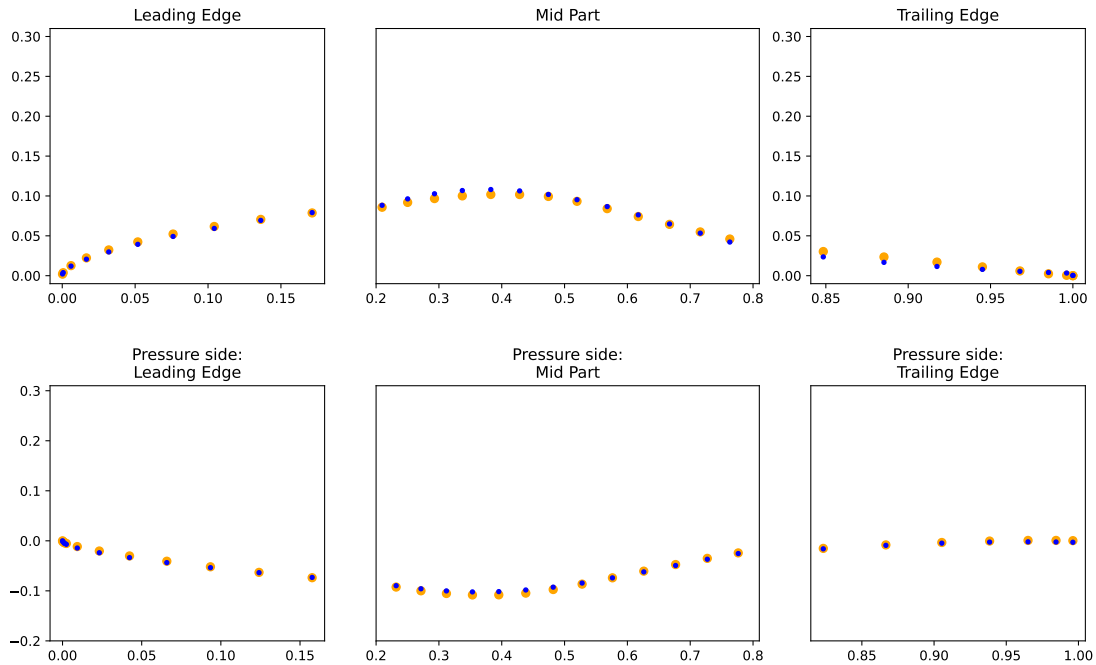


Figure 3.14: Tblade3 airfoil parts after interpolation to calculate least square difference - NREL s809

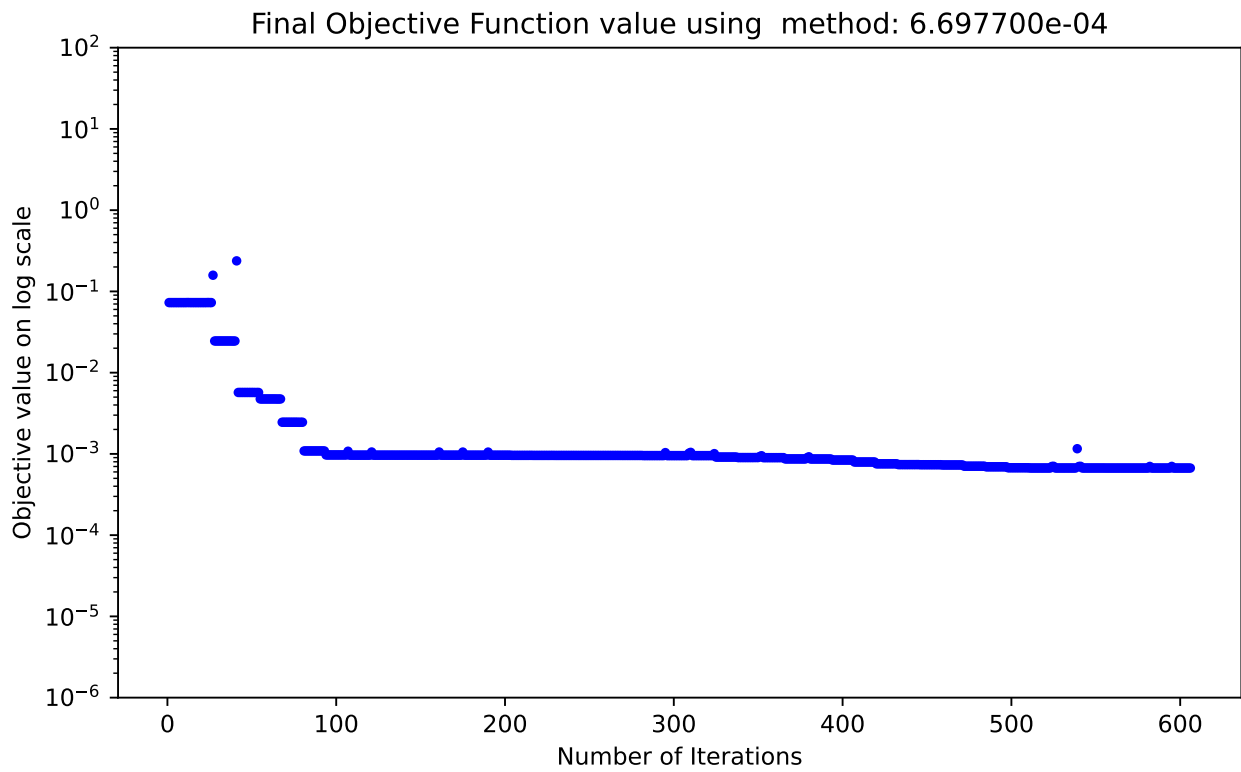


Figure 3.15: Least square difference between target airfoil and Tblade3 generated airfoil - NREL s809

	Initial input values	Final input values
in_beta	1.0	2.63609743
out_beta	-1.0	-2.62784313
cur1	-9.909	-9.80517789
cur2	3.6695	3.78786631
cur4	1.458	1.53725348
cur5	-5.8	-5.8688854
cur6	-9.82	-9.81997424
cur7	-9.81	-9.78749062
LE radius	2.5	2.71227853
u_max	0.55	0.37184864
t_max	0.246	0.21034362
t_TE	0.0001548	0.00620374

Figure 3.16: Initial and Final parameter values - NREL s809

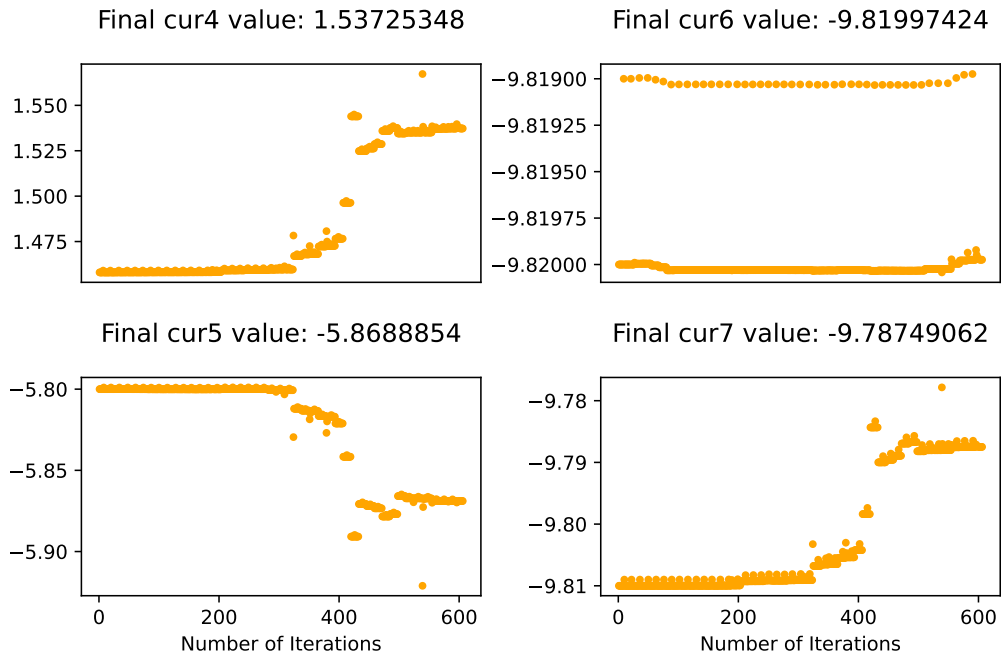


Figure 3.17: Initial and Final parameter values - NREL s809

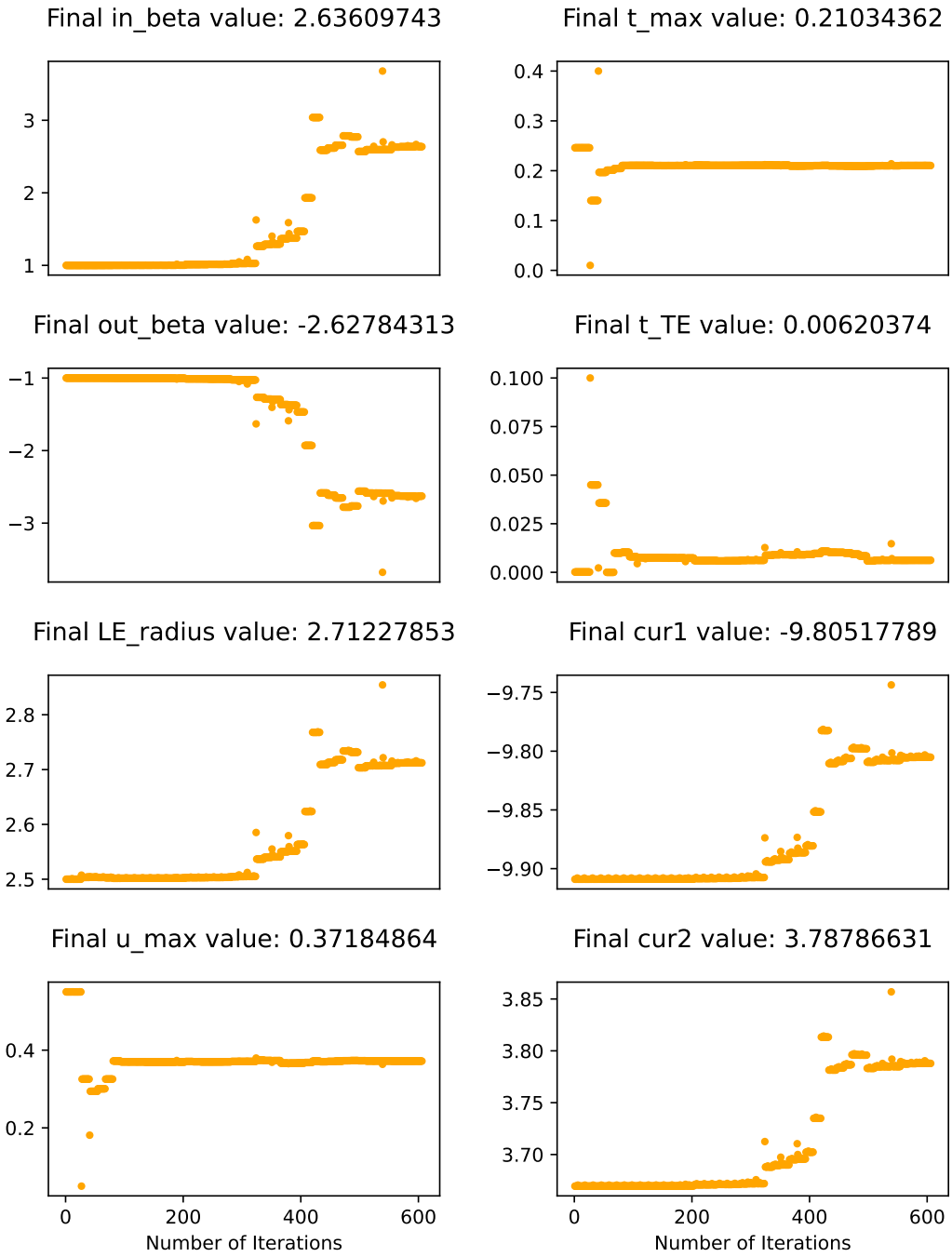


Figure 3.18: Initial and Final parameter values - NREL s809

Chapter 4

3D Blade design of E3 fan

The reverse engineering framework applied to 3D blade is demonstrated in the following sections. We look at a manual specification process that would traditionally be carried out in Tblade3 and contrast that with using reverse engineering framework for the blade design. For simplicity reasons and to focus on the blade design, the E3 Fan blade will be designed without a part-span shroud.

The E3 fan report has a snapshot of the fan configuration - Figure 4.1 and its appendix has two tables for rotor R1 describing the design properties that give further insight on the flow regime as shown in Figure 4.2 and Figure 4.3. Using information from these tables and by plot-digitizing the hub and casing we move to the first step in blade design.

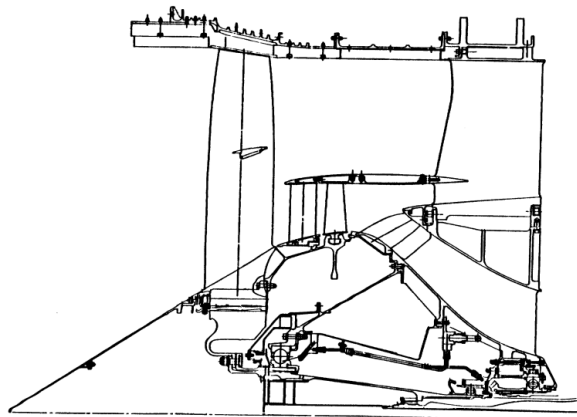


Figure 4.1: E3 report - fan configuration

4.1 Preparation of Input files

4.1.1 3dbgbinput file setup

The primary input file for Tblade3 is "3dbgbbuilder.1.dat". It takes in the metal angles, axial and radial coordinates, and surface of rotation coordinates all of which were obtained from the report except for metal angles which were along the planar sections of the blade but the input file needed them in streamline sections. This meant that the metal angles had to be estimated along the streamlines.

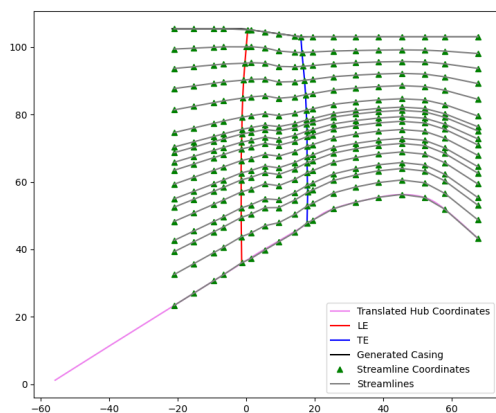


Figure 4.4: Generated E^3 surfaces of revolution for Tblade3

Along with allowing control over the airfoil section's metal angles, Tblade3 also allows these sections to be placed along surfaces of revolutions. Since page 12 of the report had the hub and casing positions, and the Appendix A had LE_z , TE_r , TE_z , and TE_r values. A python script (Appendix C.1), was written to generate these streamlines or surfaces of revolutions for Tblade3 as shown in Figure 4.4.

Now that we have the primary input file ready, we next move on to gather input values to control the curvature of the blade.

4.1.2 Spancontrolinputs file setup

The secondary input file for Tblade3 is the spancontrolinputs file. This input file has two tables, the first one helps to control the curvature of the camber and the second one helps control the LE

and TE tip thickness, and location and value of maximum thickness. Three spans of the blade were chosen to control these parameters: 0, 55, and 100. Both table parameters were defined along these spans. All the curvature points in the first table were obtained through traditional manual parameter specification of $(u - v)$ sections. The second table within the spancontrolinputs file, however, was a bit different. While the LE and TE tip thickness points were estimated using trial and error, the location and value of maximum thickness was obtained from the E^3 report. The plots in the report - Figure 4.5, Figure 4.6, Figure 4.7 were digitized and the values of total thickness at the required spans were linearly interpolated. Once we had both the input files ready, a final plotting script was written to visually compare (Figure 4.9) the output files from Tblade3 and plot digitized airfoil sections from $E3$ report. While the reports do offer relevant information, it is not a complete list of airfoil design data. To obtain that CAD info, we will be using two methods – first is a traditional manual parameter specification based, and another using the framework in the next sections.

4.2 Generation of input parameters

We start by looking at the report to analyze the information available about the three airfoils - hub, part-span shroud, and tip. The hub section's max thickness location is at 42% chord and has a tm/c value of 0.125 - Figure 4.5. Flow in the hub is subsonic with a Mach number of 0.70 at inlet rising to 0.75 at the outlet. Part span shroud section's maximum thickness location is at 55% chord with a tm/c value of 0.044 - Figure 4.6. Flow at inlet has a Mach number of 1.15 with an exit mach number of 0.68. Moving on, tip section's maximum thickness location is at 59% chord with a tm/c value of 0.024 - Figure 4.7. Flow at the inlet has the highest Mach number of 1.41 near the tip section falling to a transonic range of 0.87 at the outlet of the tip. The report also mentions the presence of a favorable oblique shock near the part-span shroud and tip section airfoil before the normal shock at the design case. With these paramaters in mind, we then move to the first approach.

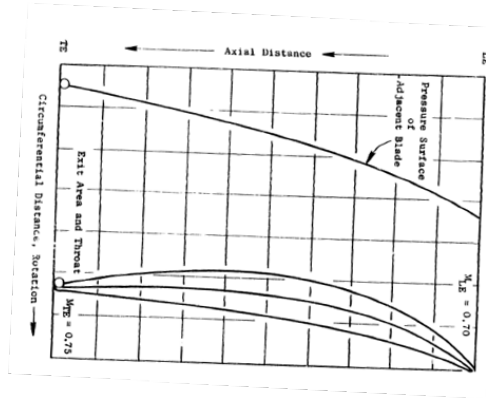


Figure 4.5: E3 engine fan - Hub airfoil section

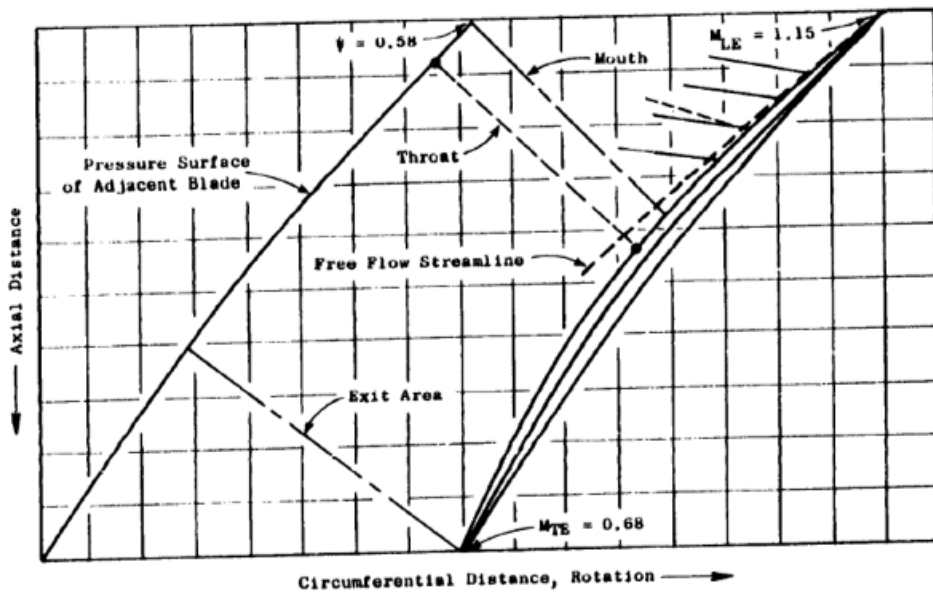


Figure 4.6: E3 engine fan - part-span shroud airfoil section

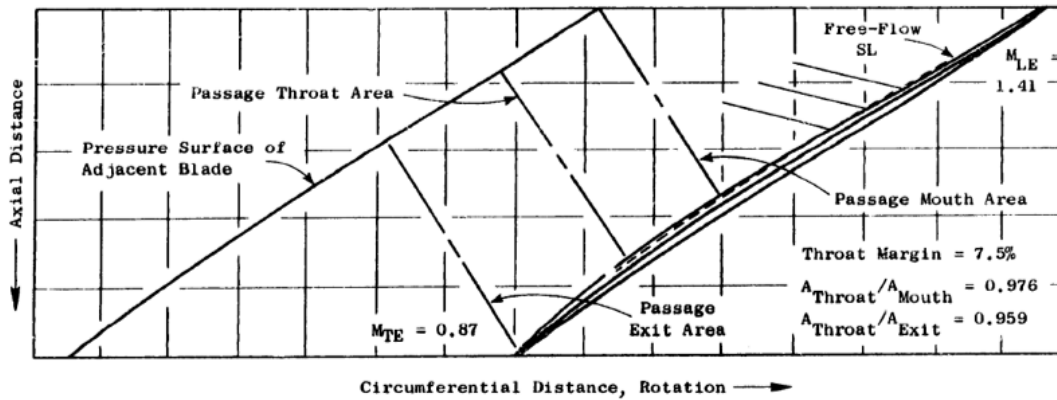


Figure 4.7: E3 engine fan - tip airfoil section

4.2.1 Traditional manual parameter specification method

Figure 4.9 shows the comparison of generated airfoil section coordinates - shown in blue and plot digitized streamlines sections shown in orange. The coordinates were normalized and rotated such that the stagger is zero and can be expressed in $(u - v)$ coordinate system with the u value between 0 and 1.

The sections in Figure 4.9 were the closest that we could obtain from traditional manual parameter specification. Figure 4.8a shows the 3D blade view of a single blade passage as visualized along with its hub and casing. On its right is its full-annulus view with all 32 blade passages. Here, we can clearly see the cone like hub. Once the blade sections were close enough to the streamline sections from the report, the Tblade3 output files were converted into a .geomturbo file format to carry out grid generation. The input values parameter values for these files were only precise until the second decimal and can be found in Appendix E.1.

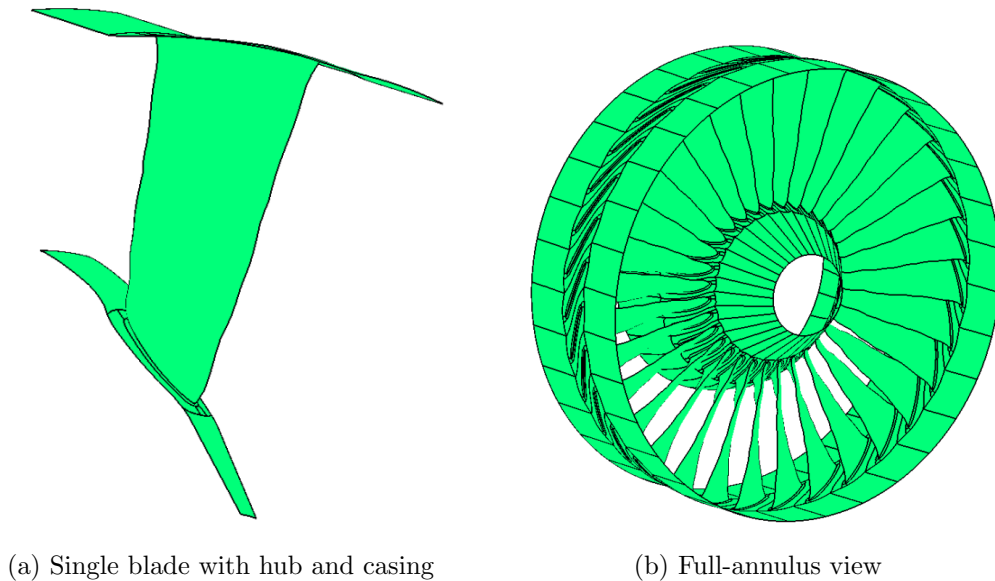
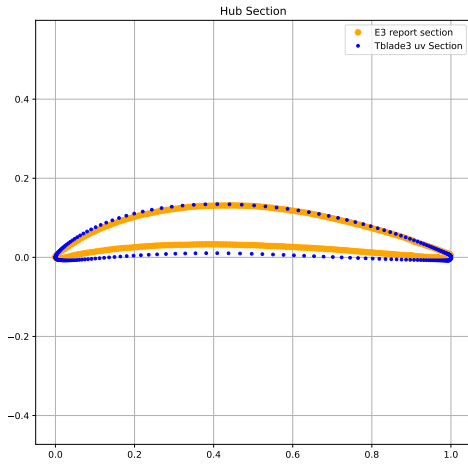
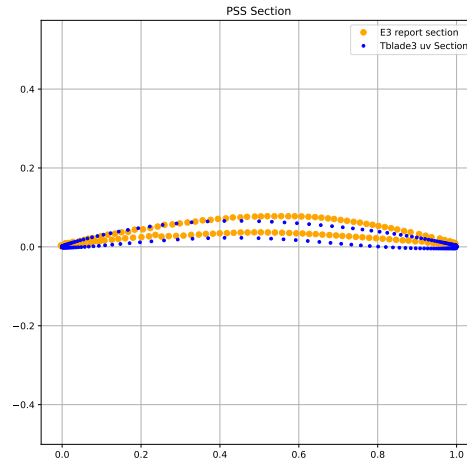


Figure 4.8: 3D blade shape from traditional manual parameter specification in Tblade3

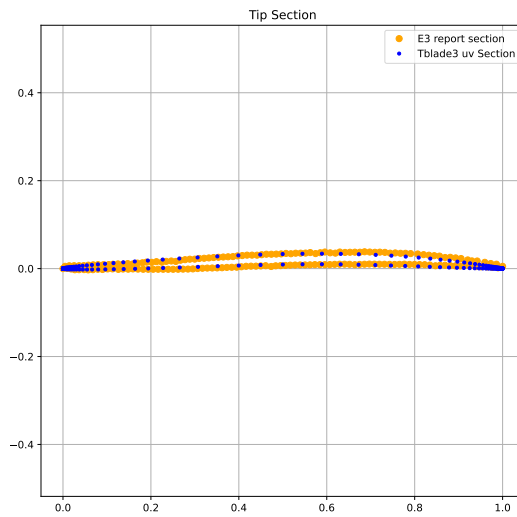
This traditional manual parameter specification approach takes a lot of back-and-forth and is not ideal when precision is needed. Reverse engineering framework is bought in next to demonstrate how quick and more precise the process can be.



(a) At 0.00% span



(b) At 55.00% span



(c) At 100.00% span

Figure 4.9: E3 Sections Comparison - sections from traditional manual parameter specification of input parameters

4.2.2 Reverse engineering framework method

E3 Hub Section

The stopping criterion was set to $1e^{-03}$ and for the plot digitized hub it took around 350 gradient evaluations for the objective function to reach a least squared difference value of $9.0006e - 04$ as shown in Figure 4.10. We can clearly see the difference in closeness when compared to Figure 4.9a. Looking at the individual sections in Figure 4.11, the squared difference between the points is the minimum near the mid-section points and increases as we move towards the extremes with the highest difference at the suction side trailing edge. The optimization progression is shown in Figure 4.12, a steep descent until 150th iteration is observed with a steady descent until 200th iteration followed by stagnation and some noise before the optimization stops near 350th iteration. Figure 4.13 contains the initial and final values of each of the twelve parameters from the optimization, the location of maximum thickness is at 0.4565529 with the maximum thickness value being 0.09702214. The plotted graph values of each of the 12 variables is in Figure 4.15 and Figure 4.14.

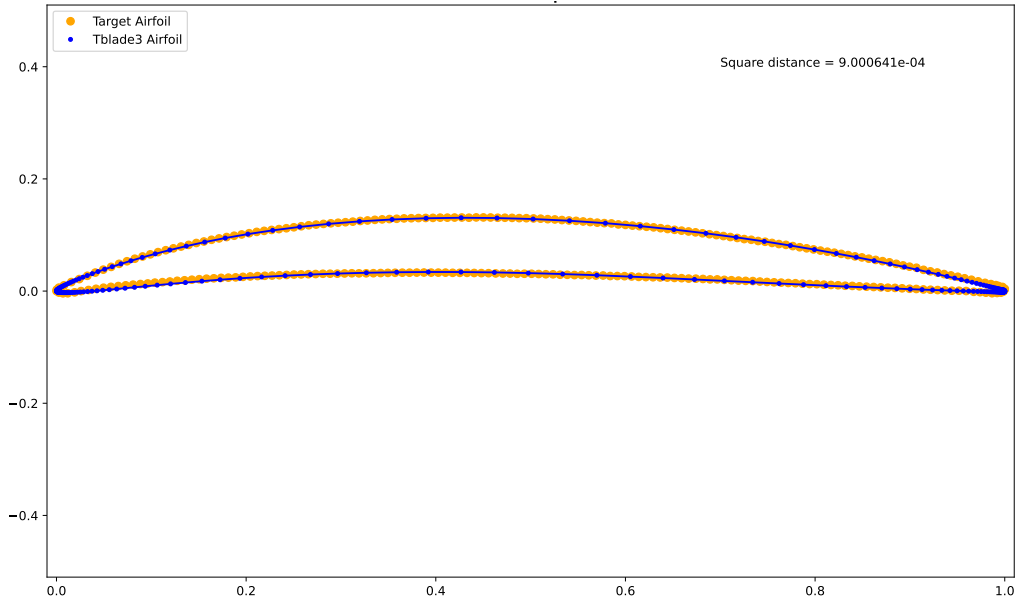


Figure 4.10: Least square difference between plot digitized hub and reverse engineered airfoil

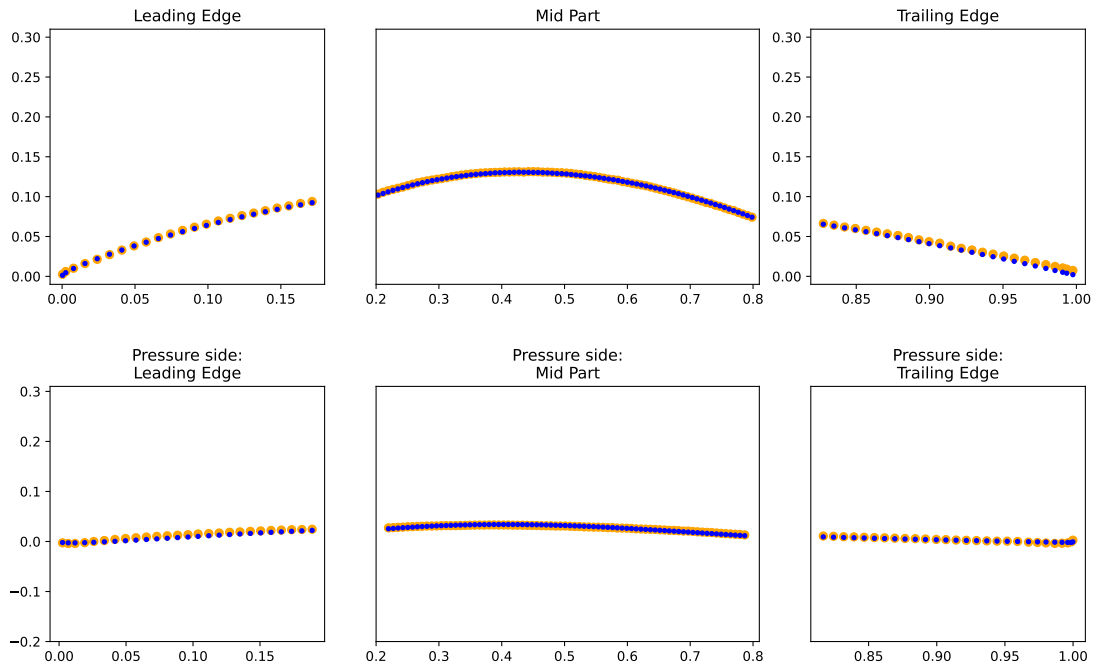


Figure 4.11: Reverse engineered section comparison for E3 hub airfoil

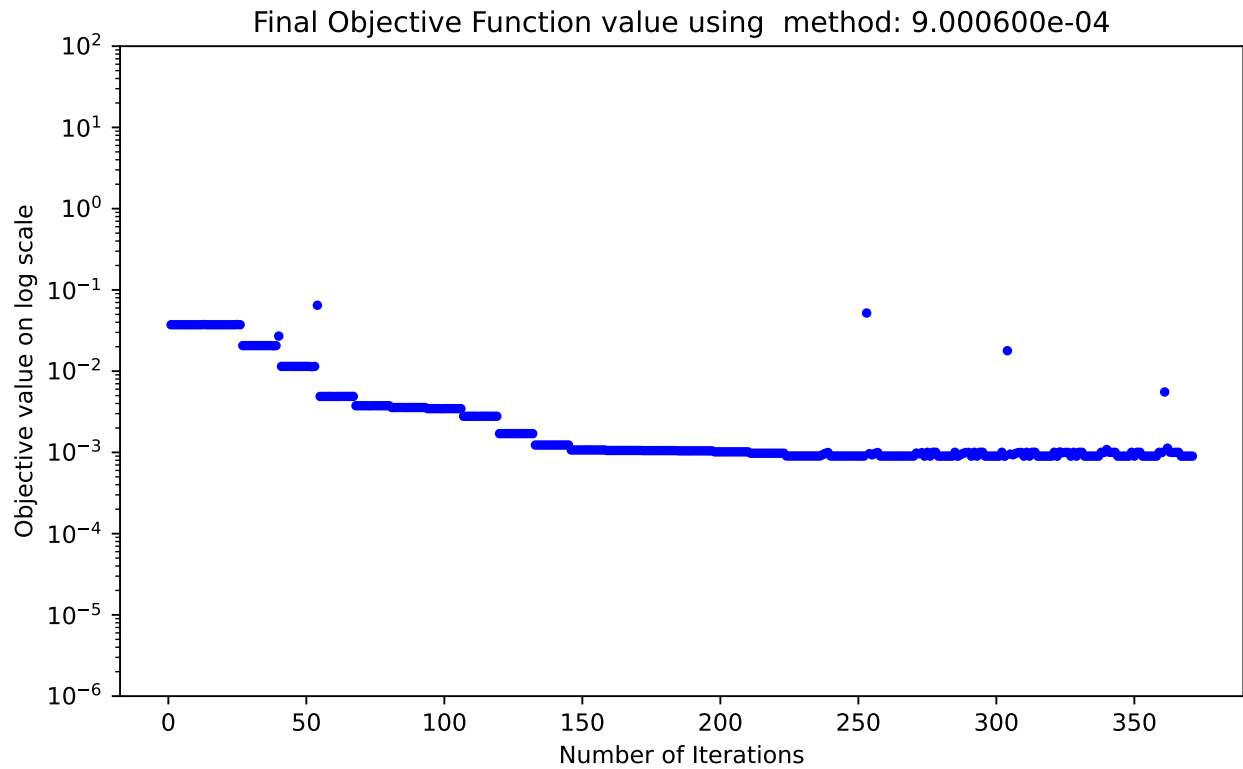


Figure 4.12: Reverse engineered section - Objective function vs iterations for E3 hub

	Initial input values	Final input values
in_beta	32.79	33.01142082
out_beta	-7.87	-8.07361942
cur1	1.909	1.69591536
cur2	3.6695	3.631585
cur4	1.458	1.75181355
cur5	0.8	0.70739264
cur6	0.82	0.5110641
cur7	0.81	0.63949916
LE radius	2.5	2.35916208
u_max	0.42	0.4565529
t_max	0.124	0.09702214
t_TE	0.01548	0.0036372

Figure 4.13: Reverse engineered Hub section - Initial and Final parameter values

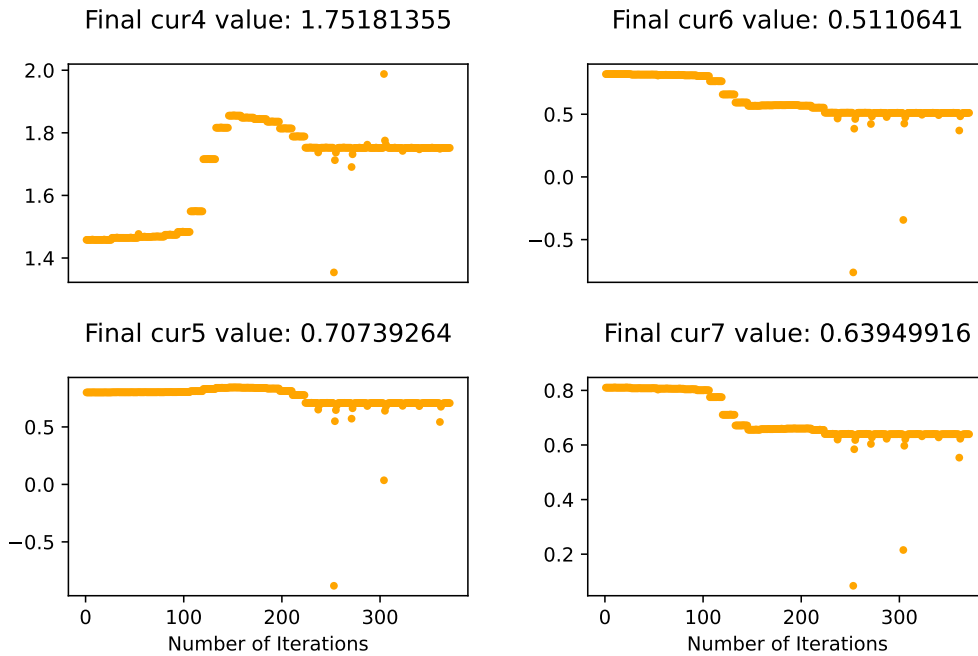


Figure 4.14: Reverse engineered Hub section - plots of variables (contd.)

