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TWO-DIMENSIONAL EM-SCATTERING BY BURIED PENETRABLE NON-CIRCULAR CYLINDERS USING THE METHOD OF MOMENTS

The Ohio State University

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TWO DIMENSIONAL EM-SCATTERING BY BURIED PENETRABLE
NON-CIRCULAR CYLINDERS USING THE METHOD OF MOMENTS

Dissertation

Presented in Partial Fulfillment of the Requirement for
the Degree Doctor of Philosophy in the Graduate
School of The Ohio State University

By

Jamaledin Izadian, B.S.E.E., M.S.E.E.

The Ohio State University

1982

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"An Underground Near Field Antenna Pattern Range", a master's thesis. Also Report No. 529081-3, July 1980, The Ohio State University ElectroScience Laboratory, Department of Electrical Engineering. Prepared under Contract No. 5014-352-0234 for Gas Research Institute.

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CHAPTER I

INTRODUCTION

Rigorous solutions for scattering problems may be obtained if there exists a coordinate system in which the field components can be separated. In practice, these cases are few, and occur only for special scatterers, i.e., spheres, circular cylinders, etc. To solve problems of more general nature, an integral equation formulation may be used. A numerical technique such as the moment method is then used to solve the integral equation. In this work the attention is focused on the penetrable non-circular cylinders of infinite length, and the Plane Wave Expansion Galerkin (PWE) is employed to solve the integral equations.

A basic introduction to the moment method is given by Harrington [1] and various examples and numerical results are presented. Richmond [2-3] introduced solutions for scattering by dielectric cylinders of infinite length, where he employed the Pulse Basis Point Matching (PBPM) technique.

Although a variety of conventional techniques has been used by geophysicists for many years as suggested by Ward [4], many improvements are being made and various EM-techniques are being introduced. Ward [4]

provides an excellent historical overview of geophysical methods and their future developments.

Parry et al. [5] treat the problem of EM-scattering from cylinders of arbitrary cross-section in a conducting half space by obtaining some integral equations in terms of the surface currents and solving them by expanding the unknown currents in terms of some quadratic algebraic functions and point matching.

D'Yakonov [6] treated the problem of a circular cylinder in a homogeneous half space. This paper is rather involved and difficult to follow. This problem was later considered by Howard [7], and some numerical solutions were given. Ogunade [8] also considered D'Yakonov's [6] problem and provided some numerical results, however, there seems to have been an incorrect symmetry in equation (21) in this paper (Richmond, Peters [9]). Ogunade and Dosso present more numerical results in [10].

During the past decade, considerable research and development effort has been devoted to underground radar at the ElectroScience Laboratory. Most efforts have been concentrated on system design [16-19] propagation and scattering [20-26], experimental measurement and data collection [27-29] identification and imaging [30-35] and computational modeling [36].

The purpose of this dissertation is to develop an efficient computational model for EM-scattering by lossy dielectric cylinders of infinite length buried in the earth. It is hoped that a frequency spectrum obtained from the computational model and a future extension of

the model would enable obtaining transient EM-scattering results for the underground radar targets. It is believed that an unwanted filled trench response in the transient echo of a buried target may be identified and ultimately eliminated which in turn would help to enhance the desired echo. An effort, however, has been made to provide a formulation for general cases, but specific examples are given for rectangular cylinders.

Additionally, it is hoped that the numerical results given here will provide additional insight and lead to a simple explanation of the effect of the air-earth interface so that some simple approximations may be employed. One such an approximation is the use of the plane wave reflection and transmission coefficients at the air-earth interface to account for most of the interface effects. This, in turn, would eliminate the costly evaluation of Sommerfeld integrals.

The formulation of the integral equations are based on the polarization current representation for dielectric bodies proposed by Rhodes [37], wherein a scatterer may be replaced by a volume of polarization currents which produce the correct scattered field everywhere. The integral equations obtained involve the electric field inside the scatterer as the unknown function. These integral equations are then solved by expanding the unknown fields in terms of some plane waves with unknown coefficients. Galerkin's method is used to obtain a set of N simultaneous linear equations with N unknowns, where the N unknowns are the coefficients of the plane waves in the expansion. A simple matrix inversion and multiplication then gives the solution for

the unknown coefficient. The problem of scattering by cylindrical inhomogeneities in a lossy medium is presented by Peters and Richmond [38], volume polarization currents are used to obtain an E-integral equation and an H-integral equation which then are solved by the moment method. The same approach is taken here except that all the integral equations in this dissertation are based on the electric field. This proved to be more stable for obtaining a convergent solution.

A. THE STRUCTURE OF THE DISSERTATION

This dissertation is basically composed of two parts: The first part deals only with the scatterers in a homogeneous ambient medium in the absence of the air-earth interface. The second part deals with buried scatterer where a Sommerfeld integral is used to account for the effects of the air-earth interface.

Chapter II gives a general formulation for the EM-scattering by lossy dielectric cylinder immersed in a homogeneous lossy medium for an electric and a magnetic line source excitations. In Chapter III, the plane wave expansion is introduced, the E-wave scattering formulation derived in Chapter II are specialized to rectangular cylindrical scatterers. In addition, some numerical results are given and discussed. In Chapter IV, a similar treatment of the H-wave scattering model is given and some specific results are provided for a rectangular cylindrical scatterer.

In Chapter V, a basic introduction to the air-earth interface effect is made for both an electric and a magnetic line source on the interface. Some radiation patterns are included and discussed. In addition, some helpful hints are given for evaluating the Sommerfeld type integrals encountered in this dissertation. In Chapter VI, a general moment method formulation is given for the EM-scattering by buried cylindrical geometries for an electric and a magnetic line source excitations. These scattering models are then specialized for buried rectangular cylindrical geometries for an electric line source excitation in Chapter VII, and a magnetic line source excitation in Chapter VIII. In Chapter IX, a discussion of the computer time required is given. A comparison is made with the computation time for a Pulse Basis Point Matching (PBPM) and a Plane Wave Expansion Galerkin (PWE) solutions for the same target.

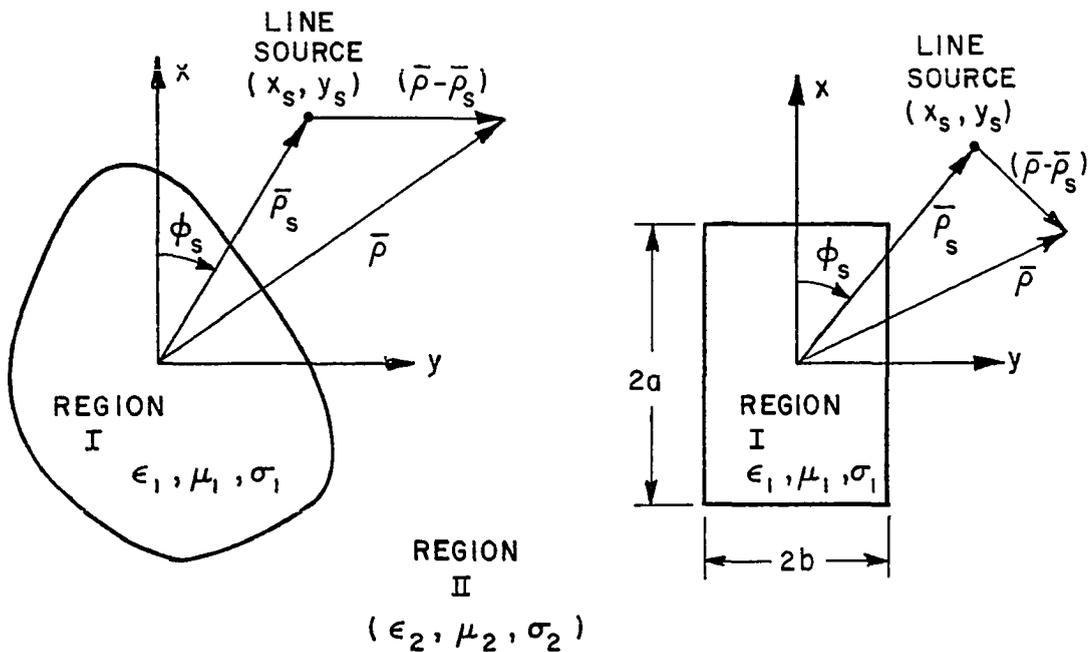
The time harmonic convention $e^{j\omega t}$ is assumed throughout this work and suppressed.

CHAPTER II

FORMULATION OF MOMENT METHOD

A. INTRODUCTION

A two-dimensional moment method formulation is to be developed in this chapter for the scattered fields of a lossy dielectric cylinder immersed in a homogeneous lossy ambient medium. Both electric and magnetic line currents are to be used as sources. The solution will have the capability of treating a cylinder of rather general cross section. Figure 1(a) shows the general geometry whereas Figure 1(b) shows the special case of most interest herein, i.e., a rectangular cylinder. This is because the target of interest at present happens to be the refilled trench in which a pipe has been placed. The region inside the cylinder is designated as Region I with electrical parameters ϵ_1 , μ_0 , and σ_1 , and the region outside the cylinder is designated as Region II with constitutive parameters ϵ_2 , μ_0 , and σ_2 . In the rectangular model it is assumed that x-dimension is greater than or equal to y-dimension, and that the length and width of the rectangular cylinder are $2a$ and $2b$ meters, respectively. The



(a) ARBITRARY CROSS SECTION (b) RECTANGULAR CROSS SECTION

Figure 2-1. Electromagnetic scattering model for two-dimensional lossy dielectric rectangular cylinders (region I) immersed in a lossy homogeneous ambient medium (region II).

coordinates of the line source are designated by (x_s, y_s) . Region I is considered to be homogeneous and source-free.

Peters, et al. [9], has presented a two-dimensional moment method formulation for both parallel and perpendicular polarizations of the incident field. When the incident electric field is in the z direction, the formulation to be used follows directly from Peters, et al. [9]. This shows a great numerical stability and convergence. This solution for the orthogonal excitation proved to be unstable. Thus for the TE_z case, a new formulation is introduced which does exhibit improved numerical stability and convergence.

The purposes of this chapter are basically the presentation of the theory for the electromagnetic scattering models and the formulation of numerical technique to solve these mathematical formulas. In this chapter the general model of Figure 2-1a is treated for any arbitrarily shaped cross-section of a two-dimensional cylinder. This will be specialized for the model of Figure 2-1b in the next chapter.

B. E-WAVE SCATTERING BY TWO-DIMENSIONAL LOSSY DIELECTRIC CYLINDERS

1. Electric Line Source Excitation

An infinitely long time harmonic electric line source with uniform current of 1 ampere is radiating in a homogeneous medium II with complex propagation constant γ_2 , produces a field

$$\vec{E}^i = \frac{-j\omega\mu_0}{2\pi} K_0(\gamma_2 |\bar{\rho} - \bar{\rho}_s|) \hat{z} \quad (2.1)$$

where K_0 is the modified Bessel function

$$\gamma_2 = j\omega \sqrt{\hat{\epsilon}_2 \mu_0} \quad , \quad (2.2a)$$

$$\omega = 2\pi f \quad , \quad (2.2b)$$

$$\hat{\epsilon}_2 = \epsilon_0 \left(\epsilon_{r2} - j \frac{\sigma_2}{\omega \epsilon_0} \right) \quad , \quad (2.2c)$$

$$|\bar{\rho} - \bar{\rho}_S| = \sqrt{(x-x_S)^2 + (y-y_S)^2} \quad , \quad \text{and} \quad (2.3)$$

(x_S, y_S) is the coordinate of the location of the line source.

When the above line source is radiating in the presence of the scatterer, the total field everywhere is the sum of the incident field and the scattered field. This field is given by

$$\bar{E}(x,y) = \bar{E}^i(x,y) + \bar{E}^s(x,y) \quad , \quad (2.4)$$

where $\bar{E}^i(x,y)$ is the field radiated by the source in the ambient homogeneous medium II (see Figure 2) in the absence of the scatterer given by Eq. (2.1),

$\bar{E}(x,y)$ is the total field observed when the source radiates in the presence of the scatterer.

Both $\bar{E}^i(x,y)$ and $\bar{E}(x,y)$ are measurable quantities, and difference of these two fields renders the scattered field $\bar{E}^s(x,y)$.

To calculate $\bar{E}^s(x,y)$, one may replace the scatterer by a volumetric equivalent polarization current \bar{J}_{eq} which when radiating in a homogeneous ambient medium gives the correct scattered field. The equivalent volume polarization current is given by Harrington [39].

$$\bar{J}_{eq}(x,y) = j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)\bar{E}^i(x,y) \quad , \quad (2.5)$$

where $\hat{\epsilon}_1$ and $\hat{\epsilon}_2$ are assumed to be constant throughout each respective region (homogeneous), and

$\bar{E}^I(x,y)$ is the total unknown field in region I.

$E_z^S(x,y)$ is given by

$$E_z^S(x,y) = \frac{-j\omega\mu_0}{2\pi} \iint_{CS} J_{eq}(x',y') K_0(\gamma_2 |\bar{\rho}-\bar{\rho}'|) ds' \quad , \quad (2.6a)$$

where ds' is the differential cross sectional area of the cylinder, and

$$|\bar{\rho}-\bar{\rho}'| = \sqrt{(x-x')^2 + (y-y')^2} \quad . \quad (2.6b)$$

From Eq. (2.5), (2.6) and (2.4), the following integral equation is obtained

$$E_z^i(x,y) = E_z^I(x,y) - \frac{\omega^2\mu_0(\hat{\epsilon}_1-\hat{\epsilon}_2)}{2\pi} \iint_{CS} E_z^I(x',y') K_0(\gamma_2 |\bar{\rho}-\bar{\rho}'|) ds' \quad . \quad (2.7)$$

The unknown function in the above integral equation is $E_z^I(x,y)$ or the field inside the scatterer. The unknown function appears both inside and outside the integral, thus this is a Fredholm integral equation of the second kind. To obtain a solution, E_z^I is expanded in terms of some known basis function $F_n(x,y)$ with unknown coefficient C_n 's.

$$E_z^I(x,y) = \sum_{n=1}^N C_n F_n(x,y) \quad . \quad (2.8)$$

Substituting the above expansion in Equation (2.7) gives

$$E_z^i(x,y) = \sum_{n=1}^N C_n \left[F_n(x,y) - \frac{\omega^2\mu_0(\hat{\epsilon}_1-\hat{\epsilon}_2)}{2\pi} \iint_{CS} F_n(x',y') K_0(\gamma_2 |\bar{\rho}-\bar{\rho}'|) ds' \right] \quad , \quad (2.9)$$

where the C_n 's are unknown. To evaluate C_n a set of simultaneous linear equations may be obtained by choosing a set of suitable testing functions, multiplying the above equation by these testing functions and then integrating over the cross-section of the scatterer. Various choices of testing methods exist. However, the two most common ones are point matching and Galerkin. The first involves use of delta function, and the latter makes use of basis function used in the expansion of unknown function in Eq. (2.8) as a testing function. It is desired to apply a testing which makes use of reciprocity theorem in electromagnetic theory, this theorem states

$$\iint_{S_m} \bar{J}_m \cdot \bar{E}_n \, dS_m = \iint_{S_n} \bar{J}_n \cdot \bar{E}_m \, dS_n \quad . \quad (2.10)$$

where

\bar{J}_m and \bar{J}_n are m^{th} and n^{th} current modes, \bar{E}_m and \bar{E}_n are field generated by these current modes, and S_m and S_n are the cross-section areas of m^{th} and n^{th} current elements. A major advantage of implementing a solution involving the above theorem is that a symmetric impedance matrix is generated. The Galerkin method is used to take advantage of the above properties, also, it provides a great numerical stability and convergence. To apply Galerkin testing, both sides of Eq. (2.9) are multiplied by the testing function $F_m(x,y)$ and integrated over the cross-section. One obtains the following set of simultaneous linear equations;

$$V_m = \sum_{n=1}^N C_n Z_{mn} \quad m = 1, 2, \dots, N, \quad (2.11)$$

where

$$V_m = \iint_{CS} F_m(x, y) E_Z^i(x, y) ds \quad m = 1, 2, \dots, N, \quad (2.12)$$

and

$$Z_{mn} = \iint_{CS} F_n(x, y) F_m(x, y) ds - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iiint_{CS} F_n(x', y') F_m(x, y) K_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds' ds. \quad (2.13)$$

The matrix form of Equation (2.11) can be written as

$$[Z_{mn}][C_n] = [V_m], \quad (2.14)$$

where $[Z_{mn}]$ is a $(N \times N)$ impedance matrix, $[C_n]$ is the unknown column matrix, and $[V_m]$ is a known voltage column matrix. For a nonsingular $[Z_{mn}]$ the above matrix equation can be solved numerically with the aid of a digital computer. Thus

$$[C_n] = [Z_{mn}]^{-1} [V_m]. \quad (2.15)$$

Once the $[C_n]$ matrix has been determined, \bar{J}_{eq} is evaluated by Equations (2.5) and (2.8). In turn $E_Z^S(x, y)$ can be calculated from Eq. (2.6a) to obtain

$$E_Z^S(x, y) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sum_{m=1}^N C_m \iint_{CS} F_m(x', y') K_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds'. \quad (2.16)$$

The above equation is valid for all scattering angles. However for backscattered case some computation time may be saved by using the following

$$E_{z(x_s, y_s)}^{B.S.} = j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) \sum_{n=1}^N C_n V_n \quad (2.17)$$

The pertinent numerical values (V_n) may be stored when setting up the voltage column matrix. These values are then retrieved when the above equation is used to calculate the backscattered field. This result can be obtained by reciprocity. Considering Figure 1, the line source has a current distribution $\bar{J}_{L.S.} = \delta(x-x_s)\delta(y-y_s)$, and radiates a field $\bar{E}^i(x,y)$ given by Equation (2.1). A particular current mode \bar{J}_n in the scatterer is given by $\bar{J}_n = j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)\bar{E}_n^I$, where \bar{E}_n^I is the total field of mode n in the scatterer. \bar{J}_n generates the n^{th} mode of the scattered field \bar{E}_n^S , where the total scattered field due to the scatterer is $\bar{E}^S(x,y) = \sum_{n=1}^N \bar{E}_n^S$. Applying reciprocity to a typical current mode \bar{J}_n in the scatterer and $\bar{J}_{L.S.}$ on the line source gives

$$\iint_{L.S.} \bar{J}_{L.S.} \cdot \bar{E}_n^S \, ds = \iint_{C.S.} \bar{J}_n \cdot \bar{E}^i(x,y) \, ds \quad (2.18)$$

or

$$\begin{aligned} E_n^S(x_s, y_s) &= j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) \iint_{C.S.} \bar{E}_n^I(x,y) \cdot \bar{E}^i(x,y) \, ds \\ &= j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) C_n \iint_{C.S.} F_n(x,y) E_z^i(x,y) \, ds \\ &= j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) C_n V_n \quad (2.19) \end{aligned}$$

Thus, Equation (2.17) is obtained.

All of the single cross-section integration encountered so far are easy to evaluate numerically. The double cross-section integration of Equation (2.13) is rather tedious because of the singular point ($x=x'$, $y=y'$). Richmond [40] has given an integration technique for evaluation of the inner most cross-section integration of Equation (2.13). A careful reapplication of the same technique can also be used to evaluate the outer most integration. This is especially useful for considering scattering by cylinders with arbitrary cross section. For the rectangular cross-section shaped cylinders, these integrations are evaluated in a closed form as will be illustrated in future chapters for specific cases.

2. E_z -plane Wave Incidence

The fields of a z-polarized incident plane wave are given by

$$E_z^i = E_0 e^{-\gamma_2 \hat{p} \cdot \hat{r}} \quad (2.20)$$

where E_0 is amplitude of the incidence plane wave which is to be set to unity, $\hat{p} = -\hat{x}\cos\phi_i - \hat{y}\sin\phi_i$ is the unit vector in direction of propagation, $\hat{r} = \hat{x}x + \hat{y}y$ is radial position vector, and ϕ_i is the angle of incidence as shown in Figure 2-2.

The incident field can now be written in the form

$$E_z^i = e^{\gamma_2(x\cos\phi_i + y\sin\phi_i)} \quad (2.21)$$

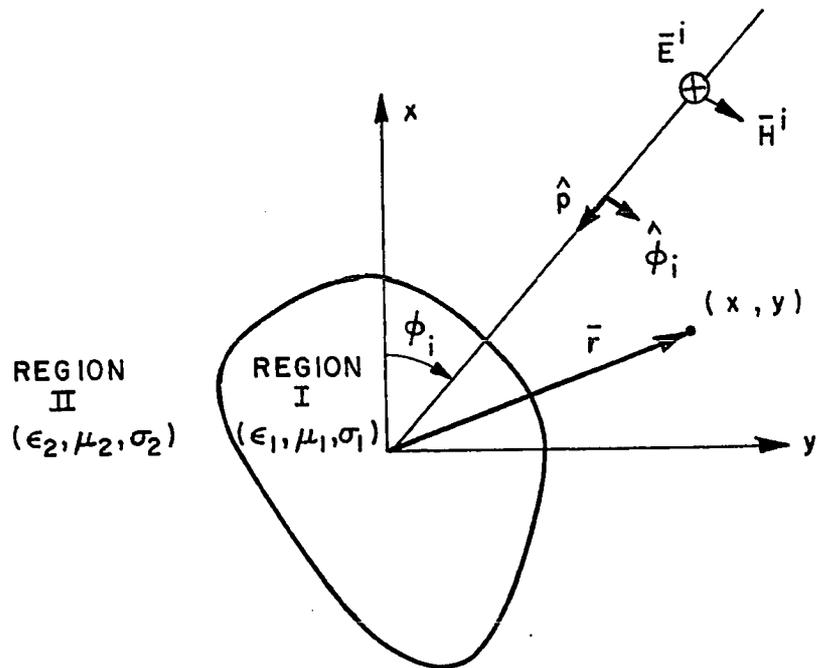


Figure 2-2. E_z -plane wave incident on the scatterer.

From Eq. (2.12)

$$V_m = \iint_{CS} F_m(x,y) e^{\gamma_2(x \cos \phi_i + y \sin \phi_i)} ds \quad . \quad (2.22)$$

In the far zone, the scattered field can be obtained by using asymptotic form of $K_0(\gamma_2 |\vec{p} - \vec{p}'|)$ in Equation (2.16)

$$E_Z^S(\rho, \phi) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sqrt{\frac{\pi}{2\gamma_2}} \sum_{m=1}^N C_m \iint_{CS} F_m(x, y) e^{\gamma_2(x \cos \phi_S + y \sin \phi_S)} \frac{e^{-\gamma_2 \rho}}{\sqrt{\rho}} ds. \quad (2.23)$$

The far field approximation has been used as illustrated in Figure 2-3.

where

$$\begin{aligned} |\bar{\rho} - \bar{\rho}'| &= \rho - \rho' \cos(\phi_S - \phi') \\ &= \rho - (x' \cos \phi_S + y' \sin \phi_S) \end{aligned} \quad (2.24)$$

When $\phi_i = \phi_S$ (Backscattered case)

$$E_Z^{B.S.}(\rho, \phi_S) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sqrt{\frac{\pi}{2\gamma_2}} \sum_{m=1}^N C_m V_m \frac{e^{-\gamma_2 \rho}}{\sqrt{\rho}} \quad (2.25)$$

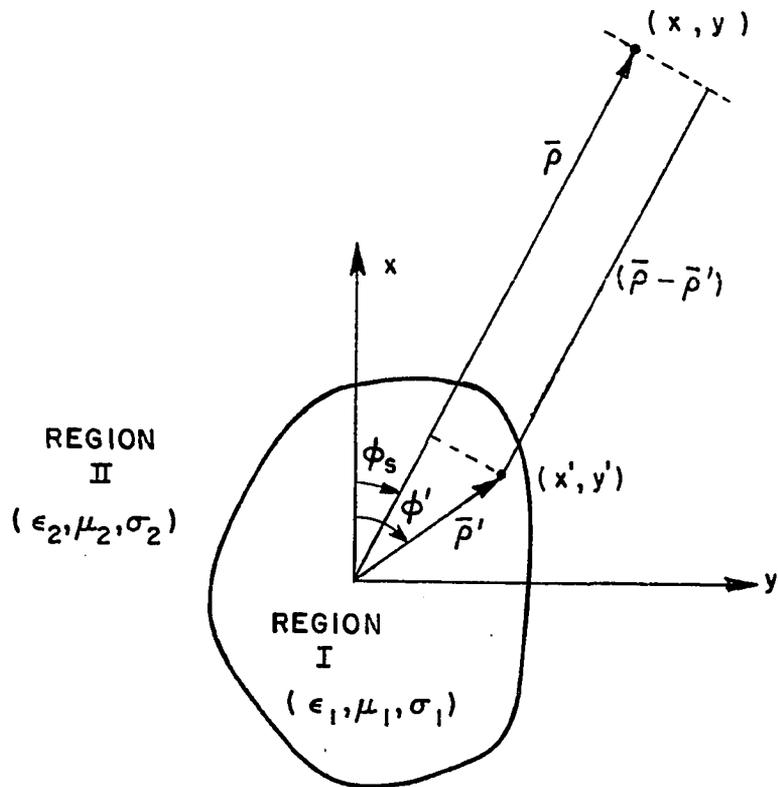
Where V_m is now given in Equation (2.22).