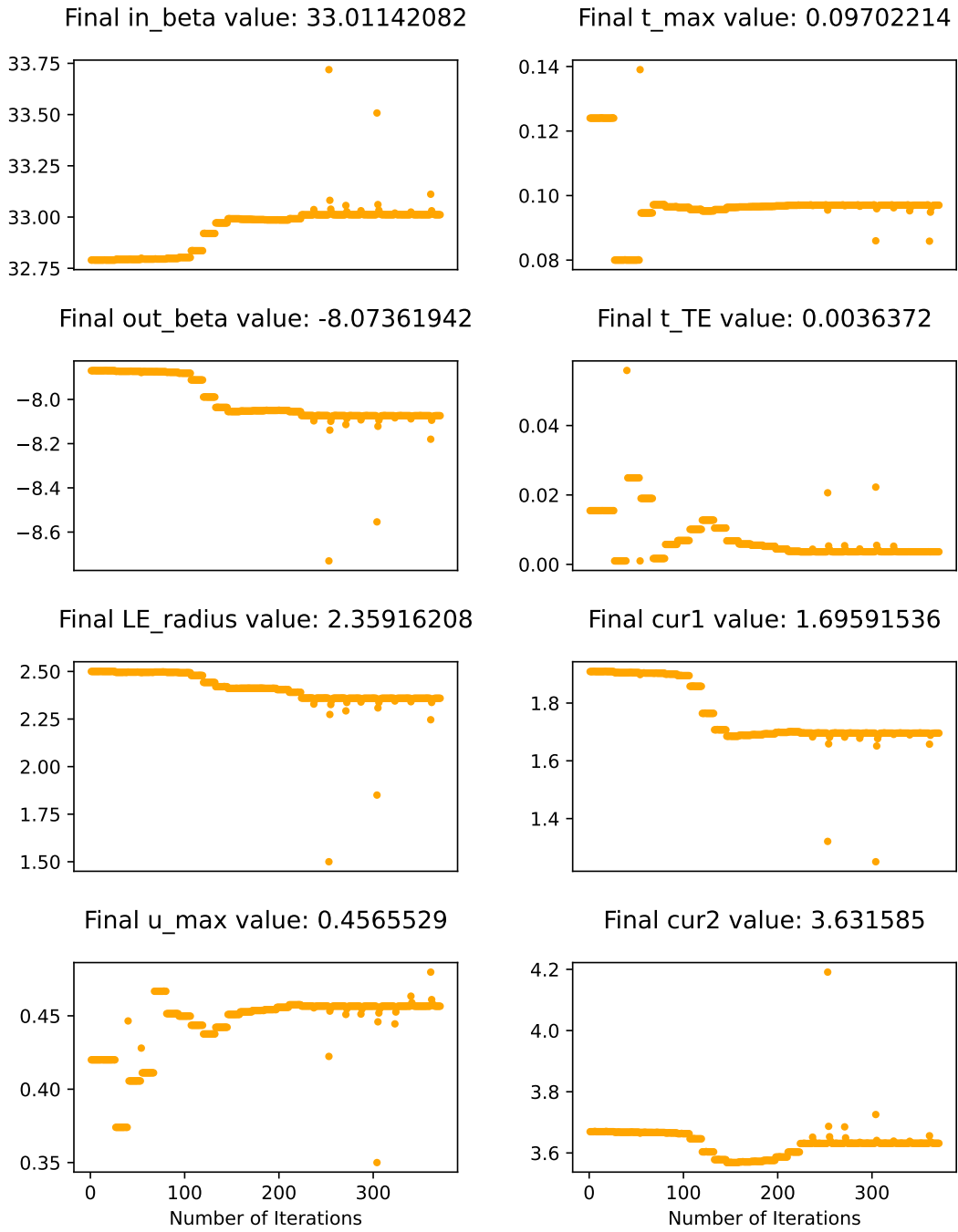


Figure 4.15: Reverse engineered Hub section(contd.) - plots of variables

E3 part-span shroud Section

The stopping criterion was set to $1e^{-03}$ and for the plot digitized part-span shroud it took around 450 gradient evaluations of the objective function to reach a least squared difference value of $9.7875e - 04$ as shown in Figure 4.16. We can clearly see the difference in closeness when compared to Figure 4.9b. Looking at the individual sections in Figure 4.17, the squared difference between the points is spread out over the span of the airfoil and is not concentrated in any particular section. The optimization progression is shown in Figure 4.18, a stepped descent until 200th iteration is observed with a steady descent until 350th iteration followed by a final step descent before the optimization stops near 450th iteration. Figure 4.19 contains the initial and final values of each of the twelve parameters from the optimization, the location of maximum thickness is at 0.61471969 with the maximum thickness value being 0.03565671. The plotted graph values of each variable are in Figure 4.21 and Figure 4.20.

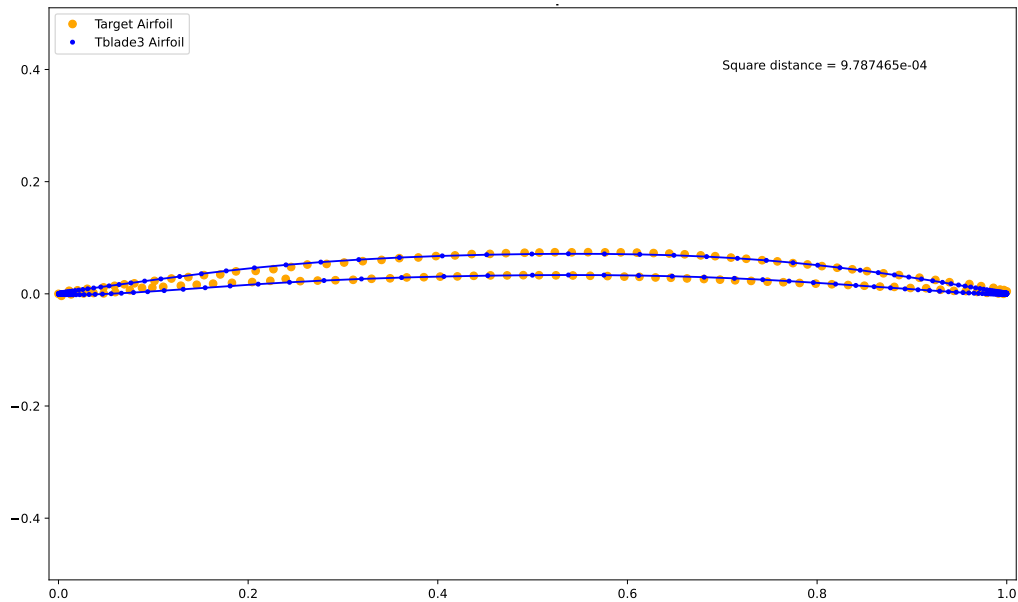


Figure 4.16: Least square difference between plot digitized part-span shroud and reverse engineered airfoil

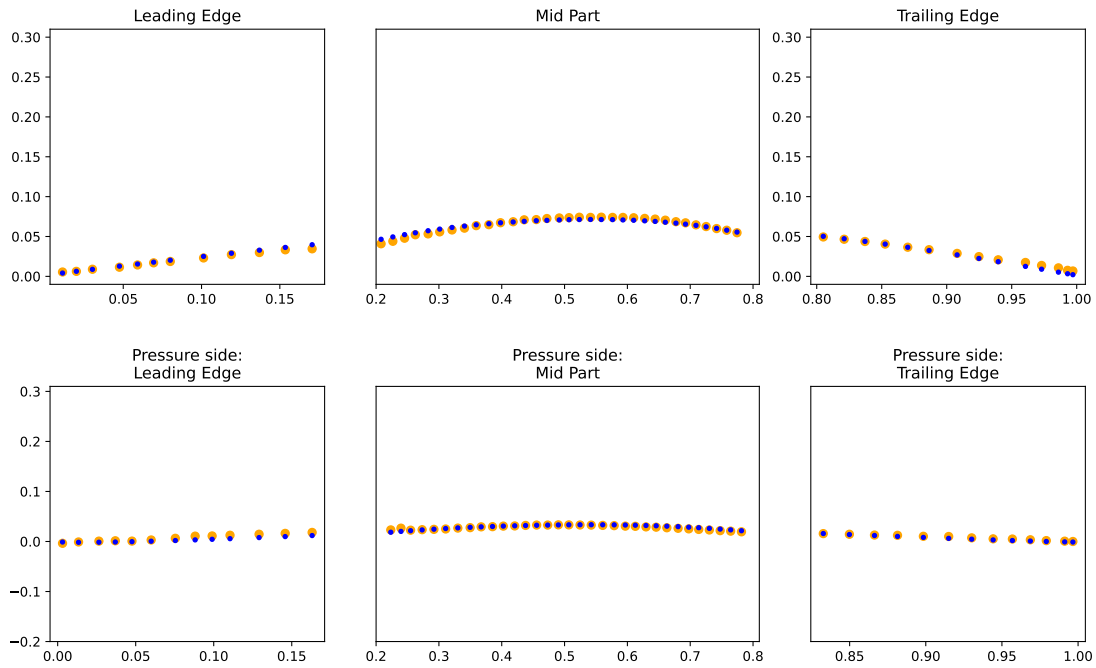


Figure 4.17: Airfoil parts comparison for E3 part-span shroud airfoil

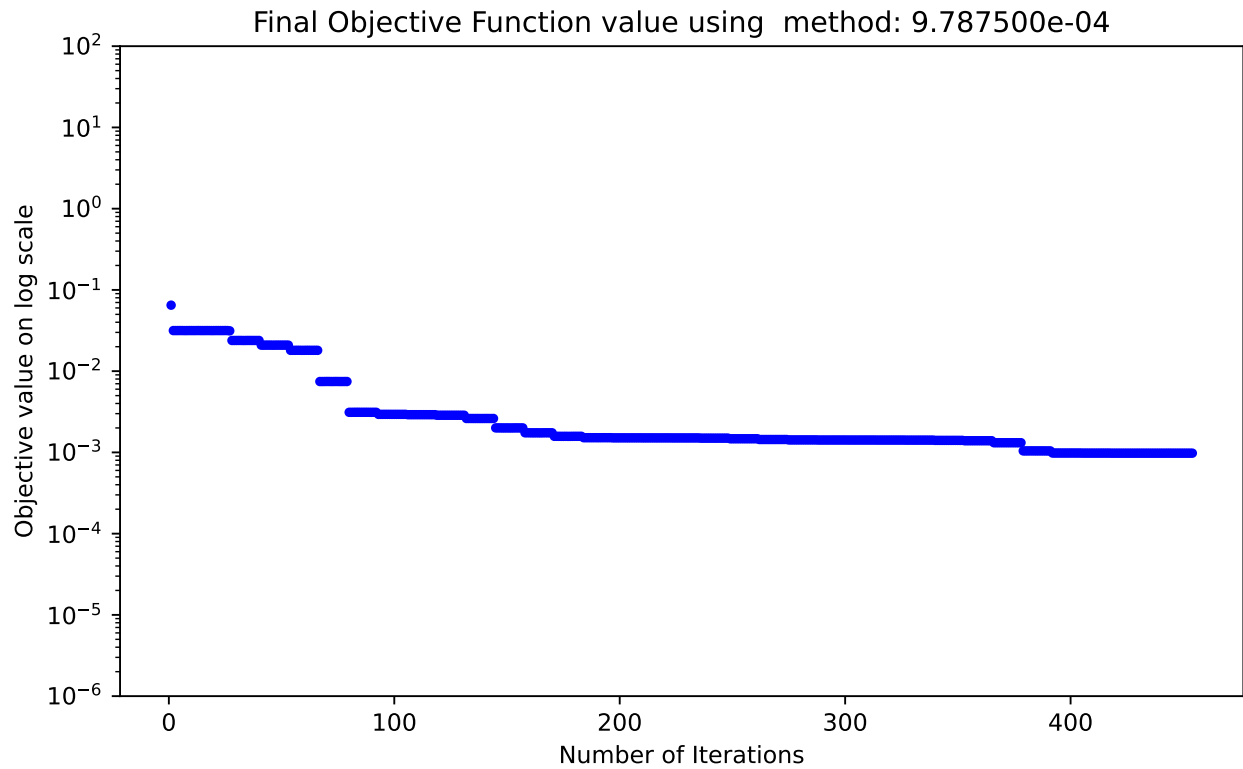


Figure 4.18: Objective function vs iterations for E3 part-span shroud

	Initial input values	Final input values
in_beta	12.01	12.6239569
out_beta	-2.81	-3.41018501
cur1	0.1	-0.95219209
cur2	0.1	0.30333961
cur4	0.1	0.02079878
cur5	0.3	0.84501973
cur6	0.4	-0.01305618
cur7	0.1	-0.66589321
LE radius	2.5	2.22871712
u_max	0.58	0.61471969
t_max	0.044	0.03565671
t_TE	0.1	0.0001

Figure 4.19: E3 part-span shroud - Initial and Final parameter values

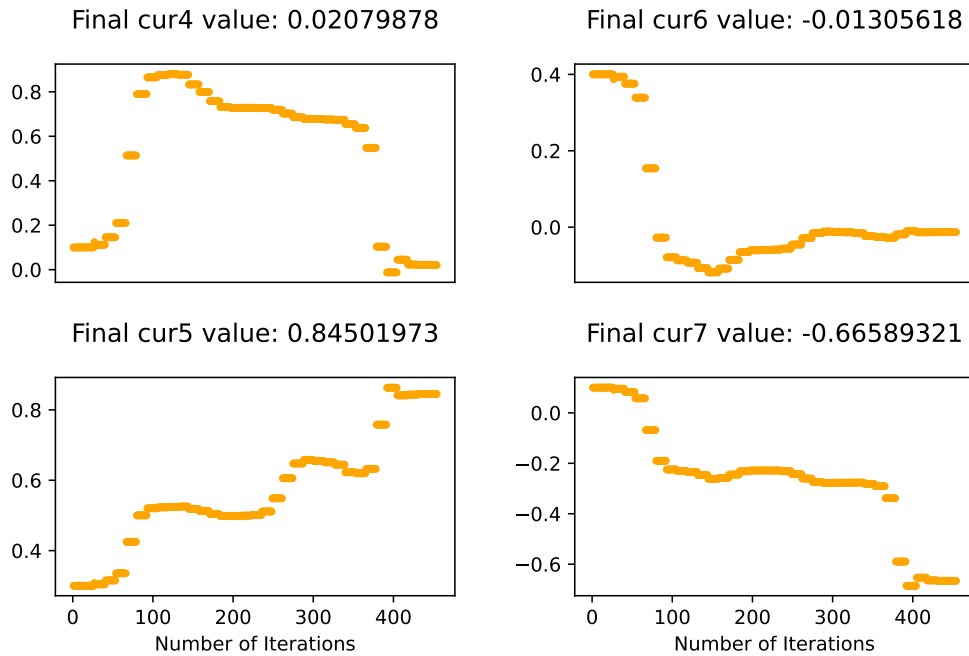


Figure 4.20: E3 part-span shroud - plots of variables (contd.)

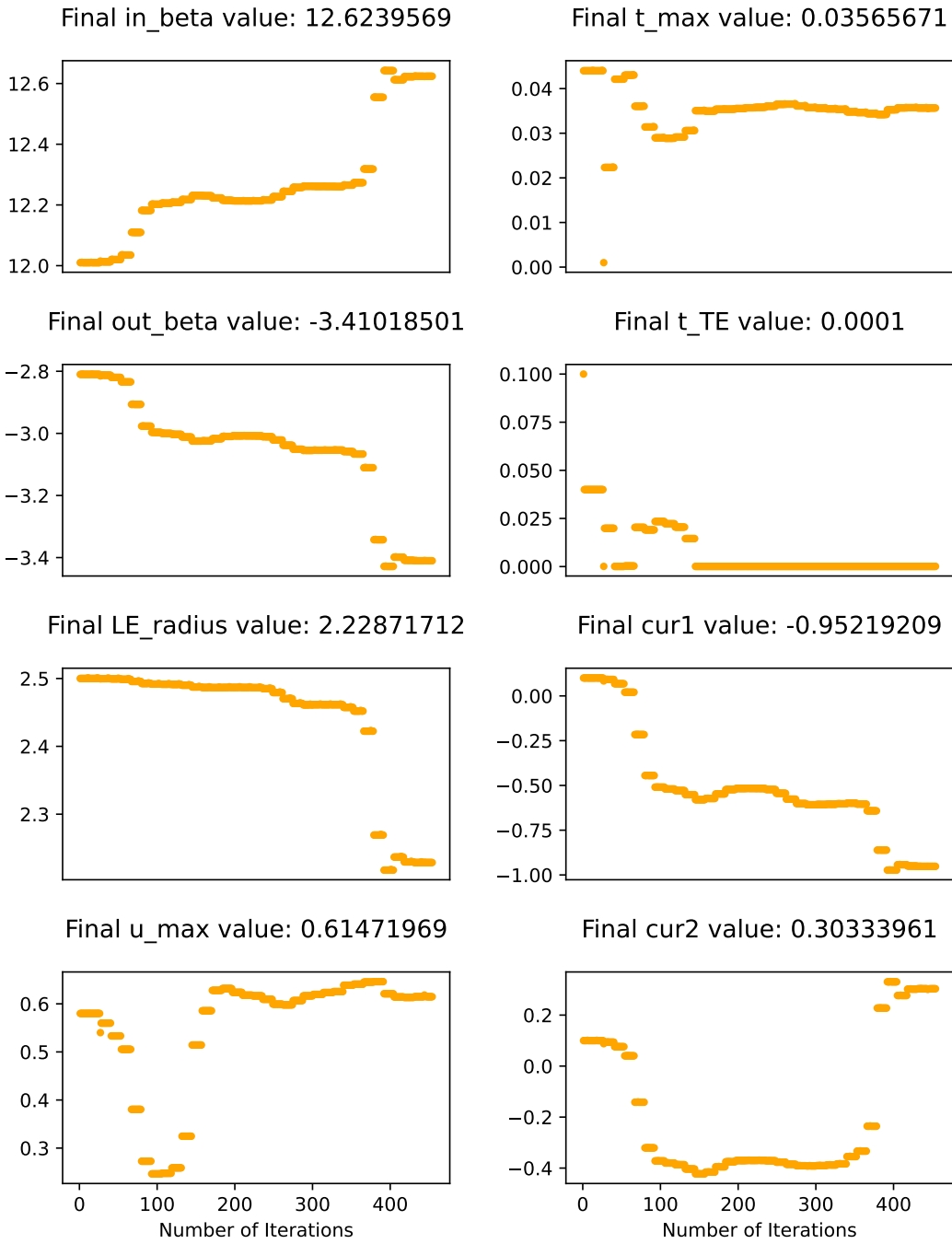


Figure 4.21: E3 part-span shroud - plots of variables

E3 tip Section

The stopping criterion was set to $1e - 03$ and for the plot digitized tip it took around 350 gradient evaluations of the objective function to reach a least squared difference value of $5.125e - 04$ as shown in Figure 4.22. We can clearly see the difference in closeness when compared to Figure 4.9c. Looking at the individual sections in Figure 4.23, the squared difference between the points is focused on the suction side mid part and the suction side trailing edge section. The optimization progression is shown in Figure 4.24, a quick stepped descent until 300th iteration with some big steps in the middle along with some areas of stagnant slopes before it stabilizes after 350th iteration. Figure 4.25 contains the initial and final values of each of the twelve parameters from the optimization, the location of maximum thickness is at 0.63168476 with the maximum thickness value being 0.02622002. The plotted graph values of each variable are in Figure 4.27 and Figure 4.26.

Shown in Figure 4.28 is the E3 blade obtained from the reverse engineering framework, ready for CFD simulation. The input files for Tblade3 for this particular case can be found in Appendix E.2.

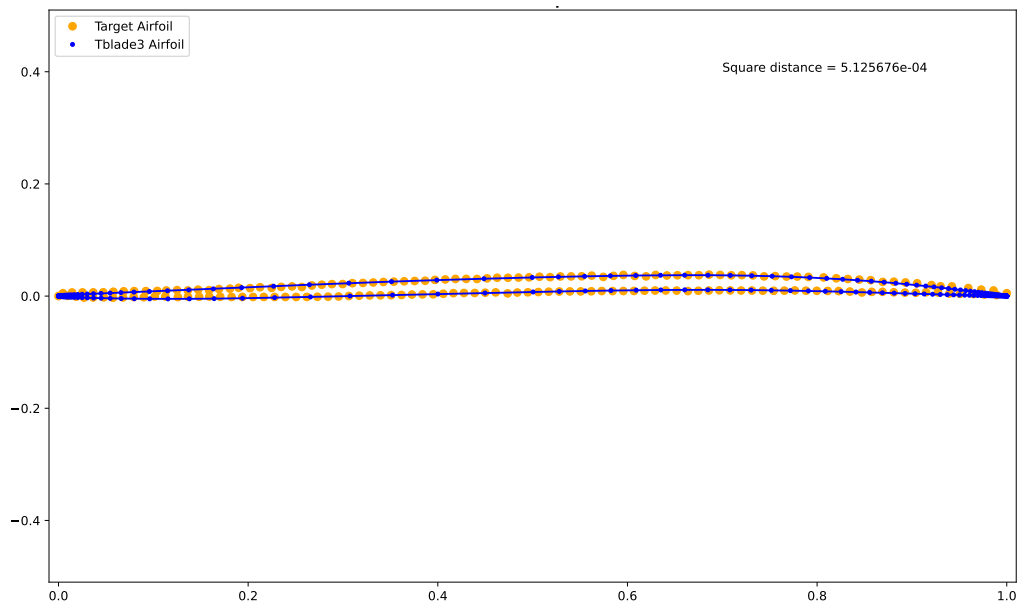


Figure 4.22: Least square difference between plot digitized tip and reverse engineered airfoil

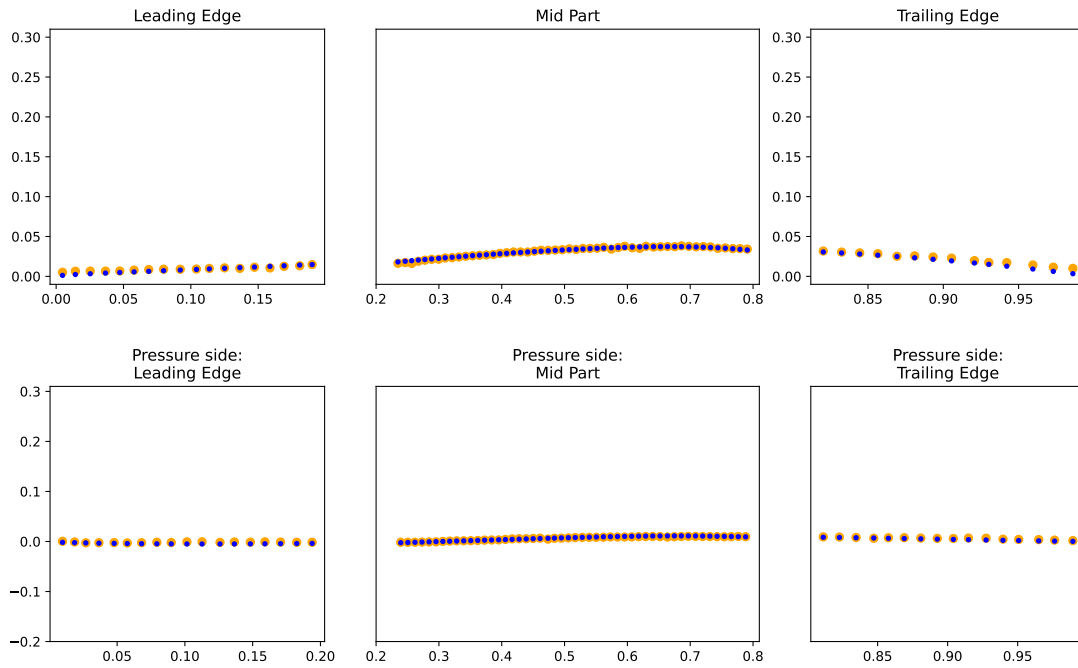


Figure 4.23: Airfoil parts comparison for E3 tip airfoil

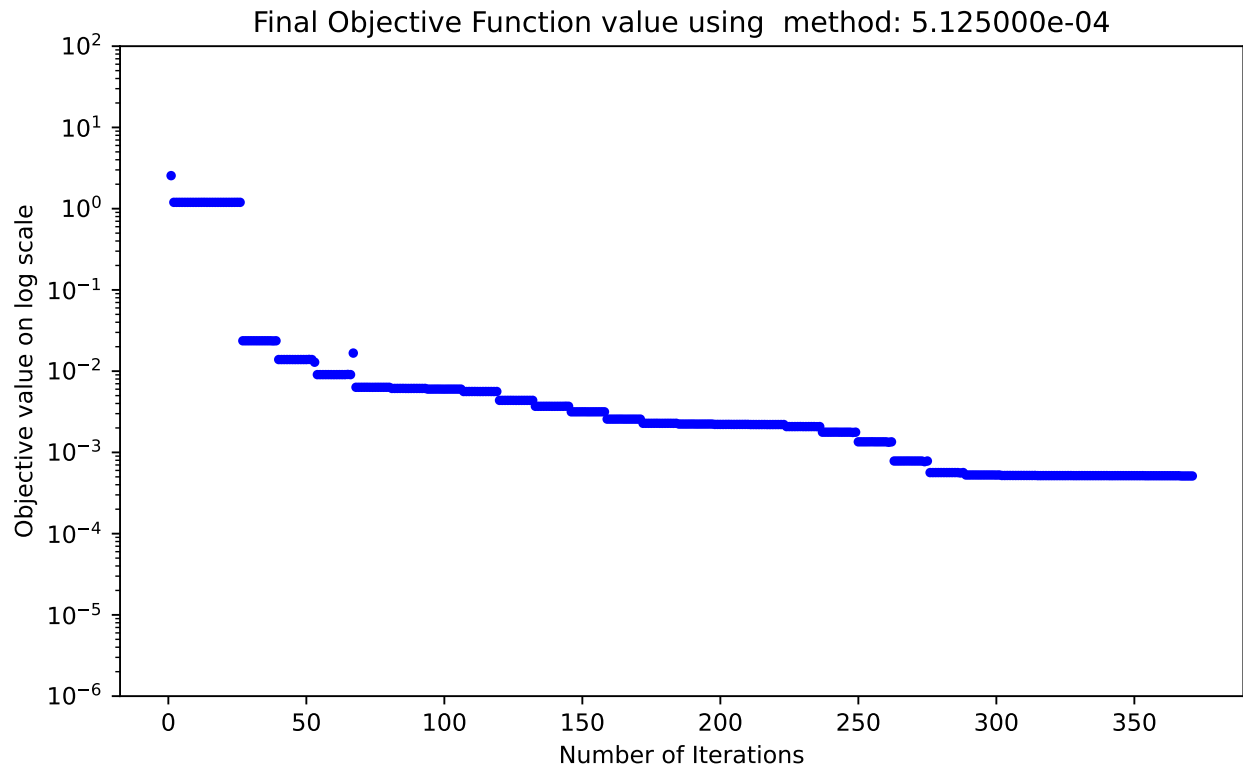


Figure 4.24: Objective function vs iterations for E3 tip

	Initial input values	Final input values
in_beta	6.52	6.60407821
out_beta	-1.42	-1.50501033
cur1	0.1	-0.43388997
cur2	0.1	-1.10842219
cur4	0.1	-0.14973654
cur5	0.3	1.81450868
cur6	0.4	1.14302249
cur7	0.1	0.10694238
LE radius	2.5	2.4577201
u_max	0.65	0.63168476
t_max	0.24	0.02622002
t_TE	0.1	0.0001

Figure 4.25: E3 tip - Initial and Final parameter values

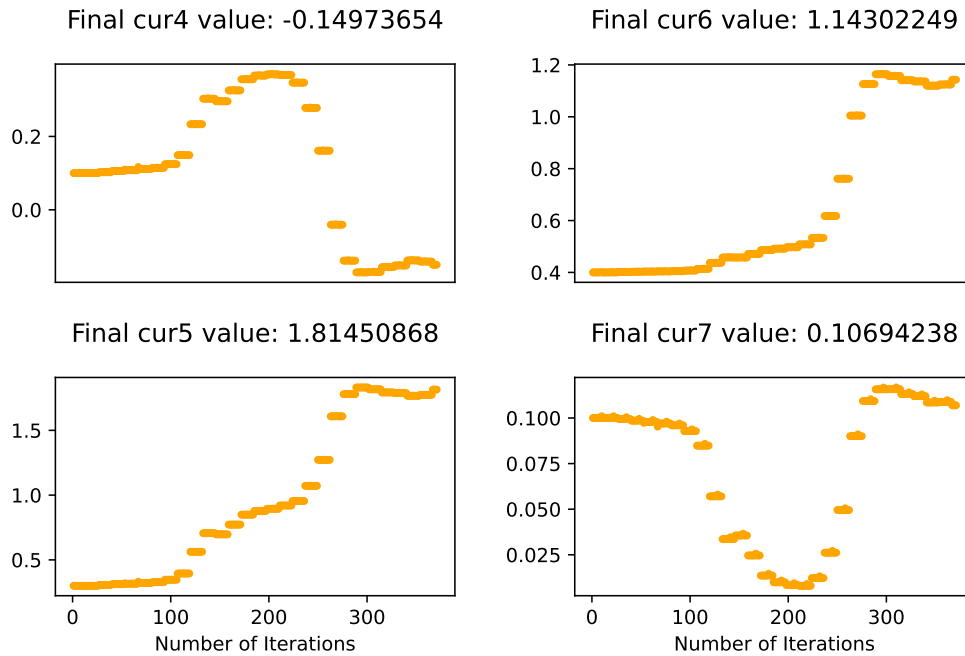


Figure 4.26: E3 tip - plots of variables (contd.)

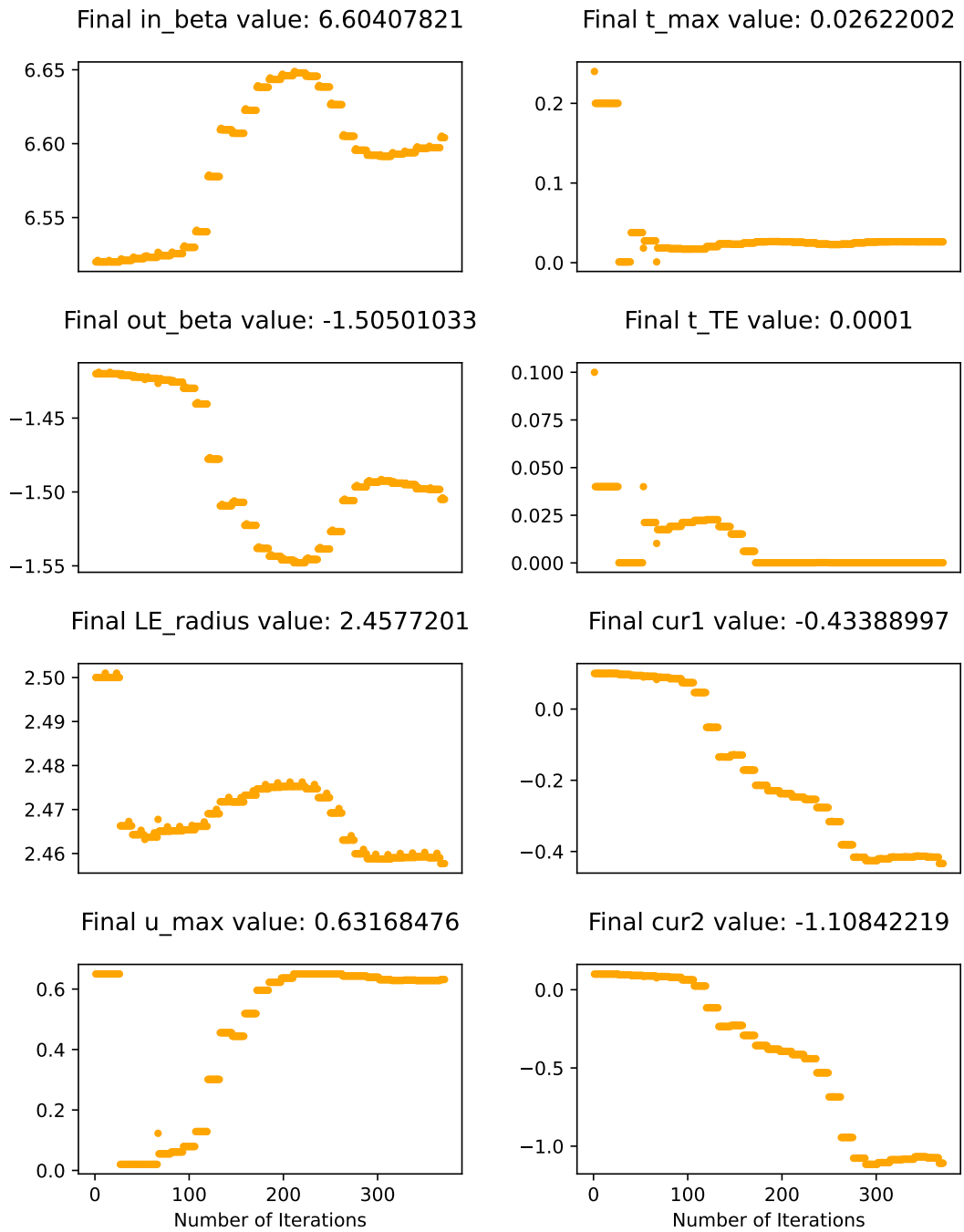


Figure 4.27: E3 tip - plots of variables

With the blade parameters found, both using traditional manual parameter specification or with the reverse engineering framework, the Tblade3 *xyz* coordinates were then converted into .geomturbo format using the code from TBlade3's website. We can now move to CFD simulation.

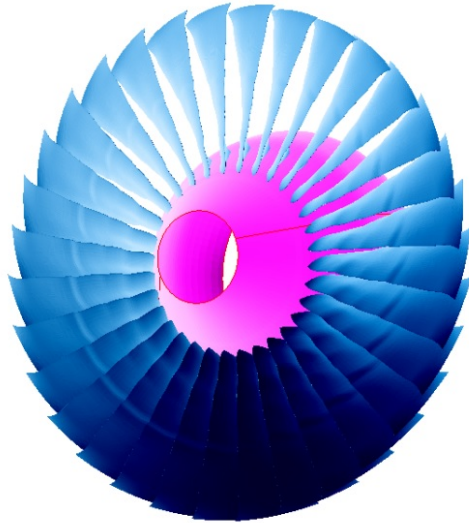


Figure 4.28: Full Annulus view of reverse engineered blade

Chapter 5

CFD simulation of E3 fan Blade

5.1 Simulation Setup

The .geomturbo file generated in the previous chapter is the input file for the FINE/Turbo environment which helps initialize the grid file to carry out further simulations. The speed case for the simulations was chosen to be one for the maximum climb with a tip speed of $411.5m/s$ and a target bypass pressure ratio of 1.65. The corrected airflow for this case with part span shroud was given to be $643.6kg/s$, ideally the obtained airflow for our simulations should be a little higher than this number for the pressure ratio.

5.1.1 Grid Generation

The .geomturbo file was imported into Autogrid5, to setup the gridding inputs for grid generation. The outlet was shrunk to a $z = 0.45$ to reduce the effects of nozzle expansion. The number of blades and calculated blade speed was input by using the LE radius as a parameter. On the next menu, tip gap was input to be 0.015% of LE and TE radius. Layer control was added with 161 spanwise grid point numbers and a wall cell width of $5.6249e - 06$, this number was obtained from Autogrid5's wall cell width formula for a $y+$ of 50. The number of points in the cell was set to around 20 million which gave around 60 Million cells for the entire grid. This was deemed sufficient to carry out the simulations in three grid levels: 222, 111, and 000 - the resolution of the cells increases from coarse to fine as grid number decreases. With the number of cells falling rapidly at each grid level to carry out speedline calculations and study grid dependence. The maximum

expansion ratio was 2.3467.

5.1.2 Solver Inputs

Once we had the grid read, it was imported into FINE/Turbo's solver to setup the inputs for the CFD simulation. The fluid model selected was perfect air with a Spalart-Allmaras Turbulent Navier stokes flow model. To calculate the Reynolds number, the solver takes in a few more parameters: Characteristic length = $0.15m$, this was the approximate chord length of the blade. Characteristic velocity = $411.5m/s$, tip velocity for the maximum climb case. Characteristic density = $1.225kg/m^3$. These input numbers were used to input Reynolds number for the simulation. Reference values of Temperature and pressure were $288.15K$ and $101300Pa$ respectively. Moving on to boundary conditions, the inlet conditions were "Total Quantities Imposed" with a tabular data of $\tan(V_r/V_z)$ values varying with radius of the inlet given in to compensate for the hub curvature and minimize entropy generation with the inlet fluid crashing into the conical hub surface. The Absolute Total Pressure and Temperature values at inlet were $101300Pa$ and $288.15K$ respectively. The outlet boundary condition was a pressure imposed boundary condition with Radial equilibrium enabled. This allows the solver to calculate the out boundary conditions using the input static pressure value at the hub to the tip. We input this pressure at various back pressure cases at the hub with a tip radius of $0.103m$. The sides of the grid were both assigned periodic boundary conditions and the hub and blade were given a rotation speed of $3728.21 rpm$ while the shroud was kept stationary.

Now that we had the basic parameters set, we move to tweak the numerical model parameters. The CFL number for the simulations was left at a default 3 and the grid level was altered based on the required level of 222, 111, or 000. Then based on the back pressure value, we initialized the file using "for turbomachinery" or previously run case file. Once we had the initial solution and numerical model setup, we move on to define the required outputs: entropy, Total and static Pressure, Temperature; Absolute and relative Mach number and various angles that were relevant to the simulation. Some quantities like β_z were not readily available and calculated accordingly in the post processor. Finally, we specify the convergence criteria, number of iterations and select the solver precision as required. Then started the simulations.

5.2 Traditional manual parameter specification simulation

Based on the above boundary conditions we did a speedline for the E3 geometry using FINE/Turbo. Once we had a mesh, we ran a case with coarse grid of level 222 and an assumed design back pressure of 95kPa. From the results of this case, we created a speedline to find a more suitable design case using the assumed design case as an initial solution. This was found at around 110250 Pa of back pressure with an efficiency of 0.9091 as shown in Figure 5.1. From E^3 report the required mass flow with a part-span shroud for this particular tip speed of $411.5m/s$ is $643.6kg/s$ and a pressure ratio of 1.65. This design case however, the obtained mass flow was $602.86kg/s$ with a pressure ratio of 1.6448. We need to tweak the airfoil sections further to obtain the required mass flow value of a few percentage points above $643.6kg/s$ so as to compensate the lack of part-span shroud.

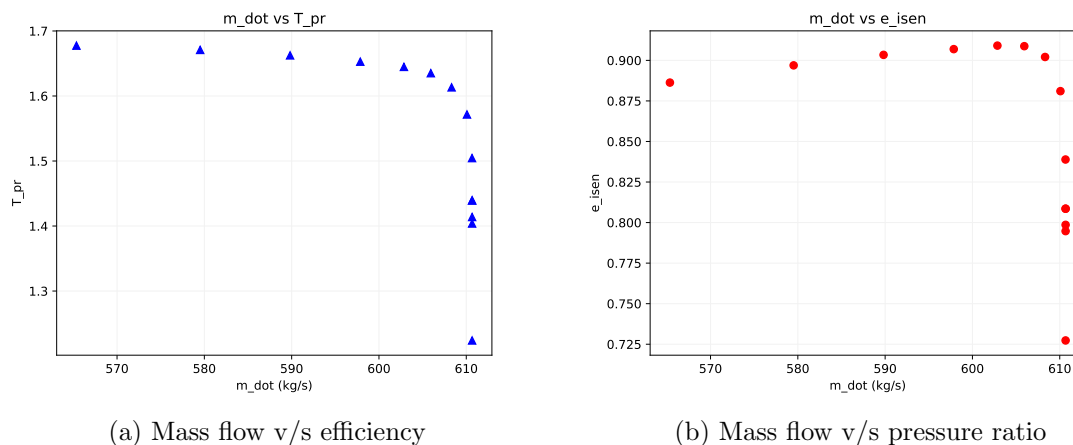


Figure 5.1: Speedline for traditional manual parameter specification of E3 geometry - required design mass flow is $643.6kg/s$

The next step was to study grid dependence. Table 5.1 shows the values of mass flow, pressure ratio, and efficiency at various grid levels: 222, 111, and 000. These grid levels represent the coarseness of the grid with higher numbers being coarser. From looking at the tables we can clearly see that the values are grid dependent. So, coarse grid of 222 is only used to obtain the characteristic curve and then the obtained back pressure value is used with lower-level grids to obtain the accurate qualities at those back pressures.

Table 5.1: Grid Dependence at 110250 Pa back pressure for traditional manual parameter specification geometry simulation

Grid level	Mass flow <i>Kg/s</i>	Pressure ratio $T_p r$	efficiency η
222	602.86	1.6448	0.9091
111	585.76	1.6356	0.8898
000	591.73	1.6413	0.8976

5.2.1 Line plots of Design case

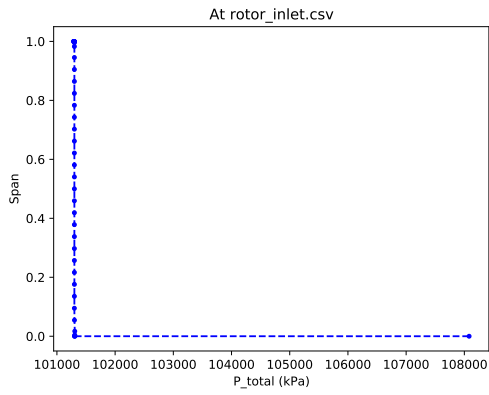
A more clear idea of the inflow and outflow parameters can be obtained from the profile plots at the inlet and outlet of the fan blade in the traditional manual parameter specification case simulation. Figure 5.2 shows the profile plots at inlet and Figure 5.4 shows the profile plots at outlet.

Profile plots at Inlet

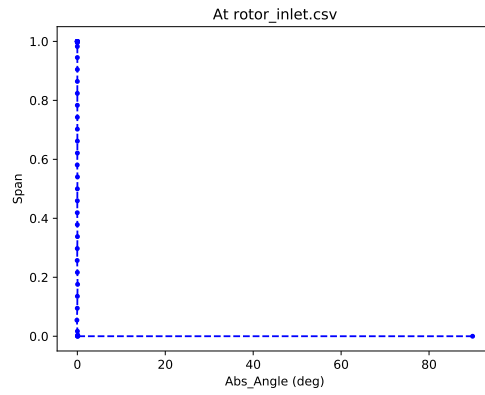
The total pressure at the rotor inlet is at a steady 101.3 kPa from 0% span at the hub to 100% span at the tip. In accordance with the input profile in FINE/Turbo, the Phi angle linearly varies from 30 to zero degrees when going from the hub to tip. This makes sure that the flow remains relatively parallel to the slope of the hub and tip.

Another important observation is in the form of the three independent directions of velocities - tangential, axial, and radial. Starting with the tangential direction, the flow from the rotating hub shows a straight impact on the flow in this direction. It is maximum on the attached flow near the hub, dropping instantaneously to zero from the next streamline and staying there for the remainder of the flow. For velocity in the radial direction, we observe that even though the flow at the hub starts at zero, it increases to a maximum near the hub showing that the flow is attached to a rotating hub. Unlike tangential velocity, radial velocity linearly falls to zero near the tip. Axial velocity vs span plot shows the characteristic "D" shape that is formed in piped flows. The velocity in this direction is zero near the hub and tip while increasing to a maximum in the majority of the flow.

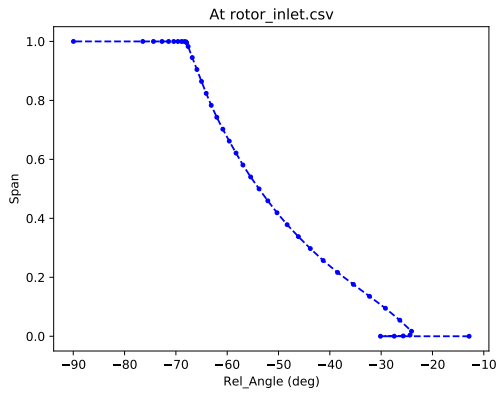
There are more plots from relative angles to Mach numbers for further diagnosis and provide an in-depth insight into where losses are being generated for the designer to create changes in the geometry.



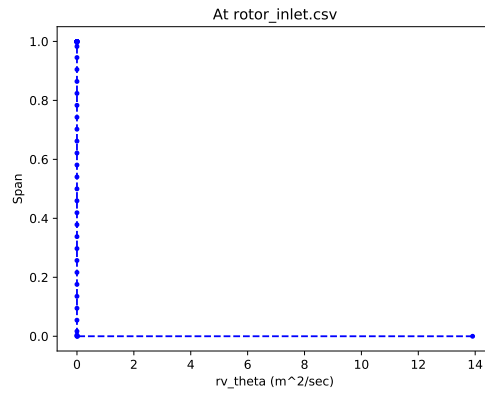
(a) Span v/s Total Pressure



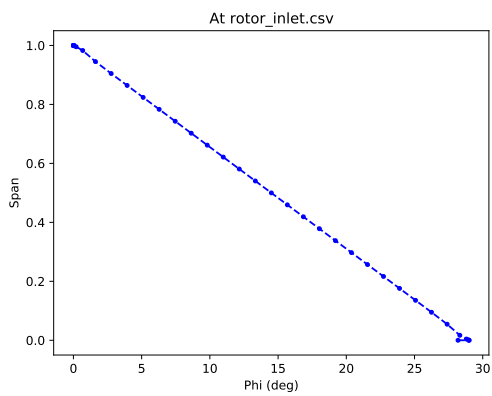
(b) Span v/s Absolute Angle



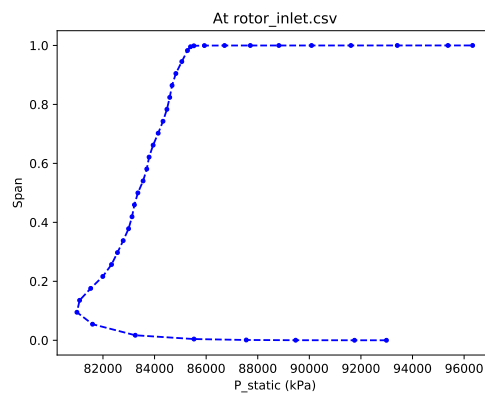
(c) Span v/s Relative Angle



(d) Span v/s $r * V_\theta$

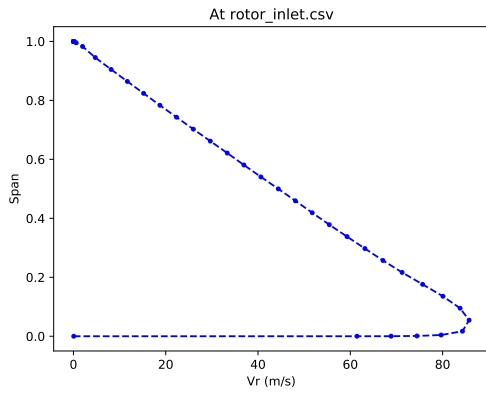


(e) Span v/s Phi

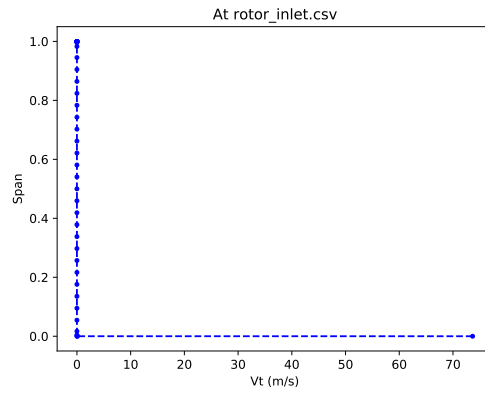


(f) Span v/s Static Pressure

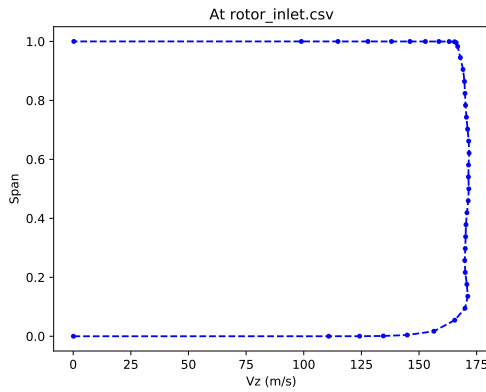
Figure 5.2: Profile plots at E^3 fan inlet for traditional manual parameter specified design



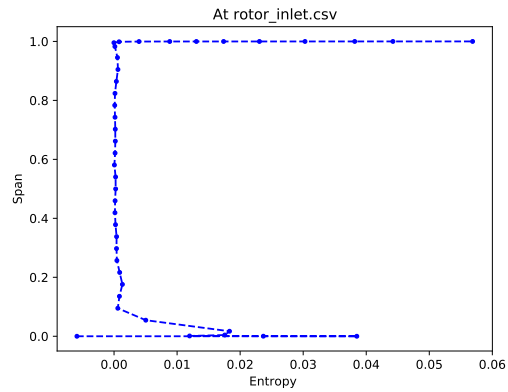
(a) Span v/s Radial Velocity



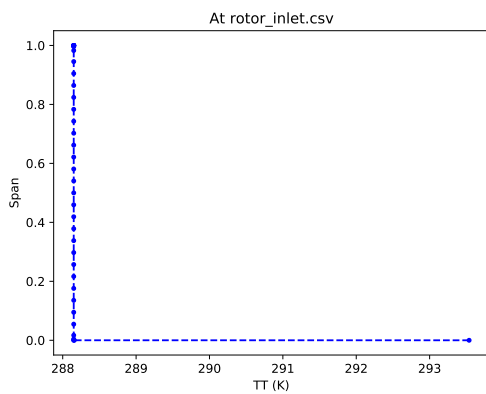
(b) Span v/s Tangential Velocity



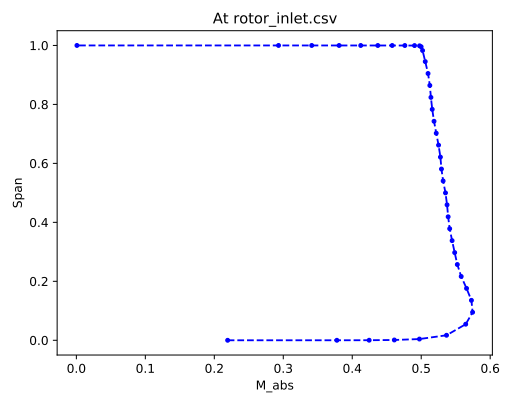
(c) Span v/s Axial Velocity



(d) Span v/s Entropy



(e) Span v/s Total Temperature



(f) Span v/s Absolute Mach Number

Figure 5.3: Profile plots at E^3 fan inlet for traditional manual parameter specified design

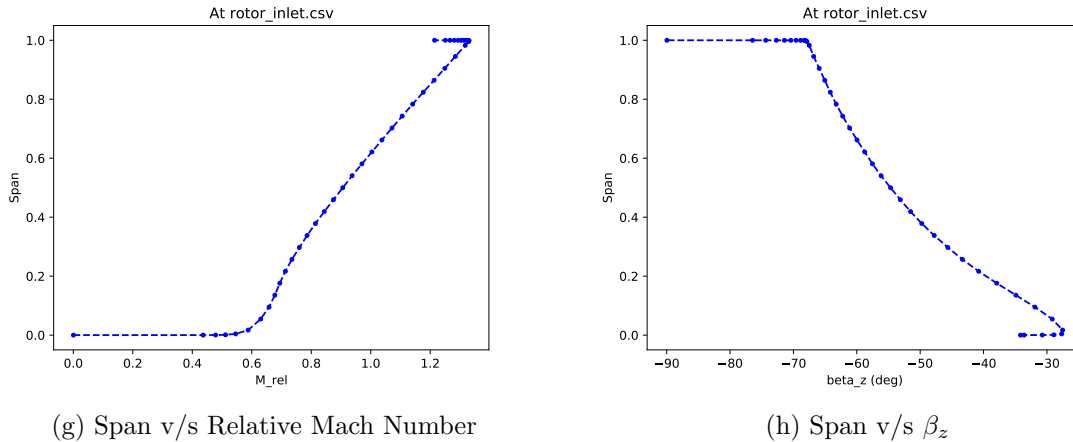


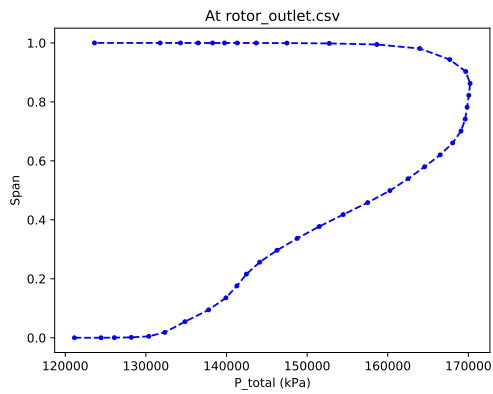
Figure 5.3: Profile plots at E^3 fan inlet for traditional manual parameter specified design

Profile plots at outlet

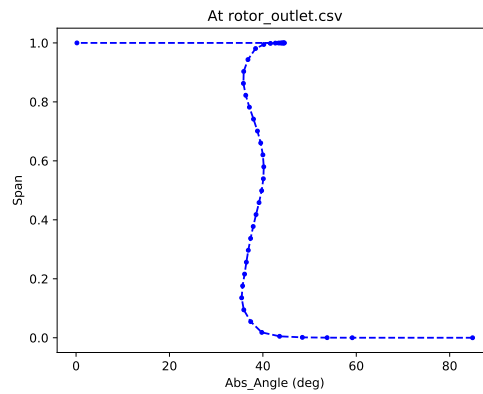
In contrast to the inlet total pressure v/s span plots, there is an addition of total pressure at the outlet. Maximum increase is seen near the upper span regions before steeply falling off near the tip. This is expected in a rotor simulation as total pressure is added to the flow. The slope of the phi angle plot is now non-linear with negative angles near the tip indicating that the flow near the tip is interfering with the other streamlines in the upper-middle spans. This will be more evident when we look at the contours of entropy in the next section.

For the velocity components, the axial component retains its characteristic shape with some added velocity near the hub and maximum velocity location. The radial velocity component too shows a similar change with a flow in the downward direction near the tip and a non-zero upward flow near the hub. In the tangential direction, however, there is a sharp contrast between the inlet flow where the air in the tangential direction is relatively stagnant to the outlet flow where there is a tangential velocity component throughout the span except for the tip.

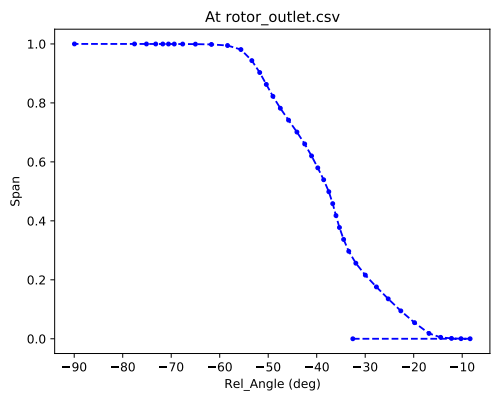
After looking at the line plots data from the traditional manual parameter specification case, we had a confirmation of the simulation input conditions to be adequately good enough for the simulations. Though more time can be spent comparing these line plots to the ones from the E3 report and those from reverse engineering framework blade simulation, emphasis is given on demonstration of these tools and comparison of the contour plots instead. To do that, we will now move to set up the reverse-engineered geometry's simulation next.



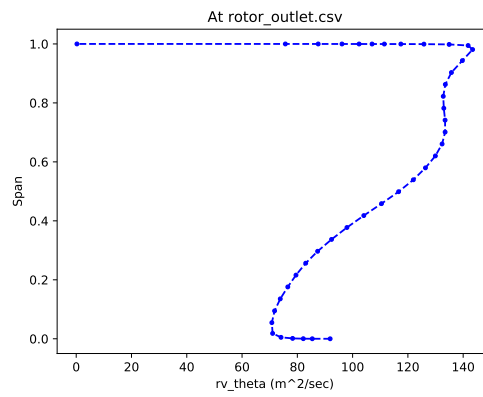
(a) Span v/s Total Pressure



(b) Span v/s Absolute Angle

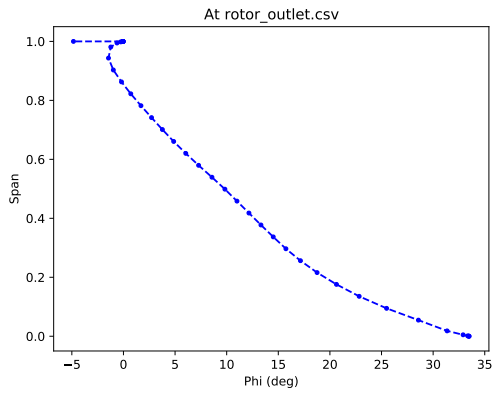


(c) Span v/s Relative Angle

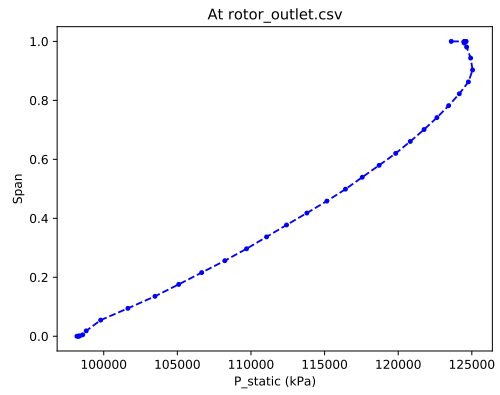


(d) Span v/s $r * V_\theta$

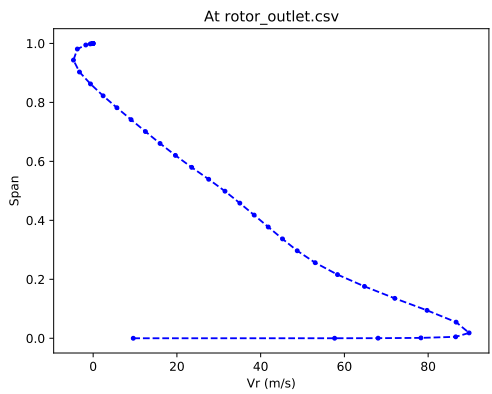
Figure 5.4: Profile plots at E^3 fan outlet for traditional manual parameter specified design



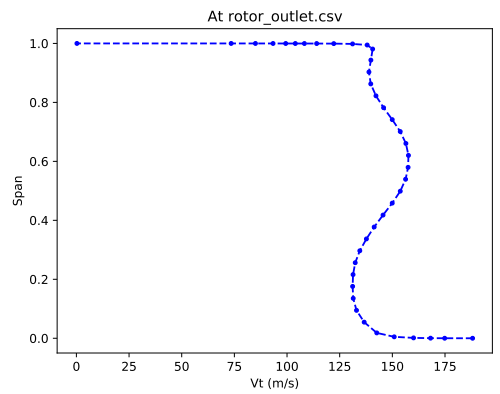
(e) Span v/s Phi



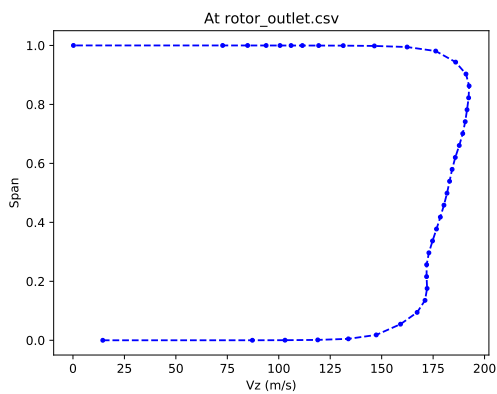
(f) Span v/s Static Pressure



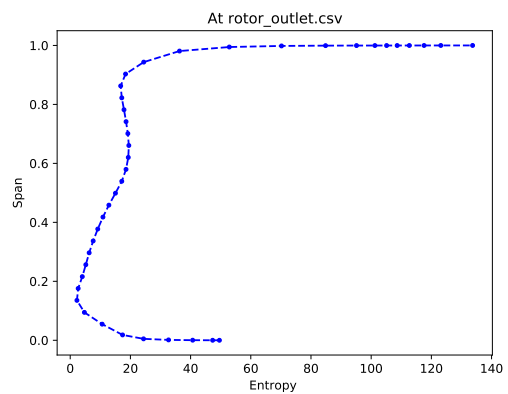
(g) Span v/s Radial Velocity



(h) Span v/s Tangential Velocity

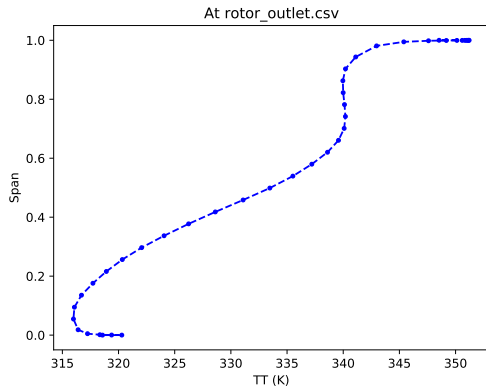


(i) Span v/s Axial Velocity

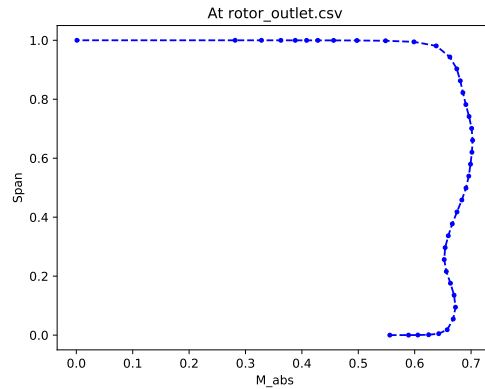


(j) Span v/s Entropy

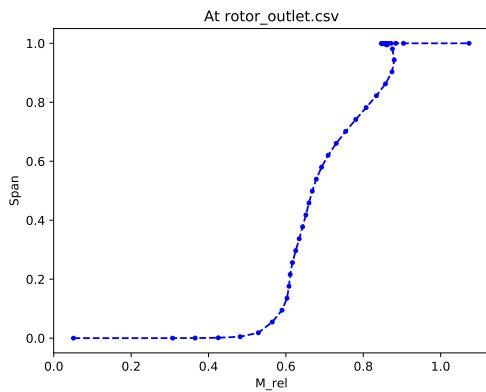
Figure 5.4: Profile plots at E^3 fan outlet for traditional manual parameter specified design



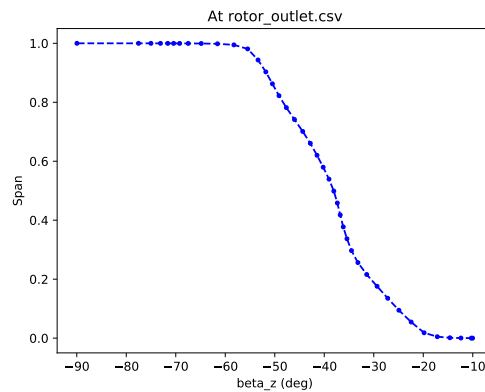
(k) Span v/s Total Temperature



(l) Span v/s Absolute Mach Number



(m) Span v/s Relative Mach Number



(n) Span v/s β_z

Figure 5.4: Profile plots at E^3 fan outlet for traditional manual parameter specified design

5.3 Reverse engineered geometry's simulation

The .geomturbo input file generated from the reverse-engineered Tblade3 output file was put through the same simulation procedures with the design case back pressure. While a speedline study could have been conducted, I have left that for further scope and will focus on the demonstration of the framework. Mass flow of this simulation with a 222 (coarse) grid level was 593.38 kg/s at a pressure ratio of 1.62. The isentropic efficiency was 0.91. There is a 1.5% reduction of mass flow from the same coarse grid level simulation with traditional manual parameter specification digitized airfoils. Both the simulations, however, are at least 7% away from the experimental mass flow of the compressor fan with a part span shroud from the report which is at 643.6 kg/s . This loss of Mass flow is attributed to Radial equilibrium boundary condition at outlet of Fan. With the quarter-stage booster aft of the fan, the back pressure will be different than radial equilibrium.

The pressure ratio could be improved from the current 1.62 to 1.65 in order to properly compare the simulations with a speedline study but is left for further work due to time constraints.

5.4 Comparison of results at design case

5.4.1 Contour plots of Entropy

An axisymmetric mass average contour plot takes a certain quantity, in this case entropy, and provides an average value for the magnitude in the radial and tangential directions. It is shown in Figure 5.5. Since the hub is conical, we needed to check if the inlet angles for the boundary conditions were causing any unnecessary separation near the hub. Contour plots are a great tool to achieve this because they map a third dimension in the form of a color-map onto a 2D Figure. In both the simulations, there is a similar amount of entropy being generated along the hub surface but as we move away from the span, we can see a drastic drop in entropy generation from the mid-span area. This sheds more light on why reverse engineering method is beneficial. To understand these differences better we need to look at blade-to-blade section plots along the spans. For simplicity, we took at these sections along three spans: 0% - hub, 55% part-span shroud and finally 99.5% - tip.