C. H-WAVE SCATTERING BY TWO DIMENSIONAL LOSSY DIELECTRIC CYLINDERS

1. Magnetic Line Source Excitation

An infinite magnetic line source with uniform current M_0 located at (x_S, y_S) when radiating in the homogeneous medium $(\epsilon_2, \mu_0, \sigma_2)$ generates the field given by

$$\bar{H}^i = -\frac{j\omega\hat{\epsilon}_2}{2\pi} K_0(\gamma_2 |\bar{\rho} - \bar{\rho}_S|) \hat{z} \quad (2.26)$$



$$\rho = \sqrt{x^2 + y^2}$$

$$\rho' = \sqrt{x'^2 + y'^2}$$

IN FAR ZONE

$$|\bar{\rho} - \bar{\rho}'| \approx \rho - \rho' \cos(\phi_s - \phi')$$

Figure 2-3. Illustration of the far field approximation for the scattered field.

The corresponding electric field generated by the above magnetic current is

$$\vec{E}^i = \frac{\gamma_2}{2\pi} K_1(\gamma_2 |\vec{\rho} - \vec{\rho}_s|) \hat{\phi}_{LS} \quad , \quad (2.27a)$$

where

$$\hat{\phi}_{LS} = -\hat{x} \sin \phi_{LS} + \hat{y} \cos \phi_{LS} \quad ; \quad \text{and} \quad (2.27b)$$

$$\phi_{LS} = \tan^{-1} \left(\frac{y-y_s}{x-x_s} \right) \quad .$$

where $\hat{\phi}_{LS}$ is the unit vector in direction of ϕ_{LS} as shown in Figure 2-4 and K_1 is the modified Bessel function of order one.

The field scattered by the dielectric cylinder is given by

$$\vec{E}^s(x,y) = -j\omega \vec{A}^s(x,y) - \nabla V(x,y) \quad . \quad (2.28)$$

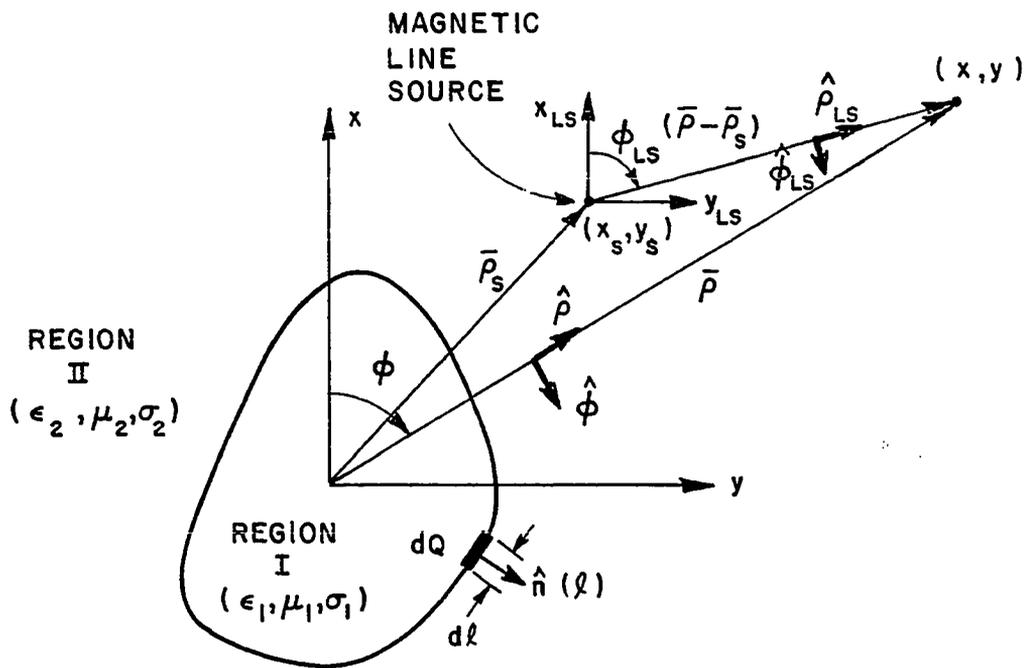
where \vec{A}^s is the electric vector potential given by

$$\vec{A}^s(x,y) = \frac{\mu_0}{2\pi} \iint_{cs} \vec{J}_{eq}(x',y') K_0(\gamma_2 |\vec{\rho} - \vec{\rho}'|) ds' \quad , \quad (2.29)$$

$V(x,y)$ is the scalar potential given by

$$V(x,y) = \frac{1}{2\pi \hat{\epsilon}_2} \int_{\ell} \rho_s(\ell') K_0(\gamma_2 |\vec{\rho} - \vec{\rho}'|) d\ell' \quad . \quad (2.30)$$

$\rho_s(\ell')$ is the surface charge density on the surfaces of the scatterer. $d\ell'$ is the differential linear element on the contour of the scatterer as shown in Figure 2-4. (The prime designates integration over the source region.)



$$\phi_{LS} = \tan^{-1} \left(\frac{y - y_s}{x - x_s} \right)$$

$$\hat{\phi}_{LS} = -\hat{x} \sin \phi_{LS} + \hat{y} \cos \phi_{LS}$$

Figure 2-4. Electromagnetic scattering model for magnetic line source excitation.

Region I is source free thus

$$\rho_v = 0. \quad (3.31)$$

The incremental current dI in an elemental length at the perimeter is obtained from the normal component of \bar{J}_{eq} as

$$dI = [\bar{J}_{eq}(\ell) \cdot \hat{n}(\ell)] d\ell \quad (2.32)$$

where $\hat{n}(\ell)$ a unit normal out of region I as illustrated in Figure 2-4.

For a time harmonic source,

$$dI = j\omega dQ \quad (2.33)$$

where dQ is the total charge in element $d\ell$. From Equations (2.32) and (2.33), and knowing $\rho_s = \frac{dQ}{d\ell}$,

$$\rho_s(\ell) = \frac{J_{eq}(\ell) \cdot \hat{n}(\ell)}{j\omega} \quad (2.34)$$

Substituting Equation (2.34) in Equation (2.30) yields

$$V_{(x,y)} = \frac{1}{j\omega 2\pi \epsilon_2} \int_{\ell} [\bar{J}_{eq}(\ell') \cdot \hat{n}(\ell')] K_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) d\ell' \quad (2.35)$$

Noting that only ρ in the integration is dependent on (x, y) , taking the gradient of $v(x,y)$ gives

$$\nabla V_{(x,y)} = - \frac{\gamma_2}{j\omega 2\pi \epsilon_2} \int_{\ell} [\bar{J}_{eq}(\ell') \cdot \hat{n}(\ell')] K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) \hat{\rho} d\ell' \quad (2.36a)$$

where

$$\hat{\rho} = \cos\phi\hat{x} + \sin\phi\hat{y}, \quad \text{and} \quad (2.36b)$$

$$\phi = \tan^{-1}\left(\frac{y-y'}{x-x'}\right).$$

Now $\bar{E}^S(x,y)$ can be written as (from Equations (2.28), (2.29) and (2.36))

$$\begin{aligned} \bar{E}^S(x,y) = & -\frac{j\omega\mu_0}{2\pi} \iint_{CS} \bar{J}_{eq}(x',y') K_0(\gamma_2|\bar{\rho}-\bar{\rho}'|) ds' \\ & + \frac{\gamma_2}{j\omega 2\pi \hat{\epsilon}_2} \int_{\mathcal{L}} [\bar{J}_{eq}(\mathcal{L}') \cdot \hat{n}(\mathcal{L}')] K_1(\gamma_2|\bar{\rho}-\bar{\rho}'|) \hat{\rho} d\mathcal{L}'. \end{aligned} \quad (2.37)$$

The integral equation is formed by substituting for \bar{J}_{eq} from Equation (2.5) in Equation (2.37), transposing Equation (2.4) and substituting from Equation (2.37) to obtain

$$\begin{aligned} \bar{E}^i(x,y) = & \bar{E}^I(x,y) - \frac{\omega^2\mu_0(\hat{\epsilon}_1-\hat{\epsilon}_2)}{2\pi} \iint_{CS} \bar{E}^I(x',y') K_0(\gamma_2|\bar{\rho}-\bar{\rho}'|) ds' \\ & - \frac{\gamma_2(\hat{\epsilon}_1-\hat{\epsilon}_2)}{2\pi\hat{\epsilon}_2} \int_{\mathcal{L}} [\bar{E}^I(x',y') \cdot \hat{n}(\mathcal{L}')] K_1(\gamma_2|\bar{\rho}-\bar{\rho}'|) \hat{\rho} d\mathcal{L}'. \end{aligned} \quad (2.38)$$

The unknown function in the above integral equation is $\bar{E}^I(x,y)$, the field in region I. The unknown function appears both inside and outside the integral. To solve this integral equation, it is convenient to expand the total magnetic field inside the scatterer (region I) in terms of a set of basis function $F_n(x,y)$, thus

$$\vec{H}^I(x,y) = \sum_{n=1}^N C_n F_n(x,y) \hat{z} \quad , \quad (2.39)$$

Where the unknowns are the C_n 's.

Using Maxwell's equation we obtain the expansion for total electric field in Region I.

$$\vec{E}^I(x,y) = p \sum_{n=1}^N C_n \vec{F}_n(x,y) \quad . \quad (2.40a)$$

where

$$\vec{F}_n(x,y) = \hat{x} \frac{\partial F_n(x,y)}{\partial y} - \hat{y} \frac{\partial F_n(x,y)}{\partial x} \quad . \quad (2.40b)$$

$$p = \frac{1}{j\omega \hat{\epsilon}_1} \quad . \quad (2.40c)$$

It will be shown in future chapters that $\vec{F}_n(x,y)$ and p will be simplified for a proper choice of basis function.

Substituting Equation (2.40a) in Equation (2.38) yields

$$\vec{E}^I(x,y) = p \sum_{n=1}^N C_n \left[\vec{F}_n(x,y) - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{CS} \vec{F}_n(x,y) K_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds' \cdot \right. \\ \left. - \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2) \gamma_2}{2\pi \hat{\epsilon}_2} \int_{\ell} [\vec{F}_n(\ell') \cdot \hat{n}(\ell')] K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) \hat{\rho} d\ell' \right] \quad . \quad (2.41)$$

and again the C_n 's are the unknowns.

It is desired to obtain a set of simultaneous linear equations given by Equation (2.11) by implementing the reciprocity theorem of Equation (2.10), thus the Galerkin testing is used in above equation. The inner product of $\bar{F}_m(x,y)$ is formed with both sides of Equation (2.41), and integrated over the cross section of the scatterer.

Using Eq. (2.27), this yields

$$\begin{aligned} V_m &= \iint_{CS} \bar{F}_m(x,y) \cdot \bar{E}_i^i(x,y) ds \quad m=1,2,3,\dots, N \\ &= \frac{\gamma_2}{2\pi} \iint_{CS} \left(\frac{\partial \bar{F}_m(x,y)}{\partial y} \sin \phi_{LS} + \frac{\partial \bar{F}_m(x,y)}{\partial x} \cos \phi_{LS} \right) K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_s|) ds, \end{aligned} \quad (2.42)$$

and

$$\begin{aligned} Z_{mn} &= \rho \iint_{CS} \bar{F}_n(x,y) \cdot \bar{F}_m(x,y) ds - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \rho \iiint_{CS} \bar{F}_n(x',y') \\ &\quad \cdot \bar{F}_m(x,y) K_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds' ds - \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2) \gamma_2}{2\pi \hat{\epsilon}_2} \rho \iiint_{CS} \bar{F}_m(x,y) \\ &\quad \cdot \hat{\rho}[\bar{F}_n(\ell') \cdot \hat{n}(\ell')] K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) d\ell' ds. \end{aligned} \quad (2.43)$$

where ϕ_{LS} is defined in Equation (2.27b) and $\hat{\rho}$ is defined in Equation (2.36b).

The difficulty encountered in evaluating the above integrals is dependent upon the choice of the basis functions. The integration in the first term is rather straight forward since there is no singular points involved in the region. The integrals of second term of Equation

(2.43) involve a singular point (when $x=x'$ and $y=y'$) but it can be evaluated in the same manner discussed for Equation (2.13). Perhaps the most difficult term in Equation (2.43) to integrate is the third term. This term involves a set of singular points on the cross-section contour for the inner most integration around the cross-section contour, and another set of singular points in the cross-section for the outer most integration over the cross-section. It is suggested that when approximating the scatterer by a set of overlapping small circular cylinders, the surface charge density due to all cells be included and summed. For a rectangular cross-section, however, all the integrals of the Equations (2.42) and (2.43) can be evaluated in closed form for a proper choice of testing function. This will be illustrated in future chapters.

After numerically solving for C_n 's the scattered field can be found by

$$\bar{H}^S = \frac{1}{\mu_0} \nabla \times \bar{A}^S \quad . \quad (2.44)$$

where \bar{A}_S is given by Equation (2.29) and \bar{J}_{eq} is given by Equations (2.5) and (2.40a).

$$\bar{H}_{(x,y)}^S = \frac{j\omega\gamma_2(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \hat{\rho} \sum_{m=1}^N C_m \left[\iint_{CS} \bar{F}_m(x',y') \times \hat{\rho} K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds' \right] \hat{z} \quad . \quad (2.45a)$$

where

$$\bar{F}_n(x',y') \times \hat{\rho} = \hat{z} \left(\frac{\partial F_n(x',y')}{\partial y'} \sin \phi + \frac{\partial F_n(x',y')}{\partial x'} \cos \phi \right) \quad . \quad (2.45b)$$

Thus

$$\begin{aligned} \bar{H}^S(x,y) = & \frac{j\omega\gamma_2 \mathbf{p}(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sum_{m=1}^N C_m \left[\iint_{cs} \left(\frac{\partial F_m(x',y')}{\partial y'} \sin\phi \right. \right. \\ & \left. \left. + \frac{\partial F_m(x',y')}{\partial x'} \cos\phi \right) K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) ds' \right] \hat{z} . \end{aligned} \quad (2.46)$$

The above is valid for all scattering angles. However for backscattering, some computation time may be saved by using

$$\bar{H}^{B.S.}(x_s, y_s) = -j\omega p^2 (\hat{\epsilon}_1 - \hat{\epsilon}_2) \sum_{m=1}^N C_m V_m \hat{z} . \quad (2.47)$$

where V_m is given by Equation (2.42).

2. H_z-Plane Wave Incidence

Using expansions similar to those involving the E_z-Plane Wave incidence case, one may analyze a z-polarized plane magnetic field incident on the scatterer as shown in Figure 2-5. The incident fields are given by

$$\begin{aligned} \bar{H}^i &= \hat{z} H_0 e^{\gamma_2(x \cos\phi_i + y \sin\phi_i)} \\ \bar{E}^i &= n_2 (\bar{H}^i \times \hat{\rho}) = -n_2 e^{\gamma_2(x \cos\phi_i + y \sin\phi_i)} \hat{\phi}_i . \end{aligned} \quad (2.48a)$$

where $H_0 = 1$ is assumed and

$$\text{where } \hat{\phi}_i = -\hat{x} \sin\phi_i + \hat{y} \cos\phi_i , \quad (2.48b)$$

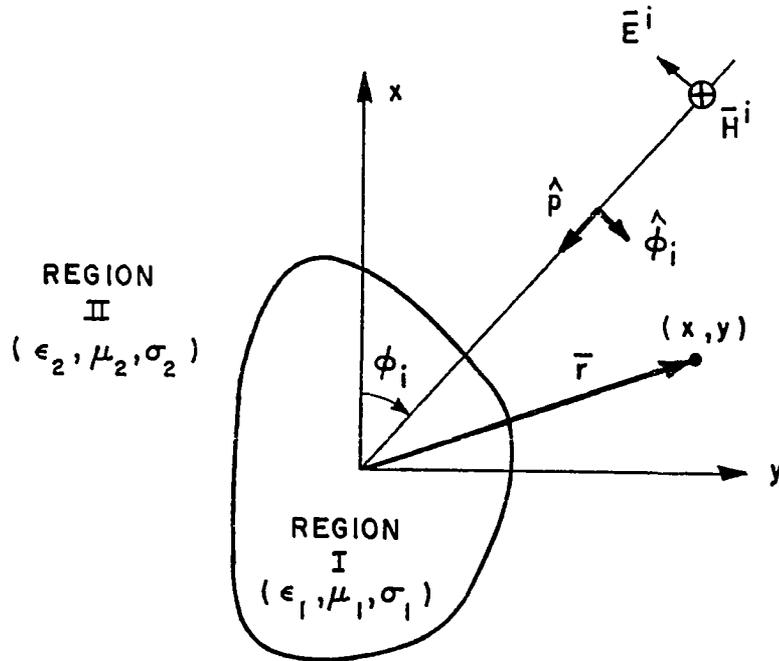


Figure 2-5. H_z -plane wave incident on the scatterer.

$\eta_2 = \sqrt{\frac{\mu_0}{\hat{\epsilon}_2}}$ is the the intrinsic impedance of homogeneous Region II.

From Equation (2.42).

$$V_m = \eta_2 \iint_{cs} \left(\frac{\partial F_m(x,y)}{\partial y} \sin \phi_i + \frac{\partial F_m(x,y)}{\partial x} \cos \phi_i \right) e^{\gamma_2(x \cos \phi_i + y \sin \phi_i)} ds . \quad (2.49)$$

To calculate the far zone scattered field, Equation (2.46) can be utilized where $K_1(\gamma_2 |\bar{p} - \bar{p}'|)$ is replaced by its asymptotic form and using a similar far field approximation as in Figure 2-3 and Equations (2.23) and (2.24) yields

$$\frac{\underline{s}}{H(\rho, \phi)} = \frac{j\omega\gamma_2\rho(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sqrt{\frac{\pi}{2\gamma_2}} \sum_{m=1}^N C_m \left[\iint_{CS} \left(\frac{\partial F_m(x', y')}{\partial y'} \sin\phi_s + \frac{\partial F_m(x', y')}{\partial x'} \cos\phi_s \right) e^{-\gamma_2(x' \cos\phi_s + y' \sin\phi_s)} ds' \right] \frac{e^{-\gamma_2\rho}}{\sqrt{\rho}} \hat{z} \quad (2.50)$$

ϕ_s is the angle of scattered field as shown in Figure 2-3. When $\phi_s = \phi_i$ the backscattered far field is given by

$$\frac{\underline{B.S.}}{H(\rho, \phi_s)} = \frac{j\omega\gamma_2\rho(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sqrt{\frac{\pi}{2\gamma_2}} \sum_{m=1}^N C_m V_m \frac{e^{-\gamma_2\rho}}{\sqrt{\rho}} \quad (2.60)$$

V_m is given by Equation (2.49).

In this chapter all the derivations have been very general and can be applied directly to any suitable two dimensional electromagnetic model by simply choosing a suitable expansion function. It is however essential that a stable convergence be obtained. Thus the first test to be made is a convergence test. In the following chapters these theories are applied to scattering by a two dimensional lossy dielectric rectangular cylinders hereafter referred to as rectangular cylinders. In each case a convergence test is included which exhibits the reliability of the numerical solution.

CHAPTER III

E-WAVE SCATTERING BY LOSSY DIELECTRIC RECTANGULAR CYLINDERS OF INFINITE LENGTH IN A LOSSY HOMOGENEOUS MEDIUM

A. INTRODUCTION

In this chapter, the plane wave expansion is introduced and an example of the convergence properties is given. Examples of typical scattered field patterns are presented for the cases of a lossy rectangular cylinder in a free space environment and for an air cylinder in a lossy ambient medium.

B. PLANE WAVE EXPANSION

The expansion of the field inside the cylinder in terms of a set of basis function F_n is given in Equation (2.8). The choice of F_n as a spectrum of plane waves is such that each F_n satisfies the Helmholtz wave equation inside the cylinder. Since the electric fields are z -directed, it is only necessary to treat the scalar problem. Thus the basis function equals

$$F_n(x,y) = e^{-jf_n x} e^{-jg_n y} \quad (3.1a)$$

From Equation (2.40b)

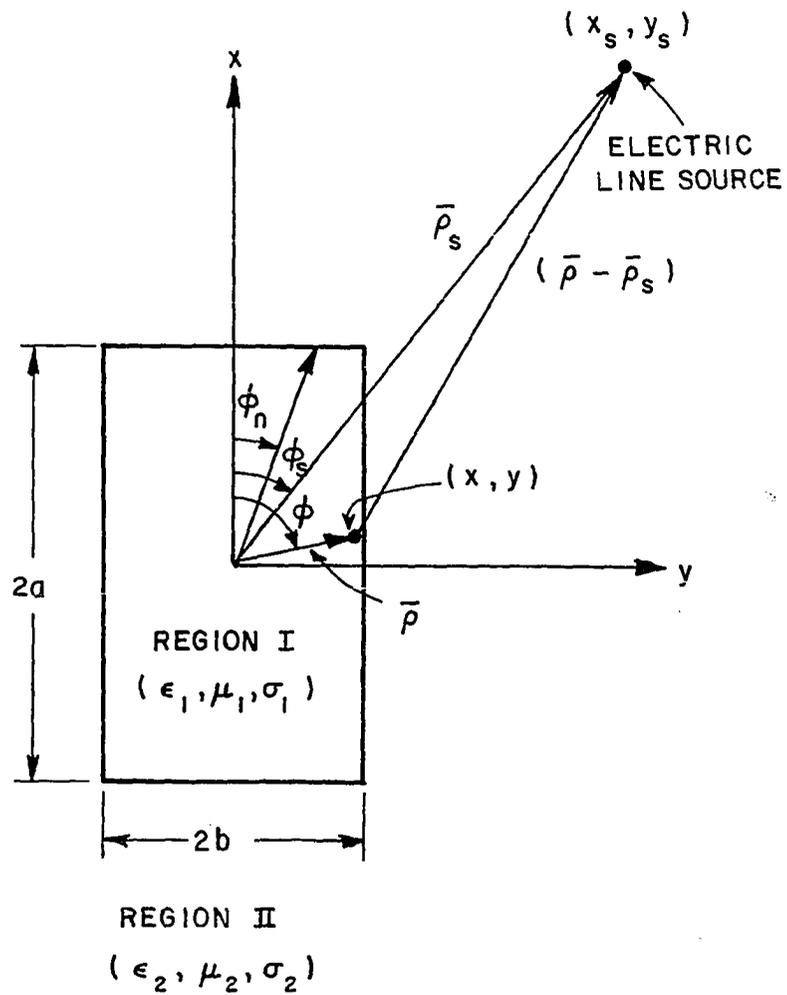


Figure 3-1. E-wave, electromagnetic scattering model for a lossy, dielectric rectangular cylinder of infinite length immersed in a lossy medium.

$$\begin{aligned}\bar{F}_n &= -jk_1(\cos\phi_n \hat{x} - \sin\phi_n \hat{y}) e^{-jf_n x} e^{-jg_n y} \\ &= -jk_1(\cos\phi_n \hat{x} - \sin\phi_n \hat{y}) F_n(x,y) \quad .\end{aligned}\quad (3.1b)$$

From the wave equation and Equation (3.1)

$$f_n^2 + g_n^2 = k_1^2 \quad , \quad (3.2a)$$

where

$$f_n = k_1 \cos\phi_n \quad , \quad (3.2b)$$

$$g_n = k_1 \sin\phi_n \quad , \quad (3.2c)$$

$$\phi_n = \frac{(n-1)}{N} 2\pi \quad , \quad (3.2d)$$

$$k_1 = \omega \sqrt{\mu_0 \hat{\epsilon}_1} \quad , \quad (3.2e)$$

$$\hat{\epsilon}_1 = \epsilon_0 \left(\epsilon_{r1} - j \frac{\sigma_1}{\omega \epsilon_0} \right) \quad , \quad (3.2f)$$

where ϕ_n is shown in Figure 3-1. Observe that once the number of terms N retained in this plane wave expansion is given, the individual F_n 's are completely specified, thus Equation (2.8) becomes

$$E_z^I(x,y) = \sum_{n=1}^N C_n e^{-jf_n x} e^{-jg_n y} \quad . \quad (3.3)$$

To obtain a set of simultaneous linear equations such as Equation (2.11), Equation (3.1) is substituted in Equations (2.12) and (2.13). The terms of the excitation column matrix now take the form

$$V_m = -\frac{j\omega\mu_0}{2\pi} \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} k_0(\gamma_2 |\bar{\rho} - \bar{\rho}_S|) dx dy ; m = 1, 2, \dots, N . \quad (3.4)$$

The impedance matrix

$$\begin{aligned} Z_{mn} &= \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} \int_{-a}^a \int_{-b}^b e^{-jf_n x'} e^{-jg_n y'} dx dy - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \int_{-a}^a \int_{-b}^b \int_{-a}^a \int_{-b}^b \\ &\quad e^{-jf_n x'} e^{-jg_n y'} e^{-jf_m x} e^{-jg_m y} k_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) dx' dy' dx dy \\ &= R_{mn} + S_{mn} . \end{aligned} \quad (3.5a)$$

The first integral may be integrated in closed form to obtain

$$R_{mn} = \frac{4 \sin[(f_m + f_n)a] \sin[(g_m + g_n)b]}{(f_m + f_n)(g_m + g_n)} . \quad (3.5b)$$

The second term of Equation (3.5a) is

$$S_{mn} = C_1 \int_{-a}^a \int_{-b}^b \int_{-a}^a \int_{-b}^b e^{-jf_n x'} e^{-jg_n y'} e^{-jf_m x} e^{-jg_m y} k_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|) dx' dy' dx dy , \quad (3.5c)$$

where

$$C_1 = -\frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} . \quad (3.5d)$$

To evaluate Equations (3.4) and (3.5c) we utilized the spectral transform of $k_0(\gamma_2 |\bar{\rho} - \bar{\rho}'|)$ is utilized

$$K_0(\gamma_2|\rho-\rho'|) = \int_0^\infty \frac{e^{-f|x-x'|} \cos[g(y-y')]}{f} dg \quad (3.6a)$$

From the wave equation

$$f^2 - g^2 = \gamma_2^2 \quad (3.6b)$$

Note that f and g should not be mistaken with f_n and g_n in Equation (3.2a).