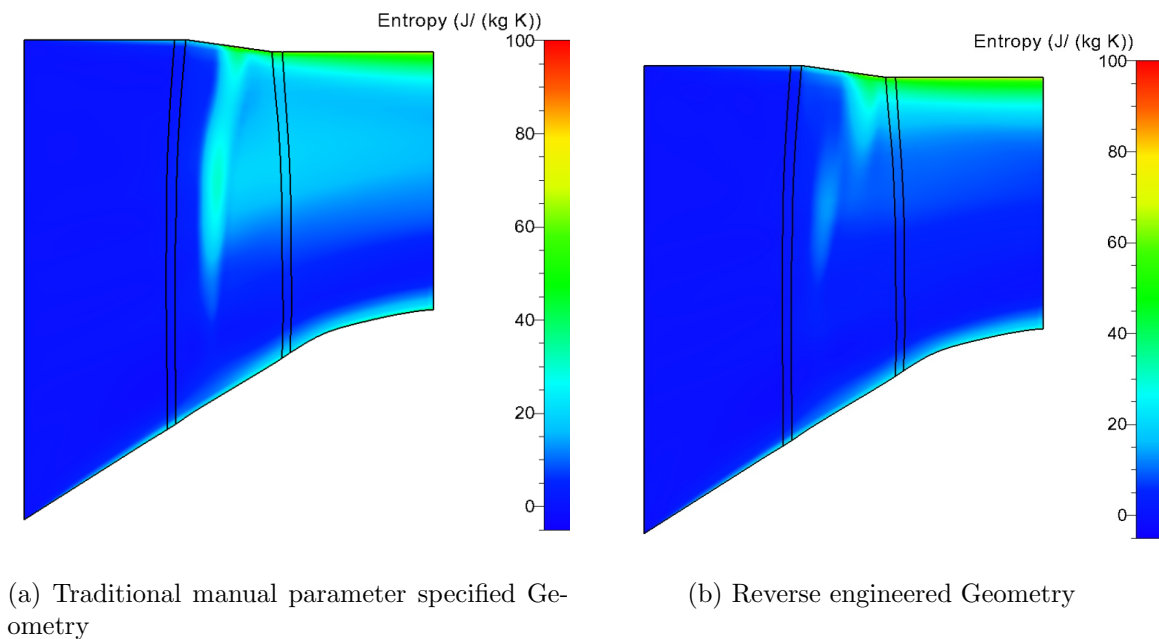


Figure 5.5: Axisymmetric averages of Entropy

Unlike the axisymmetric mass average contour plot, the blade-to-blade contour plots do not take an average quantity but plot the exact mesh values of the quantity at a constant radius from the origin. There is a provision in FINE/Turbo to specify how many blade channels are visible at a given time we have chosen two to show the throat area.

5.4.2 Contour plots at Hub

Near the hub, we start by looking at total pressure values across the blade span. There is no abrupt pressure change in the contour plots across this span Figure 5.6, it is also the case in total temperature plots - Figure 5.6. For relative Mach number plots, we can see that the reverse engineering case is not reaching a greenish color near below the suction side indicating that a Speedline simulation run might help increase mass flow unlike the case with traditional manual parameter specification designed blade. In both cases, there is a significant reduction in massflow near the Leading Edge and Trailing Edge, and the design could be further tweaked to minimize these losses.

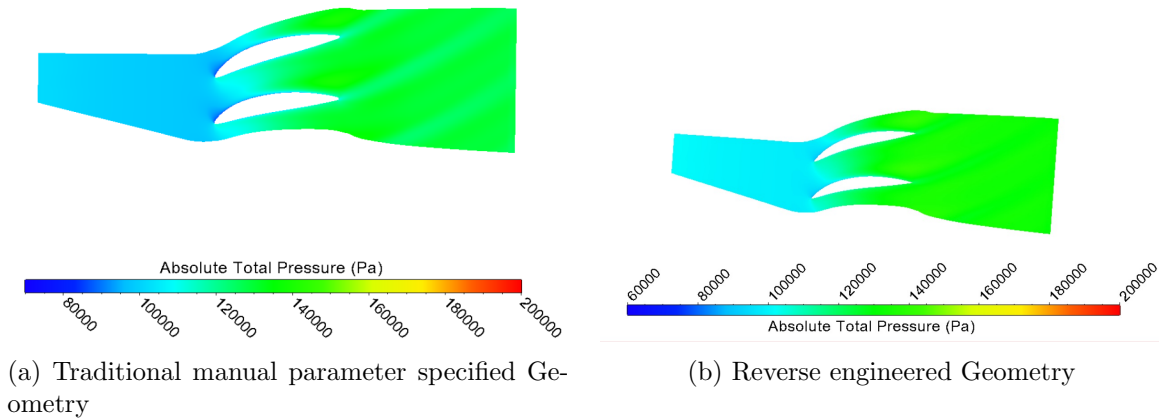


Figure 5.6: Contour plots of Total Pressure near hub

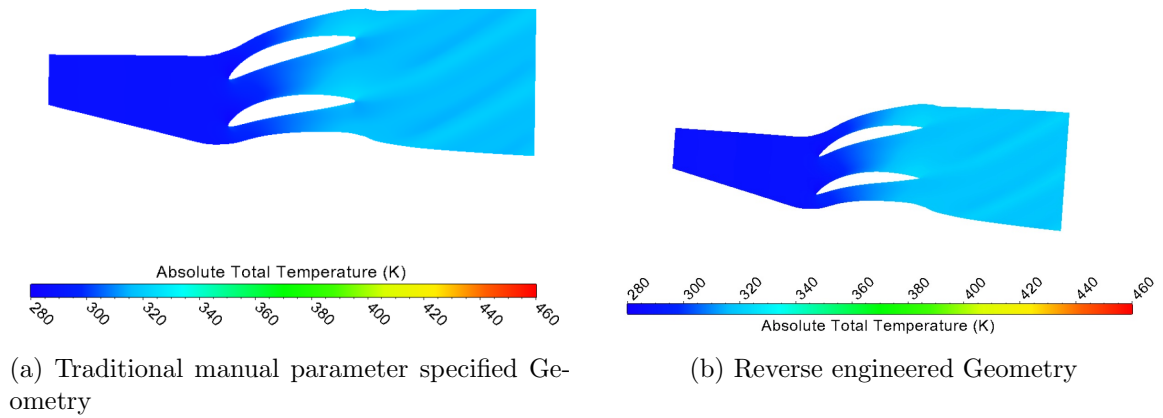


Figure 5.7: Contour plots of Total Temperature near hub

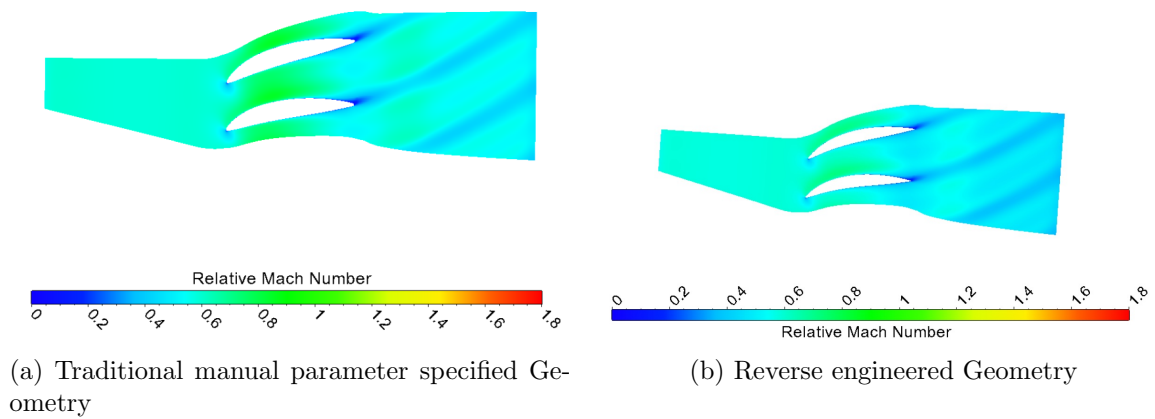


Figure 5.8: Contour plots of Relative Mach Number near hub

5.4.3 Contour plots at Part-span shroud

Figure 5.11 shows the relative Mach number contour plots for part-span-shroud section located at 55% blade span. Quickly looking at part-span shroud from the E3 report - Figure 4.6, we note that the location of the throat is after the 50% chord. While there is a normal shock for both the airfoils that originate near the 55% blade chord, as seen from the sudden rise in total temperature plots. The normal shock in the case of reverse engineered blade is not completely developed on the throat and is impinged by the oblique shock near the suction side of the airfoil. From the relative Mach number plots, it is also evident that the flow stalls after the shock in the traditional manual parameter specified design and is not as much stall when it comes to the reverse engineered blade.

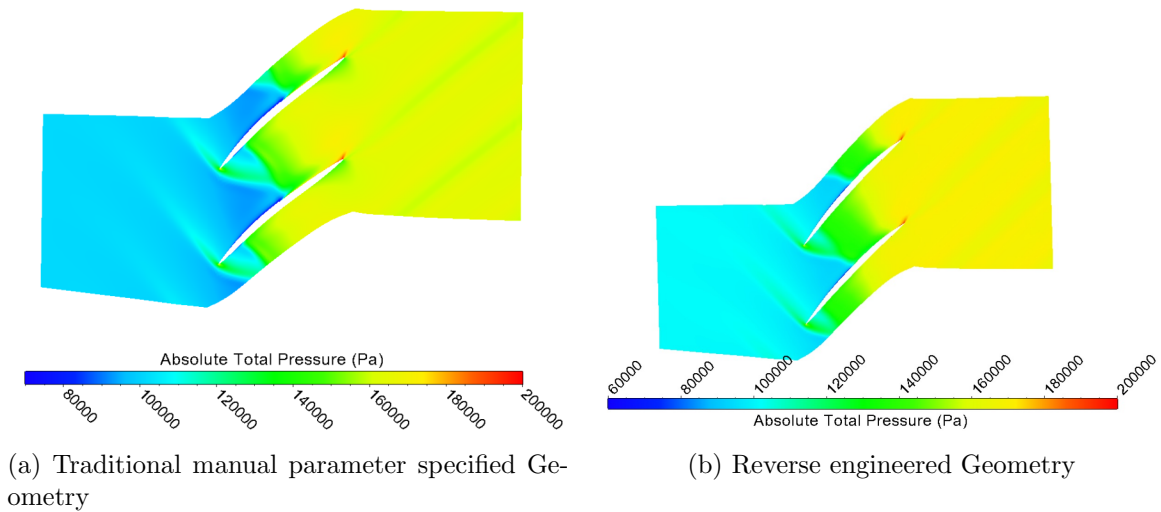


Figure 5.9: Contour plots of Total Pressure near part-span shroud

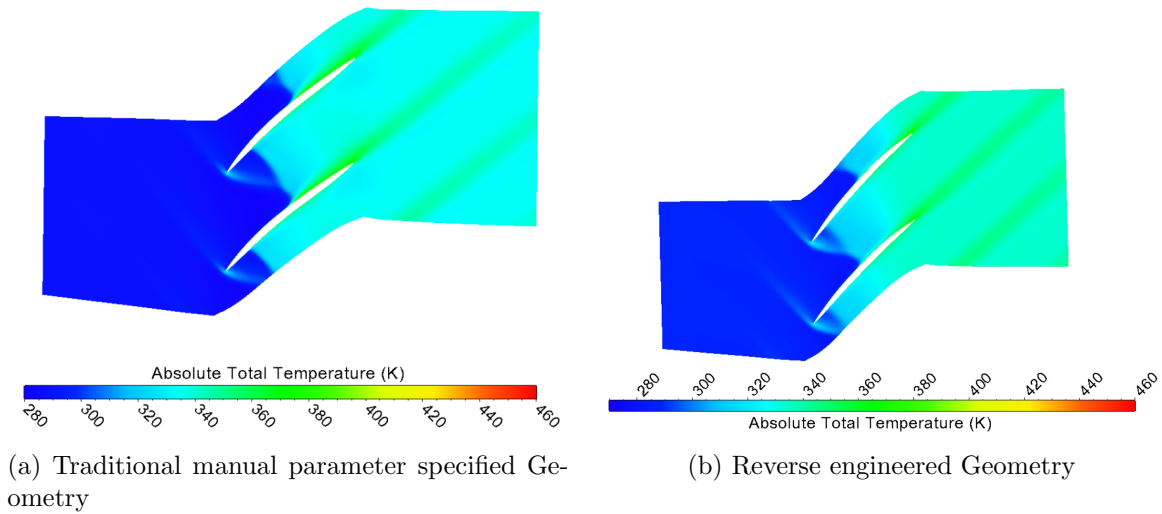


Figure 5.10: Contour plots of Total Temperature near part-span shroud

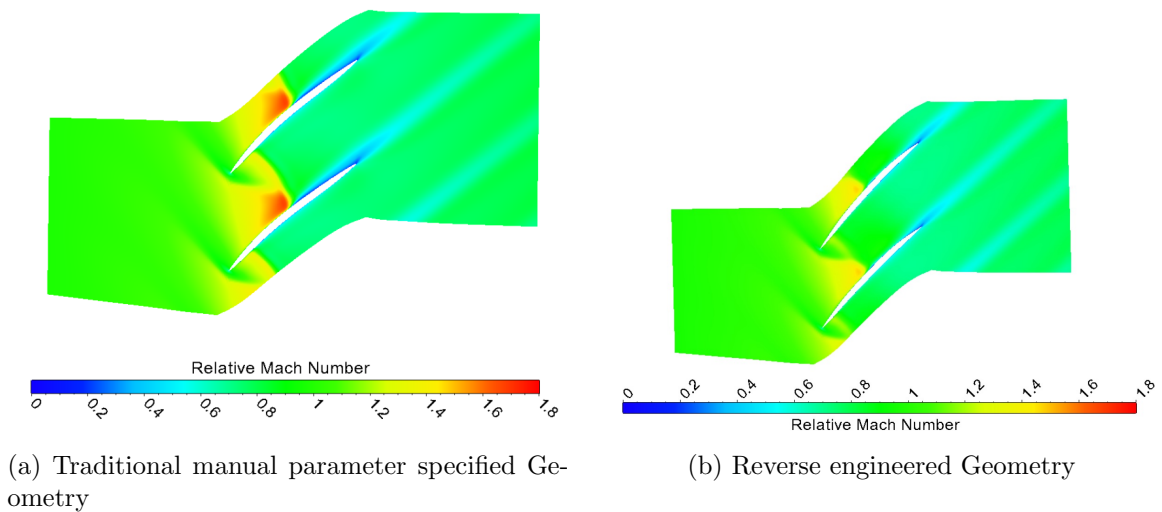


Figure 5.11: Contour plots of Relative Mach Number near part-span shroud

5.4.4 Contour plots at Casing

As we move higher up the span, a much stronger oblique shock is formed near the LE of the tip section blade as seen in Absolute Total Pressure plots. Figure 5.12. The throat area is shown in Figure 5.14 by 95% chord in the reverse-engineered airfoil section. This is in contrast to the normal shock location in E3 report Figure 4.7 where the throat area is near 80% chord. The traditional manual parameter specified geometry better matches this shock location but suffers from more stall after the shock.

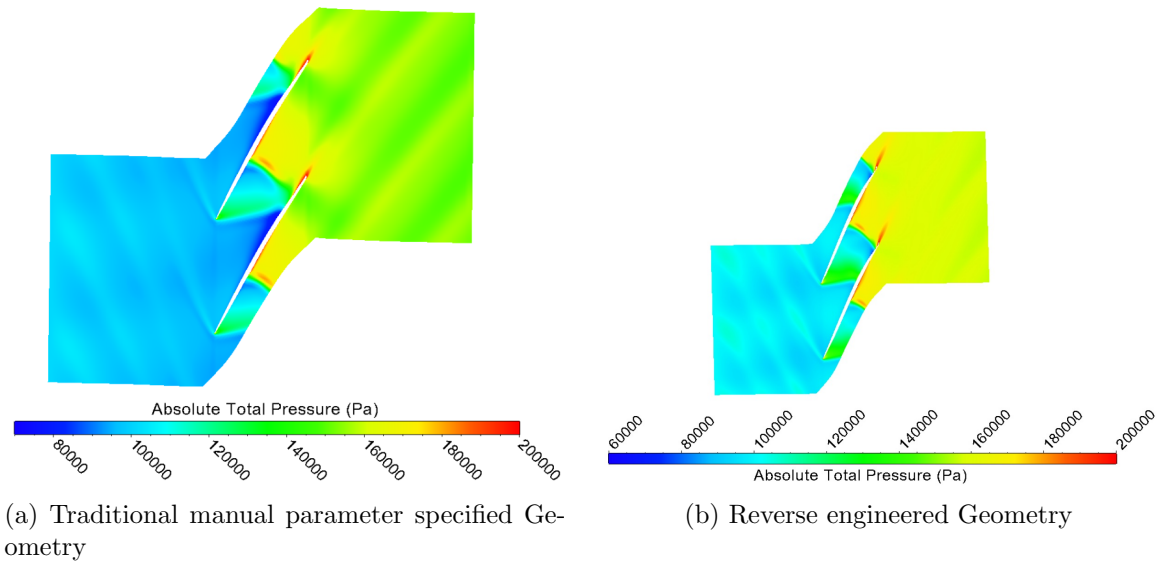


Figure 5.12: Contour plots of Total Pressure near tip

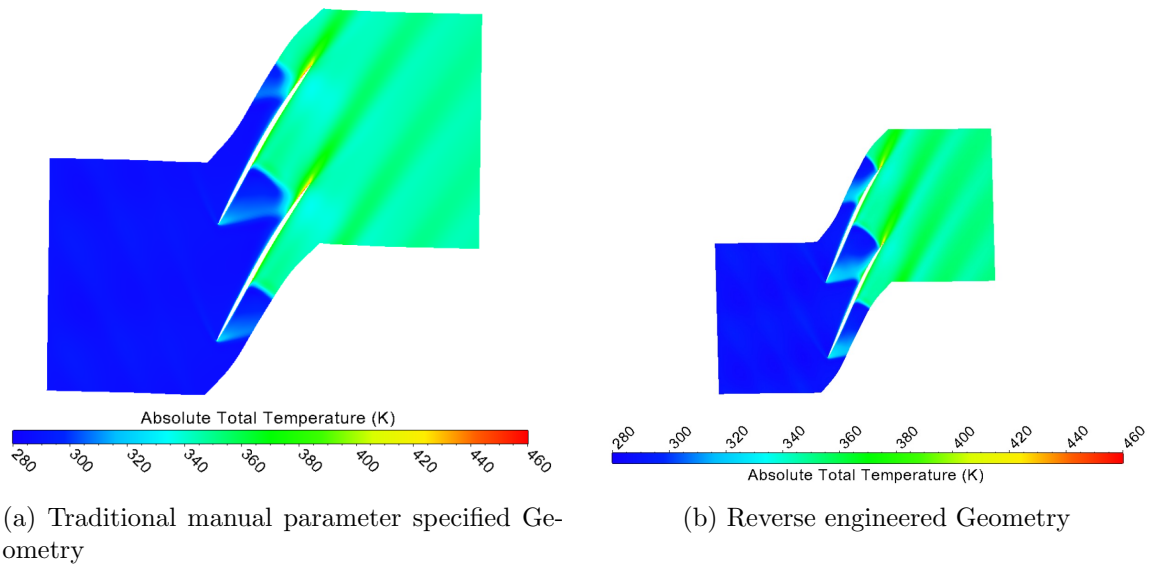


Figure 5.13: Contour plots of Total Temperature near tip

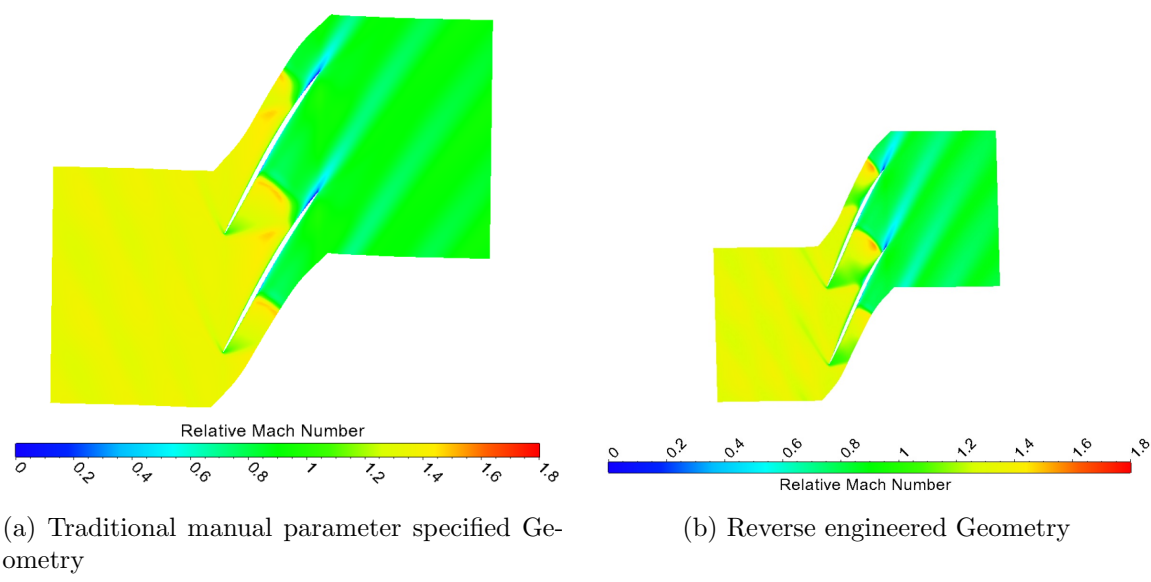


Figure 5.14: Contour plots of Relative Mach Number near tip

5.5 Suggestions to improve mass flow and total pressure ratio comparison

A comparison of total pressure ratio and mass flow values from three design sources- GE E3 report, Traditional manual parameter specified Geometry simulation, and Reverse engineered Geometry simulation for maximum climb are summarized in Table 5.2. The target mass flow from the E3 report is for a case with the part-span shroud.

5.5.1 Improving total pressure ratio and mass flow

By comparing the shock locations from relative Mach number contours in the design case of the traditional manual parameter specification geometry (Figure 5.14a) and reverse engineered blade geometry (Figure 5.14b), one can infer that the back pressure for the reverse engineering case is near choke. The required total pressure ratio of 1.65 can be obtained by changing back pressure to get a better total pressure ratio although that would further reduce the mass flow rate. Discrepancies in mass flow are speculated to be due to:

- Not having the true blades,
- Blade stagger angles are not correct,
- Number of blade span definitions is three and can be as increased to many more,
- Not identical hub and casing geometry, and
- Lack of inclusion of quarter stage booster in the simulations and the island splitter which lead to an incorrect static pressure profile.

The above suggestions can help increase mass flow to a given extent. However, the target mass flow from the E3 report is for a case with the part-span shroud. When simulating without a part-span shroud, the mass flow value should be higher.. With the focus of this thesis being on the demonstration of reverse engineering framework, this aspect is left for future work.

Table 5.2: Comparison of mass flow and pressure ratio across all three sources for maximum climb

Design source	Mass flow <i>Kg/s</i>	Pressure Ratio <i>T_pr</i>
GE E3 report - with part span shroud	643.6	1.65
Traditional manual parameter specified Geometry - without part span shroud	602.86	1.6448
Reverse Engineered Geometry - without part span shroud	593.38	1.6176

Chapter 6

Outcomes

1. This work was presented at AIAA SciTech 2023 conference held in Washington D.C.[36].
2. The author also went through UC's Venture Lab program to study the commercialization potential of the code and to further understand the relevance of this work in the industry. customer discovery interviews were carried out with blade manufacturers in ASME TurboExpo 2023 held in June.
3. The resulting venture "DigiE3Turbo" has been accepted into Founder Institute's Chicago cohort for Spring 2024 where further commercialization exploration is being carried out by the author.

Chapter 7

Conclusion

A framework to reverse engineer airfoil section parameters has been presented. A multivariable single objective optimization is used to reduce the difference between various parts of an airfoil blade section to obtain Tblade3 parameters. The method divides input airfoil into six parts to simplify blade difference calculation. A turbomachine blade section is obtained using the new input files which contain the optimized parameters in beta, out beta, six curvature control points, LE radius, u max, t max, t TE.

A demonstration of the developed method was carried out by reverse engineering the E3 transonic fan blade from its sections. This fan blade was chosen due to its uniqueness of having a sloped hub. The airfoil sections were plot digitized from E3 report which were run through the framework to get reverse engineered parameters. A subsequent 3D simulation of the blade has been carried out to compare the reverse engineered blade with its design report. A grid dependence of coarse level with fine level was established using the rotor's off design (full speedline) simulation. Insights on further directions to obtain design corrected mass flow rate were suggested after inspecting shock locations of blade at different spans using contour plots and profile plots to improve the comparison.

This capability can be utilized as general capability to reverse engineer other blade sections.

Chapter 8

Future Work

While care was taken to think and work on all the suggested directions throughout the thesis, there are a lot of directions for future work that can be used to improve the work. The following list is an attempt to capture those directions:

1. Modify the design further to match the mass flow and pressure ratios from the report
2. Create a new design with a span shroud and understand how this will impact mass flow in contrast to a part-span shroud less design.
3. Carry out the simulations at multiple design speed conditions and a grid dependence study.
4. Increase the number of curvature points in `spancontrolinputs` file to obtain better curvature control.
5. Carry out design of *E3* engine fan with a few parameters from the report, instead of a 13 variable design.
6. Rewrite the blade difference calculator to consider squared difference in *u* and *v* dimensions instead of the current *v*.
7. Study the effects of using piecewise cubic and higher order interpolations and compare the errors with piecewise linear interpolation.

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Appendix A

Procedure to run airfoil reverse engineering code

The framework started from Tom Viars mini-thesis and Chris Feldmen who worked on an initial version of blade digitizer which was rewritten along with added preprocessing of coordinates to account for any general selig format airfoil. My version preprocesses data, has vectorized operations, has a more robust error handling, uses total least squared difference objective function and provides pdf reports to understand the optimization progression.

A.1 Test Run

It is assumed that the code is being run on a Linux system with enough privileges to run a shell script on a given directory. Python, Tblade3, and OpenMDAO are also assumed to be installed. Tblade3 can be obtained from [GTSL's Github](#) website. The test case steps below are for reverse engineering the NREL s809 airfoil.

1. Open a terminal in `/$./AREF v1.0.0/001 test case files/` This directory contains the files required to test if our Framework is properly set up.
2. Run `$ tblade3 3dbginput.1.dat dev > tblade.log` to generate Tblade3 output files and initial files for the optimizer. This also tests a successful setup of Tblade3.

3. `$python3 blades_difference_calculator *.py` to test squared-difference calculator and obtain initial square difference log files.
4. `$python3 blade_reverse_engineering*.py > optimization*.txt` This runs the optimization code and writes input variables and square distance values from each iteration.
5. `$ python3 optimization_post_processor_*.py optimization*.txt` This produces a .pdf file with plots of the iteration data to look at the optimization status.

A.2 Input and output files Description

Before we begin reverse engineering we need to make sure that we have all the prerequisite files shown in Table A.1.

A.3 Optimization Framework

Shown in figure A.1 is the overview of ARE framework. The process begins with preparing the plot-digitized airfoil coordinates and sorting them into Selig airfoil coordinates format. This gives us the target coordinates for the reverse engineering framework. Once we have them, we prepare TBlade3 input files `3dbgbinput.1.dat` and `spancontrolinputs.1.dat` and populate them with input and output metal angles, curvature control points, LE radius, thickness of max camber, location of max. camber thickness, and TE thickness. These values could be a best guess value for each variable. Though more modifications can be carried out to obtain a blade for a given set of coordinates, we assume that the user is currently interested only in reverse engineering airfoil coordinate values and not in obtaining a 3D blade. Once we have these values, we do a run of `tblade3` to obtain the initial airfoil coordinates of our reverse engineering blade.

Now that we have the target and initial blade coordinates in a standard format, we will then run the OpenMDAO script file. The script file runs Tblade3 on the initial Tblade3 input files to produce the u-v coordinates of the airfoil. Once we have this airfoil, it runs an external python script to calculate squared difference between target and generated airfoil coordinates, then saves the values into a .dat file. This script also creates a .pdf report of the airfoil sections and writes an image file showing a visual comparison of generated airfoil with the target airfoil along with the

Table A.1: Input files for Reverse Engineering framework

File name	Description
<i>3dbgbinputfile.1.base</i>	Stores the template file for OpenMDAO to write Tblade3 input <i>3dbgbinputfile.1.dat</i> file.
<i>3dbgbinputfile.1.dat</i>	Tblade3 input file: controls input, and output angles in this optimization. These values are overwritten after each iteration.
<i>spancontrolinputs.1.base</i>	Stores the template file for OpenMDAO to write Tblade3 input <i>3dbgbinputfile.1.dat</i> file.
<i>spancontrolinputs.1.dat</i>	Tblade3 input file: stores spanwise curvature control points, leading-edge radius value, chord-wise location of the maximum thickness, maximum thickness, and thickness of the trailing edge.
<i>plot_digitized_coordinates.dat</i>	Plot digitized blade coordinates in *.dat format. These coordinates should start at TE going up in v towards LE and return to TE - Selig format, Section B.1 has a code to rewrite a given set of coordinates into this specific order.
<i>blades_difference_calculator*.py</i>	Calculates squared difference between plot digitized coordinates and reverse engineered blade iterations.
<i>uvblade.1.1.*</i>	u-v coordinates of reverse engineered blade after initial run. Blade difference calculator will use this as a starting point to calculate the squared difference.
<i>run_least_squares*.sh</i>	This shell script governs the optimization process and clears off the input files to help with the next run. It also automates Tblade3 run and calculation of squared differences.
<i>blade_reverse_engineering*.py</i>	Contains the OpenMDAO script with parameters for running the optimizer. The output from this code is saved into a *.txt file.
<i>optimization_post_processor*.py</i>	Post processor to visualize optimization run .dat file.

squared difference annotated on the top right corner. Once the script is done, the OpenMDAO script takes over and prints the values of input parameters and squared difference to the screen, it also writes the parameters into the .base, .log, and .dat template files and saves them. It then checks the least squared difference value with the given tolerance, if the tolerance is lower than the specified value or if the value of the least squared difference is stagnating, then the solver exits. Else, it goes back to the beginning and alters values using the SLSQP algorithm while using the

Table A.2: Output files for Reverse Engineering Framework

File name	Description
<i>tblade.log</i>	Stores run information from Tblade3 run. This file is to be used to troubleshoot a failed Tblade3 run.
<i>Sq_diff_out.dat</i>	Stores value of squared distance between plot digitized and reverse engineered airfoil.
<i>./reports/problem1/n2.html</i>	N^2 diagram for the optimization model.
<i>uvblade.1.1.*</i>	Reverse engineered blade u-v coordinates
<i>blades_difference_calculator*.pdf</i>	Stores .pdf plot reports of blade difference from final run of optimization run.
<i>optimization*.txt</i>	Output file from OpenMDAO run. This is used as the input file for <i>optimization_post_processor*.py</i> script to obtain <i>optimization*.txt.pdf</i>
<i>optimization*.txt.pdf</i>	Post-processing plots from <i>optimization_post_processor_*.py</i> and <i>optimization*.txt</i> files. This .pdf file plots squared distance, and other control variables with respect to iterations.
<i>Airfoil_fit.png</i>	A picture comparing plot digitized target airfoil with the reverse engineered plot with squared distance annotated on the top right.

generated blades as the new initial blade. This way it approached the target blade by minimizing the least squared distance value.

Once the optimization reaches an exit value, we then run the optimization post-processor script, which takes in the log file from the final optimization run and prepares a .pdf report with iteration vs value plots of squared difference and other input variables. It also prints out a table comparing the initial vs target values of the variables.

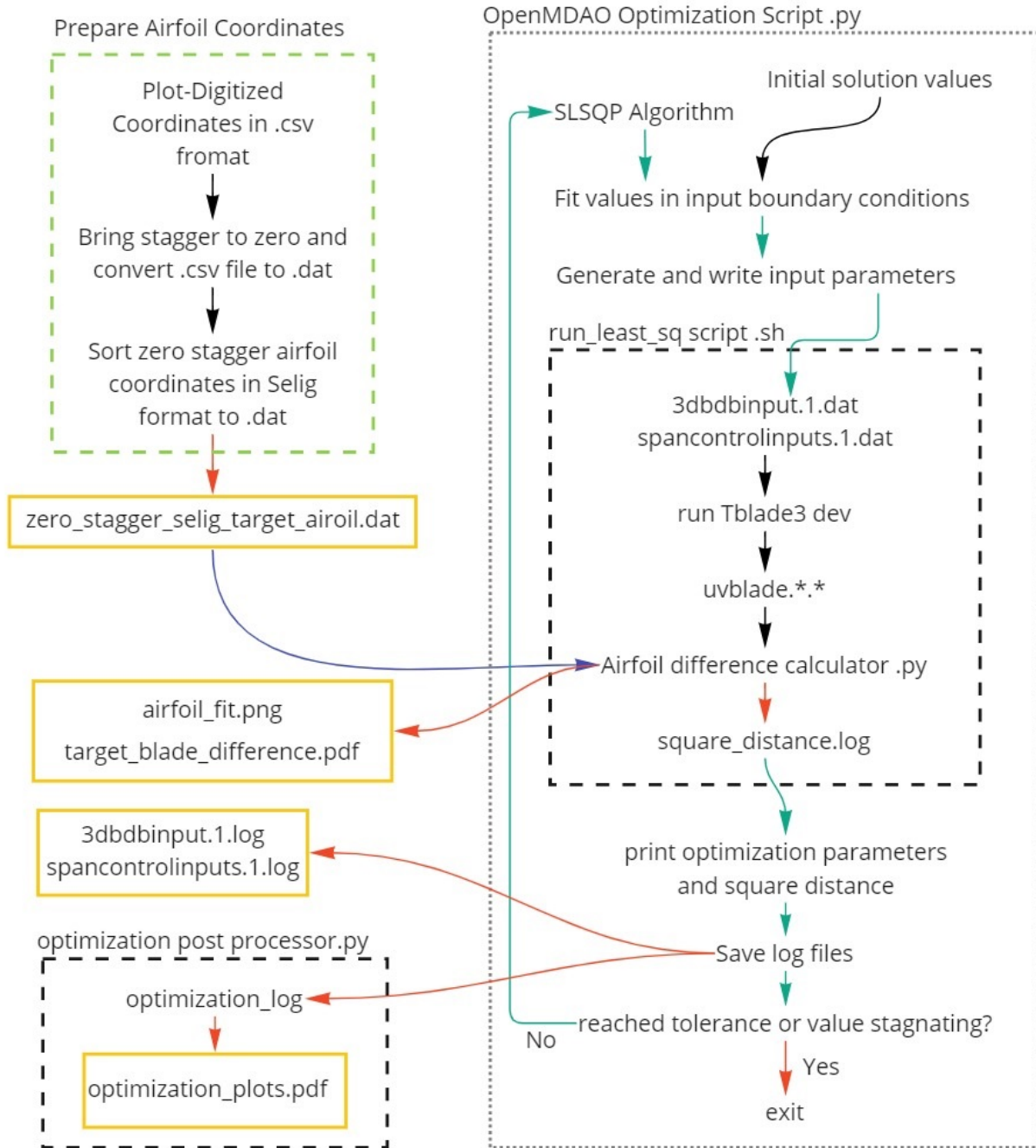


Figure A.1: Overview of Airfoil parameters reverse engineering framework

Appendix B

Codes for Airfoil Manipulation

Several airfoil manipulation codes are included in this section to help prepare any airfoil coordinates as input to our framework.

B.1 Code to sort Airfoil coordinates from TE to TE

This code sorts airfoil coordinates in any format into a selig format: *LE to TE and then back to LE*.

```
1 """
2 UC GTSL Lab: Sort airfoil coordinates from LE to TE and back to LE.
3
4 Iteration 001: Calculate a mean camberline from the input airfoil coordinates using
   linear curve fitting to obtain (u,v) coordinates of mean camber line. Then for a
   given u in the input coordinates if the value of v is higher than the
   corresponding value in the mean camber line the side will be pressure side. If not
   , then the side will be classified as suction side.
5 Iteration 005: We just realized that the order to sort airfoils was TE to LE to TE
   and not the originally thought version of LE to TE to LE.
6
7
8 # Expect issue with the u extremes where u = 0 and 1. Just assign them to Suction
   side.
9 # Issue with 001 mcl line not being as expected. We intended to curve the mid section
   of mcl line to produce optimum line.
```

```

10 # Added in plotteer to help write changes to file. Also added in a "v_sorting_flag"
    to compensate for optional requirement of v sorting near TE of Tip airfoil
11
12
13 ### Always use np.argsort to sort an array by column.
14
15
16 Written by: Bharadwaj "Ben" Dogga
17
18 """
19
20
21
22 import os
23 import numpy as np
24 import matplotlib.pyplot as plt
25 from matplotlib.backends.backend_pdf import PdfPages
26
27
28 #%% Functions to perform operations
29
30 #import both normalized airfoils using numpy and ensure that coordinates fit into a
    0<u<1 and -1<v<1 range
31
32 def import_airfoil_coordinates(name_argument1, name_argument2):
33
34     # Determine the name of the main T-Blade3 input files
35     current_dir                = os.getcwd()
36     files                      = os.listdir(current_dir)
37     for file in files:
38         if name_argument1 in file and name_argument2 in file:
39             input_file        = file.strip()
40             break
41
42     # Read main T-Blade3 input file and store the input in a list
43     f                          = open(input_file, 'r')

```

```

44     lines                = f.readlines()
45     f.close()
46
47     # lines1 = lines[106:197] # Select the range of lines that has 3 coordinates of
the airfoil
48     lines1 = lines.copy() # Select the range of lines that has 3 coordinates of the
airfoil
49
50     # numpy arrays for storing blade section coordinates read from the file
51     m_prime              = np.zeros(len(lines1))
52     theta                = np.zeros(len(lines1))
53
54     # Store the blade coordinates read from the file in the arrays defined above
55     i                    = 0
56     for line in lines1:
57         m_prime[i]      = float(line.split()[0])
58         theta[i]        = float(line.split()[1])
59         i                = i + 1
60
61     m_prime = m_prime - np.amin(m_prime)
62     theta = theta - theta[np.argmax(m_prime)]
63
64     airfoil = np.column_stack((m_prime, theta))
65
66     return airfoil
67
68
69     %% Import the airfoil coordinates:
70
71
72     foil1_numpy = import_airfoil_coordinates(name_argument1="E3_hub_coordinates",
name_argument2=".dat")
73     foil1_numpy = foil1_numpy/np.amax(foil1_numpy[:,0])
74
75

```

```

76 foil2_numpy = import_airfoil_coordinates(name_argument1="E3_pss_coordinates",
      name_argument2=".dat")
77 foil2_numpy = foil2_numpy/np.amax(foil2_numpy[:,0])
78
79
80 foil3_numpy = import_airfoil_coordinates(name_argument1="E3_tip_coordinates",
      name_argument2=".dat")
81 foil3_numpy = foil3_numpy/np.amax(foil3_numpy[:,0])
82
83 ### A function to calculate mean camberline from input coordiantes
84
85 def fit_camber_using_polyfit(foil_numpy_input, polyfit_order=2, plot_mcl='no'):
86
87
88     z = np.polyfit(foil_numpy_input[:, 0], foil_numpy_input[:, 1], polyfit_order)
89     p = np.poly1d(z)
90     foil_numpy_side_u = foil_numpy_input[:, 0]
91
92     mcl_curve = np.stack((foil_numpy_side_u, p(foil_numpy_side_u)), axis=1)
93     mcl_curve = mcl_curve[np.argsort(mcl_curve[:, 0])]
94
95
96     if (plot_mcl=='yes'):
97         plt.plot(mcl_curve[:, 0], mcl_curve[:, 1], 'o')
98
99     return mcl_curve
100
101
102 ### Function to divide sections of airfoil and calculate coordinates of mcl line to
      fix hub airfoil TE section
103
104
105 def calc_mean_camber_line(foil_numpy, view_airfoil=False):
106
107
108     foil1_numpy_LE_side = foil_numpy[foil_numpy[:, 0] <= 0.2]

```

```

109     foil1_numpy_mcl_LE = fit_camber_using_polyfit(foil1_numpy_LE_side, polyfit_order
110     =2, plot_mcl='no')
111
112     foil1_numpy_mid = foil_numpy[(foil_numpy[:, 0] > 0.2) & (foil_numpy[:, 0] <=
113     0.8)]
114     foil1_numpy_mcl_mid = fit_camber_using_polyfit(foil1_numpy_mid, polyfit_order=2,
115     plot_mcl='no')
116
117     foil1_numpy_TE_side = foil_numpy[foil_numpy[:, 0] > 0.8]
118     foil1_numpy_mcl_TE1 = fit_camber_using_polyfit(foil1_numpy_TE_side,
119     polyfit_order=2, plot_mcl='no')
120
121     mcl_curve = np.concatenate((foil1_numpy_mcl_LE, foil1_numpy_mcl_mid,
122     foil1_numpy_mcl_TE1))
123
124     if view_airfoil==True:
125         plt.plot(foil1_numpy_LE_side[:, 0], foil1_numpy_LE_side[:, 1], 'b.', label='
126         input airfoil')
127         plt.plot(foil1_numpy_mcl_LE[:, 0], foil1_numpy_mcl_LE[:, 1], 'g.', label='
128         Mean Camber line')
129
130         plt.plot(foil1_numpy_mid[:, 0], foil1_numpy_mid[:, 1], 'b.')
131         plt.plot(foil1_numpy_mcl_mid[:, 0], foil1_numpy_mcl_mid[:, 1], 'g.')
132
133         plt.plot(foil1_numpy_TE_side[:, 0], foil1_numpy_TE_side[:, 1], 'b.')
134         plt.plot(foil1_numpy_mcl_TE1[:, 0], foil1_numpy_mcl_TE1[:, 1], 'g.')
135
136         plt.gca().set_aspect('equal')
137         plt.ylim([-0.01, 1.1])
138         # plt.ylim([-0.01, 0.05])
139         plt.xlim([-0.01, 1.1])

```

```

138     # plt.xlim([-0.08, 0.1])
139     plt.legend()
140     plt.figure()
141
142
143     return mcl_curve
144
145 mcl_curve_001 = calc_mean_camber_line(foil1_numpy, view_airfoil=False)
146 mcl_curve_002 = calc_mean_camber_line(foil2_numpy, view_airfoil=False)
147 mcl_curve_003 = calc_mean_camber_line(foil3_numpy, view_airfoil=False)
148
149
150 ### Use the mcl curve values for u coordinates and compare their v values to
    separate the airfoil coordinates into suction and pressure sides.
151
152 # Add in a third row to store flag of pressure side and suction side: 1 => suction
    side and 0 => pressure side
153 foil1_numpy = np.append(foil1_numpy, np.zeros([len(foil1_numpy), 1]), 1)
154 foil2_numpy = np.append(foil2_numpy, np.zeros([len(foil2_numpy), 1]), 1)
155 foil3_numpy = np.append(foil3_numpy, np.zeros([len(foil3_numpy), 1]), 1)
156
157 # Now, change the flag of suction side by comparing 'v' values of mcl and airfoil
    coordinates for a given 'u'.
158
159 def order_problems_in_coordinate_position(foil1_numpy, mcl_curve_001, v_sorting_flag
    =False):
160
161     indices_suction = []
162     for ii in range(len(foil1_numpy)):
163         indices_suction_side = np.where((foil1_numpy[ii, 0] == mcl_curve_001[:, 0]))
164         [0][0]
165         if (foil1_numpy[ii, 1] >= mcl_curve_001[indices_suction_side, 1]):
166             foil1_numpy[ii, 2] = 1
167             indices_suction.append(indices_suction_side)

```

```

168 # Sort the values in third column such that all the coordinates are grouped by
169 their suction or pressure side value.
170
171 foill_numpy = foill_numpy[foill_numpy[:, 2].argsort()]
172
173 ## Now break the airfoil into suction and pressure side coordinates
174 foill_numpy_001_suction_side = foill_numpy[foill_numpy[:, 2] == 1]
175 foill_numpy_001_pressure_side = foill_numpy[foill_numpy[:, 2] == 0]
176
177 ## Sort the above arrays by u values:
178 foill_numpy_001_suction_side = foill_numpy_001_suction_side[
179 foill_numpy_001_suction_side[:, 0].argsort()]
180 foill_numpy_001_pressure_side = foill_numpy_001_pressure_side[
181 foill_numpy_001_pressure_side[:, 0].argsort()[::-1]]
182
183 ## Break the sides into LE and TE quadrants
184 index_max_suction = np.argmax(foill_numpy_001_suction_side[:, 1])
185 foill_numpy_001_suction_side_LE = foill_numpy_001_suction_side[:
186 index_max_suction, :]
187 foill_numpy_001_suction_side_TE = foill_numpy_001_suction_side[index_max_suction
188 :, :]
189
190 ## Sort by v only for hub airfoil as the order of points makes sense there.
191 if v_sorting_flag==True:
192     ### Sort these by v values
193
194     foill_numpy_001_suction_side_LE = foill_numpy_001_suction_side_LE[
195 foill_numpy_001_suction_side_LE[:, 0].argsort()]
196     foill_numpy_001_suction_side_TE = foill_numpy_001_suction_side_TE[
197 foill_numpy_001_suction_side_TE[:, 1].argsort()[::-1]]
198
199 # plt.plot(foill_numpy_001_suction_side_LE[:, 0],
200 foill_numpy_001_suction_side_LE[:, 1], '-')
```

```

195 # plt.plot(foil1_numpy_001_suction_side_TE[:, 0],
196           foil1_numpy_001_suction_side_TE[:, 1], '-')
197
198 foil1_numpy_001_suction_side = np.concatenate((foil1_numpy_001_suction_side_LE ,
199 foil1_numpy_001_suction_side_TE))
200
201 # finally combine both suction and pressure side into one airoil coordiantes.
202 # This is the line you change to order TE to LE and back to TE:
203
204 new_foil1 = np.concatenate((foil1_numpy_001_pressure_side ,
205 foil1_numpy_001_suction_side))
206
207 new_foil1 = new_foil1[:, :2]
208
209
210 return new_foil1
211
212
213 new_foil1 = order_problems_in_coordinate_position(foil1_numpy , mcl_curve_001 ,
214 v_sorting_flag=True)
215
216 new_foil2 = order_problems_in_coordinate_position(foil2_numpy , mcl_curve_002 ,
217 v_sorting_flag=True)
218
219 new_foil3 = order_problems_in_coordinate_position(foil3_numpy , mcl_curve_003 ,
220 v_sorting_flag=False)
221
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```



```

222 # compare_results(foil1_numpy, new_foil1, mcl_curve_001)
223 # compare_results(foil2_numpy, new_foil2, mcl_curve_002)
224 # compare_results(foil3_numpy, new_foil3, mcl_curve_003)
225
226 ###
227
228 def plot_airfoil(E3_report, tblade3_file, mcl_line, page_label, ylimits=[-0.4, 0.4])
    :
229
230     plt.figure(figsize=(8.5, 8.5), dpi=250)
231     # plt.figure(dpi=250)
232     plt.title(page_label)
233     # plt.xlim([0.6, 1.01])
234     # plt.ylim([-0.02, 0.0505])
235     # plt.grid(True, which='both')
236     plt.plot(E3_report[:, 0], E3_report[:, 1], '-', color='orange', label='Plot
digitized Coordiantes')
237     plt.plot(tblade3_file[:, 0], tblade3_file[:, 1], '-', color='blue', label='
Ordered Coordiantes')
238     plt.plot(mcl_line[:, 0], mcl_line[:, 1], '-', color='green', label='Interpolated
Mean camber line')
239     plt.axis('equal')
240     plt.grid()
241     # plt.gca().set_aspect("equal")
242     plt.legend()
243
244
245
246 # Add in titles, grid and write to pdf
247
248 with PdfPages('order-airfoil-plots-005.pdf') as pdf:
249
250
251 ### Code snippet to add in title page to a matplotlib pdf
252     # plt.figure()
253     # plt.axis('off')

```

```

254 # plt.text(0.5,0.5,"my title",ha='center',va='center')
255 # pdf.savefig()
256 # plt.close()
257
258 # Begin of actual plot code
259 plot_airfoil(foil1_numpy, new_foil1, mcl_curve_001, page_label='Hub Section',
ylimits=[-0.1, 1.1])
260 pdf.savefig() # saves the current figure into a pdf page
261 plt.close()
262
263 plot_airfoil(foil2_numpy, new_foil2, mcl_curve_002, page_label='PSS Section',
ylimits=[-0.1, 1.1])
264 pdf.savefig()
265 plt.close()
266
267 plot_airfoil(foil3_numpy, new_foil3, mcl_curve_003, page_label='Tip Section',
ylimits=[-0.1, 1.1])
268 pdf.savefig() # or you can pass a Figure object to pdf.savefig
269 plt.close()
270
271
272
273 ### Save the coordinates to a file.
274
275 np.savetxt('E3_hub_coordinates_sorted_TE_to_LE.dat', new_foil1)
276 np.savetxt('E3_pss_coordinates_sorted_TE_to_LE.dat', new_foil2)
277 np.savetxt('E3_tip_coordinates_sorted_TE_to_LE.dat', new_foil3)

```

Appendix C

Codes for OpenMDAO and Tblade3

The following chapter of codes help prepare data to be input for OpenMDAO and Tblade3.

C.1 Streamlines Generator for 3dbginputfile

This code helps generate streamlines or surface-of-revolution data for Tblade3. It takes in hub and casing's 2D coordinates and generates intermediate streamlines using 1D interpolation.

```
1 import numpy as np
2 import pandas as pd
3 import matplotlib.pyplot as plt
4 import math
5 import csv
6 import itertools
7 from scipy.interpolate import CubicSpline
8
9
10
11 #Import the Coordinates for Hub
12 hub = pd.read_csv("hub_export.dat", na_values = None, skipinitialspace=True, skiprows
    = [0], sep="\s+", keep_default_na=False, names = ["X", "Y", "Z"])
13 hub.dropna(axis=0, how='any', thresh=None)
14 hub.astype(float)
15 #print(hub.head())
16
```

```

17 Xmax_hub = hub[ 'X' ].max()
18 Xmin_hub = hub[ 'X' ].min()
19 Ymax_hub = hub[ 'Y' ].max()
20 Ymin_hub = hub[ 'Y' ].min()
21
22 hub[ 'X' ] = hub[ 'X' ]-Xmin_hub
23 Xdiff_hub = Xmax_hub-Xmin_hub
24 Ydiff_hub = Ymax_hub-Ymin_hub
25 #print(Xdiff_hub)
26
27
28
29 #Import the Coordinates for LE and TE
30 LE_TE = pd.read_csv("unique_LE_TE_coordinates.dat",na_values = None,skipinitialspace
    =True,skiprows=[0],sep="\s+",keep_default_na=False,names = [ "xLE", "rLE", "xTE", "
    rTE" ])
31 #Be careful with the order of coordinates. These start at hub and go down to casing
    . (Imagine measuring while standing on the ground)
32 LE_TE.dropna(axis=0,how='any',thresh=None)
33 LE_TE.astype(float)
34 LE_TE = LE_TE.sort_values(by='rLE', ascending=False)
35 #print(LE_TE.tail())
36
37 LE = LE_TE.iloc[:,0:2].rename(columns={"xLE": "X", "rLE": "Y"})
38 LE_x_coord = LE.iloc[:,0].round(3).tolist()
39 LE_y_coord = LE.iloc[:,1].round(3).tolist()
40 LE_z_coord = [0.0] * len(LE['X'])
41 LE_df = pd.DataFrame(list(zip(LE_x_coord, LE_y_coord, LE_z_coord)), columns =['X', '
    Y', 'Z'], dtype=float).sort_values(by='Y', ascending=False)
42 LE_df = LE_df.reset_index(drop=True)
43 #print(LE_df)
44 #LE_df.to_csv('sorted_LE_df.dat', sep='\t', index=False)
45
46 TE = LE_TE.iloc[:,2:4].rename(columns={"xTE": "X", "rTE": "Y"})
47 TE_x_coord = TE.iloc[:,0].round(3).tolist()
48 TE_y_coord = TE.iloc[:,1].round(3).tolist()

```

```

49 TE_z_coord = [0.0] * len(TE['X'])
50 TE_df = pd.DataFrame(list(zip(TE_x_coord, TE_y_coord, TE_z_coord)), columns=['X', '
      Y', 'Z'], dtype=float).sort_values(by=['Y'], ascending=False)
51 TE_df = TE_df.reset_index(drop=True)
52 #print(TE_df.tail())
53 #TE_df.to_csv('sorted_TE_df.dat', sep='\t', index=False)
54
55
56 # There's been a mismatch between the coordinates of LE, TE and Hub. So we will
      normlaize the hub coordinates and then use the distance been the LE and TE
      coordinates to estimate a scaling factor for the hub coordnates.
57 # Then translate the hub coordinates so that the lowest coordinate of TE coincides
      with the 128th coordinate of the hub, this number is an estimate for now and
      could be easily altered when the right constraint is found.
58 # We are translating the hub instead of the blade because the LE and TE
      coordinates are from the NASA-GE E3 document where as the hub is just an export
      from FINE/TURBO IGG, so the primary source is given more preference.
59 # The estimation is done using Figure 40: Full-Scale Fan Test Vehicle on Page 45 of
      ""NASA-GE E3 fan design.pdf"" file
60 # Remember to update the indices with the maximum and minimum value
61 dist_LE0_TE0 = np.sqrt( ((LE_TE.iloc[-1,0]-LE_TE.iloc[-1,2])**2)+((LE_TE.iloc[-1,1]-
      LE_TE.iloc[-1,3])**2) )
62 #print(dist_LE0_TE0)
63 norm_hub = hub.copy()
64 norm_hub = norm_hub/Xdiff_hub
65 #print(norm_hub.head())
66 scaled_hub = norm_hub.copy()
67 scaled_hub = scaled_hub*dist_LE0_TE0*5.5
68 translated_hub = scaled_hub.copy()
69 xhub_TE_diff = LE_TE.iloc[-1,2] - translated_hub.iloc[127,0]
70 yhub_TE_diff = LE_TE.iloc[-1,3] - translated_hub.iloc[127,1]
71 #print(xhub_TE_diff)
72 #print(yhub_TE_diff)
73 translated_hub['X'] = translated_hub['X'] + xhub_TE_diff
74 translated_hub['Y'] = translated_hub['Y'] + yhub_TE_diff - 30e-2
75 translated_hub = translated_hub.round(17)

```

```

76 translated_hub.to_csv('translated_hub.dat', sep='\t', index=False)
77
78
79 # Using LE, TE and the scaled Hub Coordinates, construct the casing.
80 # We will construct the casing using three sections, one before the LE, second from
    LE to TE and finally
81
82 casing = translated_hub.copy()
83 #print(casing.head())
84 # Part 1 of casing
85 casing.iloc[:95,1] = LE_TE.iloc[0,1]+30e-2
86 casing1 = casing.iloc[0:95,:]
87 #print(casing1.tail())
88
89 # Part 2 of casing
90 def intermediates(p1, p2, nb_points=8):
91     """Return a list of nb_points equally spaced points
92     between p1 and p2"""
93     # If we have 8 intermediate points, we have 8+1=9 spaces
94     # between p1 and p2
95     x_spacing = (p2[0] - p1[0]) / (nb_points + 1)
96     y_spacing = (p2[1] - p1[1]) / (nb_points + 1)
97
98     return [[p1[0] + i * x_spacing, p1[1] + i * y_spacing, 0.0]
99             for i in range(1, nb_points+1)]
100 case3_points = intermediates([casing.iloc[93,0]+10e-1, LE_TE.iloc[0,1]+30e-2], [
    casing.iloc[125,0]-10e-2, LE_TE.iloc[0,3]+1e-2], nb_points=29)
101 case3_df = pd.DataFrame(case3_points, columns=['X', 'Y', 'Z'])
102 casing1_df = casing1.append(case3_df, ignore_index=True)
103
104 # Part 3 of casing
105 casing.iloc[124:,1] = LE_TE.iloc[0,3]+10e-2
106 casing1_dg = casing1_df.append(casing.iloc[124:], ignore_index=True)
107 casing1_dg = casing1_dg.round(6)
108 casing1_dg.to_csv('casing1_dg.dat', sep='\t', index=False)
109

```

```

110 #This equates the number of points in the casing to the number of points in the hub,
111 # this can also be achieved by simply making sure that the ending abscissa of both
112 # the casing and hub are the same
113
114 #final comparison of coordinates:
115 #print(translated_hub.tail())
116 #print(caseing1_dg.head())
117
118
119
120 # Streamline construction: We need to construct 21 streamlines between the hub and
    casing. Also, we need to make sure that the streamlines include the LE and TE
    coordinates.
121 # This is done in three parts. We start with making a dataframe of all the points
    on the left of LE and divide them into 21 sections
122
123 def streamline_coordinates_construct(x_iloc):
124
125     if x_iloc < 110:
126         #Use the LE coordinates to space the streamlines
127         temp_coords = []
128         for i in range(len(LE_df['X'])):
129             y20 = translated_hub.iloc[x_iloc, 1] + ((LE_df.iloc[i, 1]) * ((caseing1_dg.iloc[
130                 x_iloc, 1] - translated_hub.iloc[x_iloc, 1]) / (LE_df.iloc[0, 1] - LE_df.iloc[-1, 1])))
131             temp_coords.append(y20)
132             temp_coords = [round(num, 6) for num in temp_coords]
133             sorted(temp_coords, reverse=True)
134         #print(temp_coords)
135         #print(translated_hub.iloc[x_iloc, 1])
136         stream_deav = max(temp_coords) - caseing1_dg.iloc[x_iloc, 1]
137         temp_coords = [x - stream_deav for x in temp_coords]
138         streamlines_sect_1_y = temp_coords
139         # to evenly space the streamlines
140         #streamlines_sect_1_y = np.linspace(caseing1_dg.iloc[x_iloc, 1], translated_hub.
    iloc[x_iloc, 1], 21)
141         #print(streamlines_sect_1_y)

```

```

141     streamlines_sect_1_x = [caseing1_dg.iloc[x_iloc,0]] * len(streamlines_sect_1_y
)
142     #print(streamlines_sect_1_x)
143     streamlines_sect_1_z = [0.0] * len(streamlines_sect_1_x)
144     #print(streamlines_sect_1_z)
145     streamlines_sect_next_df = pd.DataFrame(list(zip(streamlines_sect_1_x ,
streamlines_sect_1_y , streamlines_sect_1_z)), columns =['X', 'Y', 'Z'], dtype=
float)
146     #print(streamlines_sect_next_df.tail())
147 else:
148     temp_coords=[]
149     for i in range(len(TE_df['X'])):
150         y20 = translated_hub.iloc[x_iloc,1]+((TE_df.iloc[i,1])*((caseing1_dg.iloc[
x_iloc,1]-translated_hub.iloc[x_iloc,1])/(TE_df.iloc[0,1]-TE_df.iloc[-1,1])))
151         temp_coords.append(y20)
152         temp_coords = [round(num, 6) for num in temp_coords]
153         sorted(temp_coords, reverse=True)
154     stream_deav = max(temp_coords) - caseing1_dg.iloc[x_iloc, 1]
155     temp_coords = [x-stream_deav for x in temp_coords]
156     streamlines_sect_1_y = temp_coords
157     streamlines_sect_1_x = [caseing1_dg.iloc[x_iloc,0]] * len(streamlines_sect_1_y
)
158     streamlines_sect_1_z = [0.0] * len(streamlines_sect_1_x)
159     streamlines_sect_next_df = pd.DataFrame(list(zip(streamlines_sect_1_x ,
streamlines_sect_1_y , streamlines_sect_1_z)), columns =['X', 'Y', 'Z'], dtype=
float)
160     #streamlines_sect_next_df = streamlines_sect_next_df.sort_values(by='Y',
ascending=False)
161     return streamlines_sect_next_df
162
163 list_x_vals = [np.arange(60, 209, 10)]
164 #print(list_x_vals)
165
166 #Part1: Generate the points from LE and LE
167
168 streamlines_sect01_next_df = streamline_coordinates_construct(60)

```



```

169 #print(streamlines_sect01_next_df.tail())
170 streamlines_sect02_next_df = streamline_coordinates_construct(70)
171 streamlines_sect03_next_df = streamline_coordinates_construct(80)
172 streamlines_sect04_next_df = streamline_coordinates_construct(85)
173 streamlines_sect05_next_df = streamline_coordinates_construct(98)
174 streamlines_sect06_next_df = streamline_coordinates_construct(105)
175 streamlines_sect07_next_df = streamline_coordinates_construct(112)
176 streamlines_sect08_next_df = streamline_coordinates_construct(120)
177 streamlines_sect09_next_df = streamline_coordinates_construct(130)
178 streamlines_sect10_next_df = streamline_coordinates_construct(140)
179 streamlines_sect11_next_df = streamline_coordinates_construct(150)
180 streamlines_sect12_next_df = streamline_coordinates_construct(160)
181 streamlines_sect13_next_df = streamline_coordinates_construct(170)
182 streamlines_sect14_next_df = streamline_coordinates_construct(180)
183 streamlines_sect15_next_df = streamline_coordinates_construct(190)
184 streamlines_sect16_next_df = streamline_coordinates_construct(209)
185
186 #print(list_of_coordinates)
187
188 """ There is an issue with the current LE and TE coordinates where in they are no
        uniformly spaced and there are duplicated values as well. We replace them with an
        evenly spaced linear interpolation version using "interpolation_LE_TE.py" file """
189
190 #interp_LE_df = pd.read_csv("/home/bharadwaj/work/Meeting_10/Meeting_docs/Chris
        Feldman_Docs/E3_trial1/E3_streamlines/sorted_LE_df.dat",na_values = None,
        skipinitialspace=True,sep="\s+")
191 #print(interp_LE_df)
192 #interp_TE_df = pd.read_csv("/home/bharadwaj/work/Meeting_10/Meeting_docs/Chris
        Feldman_Docs/E3_trial1/E3_streamlines/sorted_TE_df.dat",na_values = None,
        skipinitialspace=True,sep="\s+")
193 #print(interp_TE_df)
194
195 #Part2: Append the generated points into a single dataframe
196
197 streamlines_final_df = streamlines_sect01_next_df.append(streamlines_sect02_next_df,
        ignore_index = True)

```

```

198 #print(streamlines_final_df.tail())
199 streamlines_final_df = streamlines_final_df.append(streamlines_sect03_next_df,
    ignore_index = True)
200 streamlines_final_df = streamlines_final_df.append(streamlines_sect04_next_df,
    ignore_index = True)
201 streamlines_final_df = streamlines_final_df.append(LE_df, ignore_index = True)
202 streamlines_final_df = streamlines_final_df.append(streamlines_sect05_next_df,
    ignore_index = True)
203 streamlines_final_df = streamlines_final_df.append(streamlines_sect06_next_df,
    ignore_index = True)
204 streamlines_final_df = streamlines_final_df.append(streamlines_sect07_next_df,
    ignore_index = True)
205 streamlines_final_df = streamlines_final_df.append(streamlines_sect08_next_df,
    ignore_index = True)
206 streamlines_final_df = streamlines_final_df.append(TE_df, ignore_index = True)
207 streamlines_final_df = streamlines_final_df.append(streamlines_sect09_next_df,
    ignore_index = True)
208 streamlines_final_df = streamlines_final_df.append(streamlines_sect10_next_df,
    ignore_index = True)
209 streamlines_final_df = streamlines_final_df.append(streamlines_sect11_next_df,
    ignore_index = True)
210 streamlines_final_df = streamlines_final_df.append(streamlines_sect12_next_df,
    ignore_index = True)
211 streamlines_final_df = streamlines_final_df.append(streamlines_sect13_next_df,
    ignore_index = True)
212 streamlines_final_df = streamlines_final_df.append(streamlines_sect14_next_df,
    ignore_index = True)
213 streamlines_final_df = streamlines_final_df.append(streamlines_sect15_next_df,
    ignore_index = True)
214 streamlines_final_df = streamlines_final_df.append(streamlines_sect16_next_df,
    ignore_index = True)
215 #print(streamlines_final_df.head())
216 #print(streamlines_final_df.tail())
217
218 #df.iloc[:, :5, :]
219

```

```

220 #Part3: Regroup the coordinates into separate dataframes containing individual
      streamline data.
221 strm_cutoff = int(len(TE_df))
222
223 streamline_01_coordiantes = streamlines_final_df.iloc [::strm_cutoff, :].reset_index(
      drop=True)
224 #print(streamline_01_coordiantes.tail())
225 streamline_02_coordiantes = streamlines_final_df.iloc [1::strm_cutoff, :].reset_index
      (drop=True)
226 streamline_03_coordiantes = streamlines_final_df.iloc [2::strm_cutoff, :].reset_index
      (drop=True)
227 streamline_04_coordiantes = streamlines_final_df.iloc [3::strm_cutoff, :].reset_index
      (drop=True)
228 streamline_05_coordiantes = streamlines_final_df.iloc [4::strm_cutoff, :].reset_index
      (drop=True)
229 streamline_06_coordiantes = streamlines_final_df.iloc [5::strm_cutoff, :].reset_index
      (drop=True)
230 streamline_07_coordiantes = streamlines_final_df.iloc [6::strm_cutoff, :].reset_index
      (drop=True)
231 streamline_08_coordiantes = streamlines_final_df.iloc [7::strm_cutoff, :].reset_index
      (drop=True)
232 streamline_09_coordiantes = streamlines_final_df.iloc [8::strm_cutoff, :].reset_index
      (drop=True)
233 streamline_10_coordiantes = streamlines_final_df.iloc [9::strm_cutoff, :].reset_index
      (drop=True)
234 streamline_11_coordiantes = streamlines_final_df.iloc [10::strm_cutoff, :].
      reset_index(drop=True)
235 streamline_12_coordiantes = streamlines_final_df.iloc [11::strm_cutoff, :].
      reset_index(drop=True)
236 streamline_13_coordiantes = streamlines_final_df.iloc [12::strm_cutoff, :].
      reset_index(drop=True)
237 streamline_14_coordiantes = streamlines_final_df.iloc [13::strm_cutoff, :].
      reset_index(drop=True)
238 streamline_15_coordiantes = streamlines_final_df.iloc [14::strm_cutoff, :].
      reset_index(drop=True)

```

```

239 streamline_16_coordiantes = streamlines_final_df.iloc[15::strm_cutoff, :].
      reset_index(drop=True)
240 streamline_17_coordiantes = streamlines_final_df.iloc[16::strm_cutoff, :].
      reset_index(drop=True)
241 streamline_18_coordiantes = streamlines_final_df.iloc[17::strm_cutoff, :].
      reset_index(drop=True)
242
243
244 #print(streamline_18_coordiantes.tail())
245
246 # Though this was a crude way to get the streamlines, a more smoother approach
      instead of calculating all the streamline coordninates using LE or TE coordintes
      would be to just calculate the first and last column of coordrinates using the
      above method (Part1) and then linerarly interpolate any number of points between
      them such that you would have a smoother transition between inlet, LE, TE and
      outlet.
247
248
249 caseing1_dg = caseing1_dg.iloc[59:,:] #This chops off the casing extesnion and
      provides a more realistic view of the geometry.
250
251
252 # Part4: Create an output file such that you can paste the hub, streamlines and
      casing data into 3dbgb input file. The order is: Hub, Streamlines, casing.
253 list_0 = [0]
254 zero_df = pd.DataFrame(list(zip(list_0, list_0)), columns=['x-s', 'r-s'], dtype=int
      )
255
256
257 streamlines_hub_tblade3 = pd.DataFrame(list(zip(translated_hub['X'], translated_hub[
      'Y'])), columns=['x-s', 'r-s'], dtype=float)
258 streamlines_df = streamlines_hub_tblade3.copy()
259 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
260 streamlines_01_tblade3 = pd.DataFrame(list(zip(streamline_18_coordiantes['X'],
      streamline_18_coordiantes['Y'])), columns=['x-s', 'r-s'], dtype=float)
261 streamlines_01_tblade3 = streamlines_01_tblade3.round(7)

```

```

262 streamlines_df = streamlines_df.append(streamlines_01_tblade3 , ignore_index = True)
263 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
264 streamlines_02_tblade3 = pd.DataFrame(list(zip(streamline_17_coordiantes ['X'],
        streamline_17_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
265 streamlines_02_tblade3 = streamlines_02_tblade3.round(7)
266 streamlines_df = streamlines_df.append(streamlines_02_tblade3 , ignore_index = True)
267 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
268 streamlines_03_tblade3 = pd.DataFrame(list(zip(streamline_16_coordiantes ['X'],
        streamline_16_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
269 streamlines_03_tblade3 = streamlines_03_tblade3.round(7)
270 streamlines_df = streamlines_df.append(streamlines_03_tblade3 , ignore_index = True)
271 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
272 streamlines_04_tblade3 = pd.DataFrame(list(zip(streamline_15_coordiantes ['X'],
        streamline_15_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
273 streamlines_04_tblade3 = streamlines_04_tblade3.round(7)
274 streamlines_df = streamlines_df.append(streamlines_04_tblade3 , ignore_index = True)
275 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
276 streamlines_05_tblade3 = pd.DataFrame(list(zip(streamline_14_coordiantes ['X'],
        streamline_14_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
277 streamlines_05_tblade3 = streamlines_05_tblade3.round(7)
278 streamlines_df = streamlines_df.append(streamlines_05_tblade3 , ignore_index = True)
279 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
280 streamlines_06_tblade3 = pd.DataFrame(list(zip(streamline_13_coordiantes ['X'],
        streamline_13_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
281 streamlines_06_tblade3 = streamlines_06_tblade3.round(7)
282 streamlines_df = streamlines_df.append(streamlines_06_tblade3 , ignore_index = True)
283 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
284 streamlines_07_tblade3 = pd.DataFrame(list(zip(streamline_12_coordiantes ['X'],
        streamline_12_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
285 streamlines_07_tblade3 = streamlines_07_tblade3.round(7)
286 streamlines_df = streamlines_df.append(streamlines_07_tblade3 , ignore_index = True)
287 streamlines_df = streamlines_df.append(zero_df , ignore_index = True)
288 streamlines_08_tblade3 = pd.DataFrame(list(zip(streamline_11_coordiantes ['X'],
        streamline_11_coordiantes ['Y'])), columns=['x_s', 'r_s'], dtype=float)
289 streamlines_08_tblade3 = streamlines_08_tblade3.round(7)
290 streamlines_df = streamlines_df.append(streamlines_08_tblade3 , ignore_index = True)

```