This transform is easily obtained by redefining some parameters in the form given by Tyras [41].

Substituting Equation (3.6a) in Equation (3.4) with $x'=x_s$ and $y'=y_s$ and changing the order of integration one obtains

$$V_m = -\frac{j\omega\mu_0}{2\pi} \int_0^\infty \left[\frac{1}{f} \int_{-a-b}^a \int_{-a-b}^b e^{-jf_m x} e^{-jg_m y} e^{-f|x-x_s|} \cos g[(y-y_s)] dx dy \right] dg \quad (3.7)$$

The integration over the cross-section is easily evaluated in a closed form to obtain.

$$V_m = -\frac{j\omega\mu_0}{\pi} \int_0^\infty \frac{1}{f} (F_m \cdot GE_m^V) dg \quad (3.8a)$$

where

$$F_m = \left\{ \begin{array}{ll} \frac{\sin[(f_m+jf)a]}{(f_m+jf)} e^{-fx_s} & x_s > a \\ \frac{je^{-fx_s}}{2(f_m+jf)} (e^{-j(f_m+jf)x_s} - e^{j(f_m+jf)a}) & -a \leq x_s \leq a \\ + \frac{je^{+fx_s}}{2(f_m-jf)} (e^{-j(f_m-jf)a} - e^{-j(f_m-jf)x_s}) & \\ \frac{\sin[(f_m-jf)a]}{(f_m-jf)} e^{fx_s} & x_s < -a \end{array} \right. \quad (3.8b)$$

and

$$GE_m^v = e^{-jgy_s} \frac{\sin[(g_m-g)b]}{(g_m-g)} + e^{jgy_s} \frac{\sin[(g_m+g)b]}{(g_m+g)} \quad (3.8c)$$

Thus the only remaining integration is the $\int_0^\infty dg$ which will be encountered frequently throughout this dissertation. This integration must be evaluated rather carefully, and it will be fully discussed in Chapter V.

To evaluate S_{mn} in Equation (3.5c), Equation (3.6a) is substituted into Equation (3.5c). Rearranging the order of integrations yields

$$S_{mn} = C_1 \int_0^\infty \frac{1}{T} \left[\int_{-a}^a \int_{-a}^a \int_{-a}^a \int_{-a}^a e^{-jfnx'} e^{-jgn'y'} e^{-jfm'x} e^{-jgm'y} e^{-f|x-x'|} \cos g[(y-y')] dx' dy' dx dy \right] dg \quad (3.9)$$

The integrations on y and y' are easily evaluated. The integration on x can be evaluated by integrating first, from $-a$ to x' where $|x'-x|=(x'-x)$, and then from x' to a , where $|x-x'|=(x-x')$. The result, dependent only on x' , is readily evaluated to obtain

$$S_{mn} = 4C_1 \int_0^{\infty} \frac{1}{f} (FE_{mn} \cdot GE_{mn}) dg \quad , \quad (3.10a)$$

where

$$FE_{mn} = j \left[\frac{\sin[(f_m+f_n)a]}{(f_n+jf)(f_m+f_n)} - e^{j(f_n+jf)a} \frac{\sin[(f_m-jf)a]}{(f_n+jf)(f_m-jf)} \right. \\ \left. + e^{-j(f_n-jf)a} \frac{\sin[(f_m+jf)a]}{(f_n-jf)(f_m+jf)} - \frac{\sin[(f_m+f_n)a]}{(f_n-jf)(f_m+f_n)} \right] \quad , \quad (3.10b)$$

and

$$GE_{mn} = \frac{\sin[(g_n+g)b]\sin[(g_m-g)b]}{(g_n+g)(g_m-g)} + \frac{\sin[(g_n-g)b]\sin[g_m+g)b]}{(g_n-g)(g_m+g)} \quad . \quad (3.10c)$$

The scattered field can be obtained by substituting Equations (3.1) and (3.6) in Equation (2.16) and evaluating the integrals.

$$E_z^s(x,y) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{\pi} \sum_{m=1}^N C_m \int_0^{\infty} \frac{1}{f} (F_m \cdot GE_m^V) dg \quad . \quad (3.11)$$

where F_m is given by Equation (3.8b) and $G E_m^V$ is given by Equation (3.8c) by replacing y_S by y . The above equation is valid for all scattering angles. For the backscattered case, i.e., $(x,y)=(x_S,y_S)$, the following may also be used.

$$E_{z(x_S,y_S)}^{B.S.} = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{\pi} \sum_{m=1}^N C_m V_m \quad . \quad (3.12)$$

V_m is given by Equation (3.8a). The far zone scattered field can be calculated using Equation (2.23), and Equation (3.1). In addition, Equations (2.25) and (3.8a) may be used to calculate the far zone backscattered field.

C. CONVERGENCE

Two computer programs were developed based on the moment method formulation given above. These programs are included in the Appendices A and B. To evaluate the number of plane waves required in the expansion of Equation (3.3), the program is run for increasing values of N . A typical result is given in Figure 3-2. This example gives the relative backscattered field in the form of the scattering attenuation function (SAF) [42]. The SAF is the normalized scattered field obtained by dividing the scattered field by the fields of an imaged line source in a ground plane positioned at the center of the scatterer. For the rectangular scatterer under consideration, the pictorial definition of the ground plane is shown in Figure 3-3a for backscattered case, and Figure 3-3b for bistatic case. In these figures, the ground plane is

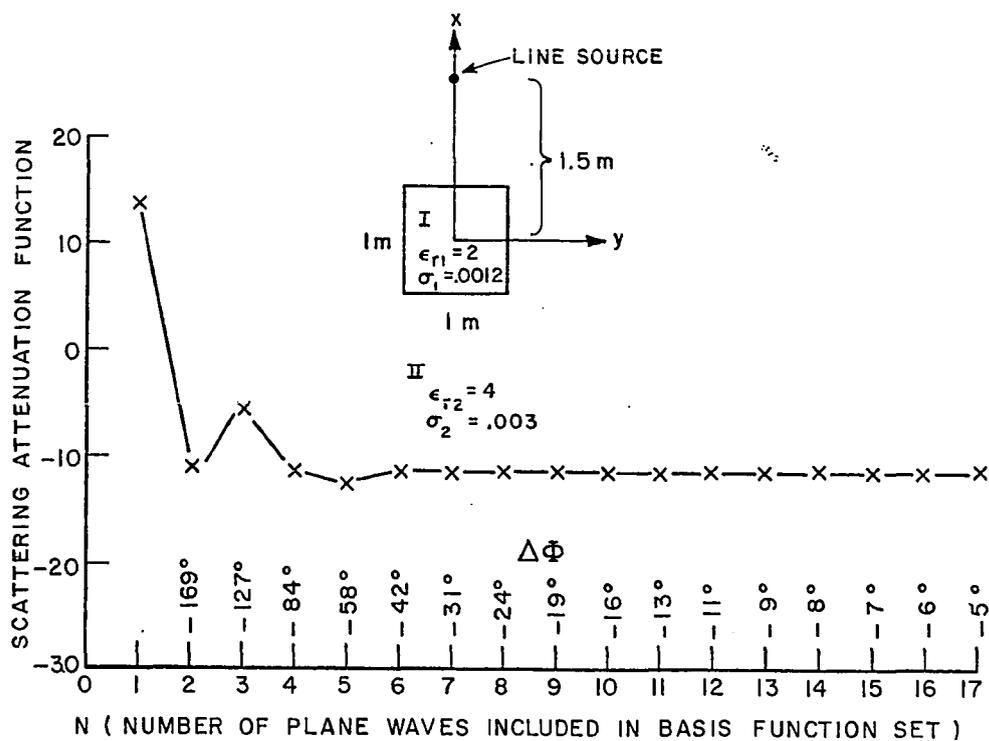


Figure 3-2. Convergence Curve for the RTUNLE or RCYLEGP computer program which uses plane wave expansion Galerkin method at 100MHz. Scattering Attenuation Function is plotted as a function of N the number of plane waves in the expansion.

specified by the plane which includes the z-axis, and is normal to the bisector of the angle between $\bar{\rho}_S$ and $\bar{\rho}$, $(\phi - \phi_S)$.

The scatterer is a 1m square cylinder with relative permittivity of $\epsilon_{r1}=2$ and conductivity of .0012 s/m. A line source is located at $x_S=1.5m$ and $y_S=0m$ in a homogeneous medium with $\epsilon_{r2}=4$. and $\sigma_2=.003$ s/m. As the number of plane waves N, used to represent the field inside the cylinder is increased, the solution converges to a single value. Figure 3-2 indicates that N=6 is sufficient to obtain a reasonably accurate solution for the particular case.

A convenient way to determine N at which convergence may occur can be based on the phase difference between the plane wave traveling in the x-direction (i.e., $\phi_1=0$ direction. See Equations (3.1) to (3.3)), and its neighboring plane wave traveling in $\phi_2=2\pi/N$ direction. This may be expressed as follows

$$E_1 = e^{-j\beta_1(x\cos\phi_1+y\sin\phi_1)} \Bigg|_{\phi_1=0} = e^{-j\beta_1x} \quad (3.13a)$$

and

$$E_2 = e^{-j\beta_1(x\cos\phi_2+y\sin\phi_2)} \Bigg|_{\substack{y=0 \\ \phi_2=\frac{2\pi}{N}}} = e^{-j\beta_1x\cos\left(\frac{2\pi}{N}\right)} \quad (3.13b)$$

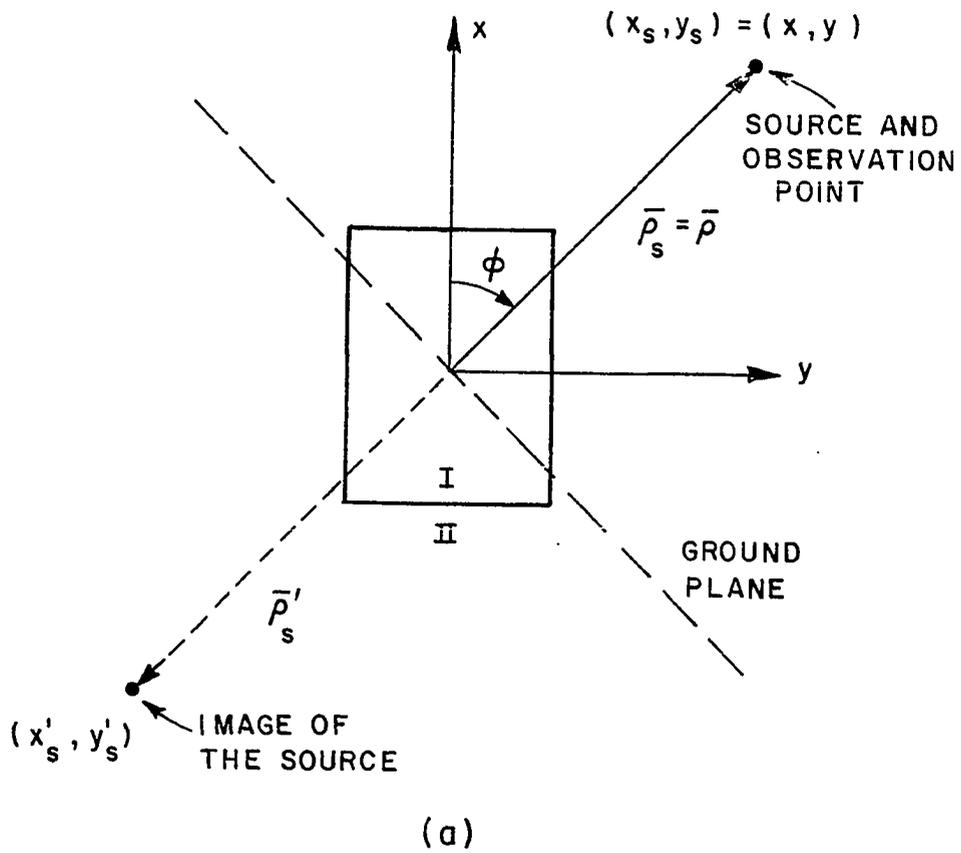


Figure 3-3. Pictorial definition for the Scattering Attenuation Function a) backscattered, b) bistatic scattering.

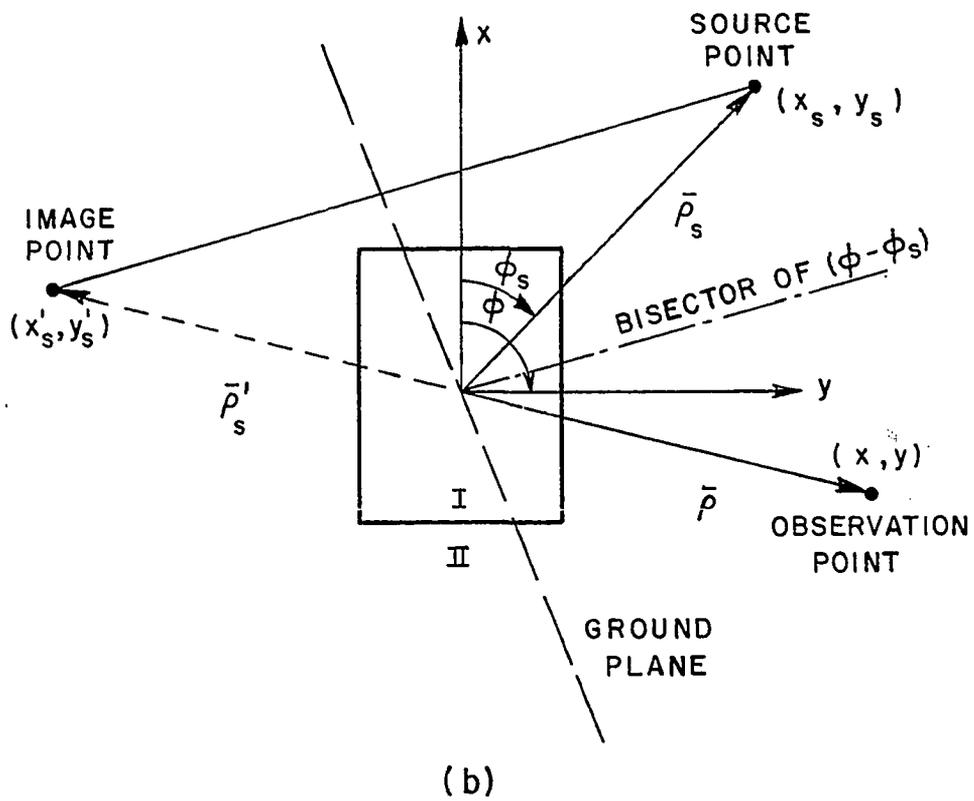


Figure 3-3. (continued)

where $\gamma_1 = \alpha_1 + j\beta_1$ and $\alpha_1 = 0$ is assumed without loss of generality. The phase difference between E_1 and E_2 at $x=a$ ($a > b$) is assumed as shown in Figure 3-1) is

$$\Delta\phi = -\beta_1 a \left(1 - \cos\left(\frac{2\pi}{N}\right)\right) \quad (3.14)$$

This phase difference may be arbitrarily chosen, thus, a value for N can be calculated. Experimentally, it was determined that $\Delta\phi = -\pi/5$ is an initial suitable phase difference. N is now given by

$$N = \text{Integer} \left[\frac{2\pi}{\cos^{-1}\left[1 - \frac{\pi}{5\beta_1 a}\right]} \right] \geq 4 \quad (3.15)$$

Determination of N from Equation (3.15) is dependent on " a " and " β_1 " the phase constant inside the cylinder. The " ≥ 4 " in Equation (3.15) suggests that there should be at least four plane waves in the expansion. For various values of N , $\Delta\phi$ is calculated from Equation (3.14) and is plotted in Figure 3-2.

D. BACKSCATTERED FIELD

1. Far Zone

The first example for which the backscattered fields are to be computed is a 1m by .5m rectangular scatterer with $\epsilon_{r_1} = 4$, $\sigma_1 = .3\text{ms/m}$ which is located in a free space environment. A z-polarized plane wave is incident on this scatterer at an angle ϕ_i , as is shown in Figure 3-4. The echo width pattern is given in Figure 3-4. The frequency used is

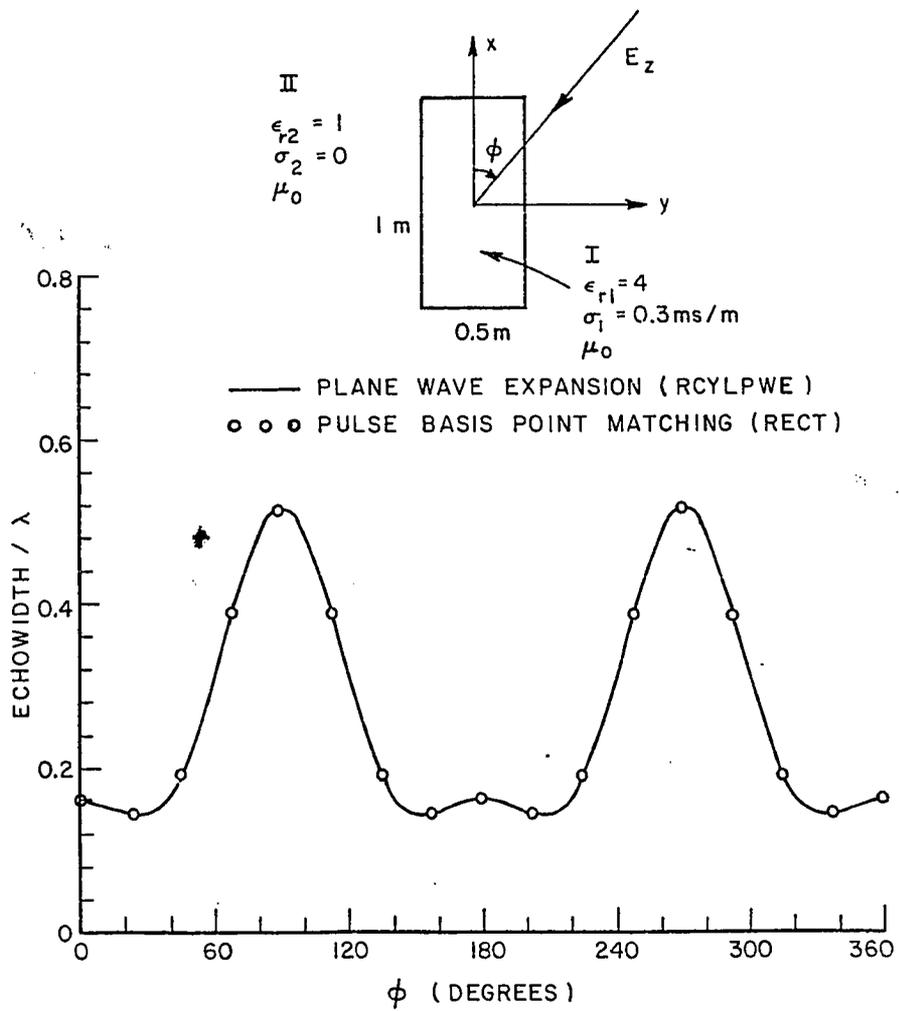


Figure 3-4. Far zone backscattered pattern for plane wave incidence at 100 MHz.

100MHz and is used throughout the remainder of this section unless specified otherwise. The maximum backscattered field is obtained when the plane wave is incident along y or -y axis ($\phi_i=90^\circ$ or $\phi_i=270^\circ$). There is comparatively smaller backscattering at x and -x direction ($\phi_i=0^\circ$ and 180°). The results of pulse basis point matching program [43] is also included for comparison which shows excellent agreement with the plane wave expansion result.

2. Near Zone

As a second example, consider a 1.m by .5m air filled rectangular cylinder located in a homogeneous dielectric medium with $\epsilon_{r_2}=4$. and $\sigma_2=.3\text{ms/m}$ as shown in the model of Figure 3-5. The electric line source is placed at the radial distance of $\rho=2\text{m}$ and the relative backscattered field is calculated as a function of ϕ_j . The SAF versus ϕ_j is shown in Figure 3-5. The result of an alternative computer program (RCYLPWE) is also included which shows a 1db discrepancy. The program RCYLPWE is included in Appendix A along with a complete description.

E. BISTATIC SCATTERING

1. Far Zone

The complete scattering patterns for three cases of plane wave incidences at $\phi_i=0^\circ$, 45° , and 90° , and for a 1m by .5m rectangular

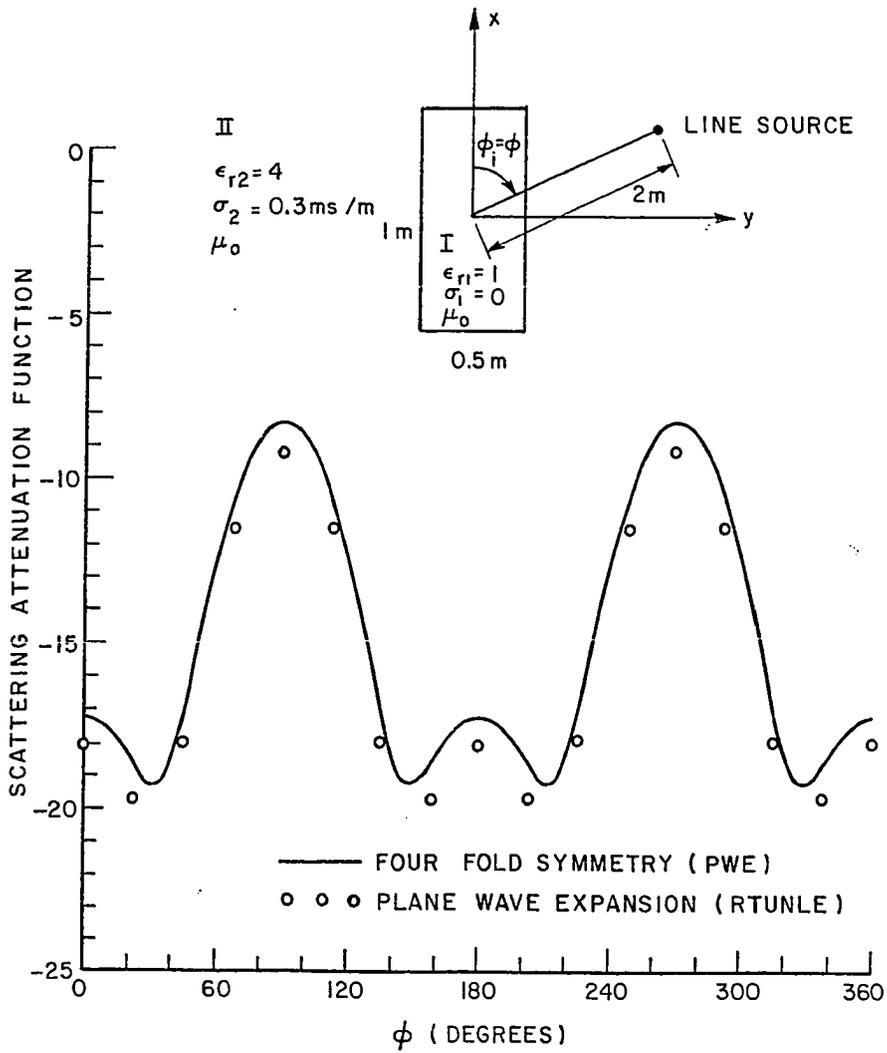


Figure 3-5. Near zone backscattering pattern for the model shown above. The line source is placed at $\rho_s=2m$. the frequency is 100 MHz.

cylinder have been computed and given in Figures 3-6, 3-7, and 3-8, respectively. The bistatic pattern for a z-polarized plane wave incident along x-axis ($\phi_i=0^\circ$) is shown in Figure 3-6. A strong forward scattered lobe is indicated at $\phi=180^\circ$. This lobe will shift and the symmetry will be altered if ϕ_i is changed. For example, at $\phi_i=45^\circ$ (see Figure 3-7) the symmetry is no longer maintained because of the non-symmetric physical situation. The maximum is now obtained around $\phi=210^\circ$. Initially, this result seemed suspicious since the maximum value of the scattered field is not in the forward direction and thus prompted further investigations. Some approximate methods were considered and proved not useful. Some of these methods will be discussed in a future section. Richmond's pulse basis point matching showed excellent agreement and is also shown in Figure 3-7. If we further increase the incidence angle to 90° so that now the plane wave is incident along y-axis, the symmetry is obtained about $\phi=270^\circ$ where the main forward lobe is maximum. This is shown in Figure 3-8 along with the pulse basis point matching result which indicates excellent agreement.