```

291 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
292 streamlines_09_tblade3 = pd.DataFrame(list(zip(streamline_10_coordiantes['X'],
        streamline_10_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
293 streamlines_09_tblade3 = streamlines_09_tblade3.round(7)
294 streamlines_df = streamlines_df.append(streamlines_09_tblade3, ignore_index = True)
295 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
296 streamlines_10_tblade3 = pd.DataFrame(list(zip(streamline_09_coordiantes['X'],
        streamline_09_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
297 streamlines_10_tblade3 = streamlines_10_tblade3.round(7)
298 streamlines_df = streamlines_df.append(streamlines_10_tblade3, ignore_index = True)
299 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
300 streamlines_11_tblade3 = pd.DataFrame(list(zip(streamline_08_coordiantes['X'],
        streamline_08_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
301 streamlines_11_tblade3 = streamlines_11_tblade3.round(7)
302 streamlines_df = streamlines_df.append(streamlines_11_tblade3, ignore_index = True)
303 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
304 streamlines_12_tblade3 = pd.DataFrame(list(zip(streamline_07_coordiantes['X'],
        streamline_07_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
305 streamlines_12_tblade3 = streamlines_12_tblade3.round(7)
306 streamlines_df = streamlines_df.append(streamlines_12_tblade3, ignore_index = True)
307 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
308 streamlines_13_tblade3 = pd.DataFrame(list(zip(streamline_06_coordiantes['X'],
        streamline_06_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
309 streamlines_13_tblade3 = streamlines_13_tblade3.round(7)
310 streamlines_df = streamlines_df.append(streamlines_13_tblade3, ignore_index = True)
311 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
312 streamlines_14_tblade3 = pd.DataFrame(list(zip(streamline_05_coordiantes['X'],
        streamline_05_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
313 streamlines_14_tblade3 = streamlines_14_tblade3.round(7)
314 streamlines_df = streamlines_df.append(streamlines_14_tblade3, ignore_index = True)
315 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
316 streamlines_15_tblade3 = pd.DataFrame(list(zip(streamline_04_coordiantes['X'],
        streamline_04_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
317 streamlines_15_tblade3 = streamlines_15_tblade3.round(7)
318 streamlines_df = streamlines_df.append(streamlines_15_tblade3, ignore_index = True)
319 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)

```

```

320 streamlines_16_tblade3 = pd.DataFrame(list(zip(streamline_03_coordiantes['X'],
        streamline_03_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
321 streamlines_16_tblade3 = streamlines_16_tblade3.round(7)
322 streamlines_df = streamlines_df.append(streamlines_16_tblade3, ignore_index = True)
323 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
324 streamlines_17_tblade3 = pd.DataFrame(list(zip(streamline_02_coordiantes['X'],
        streamline_02_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
325 streamlines_17_tblade3 = streamlines_17_tblade3.round(7)
326 streamlines_df = streamlines_df.append(streamlines_17_tblade3, ignore_index = True)
327 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
328 streamlines_18_tblade3 = pd.DataFrame(list(zip(streamline_01_coordiantes['X'],
        streamline_01_coordiantes['Y'])), columns=['x_s', 'r_s'], dtype=float)
329 streamlines_18_tblade3 = streamlines_18_tblade3.round(7)
330 streamlines_df = streamlines_df.append(streamlines_18_tblade3, ignore_index = True)
331 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
332 streamlines_casing_tblade3 = pd.DataFrame(list(zip(caseing1_dg['X'], caseing1_dg['Y']
        ))), columns=['x_s', 'r_s'], dtype=float)
333 streamlines_df = streamlines_df.append(streamlines_casing_tblade3, ignore_index =
        True)
334 streamlines_df = streamlines_df.append(zero_df, ignore_index = True)
335 print(streamlines_df)
336 streamlines_df.to_csv('tblade3_streamlines_w_format.dat', sep='\t', index=False)
337
338
339
340 # Plot the files
341 plt.plot(translated_hub['X'], translated_hub['Y'], label='Translated Hub Coordinates'
        , color='Violet')
342 plt.plot(LE_TE['xLE'], LE_TE['rLE'], label='LE', color='red')
343 plt.plot(LE_TE['xTE'], LE_TE['rTE'], label='TE', color='blue')
344 plt.plot(caseing1_dg['X'], caseing1_dg['Y'], label='Generated Casing', color='black')
345 plt.plot(streamlines_final_df['X'], streamlines_final_df['Y'], 'g^', label='
        Streamline Coordinates')
346
347 # Plot Streamlines

```

```
348 plt.plot(streamline_01_coordiantes['X'],streamline_01_coordiantes['Y'], label='
      Streamlines', color='grey')
349 plt.plot(streamline_02_coordiantes['X'],streamline_02_coordiantes['Y'], color='grey'
      )
350 plt.plot(streamline_03_coordiantes['X'],streamline_03_coordiantes['Y'], color='grey'
      )
351 plt.plot(streamline_04_coordiantes['X'],streamline_04_coordiantes['Y'], color='grey'
      )
352 plt.plot(streamline_05_coordiantes['X'],streamline_05_coordiantes['Y'], color='grey'
      )
353 plt.plot(streamline_06_coordiantes['X'],streamline_06_coordiantes['Y'], color='grey'
      )
354 plt.plot(streamline_07_coordiantes['X'],streamline_07_coordiantes['Y'], color='grey'
      )
355 plt.plot(streamline_08_coordiantes['X'],streamline_08_coordiantes['Y'], color='grey'
      )
356 plt.plot(streamline_09_coordiantes['X'],streamline_09_coordiantes['Y'], color='grey'
      )
357 plt.plot(streamline_10_coordiantes['X'],streamline_10_coordiantes['Y'], color='grey'
      )
358 plt.plot(streamline_11_coordiantes['X'],streamline_11_coordiantes['Y'], color='grey'
      )
359 plt.plot(streamline_12_coordiantes['X'],streamline_12_coordiantes['Y'], color='grey'
      )
360 plt.plot(streamline_13_coordiantes['X'],streamline_13_coordiantes['Y'], color='grey'
      )
361 plt.plot(streamline_14_coordiantes['X'],streamline_14_coordiantes['Y'], color='grey'
      )
362 plt.plot(streamline_15_coordiantes['X'],streamline_15_coordiantes['Y'], color='grey'
      )
363 plt.plot(streamline_16_coordiantes['X'],streamline_16_coordiantes['Y'], color='grey'
      )
364 plt.plot(streamline_17_coordiantes['X'],streamline_17_coordiantes['Y'], color='grey'
      )
365 plt.plot(streamline_18_coordiantes['X'],streamline_18_coordiantes['Y'], color='grey'
      )
```



```

366 #plt.plot(streamline_21_coordiantes['X'],streamline_21_coordiantes['Y'], color='grey
      ')
367
368
369
370
371 #plt.plot(case3_df['X'],case3_df['Y'], label='slant Casing', color='red')
372 plt.legend()
373 plt.show()
374
375 #Write to file
376 #caseing1_df.to_csv('caseing1_df.dat', sep='\t', index=False)
377
378 #Debugging
379 #plt.plot(foil_level05['X'],foil_level05['Y'], label='Blade Level 05', color='blue')
380 #plt.plot(r_div, casing['Y'], label='r_div', marker='o')
381 #plt.plot(hub['X'],hub['Y'], label='Hub Coordinates', color='red')
382 #plt.plot(scaled_hub['X'],scaled_hub['Y'], label='Scaled Hub Coordinates', color='
      red')
383 #plt.plot(norm_hub['X'],norm_hub['Y'], label='Norm Hub Coordinates', color='pink')
384 #print(intermediates([casing.iLoc[127,1]+10e-4, 2+10e-4], [10+10e-4, 6.5+10e-4],
      nb_points=34))
385 #print(casing.iLoc[127,1]+10e-4)
386 #print(casing.iLoc[91,1]+10e-4)
387 #plt.plot(casing['X'],casing['Y'], label='Generated Casing', color='blue')

```

C.2 Blade difference calculator

This code implements least squared difference calculation as explained in Section 2.1 along with diagnosis plots on optimization.

```

1 """
2
3 Why iter 007:
4     The initial idea was to use squared difference instead of root of squared
      difference and we missted that part.

```

```

5         This issue was fixed by removing the root in all difference calculations.
6
7 Why iter 006:
8     There is an issue with the new airfoils where the mid suction side only has one
9     point. Figure out why?
10    The issue was caused by the definitiaon with which we defined suction and
11    pressure sides using mean of the v values on both sides.
12    Once thickness began to reduce, the code began eliminating suction side points
13    .
14    We fixed it by adding in a function to calculate mcl line and then use the mcl
15    line to define which point goes to the suciton side and which one goes to the
16    pressure side. That fixed the issue for now.
17
18
19
20 Written by: Bharadwaj "Ben" Dogga
21
22 """
23
24
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99
100

```

```

34
35 # Determine the name of the main T-Blade3 input files
36 current_dir          = os.getcwd()
37 files                = os.listdir(current_dir)
38 for file in files:
39     if name_argument1 in file and name_argument2 in file:
40         input_file    = file.strip()
41         break
42
43 # Read main T-Blade3 input file and store the input in a list
44 f                    = open(input_file, 'r')
45 lines                = f.readlines()
46 f.close()
47
48 # lines1 = lines[106:197] # Select the range of lines that has 3 coordinates of
the airfoil
49 lines1 = lines.copy() # Select the range of lines that has 3 coordinates of the
airfoil
50
51 # numpy arrays for storing blade section coordinates read from the file
52 m_prime              = np.zeros(len(lines1))
53 theta                = np.zeros(len(lines1))
54
55 # Store the blade coordinates read from the file in the arrays defined above
56 i                    = 0
57 for line in lines1:
58     m_prime[i]        = float(line.split()[0])
59     theta[i]          = float(line.split()[1])
60     i                 = i + 1
61
62 m_prime = m_prime - np.amin(m_prime)
63 theta = theta - theta[np.argmin(m_prime)]
64
65 airfoil = np.column_stack((m_prime, theta))
66
67 return airfoil

```

```

68
69
70
71 # Interpolate values between two sets
72
73 def interpolate_section(xvals, xx, yy):
74     yvals = np.interp(xvals, xx, yy)
75     f = interpolate.interp1d(xx, yy)
76     yvals = f(xvals)
77     return np.array((xvals, yvals)).T
78     # return {'yvalues': yvals, 'xvalues': xvals}
79
80
81
82 # Make sure that x is a subset of xx
83 def make_sure_x_subset_of_xx_2D_array(x, xx, ascending=False):
84
85     if ascending==False:
86         for ii in range(len(x)):
87             if (x[0,0] > xx[0,0]):
88                 # print(x[0,0] < xx[0,0])
89                 x = np.delete(x, [0, 0], axis=0)
90                 # print(x)
91                 if (x[0,0] == xx[0,0]):
92                     break
93             else:
94                 # print("within xx - lower")
95                 break
96         # print(x)
97
98         for jj in reversed(range(len(x))):
99             if (x[-1,0] < xx[-1,0]):
100                 # print(x[-1,0] < xx[-1,0])
101                 x = np.delete(x, [-1,-1], axis=0)
102                 if (x[-1,0] == xx[-1,0]):
103                     break

```

```

104         else:
105             # print("within xx - upper")
106             break
107
108     else:
109         for ii in range(len(x)):
110             if (x[0,0] < xx[0,0]):
111                 # print(x[0,0] < xx[0,0])
112                 x = np.delete(x, [0, 0], axis=0)
113                 # print(x)
114                 if (x[0,0] == xx[0,0]):
115                     break
116             else:
117                 # print("within xx - lower")
118                 break
119     # print(x)
120
121     for jj in reversed(range(len(x))):
122         if (x[-1,0] > xx[-1,0]):
123             x = np.delete(x, [-1,-1], axis=0)
124             if (x[-1,0] == xx[-1,0]):
125                 break
126         else:
127             # print("within xx - upper")
128             break
129     # print(x)
130     return x
131
132
133
134 def test_plot(numpy_array):
135     plt.figure(dpi=150)
136     plt.plot(numpy_array[:, 0], numpy_array[:, 1], '- ', numpy_array[:, 0],
137             numpy_array[:, 1], '.', color='blue')
138

```

```

139 def assign_coordinates_to_suction_and_pressure_side(suction_side, pressure_side):
140     """ Ensure that pressure and suction are appropriately allocated
141     if (sum(pressure_side[:, 1]) > sum(suction_side[:, 1])):
142         suction_side_store = pressure_side
143         pressure_side_store = suction_side
144     else:
145         pressure_side_store = pressure_side
146         suction_side_store = suction_side
147
148     return suction_side_store, pressure_side_store
149
150
151 def order_coordinates(airfoil_part_coordinates, suction_side_flag=False):
152     if (suction_side_flag==True):
153         if (airfoil_part_coordinates[0, 0] < airfoil_part_coordinates[-1, 0]):
154             airfoil_part_coordinates = airfoil_part_coordinates[::-1]
155
156     else:
157         if (airfoil_part_coordinates[0, 0] > airfoil_part_coordinates[-1, 0]):
158             airfoil_part_coordinates = airfoil_part_coordinates[::-1]
159
160     return airfoil_part_coordinates
161
162
163
164 def center_v_1_in_Trailing_Edge_array(Trailing_Edge_array):
165     """
166     This function takes in the trailing edge section and returns the array rolled
167     with the maximum v difference points on the extremes of array.
168     It ensures that the cut section array begins at u = uTE and goes up to u = 1 and
169     comes back to u = uTE to ensure proper calculation of difference.
170     """
171     difference_array = np.zeros(len(Trailing_Edge_array))
172     for ii in range(len(Trailing_Edge_array)):
173         if ii == len(Trailing_Edge_array):

```

```

173         difference_value = Trailing_Edge_array[-1, 1] - Trailing_Edge_array[0,
174         1]
175         difference_array[-1] = abs(difference_value)
176     else:
177         difference_value = Trailing_Edge_array[ii, 1] - Trailing_Edge_array[ii
178         -1, 1]
179         difference_array[ii] = abs(difference_value)
180
181     ##### The next line is the code that fixed issues with rolling.
182     difference_index = len(Trailing_Edge_array) - np.argmax(difference_array)
183     Trailing_Edge_array = np.roll(Trailing_Edge_array, difference_index, axis=0)
184
185     return Trailing_Edge_array
186
187 ##### A function to calculate mean camberline from input coordiantes
188 def fit_camber_using_polyfit(foil_numpy_input, polyfit_order=2, plot_mcl='no'):
189
190
191     z = np.polyfit(foil_numpy_input[:, 0], foil_numpy_input[:, 1], polyfit_order)
192     p = np.poly1d(z)
193     foil_numpy_side_u = foil_numpy_input[:, 0]
194
195     mcl_curve = np.stack((foil_numpy_side_u, p(foil_numpy_side_u)), axis=1)
196     mcl_curve = mcl_curve[np.argsort(mcl_curve[:, 0])]
197
198
199     if (plot_mcl=='yes'):
200         plt.figure(dpi=150)
201         plt.plot(mcl_curve[:, 0], mcl_curve[:, 1], '.', label='mcl_curve')
202         plt.plot(foil_numpy_input[:, 0], foil_numpy_input[:, 1], '.', label='
203         airfoil_coordiantes')
204         plt.xlim(-0.01, 1.01)
205         plt.ylim(-0.07, 0.2)
206         plt.legend()

```

```

206
207
208     return mcl_curve
209
210
211 ### Use mcl function to separate suction side coordinates from pressure side ones.
212
213
214
215 ### function to divide airfoil into six parts:
216 def break_airfoil_into_six_parts(airfoil_coordinates_array, uLE, uTE, visual_debug=
    False):
217
218     """
219     This function takes in an airfoil section coordinates as numpy array and breaks
    it down into six sections based on input uLE and uTE.
220     All u coordinates on suction side need to be sorted in descending order and
    pressure side u needs to be in ascending order.
221     We need to ensure that all suction parts stay on the suction side and vice versa
    for pressure side.
222     """
223
224     # Start with cutting the blade along u: LE | mid | TE
225     ## Target Airfoil section: LE
226     airfoil_coordinates_array_Leading_Edge = airfoil_coordinates_array[np.where(
    airfoil_coordinates_array[:,0] < uLE)]
227
228     ### Divide the LE side into pressure and suction side:
229     airfoil_coordinates_array_u_0_index = np.argwhere(
    airfoil_coordinates_array_Leading_Edge[:,0] == 0)
230     airfoil_coordinates_array_Leading_Edge_pressure =
    airfoil_coordinates_array_Leading_Edge[airfoil_coordinates_array_u_0_index
    [0][0],:]
231     airfoil_coordinates_array_Leading_Edge_suction =
    airfoil_coordinates_array_Leading_Edge[airfoil_coordinates_array_u_0_index
    [0][0]:,:]

```



```

232
233 airfoil_coordinates_array_Leading_Edge_suction ,
    airfoil_coordinates_array_Leading_Edge_pressure =
    assign_coordinates_to_suction_and_pressure_side(
    airfoil_coordinates_array_Leading_Edge_suction ,
    airfoil_coordinates_array_Leading_Edge_pressure)
234 airfoil_coordinates_array_Leading_Edge_suction = order_coordinates(
    airfoil_coordinates_array_Leading_Edge_suction , suction_side_flag=True)
235 airfoil_coordinates_array_Leading_Edge_pressure = order_coordinates(
    airfoil_coordinates_array_Leading_Edge_pressure , suction_side_flag=False)
236
237
238 if (visual_debug==True):
239     test_plot(airfoil_coordinates_array_Leading_Edge)
240
241
242
243
244 ## Target Airoil section: mid
245 ### The airfoil mid sections had to be sorted to align with other parts.
246 airfoil_coordinates_array_mid = airfoil_coordinates_array[np.where((
    airfoil_coordinates_array[:,0] > uLE) & (airfoil_coordinates_array[:,0] < uTE))]
247 foil_numpy_mcl_mid = fit_camber_using_polyfit(airfoil_coordinates_array_mid ,
    polyfit_order=2, plot_mcl='no')
248 foil_numpy = np.append(airfoil_coordinates_array_mid , np.zeros([len(
    airfoil_coordinates_array_mid),1]),1)
249
250 for ii in range(len(foil_numpy)):
251     indices_suction_side = np.where((foil_numpy[ii,0] == foil_numpy_mcl_mid[:,0])
    ) [0][0]
252     if (foil_numpy[ii, 1] >= foil_numpy_mcl_mid[indices_suction_side,1]):
253         foil_numpy[ii, 2] = 1
254 # print(np.shape(foil_numpy))
255
256 airfoil_coordinates_array_mid_pressure = foil_numpy[foil_numpy[:, 2] == 1]
257 airfoil_coordinates_array_mid_suction = foil_numpy[foil_numpy[:, 2] == 0]

```

```

258 airfoil_coordinates_array_mid_suction , airfoil_coordinates_array_mid_pressure =
    assign_coordinates_to_suction_and_pressure_side(
        airfoil_coordinates_array_mid_suction , airfoil_coordinates_array_mid_pressure)
259 airfoil_coordinates_array_mid_suction = order_coordinates(
        airfoil_coordinates_array_mid_suction , suction_side_flag=True)
260 airfoil_coordinates_array_mid_pressure = order_coordinates(
        airfoil_coordinates_array_mid_pressure , suction_side_flag=False)
261 airfoil_coordinates_array_mid_suction = airfoil_coordinates_array_mid_suction[:,
        :2]
262 airfoil_coordinates_array_mid_pressure = airfoil_coordinates_array_mid_pressure
       [:, :2]
263 # print(np.shape(airfoil_coordinates_array_mid_suction))
264
265
266 plot_mcl='no'
267 if (plot_mcl=='yes'):
268     plt.figure(dpi=150)
269     plt.plot(foil_numpy_mcl_mid[:, 0], foil_numpy_mcl_mid[:, 1], '.', label='
        mcl_curve')
270     plt.plot(airfoil_coordinates_array_mid_suction[:, 0],
        airfoil_coordinates_array_mid_suction[:, 1], '-', label='suction_side', color='
        blue')
271     plt.plot(airfoil_coordinates_array_mid_pressure[:, 0],
        airfoil_coordinates_array_mid_pressure[:, 1], '-', label='pressure_side', color='
        orange')
272     plt.xlim(-0.01, 1.01)
273     plt.ylim(-0.07, 0.2)
274     plt.legend()
275
276
277
278 ## Target Airoil section: TE
279 airfoil_coordinates_array_Trailing_Edge = airfoil_coordinates_array[np.where(
        airfoil_coordinates_array[:,0] > uTE)]
280 airfoil_coordinates_array_Trailing_Edge = center_v_l_in_Trailing_Edge_array(
        airfoil_coordinates_array_Trailing_Edge)

```

```

281
282 if (visual_debug==True):
283     test_plot(airfoil_coordinates_array_Trailing_Edge)
284
285 ### Divide the TE side into pressure and suction side:
286 airfoil_coordinates_array_u_1_index = np.argwhere(
    airfoil_coordinates_array_Trailing_Edge[:,0] == 1)
287 airfoil_coordinates_array_Trailing_Edge_pressure =
    airfoil_coordinates_array_Trailing_Edge[:airfoil_coordinates_array_u_1_index
    [0][0],:]
288 airfoil_coordinates_array_Trailing_Edge_suction =
    airfoil_coordinates_array_Trailing_Edge[airfoil_coordinates_array_u_1_index
    [0][0]:,:]
289 airfoil_coordinates_array_Trailing_Edge_suction ,
    airfoil_coordinates_array_Trailing_Edge_pressure =
    assign_coordinates_to_suction_and_pressure_side(
    airfoil_coordinates_array_Trailing_Edge_suction ,
    airfoil_coordinates_array_Trailing_Edge_pressure)
290 airfoil_coordinates_array_Trailing_Edge_suction = order_coordinates(
    airfoil_coordinates_array_Trailing_Edge_suction , suction_side_flag=True)
291 airfoil_coordinates_array_Trailing_Edge_pressure = order_coordinates(
    airfoil_coordinates_array_Trailing_Edge_pressure , suction_side_flag=False)
292
293
294
295 ### Combine all sections into a dictionary
296
297 return {'suction_TE': airfoil_coordinates_array_Trailing_Edge_suction , '
    suction_mid': airfoil_coordinates_array_mid_suction , 'suction_LE':
    airfoil_coordinates_array_Leading_Edge_suction , 'pressure_LE':
    airfoil_coordinates_array_Leading_Edge_pressure , 'pressure_mid':
    airfoil_coordinates_array_mid_pressure , 'pressure_TE':
    airfoil_coordinates_array_Trailing_Edge_pressure}
298
299
300

```

```

301 ### store coordinates in a numpy array called foil#_numpy
302
303
304 foil1_numpy = import_airfoil_coordinates(name_argument1="
        E3_hub_coordinates_sorted_TE_to_LE", name_argument2=".dat")
305 # foil1_numpy = import_airfoil_coordinates(name_argument1="tblade3_test_blade",
        name_argument2=".dat")
306 # foil1_numpy = import_airfoil_coordinates(name_argument1="uvblade.1.1",
        name_argument2="GE_E3_Fan_rotor")
307 foil1_numpy = foil1_numpy/np.amax(foil1_numpy[:,0])
308
309
310 test_foil1 = foil1_numpy
311
312 foil2_numpy = import_airfoil_coordinates(name_argument1="uvblade.1.1",
        name_argument2="GE_E3_Fan_rotor")
313 # foil2_numpy = import_airfoil_coordinates(name_argument1="uvblade.1.1_issue1_001",
        name_argument2="GE_E3_Fan_rotor")
314 # foil2_numpy = import_airfoil_coordinates(name_argument1="uvblade.1.1_issue1_002",
        name_argument2="GE_E3_Fan_rotor")
315 foil2_numpy = foil2_numpy/np.amax(foil2_numpy[:,0])
316
317
318 test_foil2 = foil2_numpy
319
320 ##Set u values at ends of LE and TE
321 uLE = 0.20
322 uTE = 0.80
323
324 visual_debug = True
325 ### Break target airfoil coordinates into six parts:
326
327 foil1_numpy = break_airfoil_into_six_parts(foil1_numpy, uLE, uTE, visual_debug=False
        )
328 foil2_numpy = break_airfoil_into_six_parts(foil2_numpy, uLE, uTE, visual_debug=False
        )

```

```

329
330 ### Make sure each airfoil part is a subsection of the other and calculate the
      differences between two foils:
331
332
333 """
334 We start with removing points from plot digitized u coordinates part to make their u
      coordinates a subset of tblade3 part u coordinates.
335 Next, we will interpolate between plot digitized values using u coordinates from
      tblade3 files.
336 Ensuring that the plot digitized airfoil's u coordinates are a subset of tblade3 u
      coordinates simplifies the difference calculation while retaining enough
      information from the plot digitized file.
337 """
338
339
340 # Suction side
341 # Calculate difference for Suction side Trailing Edge part:
342 part='suction_TE'
343 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
      [part], ascending=False)
344 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
      ][:,0], foil2_numpy[part][:,1])
345 diff1 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
346
347 """
348 We obtain a new set of foil1 u coordinates by making sure that they are a subset of
      foil2 u coordinates.
349 Then we take the new foil1 u coordinates and interpolate them around the foil2
      coordinates such that they have the same u values but only differ by v values.
350 These steps are essential so that taking difference would make a lot of sense.
351 The "ascending" flag is determined by the order of u coordinates from index 0.
352 """
353
354 ## Calculate difference for Suction side mid part:
355 part='suction_mid'

```

```

356 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
    [part], ascending=False)
357 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
   ][:,0], foil2_numpy[part][:,1])
358 diff2 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
359
360 ## Calculate difference for Suction side Leading Edge part:
361 part='suction_LE'
362 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
    [part], ascending=False)
363 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
   ][:,0], foil2_numpy[part][:,1])
364 diff3 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
365
366 ## Calculate difference for Pressure side Leading Edge part:
367 part='pressure_LE'
368 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
    [part], ascending=True)
369 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
   ][:,0], foil2_numpy[part][:,1])
370 diff4 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
371
372 ## Calculate difference for Pressure side mid part:
373 part='pressure_mid'
374 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
    [part], ascending=True)
375 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
   ][:,0], foil2_numpy[part][:,1])
376 diff5 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
377
378 ## Calculate difference for Pressure side TE part:
379 part='pressure_TE'
380 foil1_numpy[part] = make_sure_x_subset_of_xx_2D_array(foil1_numpy[part], foil2_numpy
    [part], ascending=True)
381 foil2_numpy[part] = interpolate_section(foil1_numpy[part][:,0], foil2_numpy[part
   ][:,0], foil2_numpy[part][:,1])

```

```

382 diff6 = (foil2_numpy[part][:,1] - foil1_numpy[part][:,1])**2
383
384
385 ## Now that we have all the differences, sum the arrays and then sum the sums to
      obtain total difference.
386 diff_total = (diff1.sum() + diff2.sum() + diff3.sum() + diff4.sum() + diff5.sum() +
      diff6.sum())
387 s = "Square distance = {}".format(diff_total)
388 print(s)
389 f = open("Sq_diff_out.dat", "w")
390 wr = np.array2string(diff_total)
391 f.write(wr)
392 f.close()
393
394 ### Finally, stitch the new coordinates together to prepare for post processing
395
396
397 foil1_post_process = np.vstack((foil1_numpy['suction_TE'], foil1_numpy['suction_mid']
      ], foil1_numpy['suction_LE'], foil1_numpy['pressure_LE'], foil1_numpy['
      pressure_mid'], foil1_numpy['pressure_TE']))
398 foil2_post_process = np.vstack((foil2_numpy['suction_TE'], foil2_numpy['suction_mid']
      ], foil2_numpy['suction_LE'], foil2_numpy['pressure_LE'], foil2_numpy['
      pressure_mid'], foil2_numpy['pressure_TE']))
399
400 ### Function to Plot and write to pdf
401
402 def plots_and_write_to_pdf():
403
404     """
405     This function creates the pdf to view and share results. The three page report
      contains:
406     Page 1: A plot of the plot digitized airfoil.
407     Page 2: A plot comparing the interpolated sections, highlighting the visual
      difference of the six parts
408     Page 3: A plot with plot digitized airfoil superimposed with Tblade3 airfoil
      to diagnose and improve upon further iterations. This plot also shows the square

```

```

distance.
"""
409
410
411 with PdfPages('blades_difference_calculator_iter006.pdf') as pdf:
412
413     ### Page 1: Plot digitized coordinates
414     ## Define page attributes
415     fig, ax1 = plt.subplots(2,10, figsize=(14,8.5), dpi=150)
416     grid1 = plt.GridSpec(2, 10, wspace=0.9, hspace=0.4)
417     fig.suptitle('Plot Digitized airfoil', fontsize=20)
418
419     ## Define plots – suction side
420     ## Suction side Trailing Edge:
421     plt.subplot(grid1[0, 7:])
422     part='suction_TE'
423     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
424 ][: ,0], foil1_numpy[part][:,1], '- ', color='orange')
425     plt.ylim([-0.01, 0.31])
426     # plt.gca().axes.get_yaxis().set_visible(False)
427     plt.title('Suction side:\nTrailing Edge')
428
429     ## Suction side Mid section:
430     plt.subplot(grid1[0, 3:7])
431     part='suction_mid'
432     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
433 ][: ,0], foil1_numpy[part][:,1], '- ', color='orange')
434     plt.gca().axes.get_yaxis().set_visible(False)
435     plt.ylim([-0.01, 0.31])
436     plt.xlim([0.2,0.81])
437     plt.title('Suction side:\nMid Part')
438
439     ## Suction side Leading Edge:
440     plt.subplot(grid1[0, :3])
441     part='suction_LE'
442     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
443 ][: ,0], foil1_numpy[part][:,1], '- ', color='orange')

```



```

441     plt.ylim([-0.01, 0.31])
442     plt.title('Suction side:\nLeading Edge')
443
444     ## Define plots – Pressure side
445     ## Suction side Leading Edge:
446     plt.subplot(grid1[1, :3])
447     part='pressure_LE'
448     plt.ylim([-0.1, 0.31])
449     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
]][:,0], foil1_numpy[part][:,1], '- ', color='orange')
450     plt.title('Pressure side:\nLeading Edge')
451
452     ## Suction side Mid section:
453     plt.subplot(grid1[1, 3:7])
454     part='pressure_mid'
455     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
]][:,0], foil1_numpy[part][:,1], '- ', color='orange')
456     plt.gca().axes.get_yaxis().set_visible(False)
457     plt.ylim([-0.1, 0.31])
458     plt.xlim([0.2,0.81])
459     plt.title('Pressure side:\nMid Part')
460
461     ## Pressure side Trailing Edge:
462     plt.subplot(grid1[1, 7:])
463     part='pressure_TE'
464     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', foil1_numpy[part
]][:,0], foil1_numpy[part][:,1], '- ', color='orange')
465     plt.gca().axes.get_yaxis().set_visible(False)
466     plt.ylim([-0.1, 0.31])
467     plt.title('Pressure side:\nTrailing Edge')
468     pdf.savefig()
469
470
471     ### Page 2: Compare interpolated sections
472     ## Define page attributes
473     fig, ax2 = plt.subplots(2,10, figsize=(14,8.5), dpi=150)

```

```

474 grid2 = plt.GridSpec(2, 10, wspace=0.9, hspace=0.4)
475 fig.suptitle('Compare interpolated parts', fontsize=20)
476
477 ## Define plots – suction side
478 ## Suction side Trailing Edge:
479 plt.subplot(grid2[0, 7:])
480 part='suction_TE'
481 plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
482 plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
483 plt.ylim([-0.01, 0.31])
484 # plt.gca().axes.get_yaxis().set_visible(False)
485 plt.title('Suction side:\nTrailing Edge')
486
487 ## Suction side Mid section:
488 plt.subplot(grid2[0, 3:7])
489 part='suction_mid'
490 plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
491 plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
492 plt.gca().axes.get_yaxis().set_visible(False)
493 plt.ylim([-0.01, 0.31])
494 plt.xlim([0.2,0.81])
495 plt.title('Suction side:\nMid Part')
496
497 ## Suction side Leading Edge:
498 plt.subplot(grid2[0, :3])
499 part='suction_LE'
500 plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
501 plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
502 plt.ylim([-0.01, 0.31])
503 plt.title('Suction side:\nLeading Edge')
504
505 ## Define plots – Pressure side
506 ## Suction side Leading Edge:
507 plt.subplot(grid2[1, :3])
508 part='pressure_LE'
509 plt.ylim([-0.1, 0.31])

```

```

510     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
511     plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
512     plt.title('Pressure side:\nLeading Edge')
513
514     ## Suction side Mid section:
515     plt.subplot(grid2[1, 3:7])
516     part='pressure_mid'
517     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
518     plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
519     plt.gca().axes.get_yaxis().set_visible(False)
520     plt.ylim([-0.1, 0.31])
521     plt.xlim([0.2,0.81])
522     plt.title('Pressure side:\nMid Part')
523
524     ## Pressure side Trailing Edge:
525     plt.subplot(grid2[1, 7:])
526     part='pressure_TE'
527     plt.plot(foil1_numpy[part][:,0], foil1_numpy[part][:,1], 'o', color='orange')
528     plt.plot(foil2_numpy[part][:,0], foil2_numpy[part][:,1], '.', color='blue')
529     plt.gca().axes.get_yaxis().set_visible(False)
530     plt.ylim([-0.1, 0.31])
531     plt.title('Pressure side:\nTrailing Edge')
532     pdf.savefig()
533
534     ### Page 3: Compare two airfoils
535     plt.figure(figsize=[14, 8.5], dpi=150)
536     plt.plot(test_foil1[:,0], test_foil1[:,1], 'o', color='orange')
537     plt.plot(test_foil2[:,0], test_foil2[:,1], '.', test_foil2[:,0], test_foil2
538    [:,1], '-.', color='blue')
539
539     plt.text(0.7,0.4,s)
540     plt.ylim([-0.51,0.51])
541     plt.xlim([-0.01,1.01])
542     plt.legend(['Target Airfoil', 'Tblade3 Airfoil'],loc='upper left')
543     plt.title('Blade Comparison', fontsize=20)
544     plt.savefig('Airfoil_fit.png', dpi=150, transparent=False)

```

```

545     pdf.savefig()
546
547
548
549
550 ### Write to pdf only if argument "plot" is given
551
552
553 plots_and_write_to_pdf()
554
555 # if len(sys.argv) > 1:
556 #     if (sys.argv[1] == 'plot'):
557 #         plots_and_write_to_pdf()
558 #         print("Saved figures to pdf.")

```

C.3 Blade Reverse Engineering - OpenMDAO script

This code carries out the optimization process using OpenMDAO as mentioned in section 2.2 and writes optimized values to 3dbgbinput and spancontrolinputs file.

```

1 # -*- coding: utf-8 -*-
2 """
3
4 Use the solution from the first run to do second round of optimizaitons. SO that the
5 cur values and LE edge values move.
6 Step size of 1e-12 did not work. Moving to step size of 1e-8. Was too fine for the
7 optimizer. Moving on to Step size 1e-6. This bought down the difference of 20
8 percent t_max down to 1e-5 instead of the usual 1e-1. MOving this to version 003.
9 Also experimenting with 1e-4 step size: Nope. It did not go well and stopped until 1
10 e-3.
11 1e-6 Yeyy!
12 1e-5:
13
14 Figure out the right step size by running single variables optimization for each
15 variables. Start with t_max. FINished all the variables.

```

```

11 Figure out the optimal step sizes for each variable by running single variable
    optimization.
12
13
14
15 """
16
17
18 import openmdao.api as om
19 import numpy as np
20
21
22 from openmdao.utils.file_wrap import InputFileGenerator
23 from openmdao.utils.file_wrap import FileParser
24
25 writeParser = InputFileGenerator()
26 readParser = FileParser()
27
28 # Next line makes sure that the numpy arrays all carry values of 16 decimal values
    instead of truncating at the usual 8.
29 ## https://openmdao.org/newdocs/versions/latest/other\_useful\_docs/file\_wrap.html
30 ## https://stackoverflow.com/questions/12956333/printing-numpy-float64-with-full-precision
31 ## https://numpy.org/doc/stable/reference/generated/numpy.set\_printoptions.html
32
33 # np.set_printoptions(precision=16)
34
35 class BladeDesignOptimizerMDAO(om.ExternalCodeComp):
36
37     def setup(self):
38
39         #link inputs
40         self.add_input('in_beta')
41         self.add_input('out_beta')
42         self.add_input('cur1')
43         self.add_input('cur2')

```

```

44     self.add_input('cur3')
45     self.add_input('cur4')
46     self.add_input('cur5')
47     self.add_input('cur6')
48     self.add_input('cur7')
49     self.add_input('LE_radius')
50     self.add_input('u_max')
51     self.add_input('t_max')
52     self.add_input('t_TE')
53
54
55     #link outputs
56     self.add_output('Sq_diff')
57
58     #setup filenames
59     self.tbladeinputfilebase = '3dbgbinput.1.base'
60     self.spancontrolfilebase = 'spancontrolinputs.1.base'
61
62     self.tbladeinputfile = '3dbgbinput.1.dat'
63     self.spancontrolfile = 'spancontrolinputs.1.dat'
64
65
66     self.Sq_diffoutfile = 'Sq_diff_out.dat'
67
68     self.options['external_input_files'] = [self.tbladeinputfile, self.
spancontrolfile]
69     self.options['external_output_files'] = [self.Sq_diffoutfile]
70
71     #setup run command
72     self.options['command'] = ["bash", "run_least_squares_002.sh"]
73
74     # self.timeout = 10
75     step_size_var = 1e-03 #-8
76     #have openmdao calculate partialerivs
77     self.declare_partials(of='*', wrt='in_beta', method='fd', step=step_size_var
)

```

```

78     self.declare_partials(of='*', wrt='out_beta', method='fd', step=
step_size_var)
79     self.declare_partials(of='*', wrt='cur1', method='fd', step=step_size_var)
80     self.declare_partials(of='*', wrt='cur2', method='fd', step=step_size_var)
81     # self.declare_partials(of='*', wrt='cur3', method='fd', step=1e-08)
82     self.declare_partials(of='*', wrt='cur4', method='fd', step=step_size_var)
83     self.declare_partials(of='*', wrt='cur5', method='fd', step=step_size_var)
84     self.declare_partials(of='*', wrt='cur6', method='fd', step=step_size_var)
85     self.declare_partials(of='*', wrt='cur7', method='fd', step=step_size_var)
86     self.declare_partials(of='*', wrt='LE_radius', method='fd', step=
step_size_var)
87     self.declare_partials(of='*', wrt='u_max', method='fd', step=1e-04)
88     self.declare_partials(of='*', wrt='t_max', method='fd', step=1e-04)
89     self.declare_partials(of='*', wrt='t_TE', method='fd', step=1e-05)
90
91
92     def compute(self, inputs, outputs):
93
94
95         in_beta = [float(inputs['in_beta'][0].astype(str))] # This code converts
numpy output to 16 digit precision instead of the usual 9.
96         out_beta = [float(inputs['out_beta'][0].astype(str))]
97         cur1 = [float(inputs['cur1'][0].astype(str))]
98         cur2 = [float(inputs['cur2'][0].astype(str))]
99         # cur3 = inputs['cur3']
100        cur4 = [float(inputs['cur4'][0].astype(str))]
101        cur5 = [float(inputs['cur5'][0].astype(str))]
102        cur6 = [float(inputs['cur6'][0].astype(str))]
103        cur7 = [float(inputs['cur7'][0].astype(str))]
104        LE_radius = [float(inputs['LE_radius'][0].astype(str))]
105        u_max = [float(inputs['u_max'][0].astype(str))]
106        t_max = [float(inputs['t_max'][0].astype(str))]
107        t_TE = [float(inputs['t_TE'][0].astype(str))]
108
109
110

```

```

111     #write output files
112
113     #Tblade file
114     writeParser.set_template_file(self.tbladeinputfilebase)
115     writeParser.set_generated_file(self.tbladeinputfile)
116     writeParser.reset_anchor()
117     writeParser.mark_anchor("Sectionwise")
118     writeParser.transfer_var(in_beta[0], 2, 2)
119     writeParser.transfer_var(out_beta[0], 2, 3)
120     writeParser.generate()
121
122
123
124     #spancontrol file
125     writeParser.set_template_file(self.spancontrolfilebase)
126     writeParser.set_generated_file(self.spancontrolfile)
127     writeParser.reset_anchor()
128     writeParser.mark_anchor("Span control points, Chord & curv")
129     writeParser.transfer_var("0.00", 3, 1)
130     writeParser.transfer_var("0.15", 3, 2)
131     writeParser.transfer_var("0.25", 3, 3)
132     writeParser.transfer_var("0.50", 3, 4)
133     writeParser.transfer_var("0.75", 3, 5)
134     writeParser.transfer_var("0.95", 3, 6)
135     writeParser.transfer_var(cur1[0], 3, 7)
136     writeParser.transfer_var(cur2[0], 3, 8)
137     writeParser.transfer_var("2.31", 3, 9)
138     writeParser.transfer_var(cur4[0], 3, 10)
139     writeParser.transfer_var("{}\t{}\t{}".format(cur5[0], cur6[0], cur7[0]), 3,
11)
140     # Move to second table
141     writeParser.reset_anchor()
142     writeParser.mark_anchor("Span control points, Chord & thick")
143     writeParser.transfer_var("0.00\t{}".format(LE_radius[0]), 3, 1)
144     writeParser.transfer_var(u_max[0], 3, 2)
145     writeParser.transfer_var(t_max[0], 3, 3)

```



```

146     writeParser.transfer_var(t_TE[0], 3, 4)
147     writeParser.generate()
148
149
150     #execute
151     super(BladeDesignOptimizerMDAO, self).compute(inputs, outputs)
152
153     #Parse:
154     with open(self.Sq_diffoutfile, 'r') as output_file:
155         Sq_diff = float(output_file.read())
156
157     print("in_beta=", in_beta)
158     print("out_beta=", out_beta)
159     print("cur1=", cur1)
160     print("cur2=", cur2)
161     # print("cur3=", cur3)
162     print("cur4=", cur4)
163     print("cur5=", cur5)
164     print("cur6=", cur6)
165     print("cur7=", cur7)
166     print("LE_radius=", LE_radius)
167     print("u_max=", u_max)
168     print("t_max=", t_max)
169     print("t_TE=", t_TE)
170     print("Sq_diff=", Sq_diff)
171     print("End iteration.\n")
172
173     outputs['Sq_diff'] = Sq_diff
174
175
176
177 if __name__ == "__main__":
178     prob = om.Problem()
179
180     model = prob.model
181

```

```

182     indeps = prob.model.add_subsystem('indeps', om.IndepVarComp())
183
184
185     indeps.add_output('in_beta', 42.12)
186     indeps.add_output('out_beta', 0.0)
187     indeps.add_output('cur1', 1.909)
188     indeps.add_output('cur2', 3.6695)
189     # indeps.add_output('cur3', 2.31)
190     indeps.add_output('cur4', 1.458)
191     indeps.add_output('cur5', 0.80)
192     indeps.add_output('cur6', 0.82)
193     indeps.add_output('cur7', 0.81)
194     indeps.add_output('LE_radius', 2.5)
195     indeps.add_output('u_max', 0.55)
196     indeps.add_output('t_max', 0.1146)
197     indeps.add_output('t_TE', 0.01548)
198
199
200
201     model.add_subsystem('runblade', BladeDesignOptimizerMDAO())
202
203     prob.driver = om.ScipyOptimizeDriver()
204     prob.driver.options['optimizer'] = 'SLSQP'
205     prob.driver.options['maxiter'] = 200
206
207
208
209     prob.model.connect('indeps.in_beta', 'runblade.in_beta')
210     prob.model.connect('indeps.out_beta', 'runblade.out_beta')
211     prob.model.connect('indeps.cur1', 'runblade.cur1')
212     prob.model.connect('indeps.cur2', 'runblade.cur2')
213     # prob.model.connect('indeps.cur3', 'runblade.cur3')
214     prob.model.connect('indeps.cur4', 'runblade.cur4')
215     prob.model.connect('indeps.cur5', 'runblade.cur5')
216     prob.model.connect('indeps.cur6', 'runblade.cur6')
217     prob.model.connect('indeps.cur7', 'runblade.cur7')

```

```

218 prob.model.connect('indeps.LE_radius', 'runblade.LE_radius')
219 prob.model.connect('indeps.u_max', 'runblade.u_max')
220 prob.model.connect('indeps.t_max', 'runblade.t_max')
221 prob.model.connect('indeps.t_TE', 'runblade.t_TE')
222
223
224 prob.model.add_design_var('indeps.in_beta', lower=35.10, upper=55.50)
225 prob.model.add_design_var('indeps.out_beta', lower=-30.00, upper=7.45)
226 prob.model.add_design_var('indeps.cur1', lower=1.7100, upper=2.10)
227 prob.model.add_design_var('indeps.cur2', lower=3.0695, upper=4.0695)
228 # prob.model.add_design_var('indeps.cur3', lower=2.01, upper=2.91)
229 prob.model.add_design_var('indeps.cur4', lower=0.615, upper=1.615)
230 prob.model.add_design_var('indeps.cur5', lower=0.50, upper=1.50)
231 prob.model.add_design_var('indeps.cur6', lower=0.50, upper=1.50)
232 prob.model.add_design_var('indeps.cur7', lower=0.50, upper=1.50)
233 prob.model.add_design_var('indeps.LE_radius', lower=2.00, upper=4.0)
234 prob.model.add_design_var('indeps.u_max', lower=0.4, upper=0.7)
235 prob.model.add_design_var('indeps.t_max', lower=0.08, upper=0.2)
236 prob.model.add_design_var('indeps.t_TE', lower=0.001, upper=0.1)
237
238
239 prob.model.add_objective('runblade.Sq_diff')
240
241 prob.driver.options['tol'] = 1e-10
242
243 prob.setup()
244
245 # prob.run_model()
246 prob.run_driver()
247
248 print("Sq_diff=", prob['runblade.Sq_diff'])

```

C.4 Controller script

This bash shell script controls the operations to ensure logs are saved from each run to later diagnose optimization runs and plot progression of parameters.

```

1 #!/bin/bash
2
3
4 #clean:
5 rm tblade.log spancontrolinputs.1.log T-Blade3-run.log square_distance.log uvblade
   .1.1.GE-E3-Fan-rotor # Airfoil-fit.png
6
7 tblade3 3dbgbinput.1.dat dev > tblade.log
8 python3 'blades_difference_calculator_iter007.py' > square_distance.log
9
10 #gio open *iter012.pdf

```

C.5 Results post-processing file

Takes log files from controller script and creates tables and line plots with respect to iterations.

```

1 # -*- coding: utf-8 -*-
2 """
3 This post processor code takes in output from our optimization runs and produces two
   plots:
4     1. Line plot of objective function vs iterations
5     2. Two pages with line plots of 12 input variables v/s iterations
6     3. Added the capability to plot by passing filename through terminal with syntax:
7         python3 optimizatin_post_processor_002.py
           optimization_12_variables_Nelder-Mead-001-001.txt
8     4. Add in capability to plot numbers in the scientific form because they appear
           below 1e-5.
9     5. Add in a table in page 1 to show a table of the parameters.
10    5. 001. Fixed issue with variable writing where iniitla number is omitted.
11
12 """
13
14 import os
15 import sys
16 import matplotlib.pyplot as plt
17 from matplotlib.backends.backend_pdf import PdfPages
18

```

```

19 ### Functions to perform operations
20
21 #import optimization output
22
23 # print(len(sys.argv)) # Prints the number of arguments available
24 # print(sys.argv[1]) # prints the name of file that we will plot
25
26 name_argument=sys.argv[1]
27 # name_argument="optimization_12_variables_Nelder_Mead_001_001.txt"
28 # name_argument="optimization_12_variables_SimpleGADriver.txt"
29 # name_argument="optimization_12_variables_SLSQP.txt"
30
31 # Determine the name of the main T-Blade3 input files
32 current_dir = os.getcwd()
33 files = os.listdir(current_dir)
34 for file in files:
35     if name_argument in file:
36         input_file = file.strip()
37         break
38
39 # Read main T-Blade3 input file and store the input in a list
40 f = open(input_file, 'r')
41 lines = f.readlines()
42 f.close()
43
44 # Find the index number of the final "End Iteration" String:
45 line_index = [ii for ii, xx in enumerate(lines) if xx == "End iteration.\n"]
46
47 # Delete the excess data and calculate number of iterations
48 lines = lines[line_index[0]-13:line_index[-1]+1]
49 iterations = [ii+1 for ii, xx in enumerate(line_index)]
50
51
52 ### Once we read the file, we next collect variable values in a dictionary.
53
54 # Collect values of variables:

```

```

55
56 def collect_values_of_variable(lines , variable_limit=7, variable_extent=3,
    variable_name="in_beta"):
57
58 values_of_variable = [xx for ii , xx in enumerate(lines) if xx[:variable_limit] ==
    variable_name]
59 if (variable_name=="Sq_diff"):
60     values_of_variable = [float(xx[variable_limit+variable_extent:]) for ii , xx in
    enumerate(values_of_variable)]
61 else:
62     values_of_variable = [float(xx[variable_limit+variable_extent:-2]) for ii , xx
    in enumerate(values_of_variable)]
63
64 return values_of_variable
65
66 def collect_variables_in_the_form_of_lists(line_index , lines):
67
68
69 in_beta = collect_values_of_variable(lines , variable_name="in_beta" ,
    variable_limit=7)
70 out_beta = collect_values_of_variable(lines , variable_name="out_beta" ,
    variable_limit=8)
71 cur1 = collect_values_of_variable(lines , variable_name="cur1" , variable_limit=4)
72 cur2 = collect_values_of_variable(lines , variable_name="cur2" , variable_limit=4)
73 cur4 = collect_values_of_variable(lines , variable_name="cur4" , variable_limit=4)
74 cur5 = collect_values_of_variable(lines , variable_name="cur5" , variable_limit=4)
75 cur6 = collect_values_of_variable(lines , variable_name="cur6" , variable_limit=4)
76 cur7 = collect_values_of_variable(lines , variable_name="cur7" , variable_limit=4)
77 LE_radius = collect_values_of_variable(lines , variable_name="LE_radius" ,
    variable_limit=9)
78 u_max = collect_values_of_variable(lines , variable_name="u_max" , variable_limit
    =5)
79 t_max = collect_values_of_variable(lines , variable_name="t_max" , variable_limit
    =5)
80 t_TE = collect_values_of_variable(lines , variable_name="t_TE" , variable_limit=4)

```

```

81 sq_diff = collect_values_of_variable(lines, variable_name="Sq_diff",
   variable_limit=7, variable_extent=2)
82
83 return { 'sq_diff': sq_diff, 'in_beta': in_beta, 'out_beta': out_beta, 'cur1':
   cur1, 'cur2': cur2, 'cur4': cur4, 'cur5': cur5, 'cur6': cur6, 'cur7': cur7, '
   LE_radius': LE_radius, 'u_max': u_max, 't_max': t_max, 't_TE': t_TE}
84
85 parameters_to_plot = collect_variables_in_the_form_of_lists(line_index, lines)
86
87
88 ##% Next, we plot the variables.
89
90 def plot_variable(iterations, variable_name, iterable):
91     plt.figure(figsize=(7,5), dpi=150)
92     plt.plot(iterations, variable_name[iterable], '-', iterations, variable_name[
   iterable], '.', color='blue')
93     if iterable=="sq_diff":
94         plt.yscale("log")
95         plt.title("Final Objective Function value: {}".format(variable_name['sq_diff'
   ][-1]))
96         plt.ylim(1e-6, 1e2)
97         plt.ylabel("Objective value on log scale")
98         plt.xlabel("Number of Iterations")
99     else:
100         plt.ylabel("value")
101         plt.xlabel("Number of Iterations")
102         plt.title("{}".format(iterable))
103
104
105 # for ii in parameters_to_plot:
106 #     # print(ii)
107 #     plot_variable(iterations, parameters_to_plot, ii)
108
109 def plot_to_pdf(iterations, parameters_to_plot, variable_name):
110
111     if variable_name=="sq_diff":

```

```

112     # plt.plot(iterations , parameters_to_plot[variable_name], '-', color='blue')
113     plt.plot(iterations , parameters_to_plot[variable_name], '.', color='blue')
114     plt.yscale("log")
115     plt.title("Final Objective Function value using {} method: {}".format(
name_argument[26:-4], parameters_to_plot['sq_diff'][-1]))
116     plt.ylim(1e-6, 1e2)
117     plt.ylabel("Objective value on log scale")
118     plt.xlabel("Number of Iterations")
119     else:
120     # plt.plot(iterations , parameters_to_plot[variable_name], '-', color='orange')
121     plt.plot(iterations , parameters_to_plot[variable_name], '.', color='orange')
122     plt.title("Final {} value: {}".format(variable_name , parameters_to_plot[
variable_name][-1]), y=1.11, fontsize=13)
123
124 rows_to_write = [['', 'in_beta', 'out_beta', 'cur1', 'cur2', 'cur4', 'cur5', 'cur6',
'cur7', 'LE_radius', 'u_max', 't_max', 't_TE'], [parameters_to_plot[xx][0] for
xx in parameters_to_plot], [parameters_to_plot[xx][-1] for xx in
parameters_to_plot]]#, ['Known target Blade values', '42.12', '0.0', '1.909',
'3.6695', '1.215', '0.8', '0.82', '0.81', '2.5', '0.55', '0.0955', '0.01548']]
125
126 rows_to_write[1][0] = 'Initial input values'
127 rows_to_write[2][0] = 'Final input values'
128
129 rows_to_write1 = list(zip(*rows_to_write))
130
131
132 def plots_and_write_to_pdf():
133
134     """
135     This function creates the pdf to view and share results. The three page report
contains:
136     Page 1: A plot of the plot digitized airfoil.
137     Page 2: A plot comparing the interpolated sections, highlighting the visual
difference of the six parts
138     Page 3: A plot with plot digitized airfoil superimposed with Tblade3 airfoil
to diagnose and improve upon further iterations. This plot also shows the square

```



```

distance.
139 """
140
141
142 with PdfPages('{ }.pdf'.format(name_argument)) as pdf:
143
144     ### Page 0: Add in parameter info from initial and final properties:
145     fig, ax0 = plt.subplots(figsize=(8.5, 11), dpi=150)
146     # hide axes
147     ax0.axis('off')
148     ax0.axis('tight')
149     # grid0 = plt.GridSpec(12, 2, wspace=0.3, hspace=10.2)
150     fig.suptitle('Variables for Optimization', fontsize=20)
151     # fig.text(0.5,0.5," Initial t_max={}".format(parameters_to_plot['t_max'][0]),
152             transform=fig.transFigure, size=24, ha="center")
153     # fig.text(0.5,0.3," Final t_max={}".format(parameters_to_plot['t_max'][-1]),
154             transform=fig.transFigure, size=24, ha="center")
155     # fig.text(0.5,0.2," Target t_max=0.0955", transform=fig.transFigure, size=24, ha
156             ="center")
157
158     the_table = ax0.table(cellText=rows_to_write1, colWidths=[0.28]*4, loc='upper
159             center')
160     the_table.set_fontsize(54)
161     pdf.savefig()
162
163
164
165     ### Page 1: Plot digitized coordinates
166     ## Define page attributes
167     fig, ax1 = plt.subplots(12, 2, figsize=(8.5, 11), dpi=150)
168     grid1 = plt.GridSpec(12, 2, wspace=0.3, hspace=10.2)
169     fig.suptitle('Variables for Optimization', fontsize=20)
170
171     using_SLSQP=False
172
173     ## Define plots – First 6 variables
174     ## in_beta:
175     plt.subplot(grid1[:3, 0])

```

```

170 plt.gca().axes.get_xaxis().set_visible(False)
171 plot_to_pdf(iterations, parameters_to_plot, variable_name='in_beta')
172
173 ## out_beta:
174 plt.subplot(grid1[3:6, 0])
175 plt.gca().axes.get_xaxis().set_visible(False)
176 plot_to_pdf(iterations, parameters_to_plot, variable_name='out_beta')
177
178 ## LE_radius:
179 plt.subplot(grid1[6:9, 0])
180 plt.gca().axes.get_xaxis().set_visible(False)
181 plot_to_pdf(iterations, parameters_to_plot, variable_name='LE_radius')
182
183 plt.subplot(grid1[9:, 0])
184 plt.xlabel("Number of Iterations")
185 plot_to_pdf(iterations, parameters_to_plot, variable_name='u_max')
186
187 ## u_max:
188 plt.subplot(grid1[:3, 1])
189 plt.gca().axes.get_xaxis().set_visible(False)
190 plot_to_pdf(iterations, parameters_to_plot, variable_name='t_max')
191
192 ## t_max:
193 plt.subplot(grid1[3:6, 1])
194 plt.gca().axes.get_xaxis().set_visible(False)
195 plot_to_pdf(iterations, parameters_to_plot, variable_name='t_TE')
196
197 ## t_max:
198 plt.subplot(grid1[6:9, 1])
199 plt.gca().axes.get_xaxis().set_visible(False)
200 if (using_SLSQP==True):
201     plt.ylim([parameters_to_plot['cur1'][0]-1e-2, parameters_to_plot['cur1'][0]+1e
202             -2])
203     plot_to_pdf(iterations, parameters_to_plot, variable_name='cur1')
204
205 ## t_TE:

```

```

205 plt.subplot(grid1[9:, 1])
206 plt.xlabel("Number of Iterations")
207 if (using_SLSQP==True):
208     plt.ylim([parameters_to_plot['cur2'][0]-1e-2, parameters_to_plot['cur2'][0]+1e
209               -2])
210 plot_to_pdf(iterations, parameters_to_plot, variable_name='cur2')
211 pdf.savefig()
212 plt.close()
213
214 ### Page 2: Plot digitized coordinates
215 ## Define page attributes
216 fig, ax1 = plt.subplots(12, 2, figsize=(8.5, 11), dpi=150)
217 grid1 = plt.GridSpec(12, 2, wspace=0.3, hspace=10.2)
218 fig.suptitle('Variables and Objective Function plots', fontsize=20)
219
220 ## Define plots – First 6 variables
221 ## in_beta:
222 plt.subplot(grid1[:3, 0])
223 if (using_SLSQP==True):
224     plt.ylim([parameters_to_plot['cur4'][0]-1e-3, parameters_to_plot['cur4'][0]+1e
225               -3])
226 plt.gca().axes.get_xaxis().set_visible(False)
227
228 plot_to_pdf(iterations, parameters_to_plot, variable_name='cur4')
229
230 ## out_beta:
231 plt.subplot(grid1[3:6, 0])
232 if (using_SLSQP==True):
233     plt.ylim([parameters_to_plot['cur5'][0]-1e-3, parameters_to_plot['cur5'][0]+1e
234               -3])
235 plt.xlabel("Number of Iterations")
236 plot_to_pdf(iterations, parameters_to_plot, variable_name='cur5')
237
238 ## LE_radius:
239 plt.subplot(grid1[:3, 1])
240 if (using_SLSQP==True):

```

```

238     plt.ylim([parameters_to_plot['cur6'][0]-1e-3, parameters_to_plot['cur6'][0]+1e
-3])
239 plt.gca().axes.get_xaxis().set_visible(False)
240 plot_to_pdf(iterations, parameters_to_plot, variable_name='cur6')
241
242 plt.subplot(grid1[3:6, 1])
243 if (using_SLSQP==True):
244     plt.ylim([parameters_to_plot['cur7'][0]-1e-3, parameters_to_plot['cur7'][0]+1e
-3])
245 plt.xlabel("Number of Iterations")
246 plot_to_pdf(iterations, parameters_to_plot, variable_name='cur7')
247
248 ## sq_diff:
249 plt.subplot(grid1[6:, :])
250 plot_to_pdf(iterations, parameters_to_plot, variable_name='sq_diff')
251 pdf.savefig()
252 plt.close()

```

Appendix D

Codes for FINE/Turbo input files

D.1 Input profile generator

This code generates input file for FINE/Turbo to ensure that the inflow is parallel to the hub.

```
1 import numpy as np
2 import math
3
4
5 col_31 = np.asarray([0.0]*18)
6 col = list(map(str, col_31))
7 col = [ii[:-2] for ii in col]
8
9 def profile_plot(physical_parameter, radius):
10
11     physical_parameter = physical_parameter.copy()
12     col_3 = np.asarray([0]*len(physical_parameter))
13     col_3 = list(map(int, col_3))
14     #map(int, col_3)
15
16
17     physical_parameter_plot = np.stack((radius, physical_parameter, col_3), axis=1)
18     physical_parameter_plot = np.round(physical_parameter_plot, 6)
19     physical_parameter_plot1 = [" ".join(item) for item in physical_parameter_plot.
20     astype(str)]
```

```

21     physical_parameter_export = line1.copy()
22     physical_parameter_export.append(line2[0])
23     [physical_parameter_export.append(ii) for ii in physical_parameter_plot1]
24     physical_parameter_export = [ii[:-2] for ii in physical_parameter_export]
25     physical_parameter_export[0] = line1[0]
26     physical_parameter_export[1] = line2[0]
27     return physical_parameter_export
28
29 def generate_FINE_Turbo_input_file(file_path , physical_parameter_export):
30
31
32
33     with open(str(file_path), "w") as outfile:
34         for ii in physical_parameter_export:
35             outfile.write(ii)
36             outfile.write("\n")
37
38     # Essential to replace Windows file ending with Linux ones:
39
40     # replacement strings
41     WINDOWS_LINE_ENDING = b'\r\n'
42     UNIX_LINE_ENDING = b'\n'
43
44     with open(file_path , 'rb') as open_file:
45         content = open_file.read()
46
47     content = content.replace(WINDOWS_LINE_ENDING, UNIX_LINE_ENDING)
48
49     with open(file_path , 'wb') as open_file:
50         open_file.write(content)
51
52
53
54 line1 = ['FINE profile file']
55 line2 = ['4 18 ']
56

```

```

57 map(str , line1)
58 map(str , line2)
59
60
61 #Hub and shroud coordinates: import these from .mf file
62 hub_radius = 0.18884 # default = 0.23640
63 shroud_radius = 1.0517 # default = 1.0517
64
65 delta_x = (-0.152382135 - -0.284952849)
66 delta_y = (0.272952139 - 0.188841641)
67 phi_hub = math.degrees(math.atan(delta_y / delta_x))
68 slope = delta_y/delta_x
69 phi_hub = 29.0000
70
71 phi = np.linspace(0, phi_hub , 18)
72 radius = np.linspace(shroud_radius , hub_radius , 18)
73
74 # Vz_by_Vm = np.cos(np.radians(phi))
75 # Vr_by_Vm = np.sin(np.radians(phi))
76 arctan_Vr_by_Vz = np.radians(phi)
77
78 # relative or absolute file path, e.g.:
79 # file_path = "Vr_by_Vm_generated.p"
80 # Vr_by_Vm_export = profile_plot(Vr_by_Vm, radius)
81 # generate_FINE_Turbo_input_file(file_path , Vr_by_Vm_export)
82
83
84 # relative or absolute file path, e.g.:
85 # file_path = "Vz_by_Vm_generated.p"
86 # Vz_by_Vm_export = profile_plot(Vz_by_Vm, radius)
87 # generate_FINE_Turbo_input_file(file_path , Vz_by_Vm_export)
88
89
90
91 # tan inverse of Vr_by_Vz in radians:
92 file_path = "arctan_Vr_by_Vz_generated_04232021_0018.p"

```

```

93 arctan_Vr_by_Vz_export = profile_plot(arctan_Vr_by_Vz, radius)
94 generate_FINE_Turbo_input_file(file_path, arctan_Vr_by_Vz_export)

```

D.2 Profile plots generator

This code plots profile plots of span vs dimension from FINE/Turbo data.