2. Near Zone

The three cases considered here place the line source at $(\rho_s, \phi_s)=(2m, 0^\circ)$, $(\rho_s, \phi_s)=(2m, 45^\circ)$, and $(\rho_s, \phi_s)=(2m, 90^\circ)$ which are analogous to $\phi_i=0^\circ$, 45° , and 90° considered in the previous section. A 1m by .5m air filled rectangular cylinder is located in a homogeneous

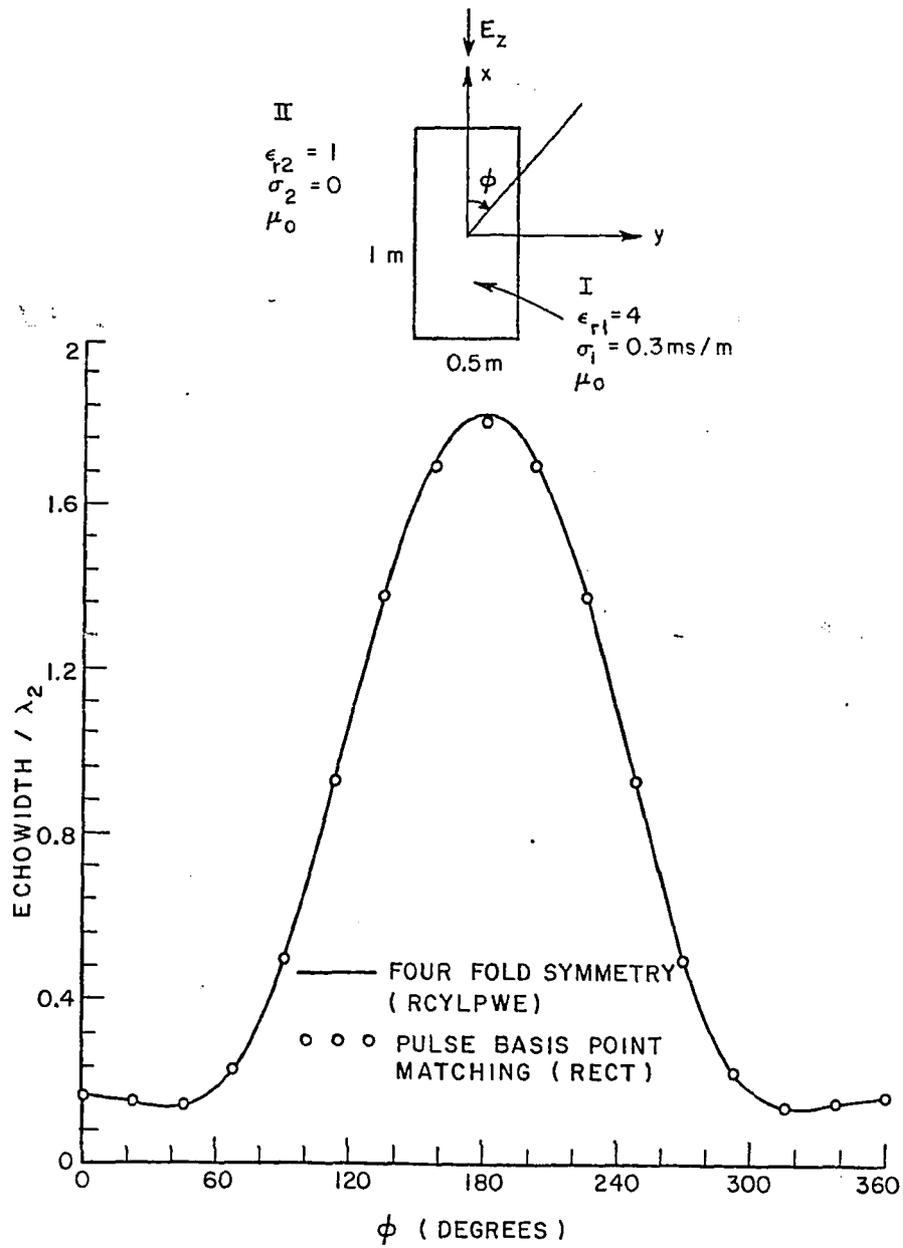


Figure 3-6. Far zone bistatic scattering pattern for a plane wave incident at $\phi_i = 0^\circ$, at 100 MHz.

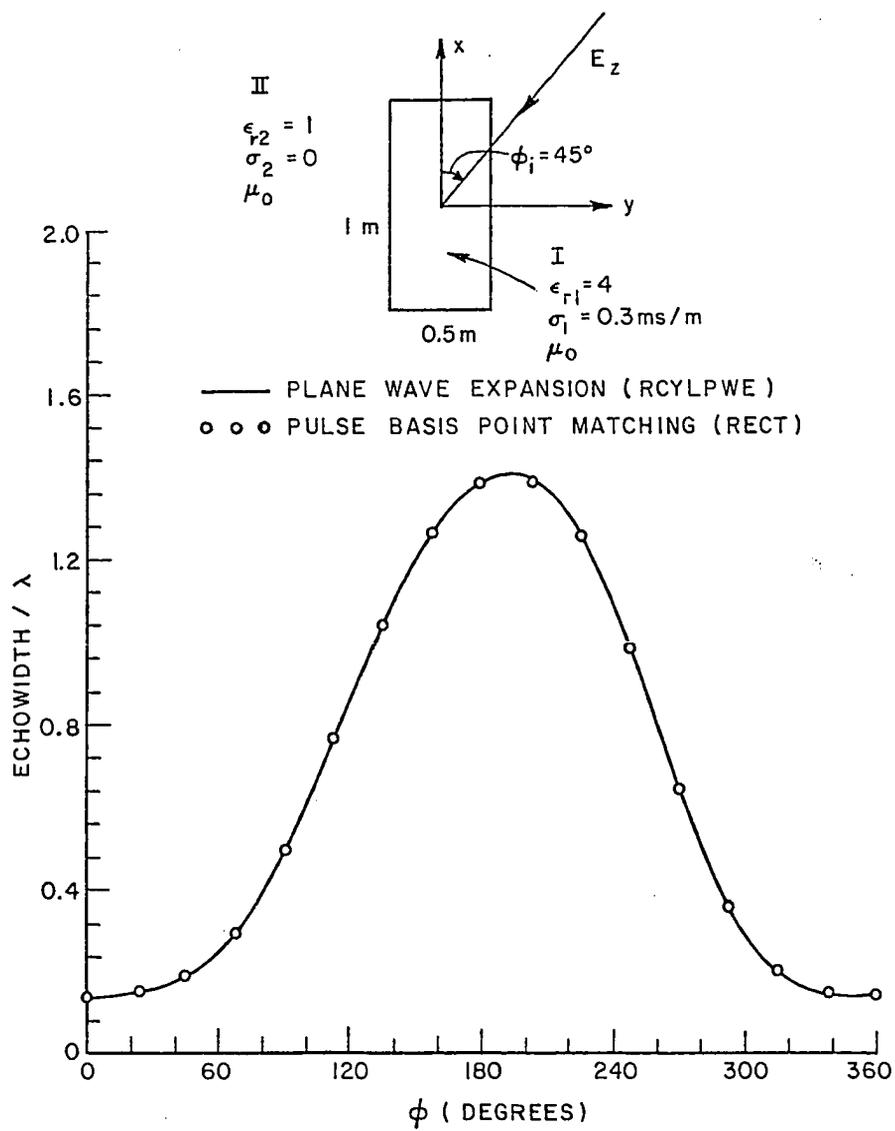


Figure 3-7. Far zone bistatic scattering pattern for a plane wave incident at $\phi_i=45^\circ$, at 100 MHz.

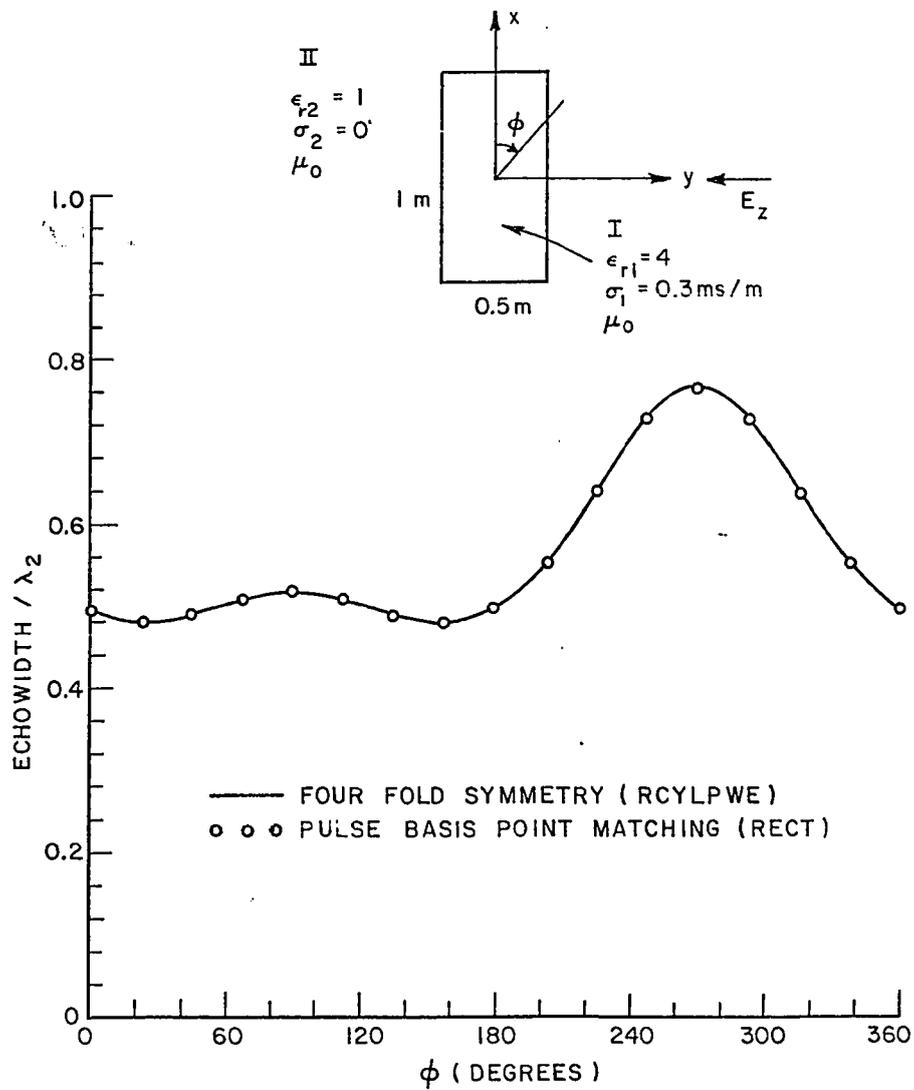


Figure 3-8. Far zone bistatic scattering pattern for a plane wave incident at $\phi_i=90^\circ$, at 100 MHz.

medium of $\epsilon_{r_2} = 4$. and $\sigma_2 = .3\text{ms/m}$. The results are shown in Figure 3-9, 3-10, and 3-11.

The field is observed at a radial distance of $\rho = 2\text{m}$. Figure 3-9 shows the bistatic pattern when the line source is located at $(\rho_S, \phi_S) = (2\text{m}, 0^\circ)$ as a function of observation angle ϕ . This pattern shows large forward scattering and small backlobe. The pattern is symmetric about $\phi = 180^\circ$ as expected. When the line source is moved to $(\rho_S, \phi_S) = (2\text{m}, 45^\circ)$, the shape of the pattern is changed and the symmetry is no longer maintained, and the main lobe is shifted to around $\phi = 240^\circ$ as may be observed in Figure 3-10. Figure 3-11 shows the bistatic pattern for the line source at $(\rho_S, \phi_S) = (2\text{m}, 90^\circ)$. A strong forward lobe and a smaller back lobe is observed ($\phi = 270^\circ$ and $\phi = 90^\circ$ respectively). The pattern is now symmetric about $\phi = 270^\circ$. Also included in Figures 3-9, 3-10, and 3-11 are the results of RCYLPWE which show good agreement in each case. The slight discrepancy is due to the nature of the numerical techniques used.

F. SCATTERING VERSUS FREQUENCY

In this section three line source locations are considered. In each case the frequency is varied from 10MHz up to 300MHz and the Scattering Attenuation Function is calculated.

A 1.m by .5m air filled rectangular cylinder is immersed in a homogeneous medium with $\epsilon_{r_2} = 4$. and $\sigma_2 = .003\text{s/m}$. Figure 3-12 shows backscattered SAF versus frequency for three line source locations. The

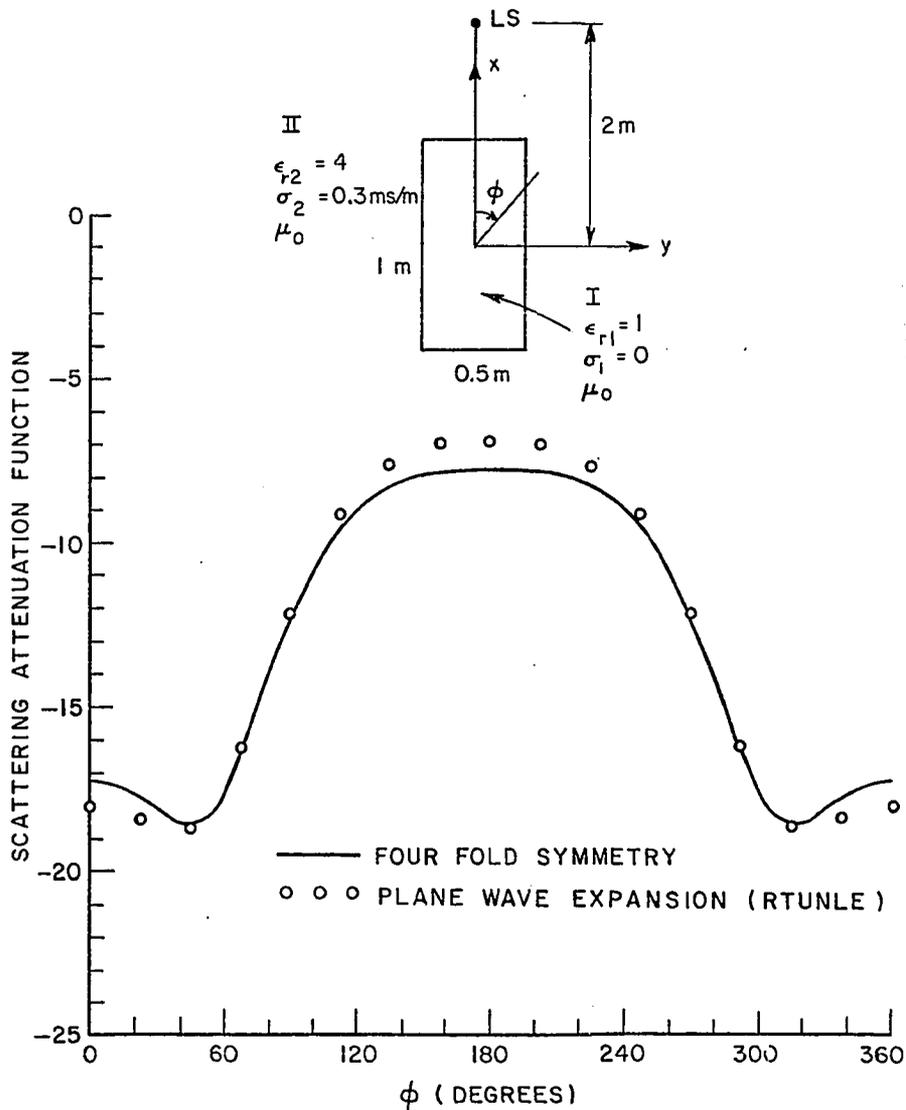


Figure 3-9. Near zone bistatic scattering pattern for an electric line source excitation placed at $(\rho_s, \phi_s) = (2m, 0^\circ)$ and at 100 MHz. The observation point is at $\rho = 2m$.

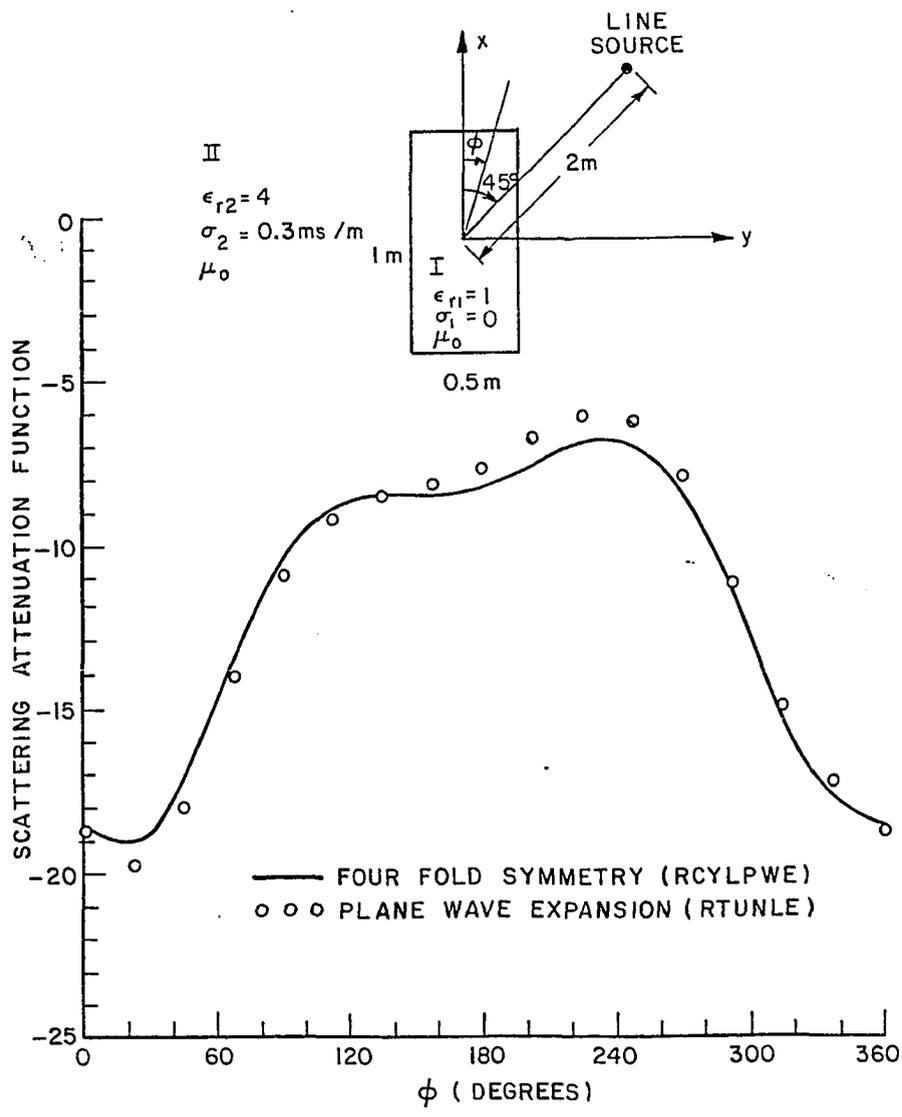


Figure 3-10. Near zone bistatic scattering pattern for an electric line source excitation placed at $(\rho_S, \phi_S) = (2\text{m}, 45^\circ)$ and at 100 MHz. The observation point is at $\rho = 2\text{m}$.

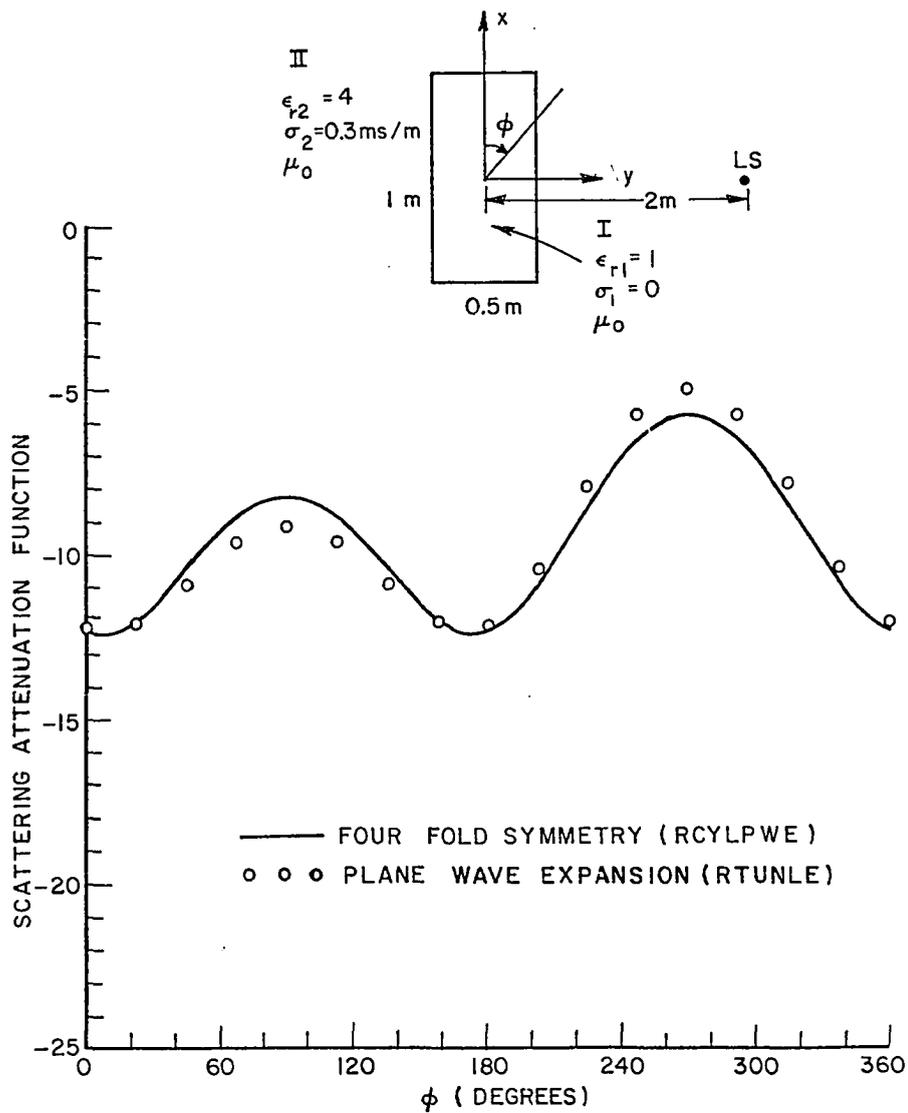


Figure 3-11. Near zone bistatic scattering pattern for an electric line source placed at $(\rho_S, \phi_S) = (2 \text{ m}, 90^\circ)$ and at 100 MHz. The observation point is at $\rho = 2 \text{ m}$.

dashed line shows the SAF versus frequency for a line source located at $(\rho_S, \phi_S) = (2m, 0^\circ)$. The solid line shows the SAF versus frequency for a line source located at $(\rho_S, \phi_S) = (2m, 45^\circ)$, and the dash-dot line shows the SAF versus frequency for a line source located at $(\rho_S, \phi_S) = (2m, 90^\circ)$. at low frequencies the rectangular scatterer looks the same to an observer at the observation point. This is the so called Rayleigh region.

In addition to moment method, two approximate methods were investigated consisting of an aperture integration solution and physical optics type of solution for dielectrics. For aperture integration approach, an aperture is defined, the Equivalence currents J_e densities are determined [44] and integrated to give the scattered field. To calculate the far zone backscattered field using this approach the aperture is defined as shown in Figure 3-13. The aperture field is the total reflected field evaluated at the aperture and the equivalent currents are $\vec{J}_e = 2\hat{n} \times \vec{H}$. The scattered field obtained by this method is shown in Figure 3-13. This does not agree with the moment method results. The physical optics approximation assumes the field in the scatterer is the same as that of a infinite slab of the same thickness (i.e., dielectric slab with thickness of $2b$) [45]. Using the physical optics, a volumetric polarization current is defined and integrated to give the scattered field. The far zone backscattered field obtained by physical optics is given in Figure 3-13. This result agrees well with the aperture integration result, but does not agree with the moment method solution.

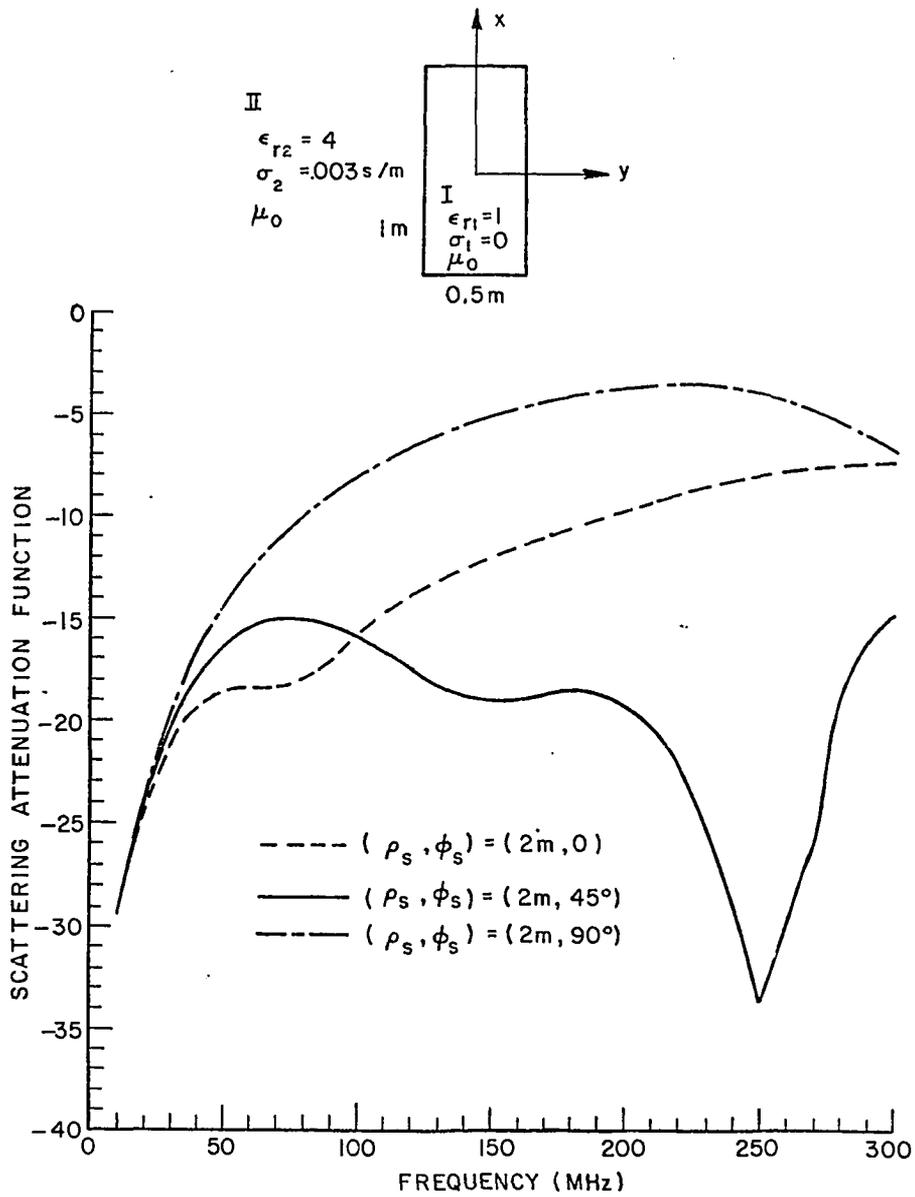


Figure 3-12. Near zone backscattering versus frequency for electric line source excitations placed at $(\rho_s, \phi_s) = (2\text{ m}, 0^\circ)$, $(2\text{ m}, 45^\circ)$, and $(2\text{ m}, 90^\circ)$.

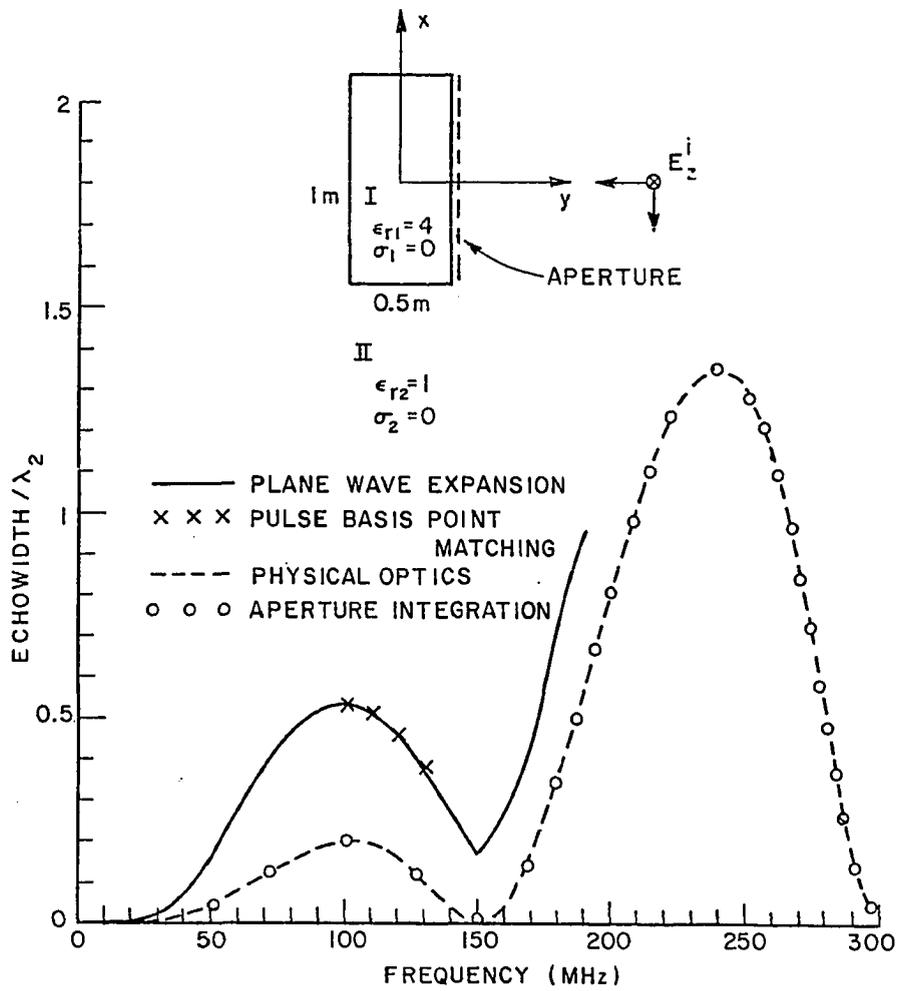


Figure 3-13. Far zone backscattering versus frequency for a plane wave incident at $\phi_i = 90^\circ$.

An analogous set of curves as Figure 3-13 is obtained for the forward scattering case, and is shown in Figure 3-14. The aperture defined for forward scattering is also shown in Figure 3-14. The aperture field is the difference of the total transmitted field and the incident field evaluated at the aperture. The aperture field and physical optics results for forward scattering shown in Figure 3-14 agree more closely with the moment method solution than the analogous results for backscattering.

Finally, a comparison is given in Figure 3-15 between a moment method solution for scattering by a 1.m-square air filled cylinder immersed in a homogeneous medium with $\epsilon_r = 4$, and $\sigma = .003\text{s/m}$ and an exact solution for an equivalent (equal cross-sectional areas) air-filled circular cylinder immersed in the homogeneous medium of the same electrical parameters as given above. These geometries are shown in Figure 3-15. For low frequencies as one may expect the two scatterers are not distinguished. This provides a good check on the validity of the moment method solution.

G. SUMMARY

In this chapter, the mathematical formulation for E-wave scattering by a two-dimensional lossy dielectric rectangular cylinder immersed in a lossy homogeneous medium was presented. A convergence curve was included and some numerical results were presented and discussed. A comparison between a moment method solution for a square cylinder and an exact solution for an equivalent circular cylinder was included.

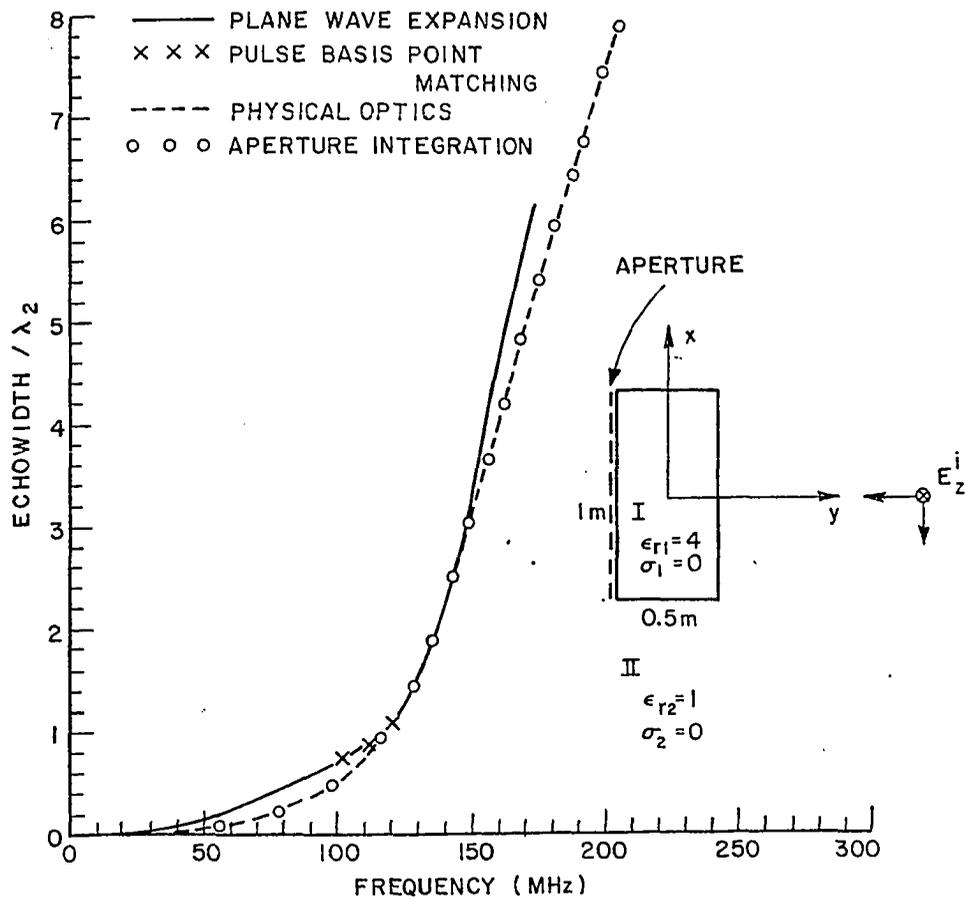


Figure 3-14. Far zone forward scattering versus frequency for a plane wave incident at $\phi_i = 90^\circ$.

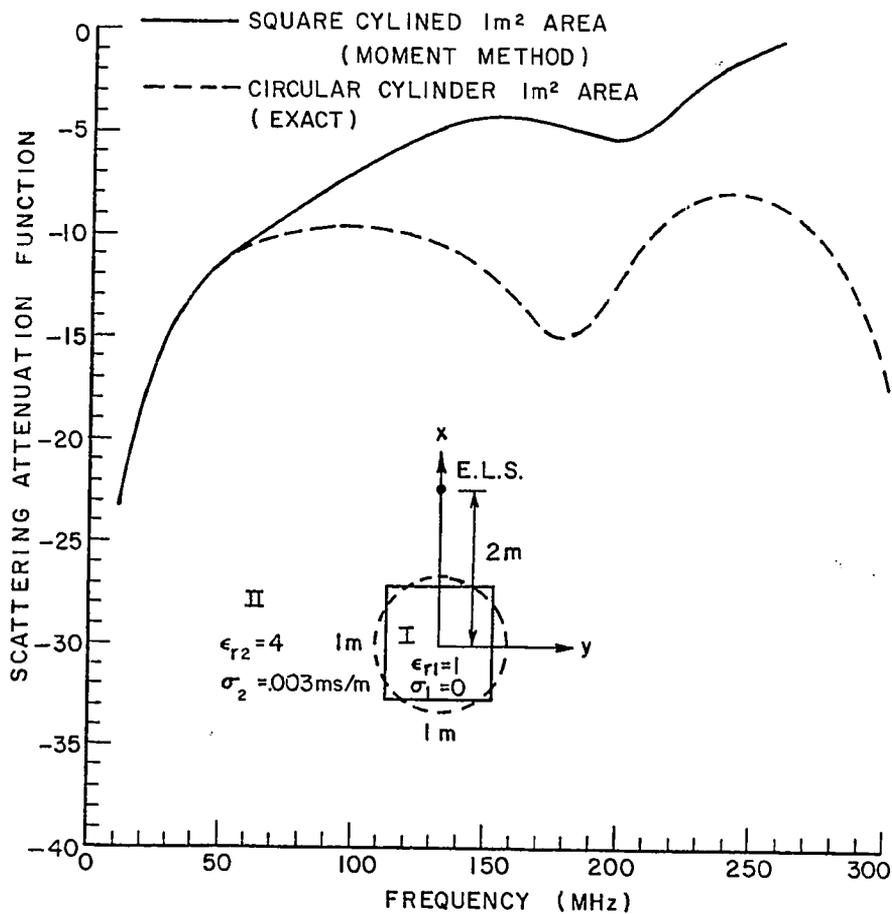


Figure 3-15. Comparison of backscattering versus frequency for a 1 m square cylinder and an equivalent cross-section area circular cylinder. The electric line source is located at $(\rho_s, \phi_s) = (2m, 0^\circ)$.

In the next chapter, the H-wave scattering by a two-dimensional lossy dielectric rectangular cylinder is treated.

CHAPTER IV

H-WAVE SCATTERING BY LOSSY, DIELECTRIC RECTANGULAR CYLINDERS OF INFINITE LENGTH, IN A LOSSY HOMOGENEOUS MEDIUM

A. INTRODUCTION

In this chapter, the plane wave expansion is applied to the H-wave scattering formulation presented in Chapter II. Some examples of the convergence properties are given. Examples of typical scattered field patterns are presented for cases of a lossy rectangular cylinder in a free space environment and for an air cylinder in a lossy ambient medium.

B. PLANE WAVE EXPANSION

The general moment method formulation for H-wave scattering by dielectric cylinders presented in Chapter II is specialized to analyze the geometry depicted in Figure 4-1, where, a $(2a)$ by $(2b)$ lossy dielectric rectangular cylinder of infinite length with the electrical parameters $\epsilon_1, \sigma_1, \mu_1$ is immersed in homogeneous medium whose electrical parameters are $\epsilon_2, \sigma_2, \mu_2$. The source is a time harmonic, infinite magnetic line source placed at (x_s, y_s) or (ρ_s, ϕ_s) .

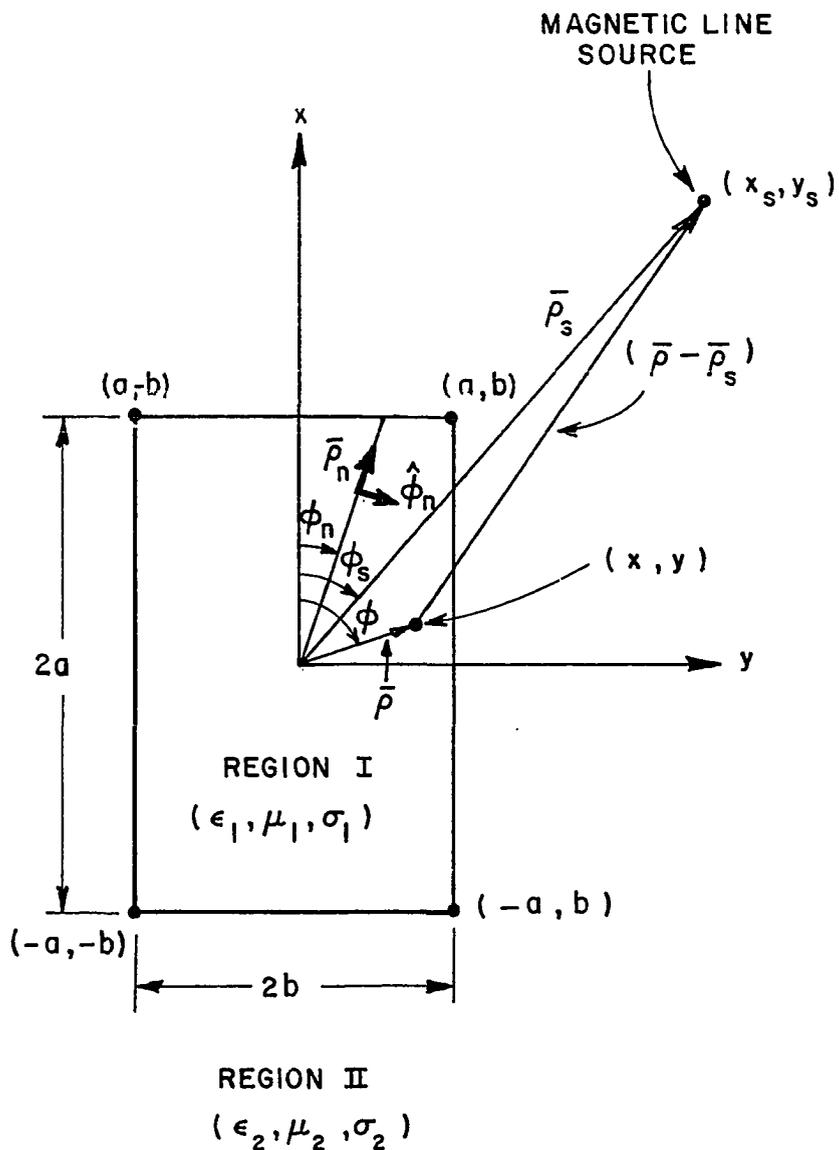


Figure 4-1. H-wave electromagnetic scattering model for a lossy dielectric rectangular cylinder of infinite length immersed in a lossy homogeneous medium.

As shown in Figure 4-1, the z-axis constitutes the cylinder axis. The magnetic fields inside this cylinder are expanded in terms of a set of basis function $F_m(x,y)$ similar to Equation (3.3). Choosing the plane wave basis function given in Equation (3.1) one obtains

$$H_z^I(x,y) = \sum_{n=1}^N C_n e^{-jf_n x} e^{-jg_n y} \quad (4.1)$$

For this plane wave expansion,

$$\vec{E}^I(x,y) = \eta_1 \sum_{n=1}^N C_n e^{-jf_n x} e^{-jg_n y} \hat{\phi}_n, \quad (4.2)$$

where

$$\hat{\phi}_n = -x \sin \phi_n + y \cos \phi_n \quad (4.3)$$

$\hat{\phi}_n$ is the unit vector associated with n^{th} plane wave traveling in direction of $\hat{\rho}_n = \hat{x} \cos \phi_n + \hat{y} \sin \phi_n$ as shown in Figure 4-1 and η_1 is the intrinsic impedance of Medium I.

It is desired to obtain a set of simultaneous linear equations as given by Equation (2.11). To obtain the elements of the voltage matrix column (V_m). Equations (3.1b) and (2.27a) are substituted in Equation (2.42) to obtain

$$V_m = \frac{-\gamma_2}{2\pi\eta_1} \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_S|) \cos(\phi_m - \phi_{LS}) dx dy, \quad (4.4)$$

where ϕ_{LS} is defined in Figure 2-4.

Equation (2.43) for Z_{mn} may be expressed as the sum of three terms

$$Z_{mn} = R'_{mn} + S'_{mn} + T_{mn} \quad . \quad (4.5a)$$

The evaluation of R'_{mn} and S'_{mn} is similar to Equations (3.5b) and (3.5c) respectively. Using Equations (3.1b) and (2.43), the equations for R'_{mn} and S'_{mn} are reduced to

$$R'_{mn} = \cos(\phi_m - \phi_n) R_{mn} \quad , \quad (4.5b)$$

and

$$S'_{mn} = \cos(\phi_m - \phi_n) S_{mn} \quad . \quad (4.5c)$$

R_{mn} and S_{mn} are given by Equations (3.5b) and (3.10a) respectively.

The remaining term in Equation (4.5a) is obtained using Equation (3.16) in the last term of Equation (2.43)

$$T_{mn} = C_2 \int_{-a}^a \int_{-b}^b \int_{\ell}^{\ell} \left[e^{-jf_n x'} e^{-jg_n y'} \left((\hat{\phi}_n \cdot \hat{n}(\ell')) \right) \right] e^{-jf_m x} e^{-jg_m y} (\hat{\phi}_m \cdot \hat{\rho}) K_1(\gamma_2 |\bar{\rho} - \bar{\rho}'|) d\ell' dx dy \quad . \quad (4.5d)$$

where

$$C_2 = - \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2) \gamma_2}{2\pi \hat{\epsilon}_2} \quad , \quad (4.5e)$$

and V_m and Z_{mn} have been normalized by $(-jk_1 \eta_1)$.

Integrations in Equations (4.4) and (4.5d) are evaluated to a closed form by using the transform of the modified Bessel function

$K_1(\gamma_2|\bar{\rho}-\bar{\rho}'|)$. Taking the gradient of both sides of Equation (3.6a) yields

$$K_1(\gamma_2|\bar{\rho}-\bar{\rho}'|)\cos\phi = \frac{1}{\gamma_2} \int_0^\infty \frac{f \operatorname{sgn}(x-x') e^{-f|x-x'|} \cos[g(y-y')] dg}{f} \quad (4.6a)$$

$$K_1(\gamma_2|\bar{\rho}-\bar{\rho}'|)\sin\phi = \frac{1}{\gamma_2} \int_0^\infty \frac{g e^{-f|x-x'|} \sin[g(y-y')] dg}{f} \quad (4.6b)$$

f and g are given in Equation (3.6b).

To evaluate Equation (4.4), the above two relations are used with $\phi = \phi_{LS}$, $\rho' = \rho_S$, $x' = x_S$ and $y' = y_S$. Changing the order of integrations yields

$$V_m = \frac{-1}{2\pi\eta_1} \int_0^\infty \frac{1}{f} \left[f \cos\phi_m \int_{-a-b}^a \int_{-a-b}^b e^{-jf_m x} e^{-jg_m y} \operatorname{sgn}(x-x_S) e^{-f|x-x_S|} \cos[g(y-y_S)] dx dy \right. \\ \left. + g \sin\phi_m \int_{-a-b}^a \int_{-a-b}^b e^{-jf_m x} e^{-jg_m y} e^{-f|x-x_S|} \sin[g(y-y_S)] dx dy \right] dg \quad (4.7)$$

$$V_m = \frac{-1}{2\pi\eta_1} \int_0^\infty \frac{1}{f} \sin\phi_m \left\{ \int_{-a}^a \frac{-jf_m x}{e} e^{-f|x-x_s|} dx \left[g \int_{-b}^b \frac{-jg_m y}{e} \sin[g(y-y_s)] dy \right] \right. \\ \left. + \cos\phi_m \int_{-a}^a \text{sgn}(x-x_s) e^{-f_m x} e^{-f|x-x_s|} dx \left[f \int_{-b}^b \frac{-jg_m y}{e} \cos[g(y-y_s)] dy \right] \right\} dg, \quad (4.8)$$

$$V_m = \frac{-1}{\pi\eta_1} \int_0^\infty \frac{1}{f} \left[F_m(g\sin\phi_m) G_0^V + G_m(f\cos\phi_m) G_E^V \right] dg, \quad (4.9a)$$

where

F_m and G_E^V are given in Equations (3.8b) and (3.8c) respectively,

$$G_0^V = -j \left(e^{-jgy_s} \frac{\sin[(g_m-g)b]}{(g_m-g)} - e^{jgy_s} \frac{\sin[(g_m+g)b]}{(g_m+g)} \right), \quad (4.9b)$$

and

$$G_m = \left\{ \begin{array}{ll} -e^{-fx_s} \frac{\sin[(f_m+jf)a]}{(f_m+jf)} & x_s > a \\ \frac{-j}{2(f_m+jf)} e^{-fx_s} e^{-j(f_m+jf)x_s} & -a \leq x_s \leq a \\ + \frac{j}{2(f_m-jf)} e^{fx_s} e^{-j(f_m-jf)a} e^{-j(f_m-jf)x_s} & \\ e^{fx_s} \frac{\sin[(f_m-jf)a]}{(f_m-jf)} & x_s < -a \end{array} \right\}. \quad (4.9c)$$

To evaluate the integrals in T_{mn} , (Equation (4.5d)) the two useful transforms of Equations (4.6a) and (4.6b) are used, but first, the integration path ℓ is broken into four segments and defined as follows; considering Figure 4-1

$$\ell = \begin{cases} \ell_1 ; \text{ from } (a, -b) \text{ to } (a, b) , \hat{n}(\ell_1) = \hat{x} \\ \ell_2 ; \text{ from } (-a, b) \text{ to } (a, b) , \hat{n}(\ell_2) = \hat{y} \\ \ell_3 ; \text{ from } (-a, -b) \text{ to } (-a, b) , \hat{n}(\ell_3) = -\hat{x} \\ \ell_4 ; \text{ from } (-a, -b) \text{ to } (a, -b) , \hat{n}(\ell_4) = -\hat{y} \end{cases} \quad (4.10)$$

Also, the inner-product $(\hat{\phi}_n \cdot \hat{n}(\ell'))$ in Equation (4.5d) is found from Equations (4.3) and (4.10) as

$$(\hat{\phi}_n \cdot \hat{n}(\ell')) = \begin{cases} -\sin\phi_n ; \text{ for } \ell_1 \quad \cdot \\ \cos\phi_n ; \text{ for } \ell_2 \quad \cdot \\ \sin\phi_n ; \text{ for } \ell_3 \quad \cdot \\ -\cos\phi_n ; \text{ for } \ell_4 \quad \cdot \end{cases} \quad (4.11)$$

Substituting Equations (4.11) in (4.5d), T_{mn} is now given by

$$T_{mn} = C_2 \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} \left\{ -\sin\phi_n \left[\int_{-b}^b e^{-jf_n a} e^{-jg_n y'} (\cos\phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_1|) \sin\alpha_1 + \sin\phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_1|) \cos\alpha_1) dy' \right] \right. \\ \left. + \left[\cos\phi_n \int_{-a}^a e^{-jf_n x'} e^{-jg_n b} (\cos\phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_2|) \sin\alpha_2 \right. \right.$$

$$\begin{aligned}
& - \sin \phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_2|) \cos \alpha_2) dx' \Big] + \\
& \left[\sin \phi_n \int_{-b}^b e^{jf_n a} e^{-jg_n y'} (\cos \phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_3|) \sin \alpha_3 \right. \\
& \left. - \sin \phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_3|) \cos \alpha_3) dy' \right] \\
& - \left[\cos \phi_n \int_{-a}^a e^{-jf_n x'} e^{jg_n b} (\cos \phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_4|) \sin \alpha_4 \right. \\
& \left. - \sin \phi_m K_1(\gamma_2 |\bar{\rho} - \bar{\rho}_4|) \cos \alpha_4) dx' \right] \Big\} dx dy \quad \cdot \quad (4.12)
\end{aligned}$$

where $(\hat{\phi}_m \cdot \hat{\rho}) = \sin(\phi - \phi_m)$ was used above ($\hat{\rho}$ is the unit vector in the direction of $\bar{\rho}$). To avoid confusion with ϕ_m and ϕ_n , ϕ is changed to α and subscripted according to the path of integration.