```

1 import matplotlib.pyplot as plt
2 import pandas as pd
3 from matplotlib.backends.backend_pdf import PdfPages
4
5
6 stations = ['rotor_inlet.csv']
7 values = ('P_total (kPa)', 'Abs_Angle (deg)', 'Rel_Angle (deg)', 'rv_theta (m^2/sec)', '
      Phi (deg)', 'P_static (kPa)', 'Vr (m/s)', 'Vt (m/s)', 'Vz (m/s)', 'Entropy ', 'TT (K)
      ', 'M_abs', 'M_rel', 'beta_z (deg)')
8
9
10 with PdfPages('profileplots_rotor_inlet_E3_GE_wo_pss.pdf') as pdf:
11
12     for stname in stations:
13         read_begin = pd.read_csv(stname)
14         for ii in range(14):
15             plt.figure()
16             plt.plot(read_begin[values[ii]], read_begin['Span'])
17             plt.title('At {}'.format(stname))
18             plt.xlabel('{}{}'.format(values[ii]))
19             plt.ylabel('Span')
20             pdf.savefig() # saves the current figure into a pdf page
21             plt.close()

```


Appendix E

Input files for cases

E.1 Traditional manual parameter specified Geometry's Tblade3 input files

E.1.1 3dbgbininput.1.dat file

```
1 Input parameters (version 1.31_TEST)
2 GE_E3_Fan_rotor
3 Blade row #:
4         1
5 Number of blades in this row:
6         32
7 Blade Scaling factor (mm):
8     10.000000000000000
9 Number of streamlines:
10        18
11 Angles in the input file (0=Beta_z (default),1=Beta_r):
12         0 inci_dev_spline
13 Airfoil camber defined by curvature control (0=no,1=yes ;spanwise_spline=
14     spancontrolinputs file):
15         1 spanwise_spline
16 Airfoil Thickness distribution (0=Wennerstrom,1=Spline,2=Spline + sharp TE):
17         5
18 Airfoil Thickness multiplier (0=no,1=yes):
```

```

18         0
19 Airfoil LE defined by spline (0=no,1=yes):
20         0
21 Non-dimensional Actual chord (0=no,1=yes,2=spline):
22         2
23 True lean and sweep (0=no,1=yes):
24         0
25 Clustering control (0=uniform,1=sine,2=exponential,3=hyperbolic,4=elliptical):
26         4 15.0
27 Sectionwise properties:
28 J      in_Beta      out_Beta      mrel_in      chord      t/c_max
          Incidence      Deviation      Sec. Flow Angle
29 1      42.12      0.00      0.00000000      0.00000000      0.000000
          3.50      12.63      0.00000000
30 2      43.20      11.90      0.00000000      0.00000000
          0.000000      5.25      9.58      0.00000000
31 3      43.79      17.92      0.00000000      0.00000000
          0.000000      4.80      7.99      0.00000000
32 4      44.38      20.62      0.00000000      0.00000000
          0.000000      4.72      7.48      0.00000000
33 5      45.50      25.61      0.00000000      0.00000000
          0.000000      4.65      6.86      0.00000000
34 6      46.53      29.62      0.00000000      0.00000000
          0.000000      4.68      6.46      0.00000000
35 7      47.22      30.91      0.00000000      0.00000000
          0.000000      4.76      6.27      0.00000000
36 8      48.66      32.40      0.00000000      0.00000000
          0.000000      5.00      5.90      0.00000000
37 9      49.83      34.45      0.00000000      0.00000000
          0.000000      5.55      5.45      0.00000000
38 10     50.55      35.72      0.00000000      0.00000000
          0.000000      5.65      5.26      0.00000000
39 11     51.41      37.30      0.00000000      0.00000000
          0.000000      5.68      5.05      0.00000000
40 12     51.89      38.13      0.00000000      0.00000000
          0.000000      5.73      4.90      0.00000000

```

41	13	53.09	40.20	0.00000000	0.00000000
		0.000000	5.70	4.56	0.00000000
42	14	54.86	43.56	0.00000000	0.00000000
		0.000000	5.66	3.93	0.00000000
43	15	56.63	46.71	0.00000000	0.00000000
		0.000000	5.50	3.43	0.00000000
44	16	58.56	49.69	0.00000000	0.00000000
		0.000000	4.95	3.22	0.00000000
45	17	61.00	52.81	0.00000000	0.00000000
		0.000000	4.66	2.96	0.00000000
46	18	63.27	55.32	0.00000000	0.00000000
		0.000000	5.00	2.48	0.00000000

47

48 LE / TE curve (x,r) definition :

49 Number of Curve points :

50 18

51	xLE	rLE	xTE	rTE
52	-1.270	36.068	17.789	47.884
53	-1.366	43.785	17.884	52.947
54	-1.429	49.488	17.981	56.958
55	-1.431	52.313	17.892	59.044
56	-1.422	57.049	17.85	62.754
57	-1.441	60.613	17.8	65.725
58	-1.449	62.683	17.782	67.491
59	-1.42	66.362	17.783	70.588
60	-1.364	69.829	17.793	73.453
61	-1.306	71.824	17.767	75.088
62	-1.237	74.234	17.699	77.273
63	-1.213	75.639	17.657	78.412
64	-1.173	79.254	17.546	81.34
65	-0.988	84.922	17.35	85.915
66	-0.707	90.238	17.062	90.211
67	-0.347	95.26	16.674	94.355
68	0.050	100.11	16.305	98.424
69	0.467	105.167	15.981	102.995

70

```

71 # Airfoil type and Variable Radial Stacking information. #
72 # stack_u: % chord stack (0.00 to 100.00). #
73 # stack_v: % below or above meanline stack (-100.00 to +100.00). #
74 # Use +200 for stacking on airfoil area centroid. #
75 Variable Radial stacking (0=no,1=yes):
76     0
77 J   type |stk_u |stk_v |umxthk |lethk |tethk | Jcells (Grid:4n+1) | eta_ofst(<=10)[
      thkc/Jmax] |BGgrid(0=no,1=yes) |
78 1   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
79 2   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
80 3   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
81 4   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
82 5   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
83 6   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
84 7   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
85 8   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
86 9   sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
87 10  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
88 11  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
89 12  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
90 13  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
91 14  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
92 15  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
93 16  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
94 17  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
95 18  sect1 25.00  0.00  0.30  0.02  0.02  15 10  0
96
97 Control table for blending section variable:
98     4           0           0
99     span                bf1        bf2
100    0.000000000000000000    1         0
101    0.333333333333333331    1         0
102    0.666666666666666663    1         0
103    1.000000000000000000    1         0
104
105 Stacking axis location (200=centroid):

```

```

106         55000
107
108 Control points for sweep:
109         4
110         span                delta_m
111         0.0000000000000000    0.0000000000000000
112         0.2500000000000000    0.0000000000000000
113         0.5000000000000000    0.0000000000000000
114         1.0000000000000000    0.0000000000000000
115
116 Control points for lean:
117         4
118         span                delta_theta
119         0.0000000000000000    0.0000000000000000
120         0.2500000000000000    0.0000000000000000
121         0.5000000000000000    0.0000000000000000
122         1.0000000000000000    0.0000000000000000
123
124 Control points for in_beta*:
125         5
126         span                in_beta*
127         0.0000000000000000    0.0000000000000000
128         0.2500000000000000    0.0000000000000000
129         0.5000000000000000    0.0000000000000000
130         0.7500000000000000    0.0000000000000000
131         1.0000000000000000    0.0000000000000000
132
133 Control points for out_beta*:
134         5
135         span                out_beta*
136         0.0000000000000000    0.0000000000000000
137         0.2500000000000000    0.0000000000000000
138         0.5000000000000000    0.0000000000000000
139         0.7500000000000000    0.0000000000000000
140         1.0000000000000000    0.0000000000000000
141

```

```

142 Control points for chord_multiplier:
143         4
144         span                chord_multiplier
145         0.0000000000000000    0.0000000000000000
146         0.2500000000000000    0.0000000000000000
147         0.5000000000000000    0.0000000000000000
148         1.0000000000000000    0.0000000000000000

```

```

149
150 Control points for tm/c:
151         4
152         span                tm/c
153         0.0000000000000000    0.0000000000000000
154         0.2500000000000000    0.0000000000000000
155         0.5000000000000000    0.0000000000000000
156         1.0000000000000000    0.0000000000000000

```

```

157
158 Hub offset
159         0.0000000000000000
160 Tip offset
161         0.0000000000000000

```

```

162
163 Streamline Data
164 x_s      r_s
165 -28.495285    18.884164
166 -15.238214    27.295215
167 -9.472585     30.949586
168 -6.590009     32.77715
169 -1.27    36.068
170 1.35768    37.855728
171 5.446081    40.393893
172 9.534482    42.852843
173 14.20694    45.649056
174 17.789    47.884
175 19.492925    49.019945
176 25.425061    52.353179
177 31.961715    54.306013

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178	38.62798	55.772693
179	45.39551	56.603429
180	52.137207	55.696729
181	57.971122	52.232159
182	67.62676	43.577681
183	0.0	0.0
184	-28.495285	21.208355
185	-15.238214	29.619406
186	-9.472585	33.273777
187	-6.590009	35.101341
188	-1.27	38.068
189	1.35768	39.855728
190	5.446081	42.393893
191	9.534482	44.852843
192	14.20694	47.649056
193	17.789	49.884
194	19.492925	51.319945
195	25.425061	54.653179
196	31.961715	56.606013
197	38.62798	58.072693
198	45.39551	58.903429
199	52.137207	57.996729
200	57.971122	54.532159
201	67.62676	45.877681
202	0.0	0.0
203	-28.495285	28.808422
204	-15.238214	36.280124
205	-9.472585	39.526374
206	-6.590009	41.149834
207	-1.366	43.785
208	1.35768	45.339242
209	5.446081	47.534739
210	9.534482	48.452355
211	14.20694	50.936022
212	17.884	52.947
213	19.492925	54.248797

214	25.425061	57.275809
215	31.961715	59.049238
216	38.62798	60.381176
217	45.39551	61.135593
218	52.137207	60.31219
219	57.971122	57.165907
220	67.62676	49.306509
221	0.0	0.0
222	-28.495285	35.903042
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224	-9.472585	45.625189
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226	-1.429	49.488
227	1.35768	50.869692
228	5.446081	52.81195
229	9.534482	52.888389
230	14.20694	55.124451
231	17.981	56.958
232	19.492925	58.153522
233	25.425061	60.937941
234	31.961715	62.569241
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236	45.39551	64.488389
237	52.137207	63.730976
238	57.971122	60.836846
239	67.62676	53.607324
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249	14.20694	57.302727

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251	19.492925	60.184252
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254	38.62798	65.569566
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258	67.62676	55.844048
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264	-1.422	57.049
265	1.35768	58.201926
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267	9.534482	59.298575
268	14.20694	61.176842
269	17.85	62.754
270	19.492925	63.795952
271	25.425061	66.229816
272	31.961715	67.655738
273	38.62798	68.72668
274	45.39551	69.333267
275	52.137207	68.671212
276	57.971122	66.141449
277	67.62676	59.822115
278	0.0	0.0
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283	-1.441	60.613
284	1.35768	61.658094
285	5.446081	63.106353

286	9.534482	62.584404
287	14.20694	64.279266
288	17.8	65.725
289	19.492925	66.688233
290	25.425061	68.942404
291	31.961715	70.26305
292	38.62798	71.254924
293	45.39551	71.816727
294	52.137207	71.203551
295	57.971122	68.860562
296	67.62676	63.007785
297	0.0	0.0
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300	-9.472585	59.735984
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302	-1.449	62.683
303	1.35768	63.665464
304	5.446081	65.021806
305	9.534482	64.537542
306	14.20694	66.123387
307	17.782	67.491
308	19.492925	68.407441
309	25.425061	70.554801
310	31.961715	71.812869
311	38.62798	72.757745
312	45.39551	73.292927
313	52.137207	72.708806
314	57.971122	70.476837
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320	-6.590009	68.312587
321	-1.364	69.829

322	1.35768	70.595254
323	5.446081	71.634283
324	9.534482	71.131318
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326	17.793	73.453
327	19.492925	74.211473
328	25.425061	75.998238
329	31.961715	77.045046
330	38.62798	77.831253
331	45.39551	78.276565
332	52.137207	77.790532
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350	45.39551	81.469704
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365	19.492925	79.03908
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371	57.971122	80.471932
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379	1.35768	79.735091
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383	17.546	81.34
384	19.492925	81.8895
385	25.425061	83.199242
386	31.961715	83.966578
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388	45.39551	84.869311
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390	57.971122	83.15169
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403	19.492925	86.343282
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406	38.62798	88.436094
407	45.39551	88.693555
408	52.137207	88.41255
409	57.971122	87.338811
410	67.62676	84.656616
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422	19.492925	90.525456
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719 61.7430658    102.995
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729 0.0           0.0

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E.1.2 spancontrolinputs.1.dat file

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1 Casename:
2 GE_E3_Fan_rotor
3 Blade row#:
4 1
5 Span control points , Chord & curvature control points
6           5       7
7 Span      u2          u3      u4      u5      u6      cur1          cur2
           cur3          cur4          cur5          cur6 cur7
8 0.00      0.15      0.25      0.50      0.75      0.95      1.909      3.6695      2.31      1.215      0.80
           0.82      0.81
9 0.25      0.15      0.25      0.50      0.75      0.95      0.00      0.20          0.19      0.105      0.00
           0.00      0.00
10 0.50      0.15      0.25      0.50      0.75      0.95      0.1      0.20      0.30      0.393      -0.04      0.00
           0.00
11 0.75      0.15      0.25      0.50      0.75      0.95      0.00      0.10          0.10      0.105      0.00
           0.00      0.00
12 1.00      0.15      0.25      0.50      0.75      0.95      -0.001    -0.002      0.00      0.33      0.4      0.2
           0.1
13
14 Span control points , Chord & thickness control points
15           5       1
16 Span      LE_radius  u_max    t_max    t_TE

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```

17 0.00    2.5    0.55    0.0955  0.01548
18 0.25    3.0    0.41    0.0583  0.0153
19 0.50    3.0    0.43    0.0439  0.008415
20 0.75    3.0    0.48    0.0320   0.00364
21 1.00    3.0    0.60    0.0251  0.001

```

E.2 Reverse Engineered Geometry's Tblade3 input files

E.2.1 3dbginput.1.dat file

```

1 Input parameters (version 1.31_TEST)
2 GE_E3_Fan_rotor
3 Blade row #:
4         1
5 Number of blades in this row:
6         32
7 Blade Scaling factor (mm):
8         10.000000000000
9 Number of streamlines:
10        18
11 Angles in the input file (0=Beta_z (default),1=Beta_r):
12        0 inci_dev_spline
13 Airfoil camber defined by curvature control (0=no,1=yes ;spanwise_spline=
14        spancontrolinputs file):
15        1 spanwise_spline
16 Airfoil Thickness distribution (0=Wennerstrom,1=Spline,2=Spline + sharp TE):
17        5
18 Airfoil Thickness multiplier (0=no,1=yes):
19        0
20 Airfoil LE defined by spline (0=no,1=yes):
21        0
22 Non-dimensional Actual chord (0=no,1=yes,2=spline):
23        2
24 True lean and sweep (0=no,1=yes):
25        0
26 Clustering control (0=uniform,1=sine,2=exponential,3=hyperbolic,4=elliptical):
27        4 15.0

```

27 Sectionwise properties:

28	J	in_Beta	out_Beta	mrel_in	chord	t/c_max
		Incidence	Deviation	Sec. Flow Angle		
29	1	42.340505069815		1.25546483167338	0.00000000	
		0.00000000	0.000000	3.50	12.63	0.00000000
30	2	43.20	11.90	0.00000000	0.00000000	
		0.000000	5.25	9.58	0.00000000	
31	3	43.79	17.92	0.00000000	0.00000000	
		0.000000	4.80	7.99	0.00000000	
32	4	44.38	20.62	0.00000000	0.00000000	
		0.000000	4.72	7.48	0.00000000	
33	5	45.50	25.61	0.00000000	0.00000000	
		0.000000	4.65	6.86	0.00000000	
34	6	46.53	29.62	0.00000000	0.00000000	
		0.000000	4.68	6.46	0.00000000	
35	7	47.22	30.91	0.00000000	0.00000000	
		0.000000	4.76	6.27	0.00000000	
36	8	48.66	32.40	0.00000000	0.00000000	
		0.000000	5.00	5.90	0.00000000	
37	9	49.83	34.45	0.00000000	0.00000000	
		0.000000	5.55	5.45	0.00000000	
38	10	51.1586409283285		35.124499025686	0.00000000	
		0.00000000	0.000000	5.65	5.26	0.00000000
39	11	51.41	37.30	0.00000000	0.00000000	
		0.000000	5.68	5.05	0.00000000	
40	12	51.89	38.13	0.00000000	0.00000000	
		0.000000	5.73	4.90	0.00000000	
41	13	53.09	40.20	0.00000000	0.00000000	
		0.000000	5.70	4.56	0.00000000	
42	14	54.86	43.56	0.00000000	0.00000000	
		0.000000	5.66	3.93	0.00000000	
43	15	56.63	46.71	0.00000000	0.00000000	
		0.000000	5.50	3.43	0.00000000	
44	16	58.56	49.69	0.00000000	0.00000000	
		0.000000	4.95	3.22	0.00000000	
45	17	61.00	52.81	0.00000000	0.00000000	


```

0.000000      4.66      2.96      0.00000000
46 18      63.3524040738981      55.2433155340594      0.00000000
      0.00000000      0.000000      5.00      2.48      0.00000000
47
48 LE / TE curve (x,r) definition :
49 Number of Curve points :
50      18
51 xLE rLE xTE rTE
52 -1.270      36.068      17.789      47.884
53 -1.366      43.785      17.884      52.947
54 -1.429      49.488      17.981      56.958
55 -1.431      52.313      17.892      59.044
56 -1.422      57.049      17.85      62.754
57 -1.441      60.613      17.8      65.725
58 -1.449      62.683      17.782      67.491
59 -1.42      66.362      17.783      70.588
60 -1.364      69.829      17.793      73.453
61 -1.306      71.824      17.767      75.088
62 -1.237      74.234      17.699      77.273
63 -1.213      75.639      17.657      78.412
64 -1.173      79.254      17.546      81.34
65 -0.988      84.922      17.35      85.915
66 -0.707      90.238      17.062      90.211
67 -0.347      95.26      16.674      94.355
68 0.050      100.11      16.305      98.424
69 0.467      105.167      15.981      102.995
70
71 # Airfoil type and Variable Radial Stacking information. #
72 # stack_u: % chord stack (0.00 to 100.00). #
73 # stack_v: % below or above meanline stack (-100.00 to +100.00). #
74 # Use +200 for stacking on airfoil area centroid. #
75 Variable Radial stacking (0=no,1=yes):
76      0
77 J type |stk_u |stk_v |umxthk |lethk |tethk |Jcells(Grid:4n+1) |eta_ofst(<=10)[
      thkc/Jmax] |BGgrid(0=no,1=yes) |
78 1 sect1 25.00 0.00 0.30 0.02 0.02 15 10 0

```



```

115
116 Control points for lean:
117     4
118     span                delta_theta
119     0.0000000000000000    0.0000000000000000
120     0.2500000000000000    0.0000000000000000
121     0.5000000000000000    0.0000000000000000
122     1.0000000000000000    0.0000000000000000
123
124 Control points for in_beta*:
125     5
126     span                in_beta*
127     0.0000000000000000    0.0000000000000000
128     0.2500000000000000    0.0000000000000000
129     0.5000000000000000    0.0000000000000000
130     0.7500000000000000    0.0000000000000000
131     1.0000000000000000    0.0000000000000000
132
133 Control points for out_beta*:
134     5
135     span                out_beta*
136     0.0000000000000000    0.0000000000000000
137     0.2500000000000000    0.0000000000000000
138     0.5000000000000000    0.0000000000000000
139     0.7500000000000000    0.0000000000000000
140     1.0000000000000000    0.0000000000000000
141
142 Control points for chord_multiplier:
143     4
144     span                chord_multiplier
145     0.0000000000000000    0.0000000000000000
146     0.2500000000000000    0.0000000000000000
147     0.5000000000000000    0.0000000000000000
148     1.0000000000000000    0.0000000000000000
149
150 Control points for tm/c:

```

```

151          4
152          span                      tm/c
153    0.000000000000000000000000    0.000000000000000000000000
154    0.250000000000000000000000    0.000000000000000000000000
155    0.500000000000000000000000    0.000000000000000000000000
156    1.000000000000000000000000    0.000000000000000000000000
157
158  Hub offset
159    0.000000000000000000000000
160  Tip offset
161    0.000000000000000000000000
162
163  Streamline Data
164  x_s      r_s
165 -28.495285    18.884164
166 -15.238214    27.295215
167 -9.472585     30.949586
168 -6.590009     32.77715
169 -1.27    36.068
170 1.35768 37.855728
171 5.446081    40.393893
172 9.534482    42.852843
173 14.20694    45.649056
174 17.789    47.884
175 19.492925    49.019945
176 25.425061    52.353179
177 31.961715    54.306013
178 38.62798     55.772693
179 45.39551     56.603429
180 52.137207    55.696729
181 57.971122    52.232159
182 67.62676     43.577681
183 0.0      0.0
184 -28.495285    21.208355
185 -15.238214    29.619406
186 -9.472585     33.273777

```

187	-6.590009	35.101341
188	-1.27	38.068
189	1.35768	39.855728
190	5.446081	42.393893
191	9.534482	44.852843
192	14.20694	47.649056
193	17.789	49.884
194	19.492925	51.319945
195	25.425061	54.653179
196	31.961715	56.606013
197	38.62798	58.072693
198	45.39551	58.903429
199	52.137207	57.996729
200	57.971122	54.532159
201	67.62676	45.877681
202	0.0	0.0
203	-28.495285	28.808422
204	-15.238214	36.280124
205	-9.472585	39.526374
206	-6.590009	41.149834
207	-1.366	43.785
208	1.35768	45.339242
209	5.446081	47.534739
210	9.534482	48.452355
211	14.20694	50.936022
212	17.884	52.947
213	19.492925	54.248797
214	25.425061	57.275809
215	31.961715	59.049238
216	38.62798	60.381176
217	45.39551	61.135593
218	52.137207	60.31219
219	57.971122	57.165907
220	67.62676	49.306509
221	0.0	0.0
222	-28.495285	35.903042

223	-15.238214	42.680548
224	-9.472585	45.625189
225	-6.590009	47.097814
226	-1.429	49.488
227	1.35768	50.869692
228	5.446081	52.81195
229	9.534482	52.888389
230	14.20694	55.124451
231	17.981	56.958
232	19.492925	58.153522
233	25.425061	60.937941
234	31.961715	62.569241
235	38.62798	63.794433
236	45.39551	64.488389
237	52.137207	63.730976
238	57.971122	60.836846
239	67.62676	53.607324
240	0.0	0.0
241	-28.495285	39.417386
242	-15.238214	45.851019
243	-9.472585	48.646257
244	-6.590009	50.044165
245	-1.431	52.313
246	1.35768	53.609219
247	5.446081	55.426035
248	9.534482	55.195437
249	14.20694	57.302727
250	17.892	59.044
251	19.492925	60.184252
252	25.425061	62.842504
253	31.961715	64.399888
254	38.62798	65.569566
255	45.39551	66.232077
256	52.137207	65.508984
257	57.971122	62.745991
258	67.62676	55.844048

259	0.0	0.0
260	-28.495285	45.309042
261	-15.238214	51.166188
262	-9.472585	53.710958
263	-6.590009	54.983606
264	-1.422	57.049
265	1.35768	58.201926
266	5.446081	59.808443
267	9.534482	59.298575
268	14.20694	61.176842
269	17.85	62.754
270	19.492925	63.795952
271	25.425061	66.229816
272	31.961715	67.655738
273	38.62798	68.72668
274	45.39551	69.333267
275	52.137207	68.671212
276	57.971122	66.141449
277	67.62676	59.822115
278	0.0	0.0
279	-28.495285	49.742713
280	-15.238214	55.166033
281	-9.472585	57.522316
282	-6.590009	58.700702
283	-1.441	60.613
284	1.35768	61.658094
285	5.446081	63.106353
286	9.534482	62.584404
287	14.20694	64.279266
288	17.8	65.725
289	19.492925	66.688233
290	25.425061	68.942404
291	31.961715	70.26305
292	38.62798	71.254924
293	45.39551	71.816727
294	52.137207	71.203551

295	57.971122	68.860562
296	67.62676	63.007785
297	0.0	0.0
298	-28.495285	52.317825
299	-15.238214	57.489174
300	-9.472585	59.735984
301	-6.590009	60.859622
302	-1.449	62.683
303	1.35768	63.665464
304	5.446081	65.021806
305	9.534482	64.537542
306	14.20694	66.123387
307	17.782	67.491
308	19.492925	68.407441
309	25.425061	70.554801
310	31.961715	71.812869
311	38.62798	72.757745
312	45.39551	73.292927
313	52.137207	72.708806
314	57.971122	70.476837
315	67.62676	64.901387
316	0.0	0.0
317	-28.495285	61.207559
318	-15.238214	65.509064
319	-9.472585	67.37795
320	-6.590009	68.312587
321	-1.364	69.829
322	1.35768	70.595254
323	5.446081	71.634283
324	9.534482	71.131318
325	14.20694	72.34912
326	17.793	73.453
327	19.492925	74.211473
328	25.425061	75.998238
329	31.961715	77.045046
330	38.62798	77.831253

331	45.39551	78.276565
332	52.137207	77.790532
333	57.971122	75.933366
334	67.62676	71.294172
335	0.0	0.0
336	-28.495285	66.687447
337	-15.238214	70.452755
338	-9.472585	72.088678
339	-6.590009	72.906809
340	-1.237	74.234
341	1.35768	74.866976
342	5.446081	75.710404
343	9.534482	75.356112
344	14.20694	76.338101
345	17.699	77.273
346	19.492925	77.930259
347	25.425061	79.485982
348	31.961715	80.39743
349	38.62798	81.081974
350	45.39551	81.469704
351	52.137207	81.046519
352	57.971122	79.429498
353	67.62676	75.390187
354	0.0	0.0
355	-28.495285	68.435289
356	-15.238214	72.029574
357	-9.472585	73.591192
358	-6.590009	74.372163
359	-1.213	75.639
360	1.35768	76.229467
361	5.446081	77.010506
362	9.534482	76.615809
363	14.20694	77.527485
364	17.657	78.412
365	19.492925	79.03908
366	25.425061	80.525914

367	31.961715	81.397002
368	38.62798	82.051234
369	45.39551	82.421795
370	52.137207	82.017349
371	57.971122	80.471932
372	67.62676	76.611486
373	0.0	0.0
374	-28.495285	72.932404
375	-15.238214	76.086655
376	-9.472585	77.45709
377	-6.590009	78.14245
378	-1.173	79.254
379	1.35768	79.735091
380	5.446081	80.355609
381	9.534482	79.854081
382	14.20694	80.585008
383	17.546	81.34
384	19.492925	81.8895
385	25.425061	83.199242
386	31.961715	83.966578
387	38.62798	84.542887
388	45.39551	84.869311
389	52.137207	84.513037
390	57.971122	83.15169
391	67.62676	79.751049
392	0.0	0.0
393	-28.495285	79.983484
394	-15.238214	82.447799
395	-9.472585	83.518476
396	-6.590009	84.053926
397	-0.988	84.922
398	1.35768	85.2316
399	5.446081	85.600433
400	9.534482	84.913881
401	14.20694	85.362386
402	17.35	85.915

403	19.492925	86.343282
404	25.425061	87.376318
405	31.961715	87.98154
406	38.62798	88.436094
407	45.39551	88.693555
408	52.137207	88.41255
409	57.971122	87.338811
410	67.62676	84.656616
411	0.0	0.0
412	-28.495285	86.596669
413	-15.238214	88.413896
414	-9.472585	89.203432
415	-6.590009	89.598281
416	-0.707	90.238
417	1.35768	90.386759
418	5.446081	90.519539
419	9.534482	89.665116
420	14.20694	89.848423
421	17.062	90.211
422	19.492925	90.525456
423	25.425061	91.29866
424	31.961715	91.751656
425	38.62798	92.091879
426	45.39551	92.284583
427	52.137207	92.074257
428	57.971122	91.270588
429	67.62676	89.263024
430	0.0	0.0
431	-28.495285	92.844115
432	-15.238214	94.050041
433	-9.472585	94.573982
434	-6.590009	94.836008
435	-0.347	95.26
436	1.35768	95.256813
437	5.446081	95.166594
438	9.534482	94.248244

439	14.20694	94.175736
440	16.674	94.355
441	19.492925	94.559657
442	25.425061	95.082223
443	31.961715	95.388378
444	38.62798	95.618316
445	45.39551	95.748554
446	52.137207	95.606406
447	57.971122	95.063251
448	67.62676	93.706449
449	0.0	0.0
450	-28.495285	98.877589
451	-15.238214	99.493151
452	-9.472585	99.760595
453	-6.590009	99.894346
454	0.05	100.11
455	1.35768	99.960072
456	5.446081	99.654491
457	9.534482	98.748424
458	14.20694	98.424732
459	16.305	98.424
460	19.492925	98.520845
461	25.425061	98.79731
462	31.961715	98.959281
463	38.62798	99.08093
464	45.39551	99.149833
465	52.137207	99.074629
466	57.971122	98.787272
467	67.62676	98.069455
468	0.0	0.0
469	-28.495285	103.167
470	-15.238214	103.167
471	-9.472585	103.167
472	-6.590009	103.167
473	0.467	103.167
474	3.5698	102.7326

475	6.6726	102.2982
476	9.7754	101.8638
477	12.8782	101.4294
478	15.981	100.995
479	19.492925	100.995
480	25.425061	100.995
481	31.961715	100.995
482	38.62798	100.995
483	45.39551	100.995
484	52.137207	100.995
485	57.971122	100.995
486	67.62676	100.995
487	0.0	0.0
488	-28.495285	105.167
489	-28.1286738	105.167
490	-27.7620626	105.167
491	-27.3954514	105.167
492	-27.0288402	105.167
493	-26.662229	105.167
494	-26.2956178	105.167
495	-25.9290066	105.167
496	-25.5623954	105.167
497	-25.1957842	105.167
498	-24.829173	105.167
499	-24.4625618	105.167
500	-24.0959506	105.167
501	-23.7293394	105.167
502	-23.3627282	105.167
503	-22.996117	105.167
504	-22.6295058	105.167
505	-22.2628946	105.167
506	-21.8962834	105.167
507	-21.5296722	105.167
508	-21.1630609	105.167
509	-20.7964497	105.167
510	-20.4298385	105.167

511	-20.0632273	105.167
512	-19.6966161	105.167
513	-19.3300049	105.167
514	-18.9633937	105.167
515	-18.5967825	105.167
516	-18.2301713	105.167
517	-17.8635601	105.167
518	-17.4969489	105.167
519	-17.1303377	105.167
520	-16.7637265	105.167
521	-16.3971153	105.167
522	-16.0305041	105.167
523	-15.6638929	105.167
524	-15.2972817	105.167
525	-14.9306705	105.167
526	-14.5640593	105.167
527	-14.1974481	105.167
528	-13.8308369	105.167
529	-13.4642257	105.167
530	-13.0976145	105.167
531	-12.7310033	105.167
532	-12.3643921	105.167
533	-11.9977809	105.167
534	-11.6311697	105.167
535	-11.2645585	105.167
536	-10.8979473	105.167
537	-10.5313361	105.167
538	-10.1647249	105.167
539	-9.7981137	105.167
540	-9.4315025	105.167
541	-9.0648913	105.167
542	-8.6982801	105.167
543	-8.3316689	105.167
544	-7.9650577	105.167
545	-7.5984465	105.167
546	-7.2318353	105.167

547	-6.8652241	105.167
548	-6.4986128	105.167
549	-6.1320016	105.167
550	-5.7653904	105.167
551	-5.3987792	105.167
552	-5.032168	105.167
553	-4.6655568	105.167
554	-4.2989456	105.167
555	-3.9323344	105.167
556	-3.5657232	105.167
557	-3.199112	105.167
558	-2.8325008	105.167
559	-2.4658896	105.167
560	-2.0992784	105.167
561	-1.7326672	105.167
562	-1.366056	105.167
563	-0.9994448	105.167
564	-0.6328336	105.167
565	-0.2662224	105.167
566	0.1003888	105.167
567	0.467	105.167
568	0.6561951	105.1405122
569	0.8453902	105.1140244
570	1.0345854	105.0875366
571	1.2237805	105.0610488
572	1.4129756	105.034561
573	1.6021707	105.0080732
574	1.7913659	104.9815854
575	1.980561	104.9550976
576	2.1697561	104.9286098
577	2.3589512	104.902122
578	2.5481463	104.8756341
579	2.7373415	104.8491463
580	2.9265366	104.8226585
581	3.1157317	104.7961707
582	3.3049268	104.7696829

583	3.494122	104.7431951
584	3.6833171	104.7167073
585	3.8725122	104.6902195
586	4.0617073	104.6637317
587	4.2509024	104.6372439
588	4.4400976	104.6107561
589	4.6292927	104.5842683
590	4.8184878	104.5577805
591	5.0076829	104.5312927
592	5.196878	104.5048049
593	5.3860732	104.4783171
594	5.5752683	104.4518293
595	5.7644634	104.4253415
596	5.9536585	104.3988537
597	6.1428537	104.3723659
598	6.3320488	104.345878
599	6.5212439	104.3193902
600	6.710439	104.2929024
601	6.8996341	104.2664146
602	7.0888293	104.2399268
603	7.2780244	104.213439
604	7.4672195	104.1869512
605	7.6564146	104.1604634
606	7.8456098	104.1339756
607	8.0348049	104.1074878
608	8.224	104.081
609	8.4131951	104.0545122
610	8.6023902	104.0280244
611	8.7915854	104.0015366
612	8.9807805	103.9750488
613	9.1699756	103.948561
614	9.3591707	103.9220732
615	9.5483659	103.8955854
616	9.737561	103.8690976
617	9.9267561	103.8426098
618	10.1159512	103.816122

619	10.3051463	103.7896341
620	10.4943415	103.7631463
621	10.6835366	103.7366585
622	10.8727317	103.7101707
623	11.0619268	103.6836829
624	11.251122	103.6571951
625	11.4403171	103.6307073
626	11.6295122	103.6042195
627	11.8187073	103.5777317
628	12.0079024	103.5512439
629	12.1970976	103.5247561
630	12.3862927	103.4982683
631	12.5754878	103.4717805
632	12.7646829	103.4452927
633	12.953878	103.4188049
634	13.1430732	103.3923171
635	13.3322683	103.3658293
636	13.5214634	103.3393415
637	13.7106585	103.3128537
638	13.8998537	103.2863659
639	14.0890488	103.259878
640	14.2782439	103.2333902
641	14.467439	103.2069024
642	14.6566341	103.1804146
643	14.8458293	103.1539268
644	15.0350244	103.127439
645	15.2242195	103.1009512
646	15.4134146	103.0744634
647	15.6026098	103.0479756
648	15.7918049	103.0214878
649	15.981	102.995
650	16.6347438	102.995
651	17.2884876	102.995
652	17.9422314	102.995
653	18.5959752	102.995
654	19.249719	102.995

655	19.9034628	102.995
656	20.5572066	102.995
657	21.2109504	102.995
658	21.8646942	102.995
659	22.518438	102.995
660	23.1721818	102.995
661	23.8259256	102.995
662	24.4796694	102.995
663	25.1334132	102.995
664	25.787157	102.995
665	26.4409008	102.995
666	27.0946446	102.995
667	27.7483884	102.995
668	28.4021322	102.995
669	29.0558759	102.995
670	29.7096197	102.995
671	30.3633635	102.995
672	31.0171073	102.995
673	31.6708511	102.995
674	32.3245949	102.995
675	32.9783387	102.995
676	33.6320825	102.995
677	34.2858263	102.995
678	34.9395701	102.995
679	35.5933139	102.995
680	36.2470577	102.995
681	36.9008015	102.995
682	37.5545453	102.995
683	38.2082891	102.995
684	38.8620329	102.995
685	39.5157767	102.995
686	40.1695205	102.995
687	40.8232643	102.995
688	41.4770081	102.995
689	42.1307519	102.995
690	42.7844957	102.995

691	43.4382395	102.995
692	44.0919833	102.995
693	44.7457271	102.995
694	45.3994709	102.995
695	46.0532147	102.995
696	46.7069585	102.995
697	47.3607023	102.995
698	48.0144461	102.995
699	48.6681899	102.995
700	49.3219337	102.995
701	49.9756775	102.995
702	50.6294213	102.995
703	51.2831651	102.995
704	51.9369089	102.995
705	52.5906527	102.995
706	53.2443965	102.995
707	53.8981403	102.995
708	54.5518841	102.995
709	55.2056278	102.995
710	55.8593716	102.995
711	56.5131154	102.995
712	57.1668592	102.995
713	57.820603	102.995
714	58.4743468	102.995
715	59.1280906	102.995
716	59.7818344	102.995
717	60.4355782	102.995
718	61.089322	102.995
719	61.7430658	102.995
720	62.3968096	102.995
721	63.0505534	102.995
722	63.7042972	102.995
723	64.358041	102.995
724	65.0117848	102.995
725	65.6655286	102.995
726	66.3192724	102.995

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727 66.9730162      102.995
728 67.62676       102.995
729 0.0            0.0

```

E.2.2 spancontrolinputs.1.dat file

```

1 Casename:
2 GE_E3_Fan_rotor
3 Blade row#:
4 1
5 Span control points , Chord & curvature control points
6           3       7
7 Span      u2          u3      u4      u5      u6      cur1          cur2
           cur3          cur4          cur5          cur6 cur7
8 0.00      0.15      0.25      0.50      0.75      0.95      1.695915356433488      3.631585002764526      2.31
           1.751813546611551      0.7073926409875017          0.5110641023004737
           0.6394991587684383
9 0.55      0.15      0.25      0.50      0.75      0.95      -0.9521920902369565      0.3033396118222525
           0.50      0.02079877565624548      0.8450197313160744      -0.01305617829214443
           -0.6658932068859058
10 1.00      0.15      0.25      0.50      0.75      0.95      -0.4338899693604618      -1.109422191592448
           0.50      -0.1487365420570926      1.81450867904997          1.1430224859446774
           0.10694237796936842
11
12 Span control points , Chord & thickness control points
13           3       1
14 Span      LE_radius      u_max      t_max      t_TE
15 0.00      2.3591620846850745      0.4565529040410505      0.09702213967820521
           0.003637203014408098
16 0.55      2.228717117381842      0.6147196915472138      0.03565671006561507
           0.00010000000000000715
17 1.00      2.4577201043140238      0.6316847625321914      0.02622001980009441      0.0001

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