$$\left\{ \begin{array}{l}
|\bar{\rho} - \bar{\rho}_1| = \sqrt{(x-a)^2 + (y-y')^2} \quad ; \quad \alpha_1 = \tan^{-1} \left(\frac{y-y'}{x-a} \right) \\
|\bar{\rho} - \bar{\rho}_2| = \sqrt{(x-x')^2 + (y-b)^2} \quad ; \quad \alpha_2 = \tan^{-1} \left(\frac{y-b}{x-x'} \right) \\
|\bar{\rho} - \bar{\rho}_3| = \sqrt{(x+a)^2 + (y-y')^2} \quad ; \quad \alpha_3 = \tan^{-1} \left(\frac{y-y'}{x+a} \right) \\
|\bar{\rho} - \bar{\rho}_4| = \sqrt{(x-x')^2 + (y+b)^2} \quad ; \quad \alpha_4 = \tan^{-1} \left(\frac{y+b}{x-x'} \right)
\end{array} \right. \quad \cdot \quad (4.13)$$

The relations given in Equations (4.6a) and (4.6b) may now be used in Equation (4.12), and the integrals are rearranged so that the line and cross sectional integrals are evaluated to a closed form. After some regrouping T_{mn} is now given by

$$T_{mn} = \frac{C_2}{\gamma_2} \int_0^{\infty} \frac{1}{f} \left[\begin{aligned} & - \sin \phi_n \cos \phi_m g(S1-S5) \\ & + \sin \phi_n \sin \phi_m f(S2-S6) \\ & + \cos \phi_n \cos \phi_m g(S3-S7) \\ & - \cos \phi_n \sin \phi_m f(S4-S8) \end{aligned} \right] dg \quad (4.14)$$

where

$$S1 = \frac{-j(f_n - jf)a}{4e} F1 \cdot G1 \quad (4.15a)$$

$$S2 = \frac{-j(f_n - jf)a}{-4e} F2 \cdot G2 \quad (4.15b)$$

$$S3 = \frac{-jg_nb}{2e} F3 \cdot G3 \quad (4.15c)$$

$$S4 = \frac{-jg_nb}{2e} F4 \cdot G4 \quad (4.15d)$$

$$S5 = \frac{-j(f_n + jf)a}{4e} F5 \cdot G5 \quad (4.15e)$$

$$S6 = \frac{-j(f_n + jf)a}{4e} F6 \cdot G6 \quad (4.15f)$$

$$S7 = \frac{jg_nb}{2e} F7 \cdot G7 \quad (4.15g)$$

$$S8 = \frac{jg_nb}{2e} F8 \cdot G8 \quad (4.15h)$$

where

$$F1 = F2 = \frac{2\sin[(f_m+jf)a]}{(f_m+jf)} \quad . \quad (4.16)$$

$$F3 = F7 = 2FE_{mn} \text{ (} FE_{mn} \text{ is given in Equation (3.10b))}$$

$$F4 = F8 = 2j \left(\frac{\sin[(f_m+f_n)a]}{(f_n+jf)(f_m+f_n)} - e^{j(f_m+jf)a} \frac{\sin[(f_m-jf)a]}{(f_n+jf)(f_m-jf)} \right. \\ \left. - e^{-j(f_n-jf)a} \frac{\sin[(f_m+jf)a]}{(f_n-jf)(f_m+jf)} + \frac{\sin[(f_m+f_n)a]}{(f_n-jf)(f_m+f_n)} \right) \quad . \quad (4.17)$$

$$F5 = F6 = \frac{2\sin[(f_m-jf)a]}{(f_m-jf)} \quad . \quad (4.18)$$

$$G1 = G5 = 2G0_{mn} \text{ where}$$

$$G0_{mn} = -j \left(\frac{\sin[(g_n+g)b]\sin[(g_m-g)b]}{(g_n+g)(g_m-g)} - \frac{\sin[(g_n-g)b]\sin[(g_m+g)b]}{(g_n-g)(g_m+g)} \right) \quad . \quad (4.19)$$

$$G2 = G6 = 2GE_{mn} ; \text{ (} GE_{mn} \text{ is given in Equation (3.10c))}$$

$$G3 = -j \left(e^{-jgb} \frac{\sin[(g_m-g)b]}{(g_m-g)} - e^{jgb} \frac{\sin[(g_m+g)b]}{(g_m+g)} \right) \quad . \quad (4.20)$$

$$G4 = e^{-jgb} \frac{\sin[(g_m-g)b]}{(g_m-g)} + e^{jgb} \frac{\sin[(g_m+g)b]}{(g_m+g)} \quad . \quad (4.21)$$

$$G7 = -j \left(e^{jgb} \frac{\sin[(g_m-g)b]}{(g_m-g)} - e^{-jgb} \frac{\sin[(g_m+g)b]}{(g_m+g)} \right) \quad . \quad (4.22)$$

$$G8 = e^{jgb} \frac{\sin[(g_m-g)b]}{(g_m-g)} + e^{-jgb} \frac{\sin[(g_m+g)b]}{(g_m+g)} \quad . \quad (4.23)$$

These steps now completely fill the matrix elements of Equation (2.14). Now the matrix can be inverted to solve for the response matrix $[C_n]$. The scattered field can be calculated by substituting Equation (3.1) into Equation (2.46)

$$H_{z(x,y)}^S = \frac{\gamma_2 j \omega (\hat{\epsilon}_1 - \hat{\epsilon}_2) p (-jK_1)}{2\pi} \sum_{m=1}^N C_m \left[\begin{array}{cc} a & b \\ \int \int & \int \int \\ -a & -b \end{array} \begin{array}{c} -j f_m x' \\ e^{-j g_m y'} \end{array} \left(\sin \phi_m \sin \phi K_1 (\gamma_2 |\bar{\rho} - \bar{\rho}'|) \right. \right. \\ \left. \left. + \cos \phi_m \cos \phi K_1 (\gamma_2 |\bar{\rho} - \bar{\rho}'|) \right) \right] dx' dy' \quad , \quad (4.24)$$

where Equations (3.2b) and (3.2c) have been used. Constant p is defined by Equation (2.40c).

Using Equation (4.6) in Equation (4.24) and simplifying yields

$$H_{z(x,y)}^S = - \frac{j \omega \eta_1 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sum_{m=1}^N \left[C_m \int_{-a}^a \int_{-b}^b \left[e^{-j f_m x'} e^{-j g_m y'} \left(\sin \phi_m \int_0^\infty \frac{e^{-f|x-x'|} \sin[g(y-y')]}{f} dg \right. \right. \right. \\ \left. \left. \left. + \cos \phi_m \int_0^\infty \frac{\text{sgn}(x-x') e^{-f|x-x'|} \cos[g(y-y')]}{f} dg \right) \right] \right] dx' dy' \quad . \quad (4.25)$$

Interchanging the order of integrations and rearranging terms gives

$$H_z^S(x,y) = \frac{j\omega\eta_1(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sum_{m=1}^N C_m \int_0^\infty \frac{1}{f} \left[\cos\phi_m f \iint_{CS} e^{-jf_m x'} e^{-jg_m y'} \text{sgn}(x'-x) e^{-f|x'-x|} \cos[g(y'-y)] dx' dy' \right. \\ \left. + \sin\phi_m g \iint_{CS} e^{-jf_m x'} e^{-jg_m y'} \sin[g(y'-y)] dx' dy' \right] dg, \quad (4.26)$$

where the arguments of the functions have been rearranged so that the results of Equation (4.7) may be used to simplify the above complicated relation.

Comparing Equations (4.26) and (4.7), and evaluating the cross-sectional integrations to a closed form, the scattered field is finally given by

$$H_z^S(x,y) = \frac{j\omega\eta_1(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{\pi} \sum_{m=1}^N C_m \int_0^\infty \frac{1}{f} \left[F_m(\sin\phi_m g) G_0^V + (\cos\phi_m f) G E_m^V \right] dg. \quad (4.27)$$

F_m , G_m , $G E_m^V$, and G_0^V are given by Equations (3.8b), (4.9c), (3.8c), and (4.9b) respectively, with (x_s, y_s) replaced by (x, y) .

The above equation gives the bistatic and backscattered fields. Additionally, when the backscattered field is needed, i.e., $(x, y) = (x_s, y_s)$, some calculation time may be saved by using the following

$$H_z^{B.S.}(x_s, y_s) = -j\omega\eta_1^2(\hat{e}_1 - \hat{e}_2) \sum_{m=1}^N C_m V_m \quad (4.28)$$

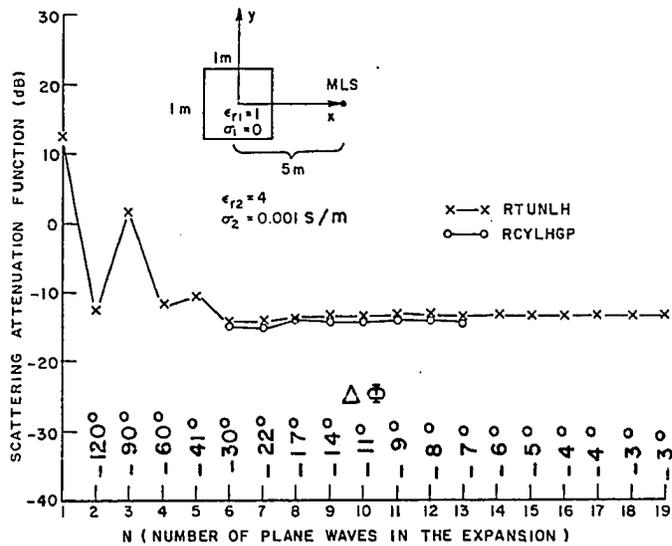
This was obtained by replacing (x, y) with (x_s, y_s) in Equation (4.26) and (4.27) and comparing the resulting equations with Equations (4.8) and (4.9a).

The far zone scattered fields may be found by using Equation (3.1) in Equation (2.50), and evaluating the resulting integrals.

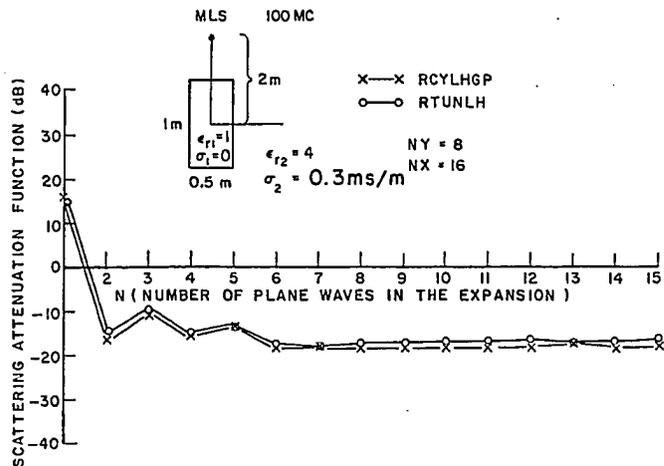
C. CONVERGENCE

Two computer programs RTUNLH and RCYLHGP were developed based on the formulation given in this chapter. RTUNLH and RCYLHGP programs are included and fully discussed in Appendices C and D. RCYLHGP was developed to enable the calculation of far zone, near zone, and back and bistatic scattering patterns, whereas, RTUNLH was developed to include all the above capabilities but was restricted so that x and $x_s > a$. This restriction is made so that the effect of an air-earth interface may be modeled. The air-earth interface is discussed extensively in the following chapter.

Two examples of convergence are shown in Figure 4-2. The backscattered field is calculated and plotted for increasing numbers of plane waves (N) in the expansion. In Figure 4-2a, a 1m by 1m square air filled cylinder immersed in a homogeneous dielectric medium with $\epsilon_r = 4$ and $\sigma = .001s/m$ is modeled. The line source is located at $(x_s, y_s) =$



(a)



(b)

Figure 4-2. Convergence curves for RTUNLH and RCYLHGP computer programs which use plane wave expansion Galerkin method at 100 MHz. (a) for square air filled cylinder, (b) for a rectangular air filled cylinder. Scattering attenuation function is plotted as a function of N the number of plane waves in the expansion.

(5m,0m). The curves of Figure 4-2a suggest that the solution converges to a single value for $N > 6$ for RTIUNLH computer program. Several points are also calculated by RCYLHGP computer program to confirm the convergence. The frequency used is 100 MHz.

The second example is shown in Figure 4-2b. A 1m by .5m, air-filled rectangular cylinder immersed in a homogeneous medium with $\epsilon_{r2} = 4$ and $\sigma_2 = .3\text{ms/m}$ illuminated by a magnetic line source placed at $(x_s, y_s) = (2\text{m}, 0\text{m})$. The curve for both programs seems to have converged to a single value at $N > 6$.

To get an idea about how many plane waves must be included in the expansion, a similar estimate as discussed for E-waves in Chapter III may be used for the expanded H-wave in the cylinder. In Figure 4-2a the $\Delta\phi$ from Equation (3.14) corresponding to each N is also included.

D. BACKSCATTERED PATTERNS

1. Far Zone

The first example for which the backscattered fields are to be computed is a 1m by .5m lossy dielectric rectangular cylinder with $\epsilon_{r1} = 4$, and $\sigma_1 = .3\text{ms/m}$ immersed in a free space environment. An H_z -polarized plane wave is incident on this scatterer at an angle ϕ_i as shown in Figure 4-3. The far zone backscattered pattern is plotted and is shown in Figure 4-3. The frequency used is 100 MHz. The maxima of backscattered field are obtained at incidence angles of 90° and 270° at which E_x is incident on the larger faces of the cylinder, and the minima

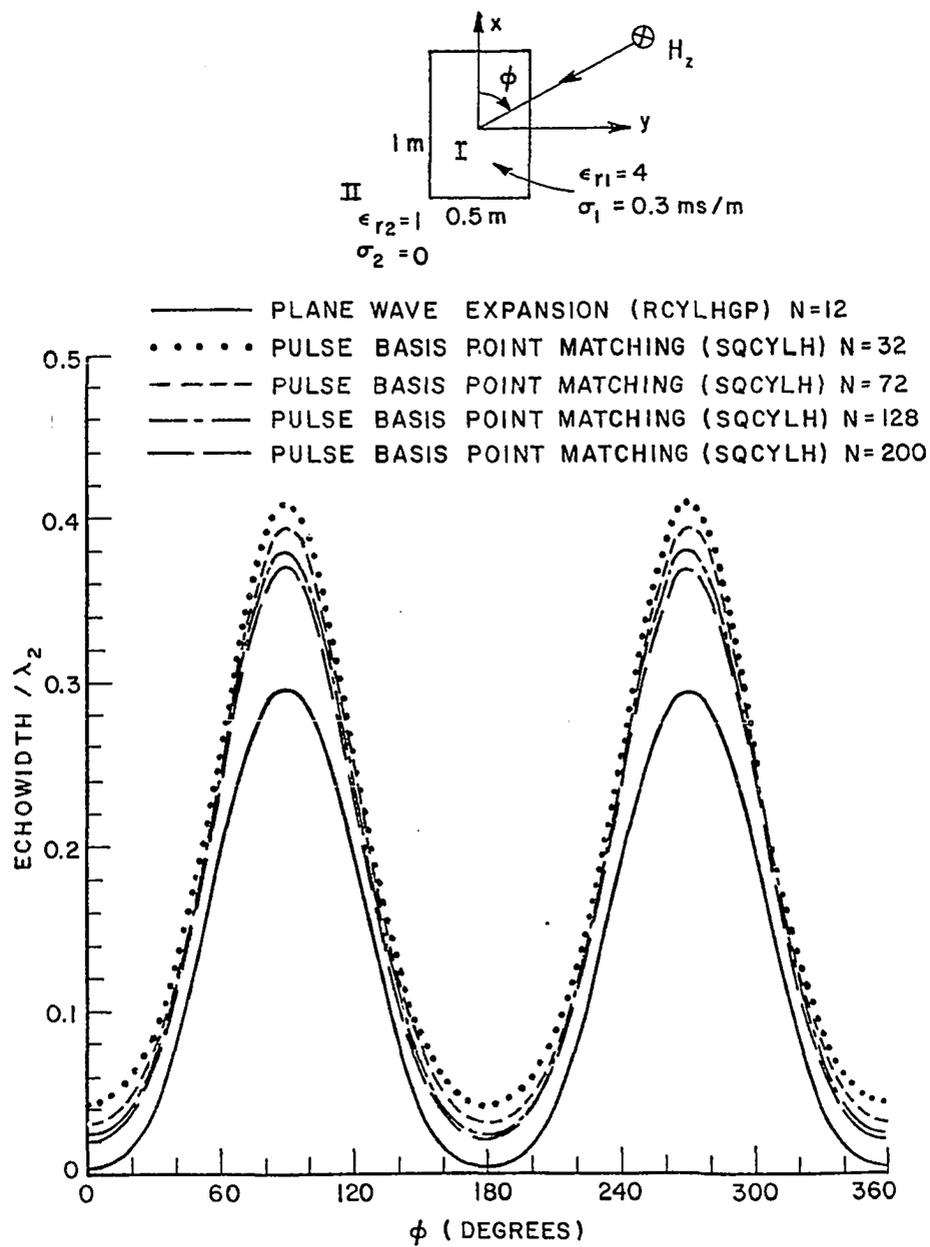


Figure 4-3. Far zone backscattered pattern for a z-polarized magnetic plane wave incidence at 100 MHz.

of scattered field are obtained at incidence angles of 0° and 180° for which E_y is incident on the smaller faces of the cylinder. In addition, some results of a pulse basis point matching program is also included which indicate that, if enough equations are included, the solution approaches that of the plane wave expansion. Four incremental cases for the pulse basis point matching shown in Figure 4-3 are for $N = 32, 72, 128,$ and 200 . It is apparent that the pulse basis method has not yet converged for $N = 200$, but the plane wave expansion has already converged for $N = 12$.

2. Near Zone

As a second example, consider an air filled, 1m by $.5\text{m}$ rectangular cylinder immersed in a lossy homogeneous medium with $\epsilon_r = 4$ and $\sigma = .3\text{ms/m}$. A magnetic line source is placed at $(\rho_s, \phi_s) = (2\text{m}, \phi_s)$. This model is shown at top of the Figure 4-4. Scattering Attenuation Function versus ϕ is shown in Figure 4-4 for backscatter for increasing values of N ; 6, 7, 8, and 9. For $N=8$ and 9, the pattern is exactly the same, this suggests that the solution has converged at $N=8$. The result of the pulse basis point matching shows excellent agreement with the plane wave expansion at the maxima, but, more equations are needed (i.e., $N > 200$) to obtain better agreement at minima. This is because the pulse basis point matching solution has not yet converged at minima regions. This was investigated by using $N = 32, 72, 128,$ and 200 and comparing the patterns. Only $N = 200$ case is included in Figure 4-3.

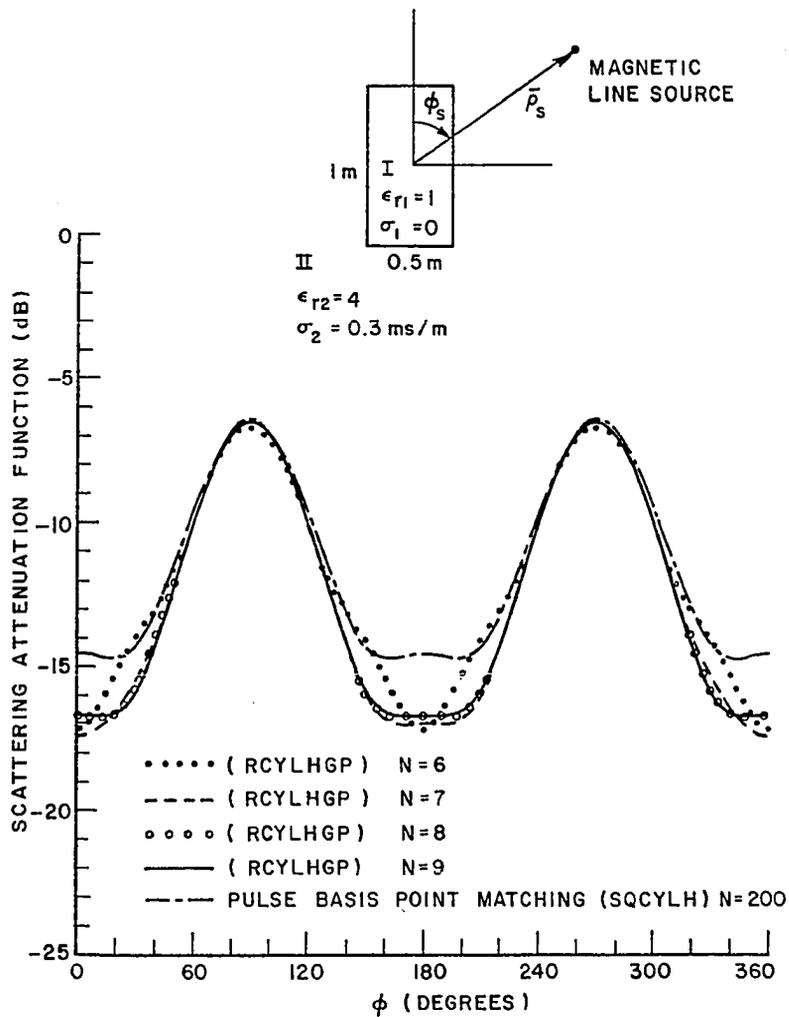


Figure 4-4. Near zone backscattered pattern for the model shown above. The line source is placed at a radial distance $\rho_s=2m$, and the frequency is 100 MHz. (RCYLHGP) is the Plane Wave Expansion Computer program used to obtain the above results.

(The frequency used is 100 MHz.) Obtaining a converged solution by the pulse basis method is costly and has not been carried out.

E. BISTATIC SCATTERING PATTERNS

1. Far Zone

The complete scattering patterns for three cases of plane wave incidences at $\phi_i = 0^\circ$, 45° , and 90° , and for a 1m by .5m lossy dielectric rectangular cylinder with $\epsilon_{r_1}=4$ and $\sigma_1=.3s/m$ located in a free space environment have been computed and given in Figures 4-5, 4-6, and 4-7, respectively. A H_z -polarized plane wave is incident on the scatterer at $\phi_i=0^\circ$ as shown in Figure 4-5. The bistatic scattering pattern shown in Figure 4-5 shows a strong forward scattering and comparatively weak backscattering, and as expected the pattern is symmetrical about 180° . (The frequency used in this section is 100 MHz.) Also included in Figure 4-5, is the pulse basis point matching result for $N=200$. As discussed in Figure 4-3, better agreement would be obtained by increasing N in the point matching solution. For a plane wave incident along 45° -axis, the bistatic scattering pattern is shown in Figure 4-6. A small lobe is observed at about 70° and a greater lobe is observed at approximately 230° . The pattern does not have a point about which it is symmetric. For a plane wave incident nearly at $\phi_i=90^\circ$, the bistatic scattering pattern of Figure 4-7 is obtained. This indicates a small backscattered lobe and a large forward scattered lobe. As expected, the pattern is symmetrical about approximately 270° . The

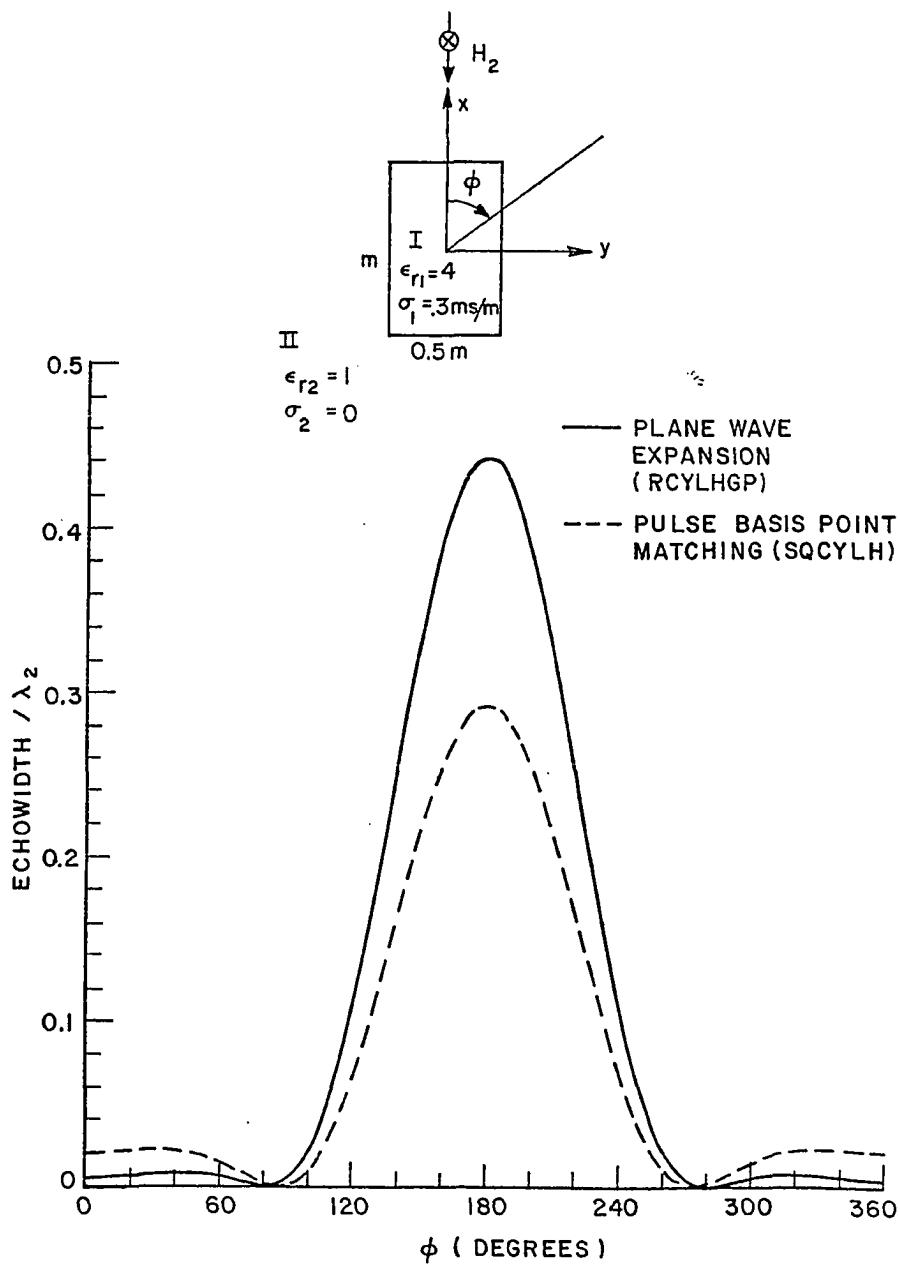


Figure 4-5. Far zone bistatic scattering pattern for a H_Z-polarized plane wave incident at $\phi_i = 0^\circ$, and at 100 MHz.

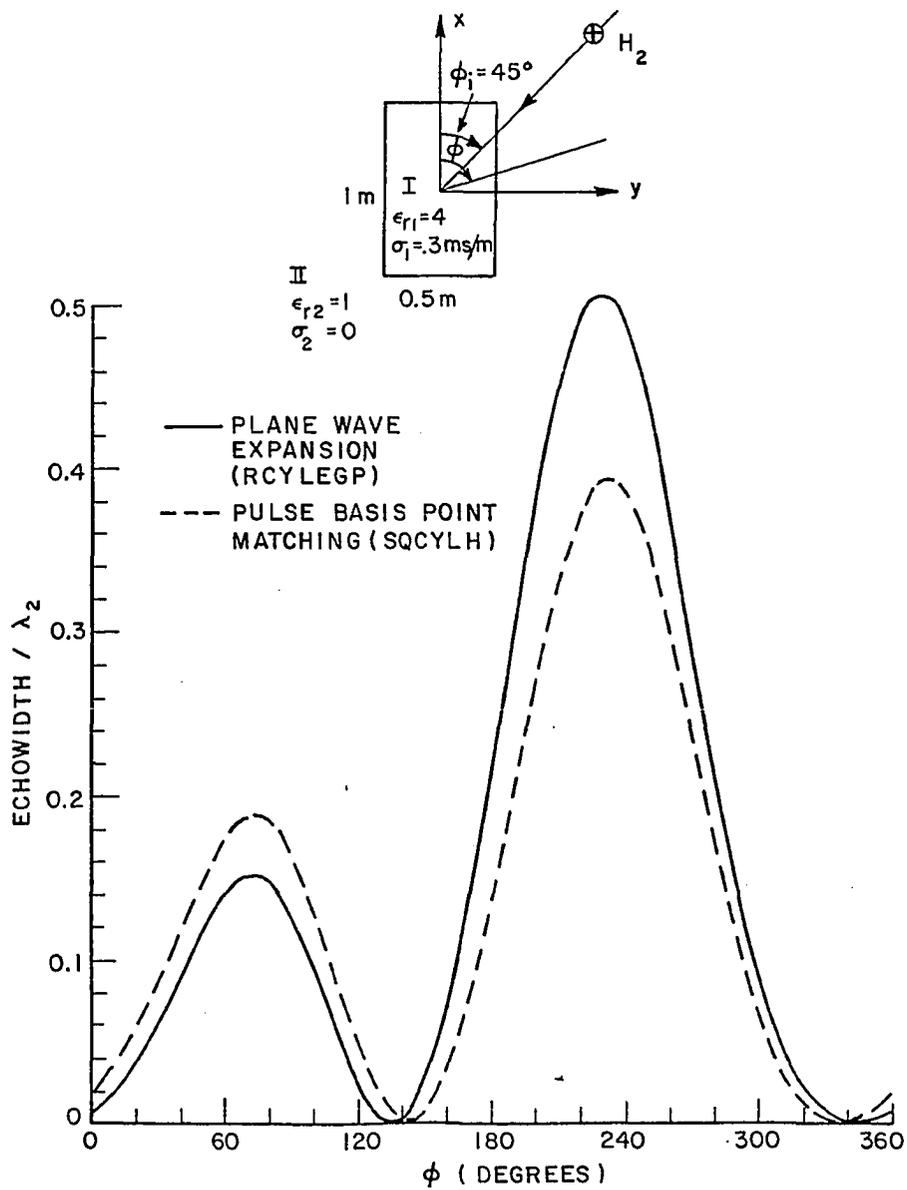


Figure 4-6. Far zone bistatic scattering pattern for a H_2 -polarized plane wave incident at $\phi_i=45^\circ$, and at 100 MHz.

pulse basis point matching solutions included in Figures 4-6, and 4-7 show a 5° discrepancy in the position of the maxima and minima as compared to the plane wave expansion solutions. In part, this is caused by numerical approximations of the trigonometric functions by the computer.

2. Near Zone

The three cases considered include line sources at $(\rho_s, \phi_s) = (2m, 0^\circ)$, $(\rho_s, \phi_s) = (2m, 45^\circ)$, and $(\rho_s, \phi_s) = (2m, 90^\circ)$ which are analogous to $\phi_i = 0^\circ$, 45° , and 90° as considered in previous section for a 1m by .5m air filled rectangular cylinder immersed in a lossy homogeneous medium with $\epsilon_{r2} = 4$ and $\sigma_2 = .3\text{ms/m}$. The scattering patterns are given in Figures 4-8, 4-9, and 4-10. The field is observed at a radial distance $\rho = 2m$, and the frequency of excitation source is 100 MHz. In each case, a pulse basis point matching solution is provided for comparison. The bistatic scattering pattern for a line source placed at $(\rho_s, \phi_s) = (2m, 0^\circ)$ is shown in Figure 4-8. This pattern shows a strong forward scattering and significantly smaller backscattering. The pattern is symmetric about 180° as expected. For a magnetic line source located at $(\rho_s, \phi_s) = (2m, 45^\circ)$, the bistatic scattering pattern is shown in Figure 4-9. The pattern is no longer symmetric and the lobes are offset accordingly. When the magnetic line source is moved to $(\rho_s, \phi_s) = (2m, 90^\circ)$, the bistatic scattering pattern of Figure 4-10 is obtained. The pattern is symmetric about 270° where the maximum of the forward scattering lobe is obtained. In each case, the pulse basis

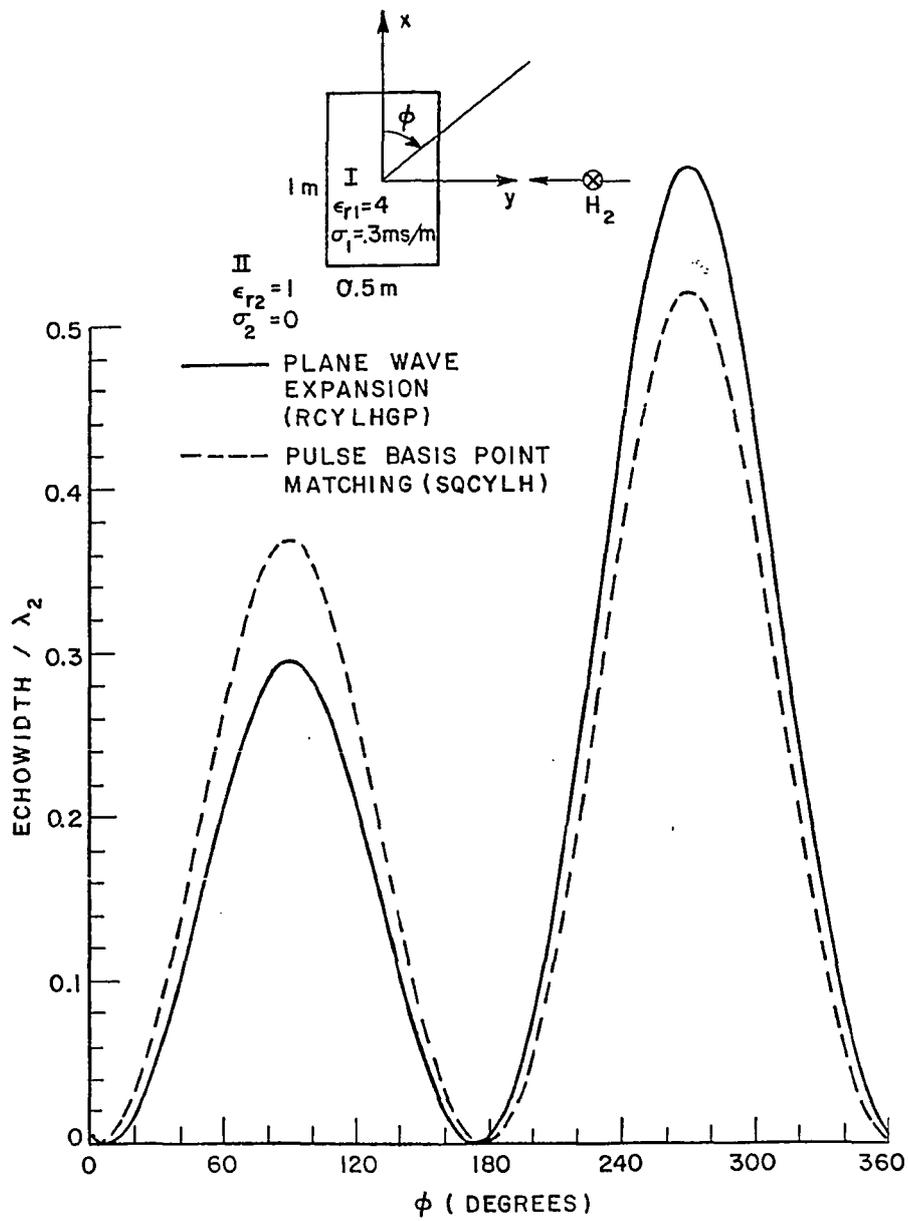


Figure 4-7. Far zone bistatic scattering pattern for a H_2 -polarized plane wave incident at $\phi_i=90^\circ$, and at 100 MHz.

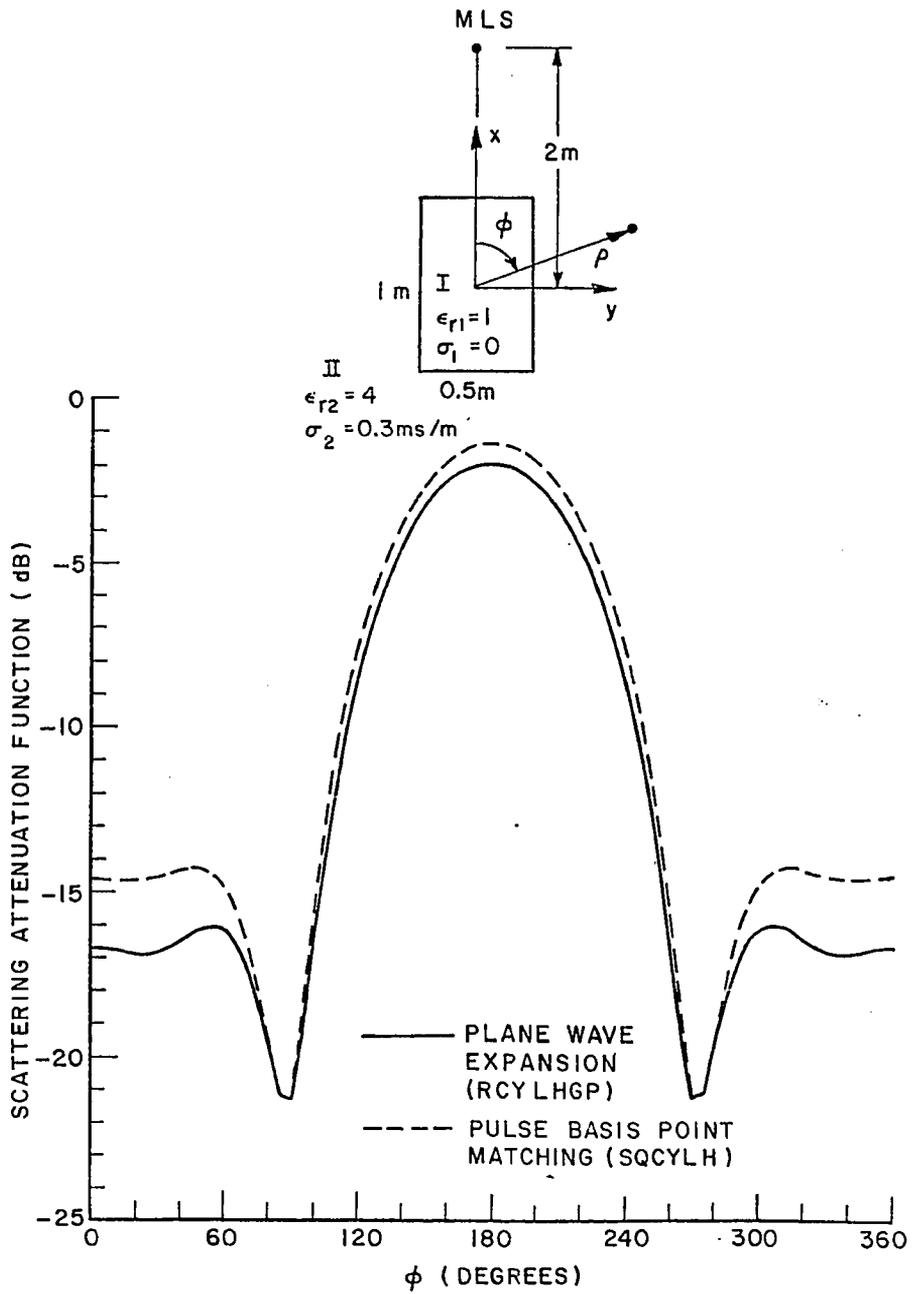


Figure 4-8. Near zone bistatic scattering pattern for a magnetic line source excitation placed at $(\rho_S, \phi_S) = (2m, 0^\circ)$ and at 100 MHz. The field is observed at a radial distance $\rho = 2m$.

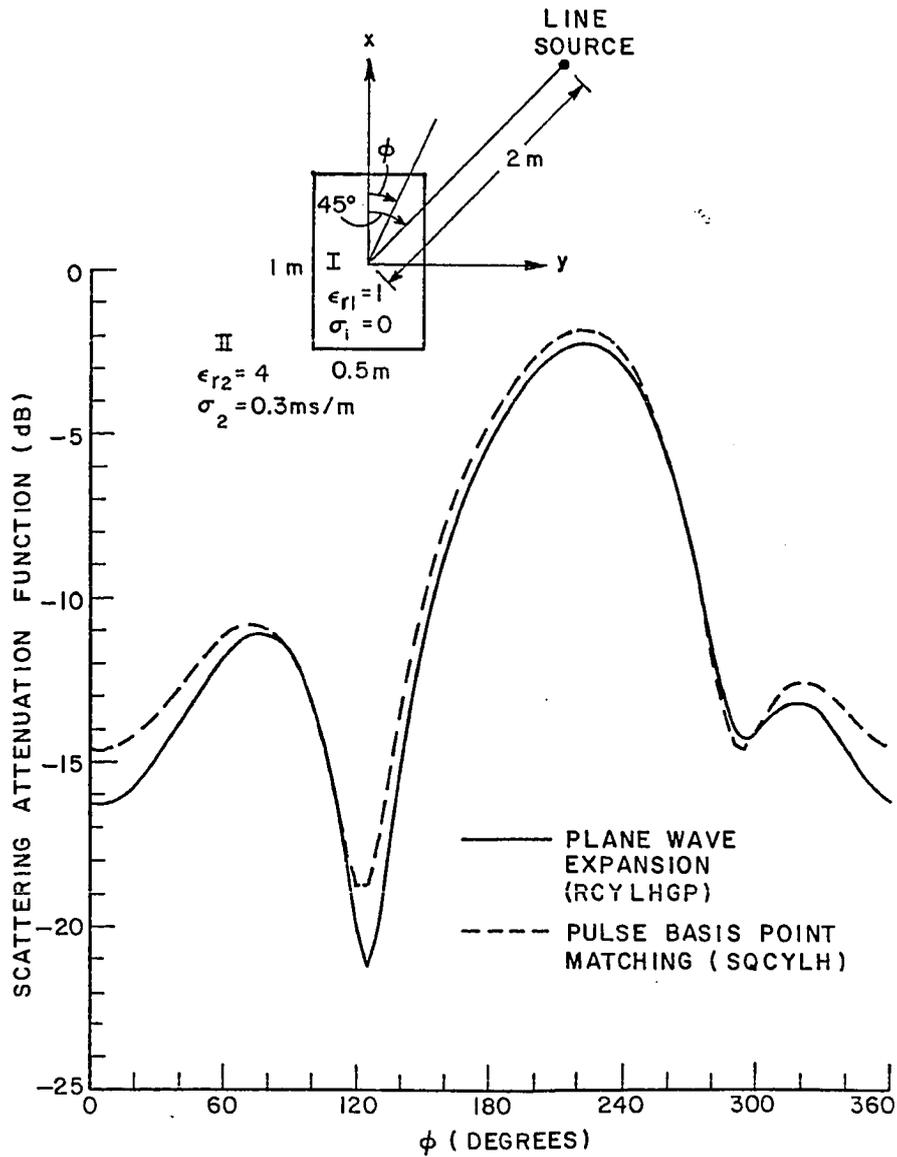


Figure 4-9. Near zone bistatic scattering pattern for a magnetic line source excitation placed at $(\rho_S, \phi_S) = (2\text{m}, 45^\circ)$ and at 100 MHz. The field is observed at a radial distance $\rho = 2\text{m}$.

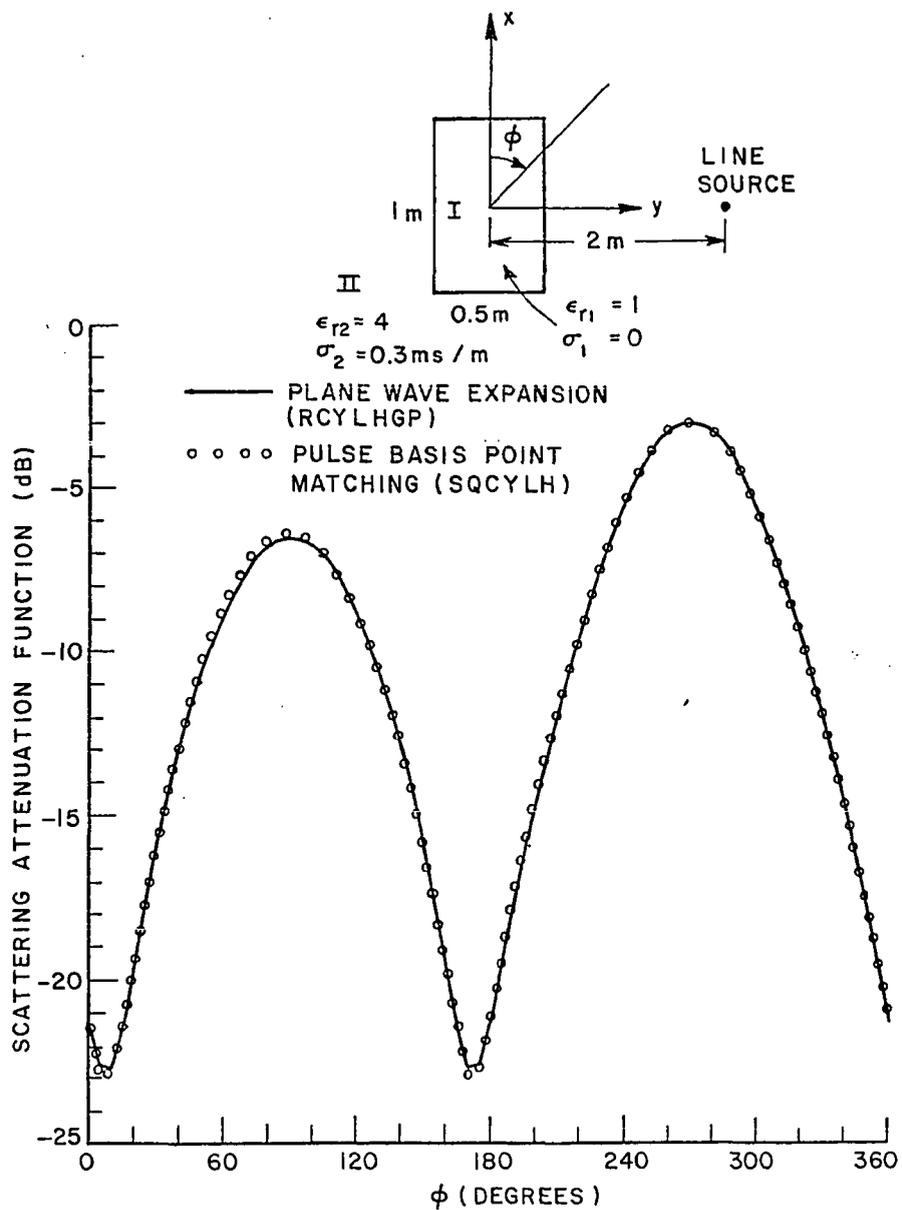


Figure 4-10. Near zone bistatic scattering pattern for a magnetic line source excitation placed at $(\rho_S, \phi_S) = (2m, 90^\circ)$ and at 100 MHz. The field is observed at a radial distance $\rho = 2m$.

point matching solution shows reasonable agreement for the number of equations N utilized. For the region off the main beam, i.e., the backlobe region, the match may be improved by increasing N in the Pulse Basis Point Matching.

F. BACKSCATTERING VERSUS FREQUENCY

In this section, three excitation examples are given for a 1m by .5m air filled rectangular cylinder immersed in a lossy homogeneous medium with $\epsilon_{r2}=4$ and $\sigma_2=.3s/m$. For these three locations of the excitation line source, backscattered fields are calculated for various frequencies. These curves are shown in Figure 4-11. It is apparent that at low frequencies, i.e., <40MHz, where the dimensions of the scatterer are small as compared to the wavelength, there seems to be no distinction between the three curves. This is the so called Rayleigh region. However, when the frequency is increased, the scattering is different for the three excitations shown in Figure 4-11.

To check the reliability of the moment method formulation given in this chapter, the frequency plots of Figure 4-12 is presented. First an air filled, 1m square cylinder immersed in a lossy homogeneous medium of $\epsilon_{r2}=4$. and $\sigma_2=.003s/m$ is considered. A magnetic line source located at $(\rho_s, \phi_s)=(2m, 0^\circ)$ is the source of excitation. This model is shown in Figure 4-12. The relative backscattered curve versus frequency is shown as the solid line in Figure 4-12. An equivalent scattering model for an air-filled circular cylinder of the same cross-sectional area as the

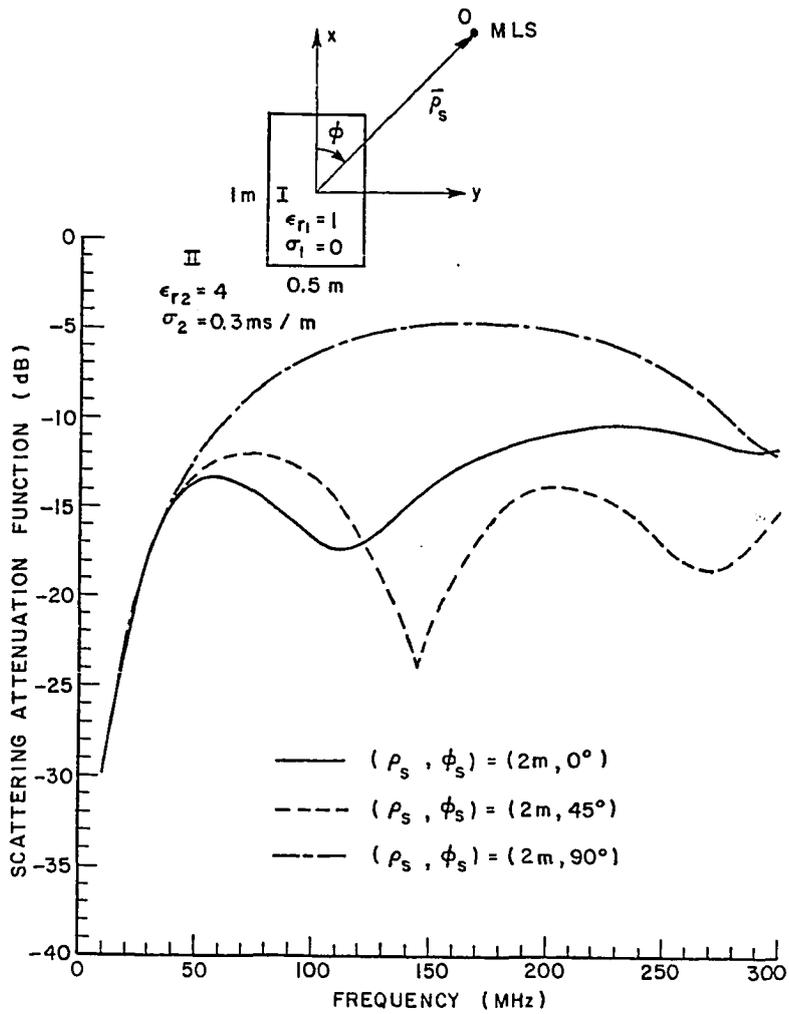


Figure 4-11. Near zone backscattering versus frequency for magnetic line source excitations placed at $(\rho_s, \phi_s) = (2 \text{ m}, 0^\circ)$, $(2 \text{ m}, 45^\circ)$, and $(2 \text{ m}, 90^\circ)$.

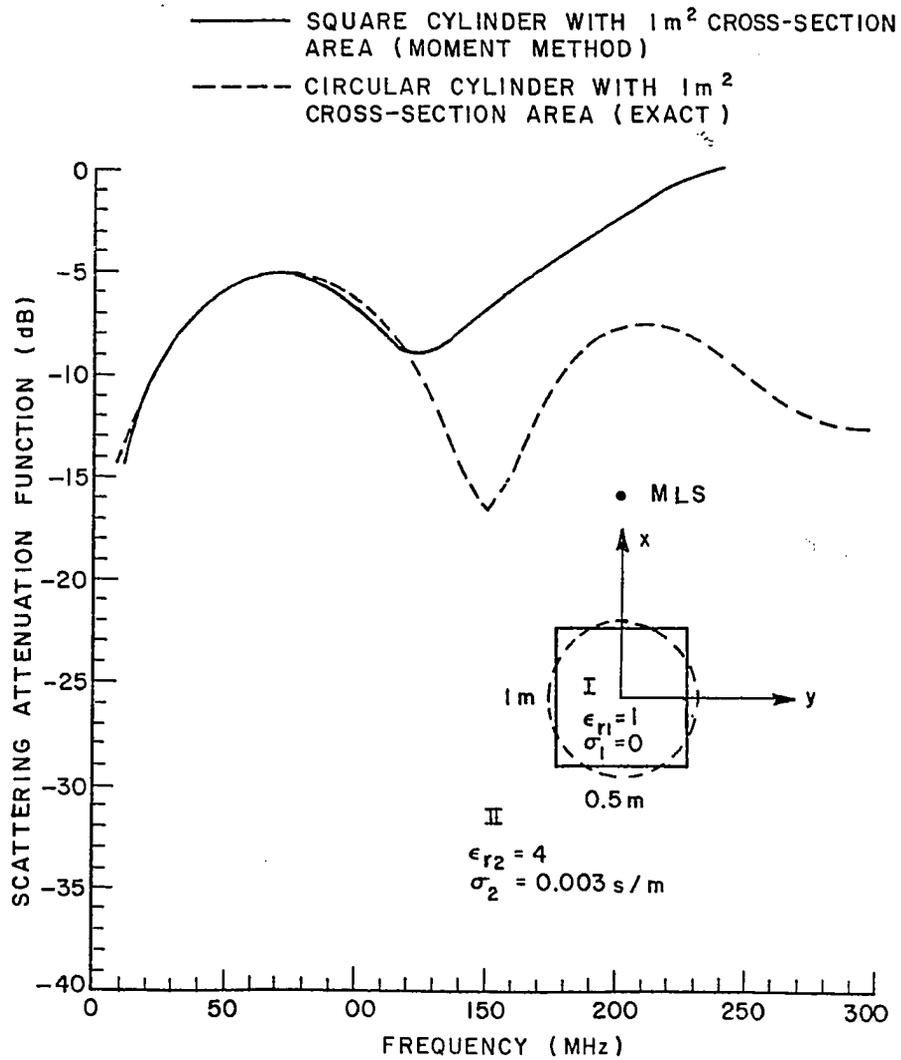


Figure 4-12. Comparison of backscattering versus frequency for a 1m square cylinder and an equivalent cross-section area air filled circular cylinder. The magnetic line source is located at $(\rho_S, \phi_S) = (2\text{m}, 0^\circ)$.

square cylinder immersed in the same lossy homogeneous medium as before is considered. This model is also shown in Figure 4-12. The dash line shows the exact relative backscattered field as a function of frequency for the circular cylindrical model. At low frequencies where the dimensions of the square are small with respect to the wavelengths, the two scatterers are indistinguishable to the observer and the current moment is the same and appears to be identically distributed in both models. However, at larger frequencies where the electrical dimensions are larger, the current distribution is different, and the two scatter curves are no longer identical.

G. SUMMARY

In this chapter the H-wave scattering by lossy rectangular cylinders immersed in a lossy homogeneous medium was considered. The moment method formulation presented in Chapter II was specialized here, and some numerical results were presented.

In the next chapter a basic introduction of the effects of air-earth interface, and the solution of the Sommerfeld integral is presented.

CHAPTER V

AIR-EARTH INTERFACE AND THE SOMMERFELD INTEGRAL

A. INTRODUCTION

The parallel and perpendicular plane wave reflection coefficients for the air-earth interface are given. These coefficients are then used to obtain radiation patterns for a magnetic line source and an electric line source when they are located directly on the interface. It will be shown that the line source radiation patterns can be reasonably approximated by $(1+R)$, where R is R_{\perp} for an electric line source and R_{\parallel} for a magnetic line source. Finally, some recommendations are included for evaluating the Sommerfeld type integrals encountered in this dissertation.

B. REFLECTION COEFFICIENTS

The simple model of Figure 5-1 is used for deriving a plane wave reflection coefficient. As shown, the yz -plane constitutes the interface between Region I (free space) and II (earth), and the x -axis is

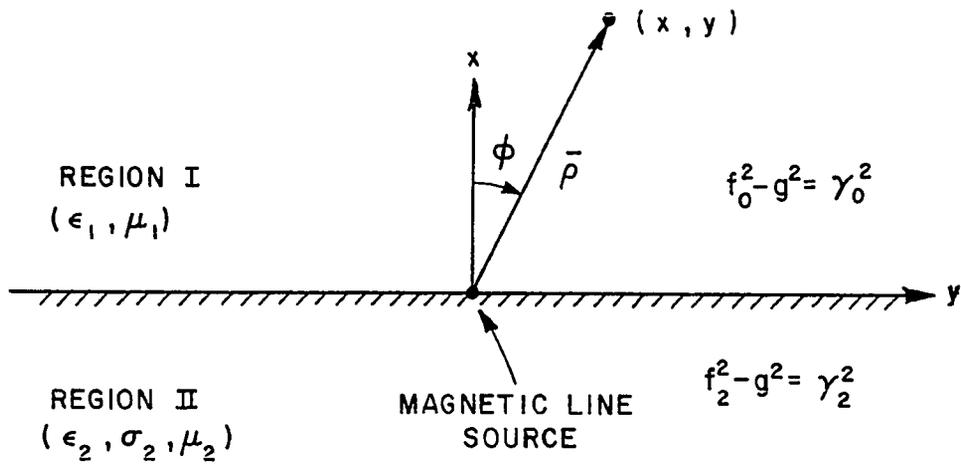


Figure 5-1. The magnetic line source, and interface model used to derive the reflection and transmission coefficients.

normal to this interface. Consider a magnetic line source with a \hat{z} directed magnetic current M_0 , located on the interface along z -axis. This line source radiates a field in the homogeneous earth region given by

$$H_z^i = - \frac{j\omega\epsilon_2 M_0}{2\pi} K_0(\gamma_2 |\bar{\rho} - \bar{\rho}_s|) \quad , \quad (5.1)$$

or

$$H_z^i = - \frac{j\omega\epsilon_2 M_0}{2\pi} \int_0^\infty \frac{e^{-f|x|} \cos(gy) dg}{f} \quad , \quad (5.2)$$

where Equation (3.6) was used.

The boundary conditions at the interface are

$$\hat{n} \times (\mathbf{H}^I - \mathbf{H}^{II}) = \mathbf{J}_S \quad , \quad (5.3a)$$

and

$$\hat{n} \times (\vec{E}^I - \vec{E}^{II}) = -\vec{M}_S \quad , \quad (5.3b)$$

where

$$\hat{n} = \hat{x} \quad . \quad (5.3c)$$

For the situation depicted in Figure 5-1, the electric surface current density \vec{J}_S is zero and the magnetic surface current density \vec{M}_S on the interface can be expressed as

$$\vec{M}_S = \hat{z} M_0 \delta(y) = \frac{\hat{z} M_0}{\pi} \int_0^{\infty} \cos(gy) dg \quad . \quad (5.4)$$

From Equation (5.2), and for the earth region where $x < 0$

$$H_Z^i = \frac{-j \omega \epsilon_2 M_0}{2\pi} \int_0^{\infty} \frac{e^{fx} \cos(gy) dg}{f} \quad x < 0 \quad . \quad (5.5a)$$

Applying Maxwell's equation to above yields

$$E_Y^i = \frac{M_0}{2\pi} \int_0^{\infty} e^{fx} \cos(gy) dg \quad ; \quad x < 0 \quad . \quad (5.5b)$$

From Equation (5.5a) the reflected magnetic field may be expressed as

$$H_Z^r = \frac{-j \omega \epsilon_2 M_0}{2\pi} \int_0^{\infty} \frac{R_{||} e^{fx} \cos(gy) dg}{f} \quad x < 0 \quad . \quad (5.6a)$$

When the observation point is below the line source , the reflected electric field has the form.

$$E_Y^r = \frac{M_0}{2\pi} \int_0^{\infty} R_{||} e^{fx} \cos(gy) dg \quad x < 0 \quad . \quad (5.6b)$$

From Equation (5.2) the transmitted field is obtained for $x > 0$ as

$$H_z^T = - \frac{j\omega\hat{\epsilon}_2 M_0}{2\pi} \int_0^{\infty} T_{\parallel} \frac{e^{-f_0 x} \cos(gy) dg}{f} ; \quad x > 0 . \quad (5.7a)$$

Again applying Maxwell's equation to above in Region I

$$E_y^T = - \frac{M_0 \hat{\epsilon}_2}{2\pi \hat{\epsilon}_1} \int_0^{\infty} f T_{\parallel} \frac{e^{-f_0 x} \cos(gy) dg}{f} ; \quad x > 0 . \quad (5.7b)$$

Now the fields are matched at the boundary. From Equations (5.3a), (5.5a), (5.6a), and (5.7a) it follows that

$$- \frac{j\omega\hat{\epsilon}_2 M_0}{2\pi} \int_0^{\infty} \frac{1}{f} (1+R_{\parallel}) - T_{\parallel} \cos(gy) dg = 0 . \quad (5.8)$$

Thus

$$T_{\parallel} = 1 + R_{\parallel} . \quad (5.9)$$

Also, from Equations (5.3b), (5.4), (5.5b), (5.6b), and (5.7b)

$$\begin{aligned} - \frac{M_0 \hat{\epsilon}_2}{2\pi \hat{\epsilon}_1} \int_0^{\infty} \frac{f_0 T_{\parallel}}{f} \cos(gy) dy - \frac{M_0}{2\pi} \int_0^{\infty} (1+R_{\parallel}) \cos(gy) dg \\ = - \frac{M_0}{\pi} \int_0^{\infty} \cos(gy) dg . \end{aligned} \quad (5.10)$$

Thus, from Equation (5.9) and (5.10), it can be shown that

$$T_{\parallel} = \frac{2\hat{\epsilon}_1 f}{\hat{\epsilon}_1 f + \hat{\epsilon}_2 f_0} . \quad (5.11a)$$

$$R_{\parallel} = \frac{\hat{\epsilon}_1 f - \hat{\epsilon}_2 f_0}{\hat{\epsilon}_1 f + \hat{\epsilon}_2 f_0} . \quad (5.11b)$$

where

$$f^2 - g^2 = \gamma_2^2 = jk_2 = j\omega \sqrt{\mu_0 \hat{\epsilon}_2} \quad (5.11c)$$

$$f_0^2 - g^2 = \gamma_0^2 = jk_0 = j\omega \sqrt{\mu_0 \hat{\epsilon}_0} \quad (5.11d)$$

$$\hat{\epsilon}_1 = \epsilon_0 \quad (5.11e)$$

and

$$\hat{\epsilon}_2 = \epsilon_0 \left(\epsilon_{r2} - j \frac{\sigma_2}{\omega \epsilon_0} \right) \quad (5.11f)$$

An analogous consideration for an electric line source renders R_{\perp} and T_{\perp} , or, a simple application of duality to Equations (5.11a) and (5.11b) gives

$$T_{\perp} = \frac{2\mu_1 f}{\mu_1 f + \mu_2 f_0} \quad (5.12a)$$

$$R_{\perp} = \frac{\mu_1 f - \mu_2 f_0}{\mu_1 f + \mu_2 f_0} \quad (5.12b)$$

R_{\parallel} and R_{\perp} are Fresnel's plane wave reflection coefficients and T_{\parallel} and T_{\perp} are the corresponding transmission coefficients.

Substituting

$$f = \gamma_2 \cos \phi_i \quad (5.13a)$$

$$f_0 = \gamma_0 \cos \phi_i \quad (5.13b)$$

and

$$g = j\gamma_2 \sin \phi_i = j\gamma_0 \sin \phi_t \quad (5.13c)$$

in T_{\parallel} , R_{\parallel} , T_{\perp} , and R_{\perp} gives the familiar forms of T and R as

The above equations are in complete agreement with Equation (5.11c) and (5.11d), and are compatible with the Snell's law.

$$T_{\parallel} = \frac{2\eta_2 \cos \phi_i}{\eta_2 \cos \phi_i + \eta_1 \cos \phi_t} \cdot \quad (5.14a)$$

$$R_{\parallel} = \frac{\eta_2 \cos \phi_i - \eta_1 \cos \phi_t}{\eta_2 \cos \phi_i + \eta_1 \cos \phi_t} \cdot \quad (5.14b)$$

$$T_{\perp} = \frac{2\eta_1 \cos \phi_i}{\eta_1 \cos \phi_i + \eta_2 \cos \phi_t} \cdot \quad (5.14c)$$

$$R_{\perp} = \frac{\eta_1 \cos \phi_i - \eta_2 \cos \phi_t}{\eta_1 \cos \phi_i + \eta_2 \cos \phi_t} \cdot \quad (5.14d)$$

where η_2 and η_1 are intrinsic impedances of media II and I respectively.

C. LINE SOURCE RADIATION ON THE AIR-EARTH INTERFACE

Consider the situation depicted in Figure 5-3, where an air-earth interface (parallel to yz -plane) is located at $x=d$. A line source is placed below the interface at point (x',y') . The fields at any point (x,y) below the interface is the sum of the direct and the reflected waves. A typical direct and reflected ray is shown in Figure 5-3.

$$E_Z^{II}(x,y) = -\frac{j\omega\mu_2 I_0}{2\pi} \int_0^{\infty} \frac{\cos[g(y-y')]}{f} \left[e^{-f|x-x'|} + R_{\perp} e^{-f(2d-x-x')} \right] dg$$

; $x < d$,

(5.15)

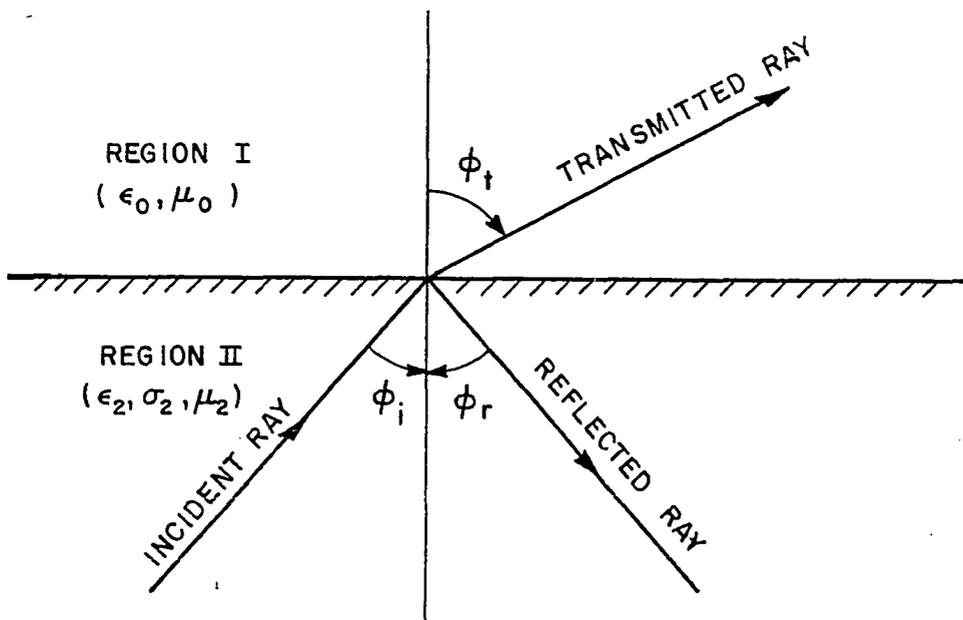


Figure 5-2. Typical ray geometry for reflection and transmission at a plane boundary between Regions I and II.

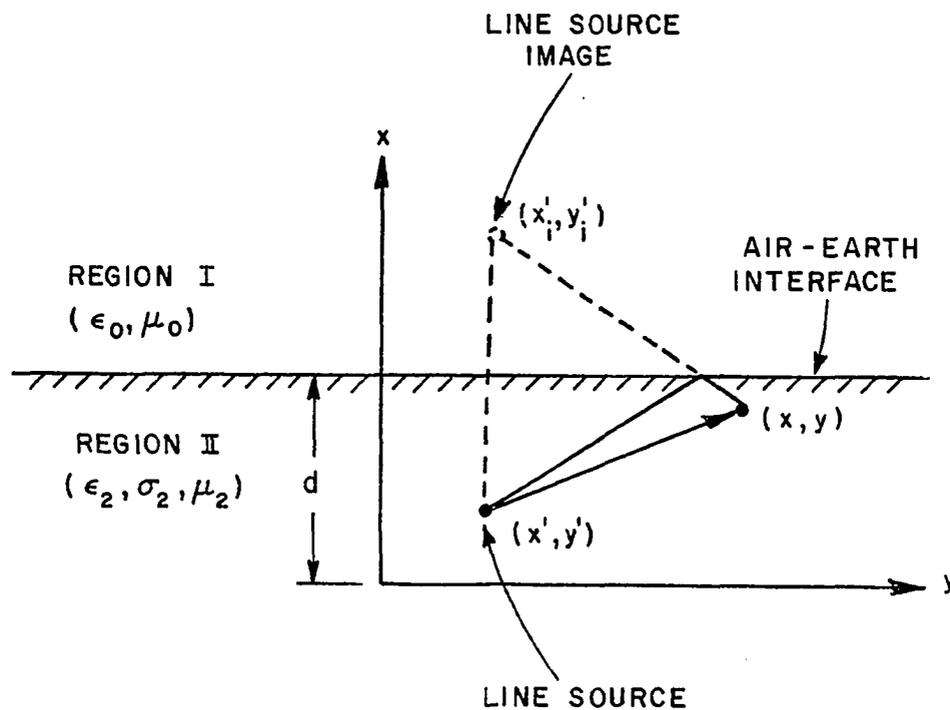


Figure 5-3. Definition of a general coordinate system and the air-earth interface and the line source. The plane interface is parallel to yz -plane and is located at $x=d$.

where I_0 is the electric current on the line source

The field observed at a point (x,y) in air may be expressed as

$$E_Z^I(x,y) = - \frac{j\omega\mu_2 I_0}{2\pi} \int_0^\infty \frac{T_\perp}{f} e^{-f(d-x')} e^{-f_0(x-d)} \cos[g(y-y')] dg \quad ; x > d . \quad (5.16)$$

where T_\perp and R_\perp are given by Equations (5.12a) and (5.12b), and f and f_0 by Equations (5.11c) and (5.11d).

For a buried magnetic line source the corresponding magnetic field observed at a point (x,y) below the interface is

$$H_Z^{II}(x,y) = - \frac{j\omega\epsilon_2 M_0}{2\pi} \int_0^\infty \frac{\cos[g(y-y')]}{f} \left(e^{-f|x-x'|} + R_\parallel e^{-f(2d-x-x')} \right) dg \quad ; x < d , \quad (5.17)$$

and the magnetic field observed at a point (x,y) above the interface is

$$H_Z^I(x,y) = - \frac{j\omega\epsilon_2 M_0}{2\pi} \int_0^\infty \frac{T_\parallel}{f} e^{-f(d-x')} e^{-f_0(x-d)} \cos[g(y-y')] dg \quad ; x > d . \quad (5.18)$$

Using Equations (5.15) and (5.16) a near zone pattern is obtained for an electric line source harmonic at 100MHz, and located on the interface (i.e., $d=x'=0$). The earth medium is represented by $\epsilon_{r2}=4$ and $\sigma_2=0$, and the field is observed at a radial distance $\rho=2m$. This pattern is shown in Figure 5-4, where the earth region is between $\phi=90^\circ$ and

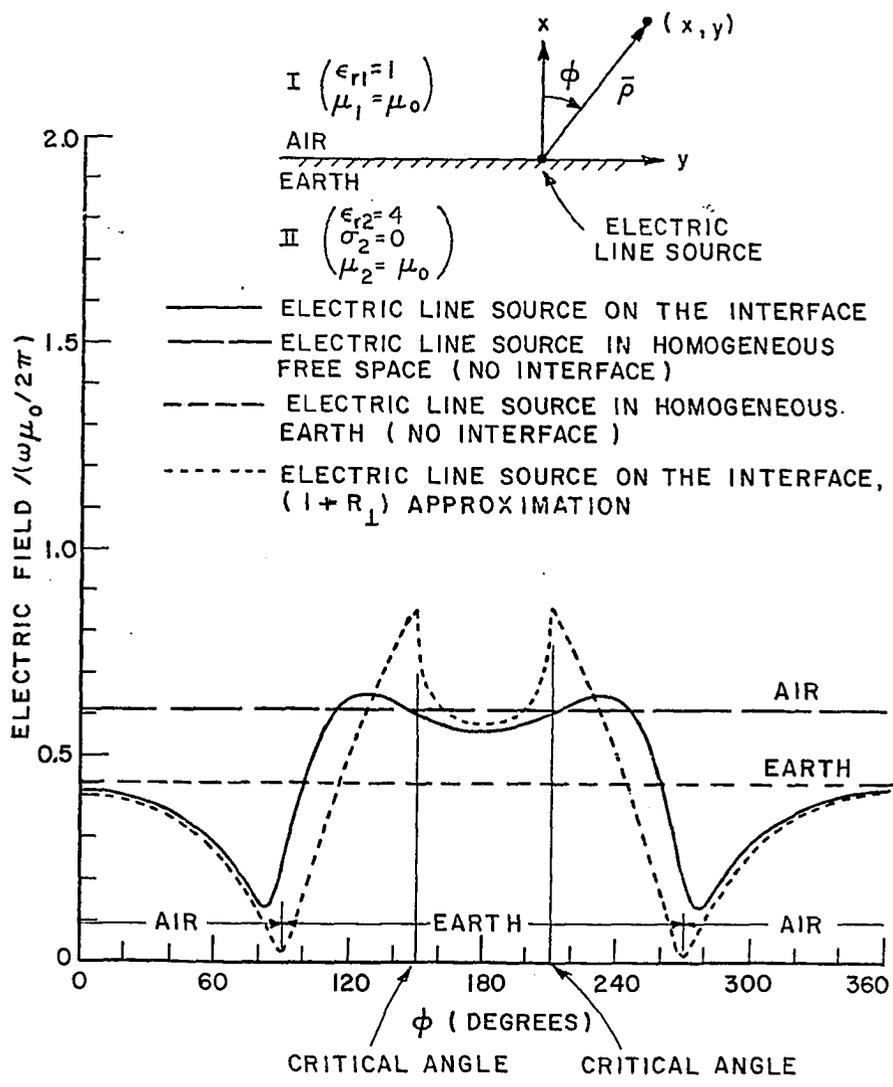


Figure 5-4. Near zone radiation pattern of an electric line source placed on the air-earth interface field is observed at a radial distance $\rho=2m$, and the frequency is 100 MHz.

$\phi=270^\circ$. The two additional curves in Figure 5-4 are the radiation pattern of an electric line source radiating in a homogeneous earth on interface and radiation pattern of an electric line source radiating in homogeneous free space. The current is kept constant in all line source cases. Note that the far field of a line source in a lossless homogeneous medium is proportional to $\epsilon_r^{-1/4}$. Thus, the difference in these two levels is caused by the change in ϵ_r . For the case where the electric line source is placed at the interface, one can use reciprocity and a test current source far from the interface to show that the radiated field is modified by a factor $(1+R_\perp)$. For the example of Figure 5-4 at $\phi=180^\circ$, $R_\perp=1/3$ and the electric field from the line source is increased accordingly. It is also observed that the power from the electric line source on the interface is radiated primarily into the earth medium. A plot of $(1+R_\perp)$ is also included in Figure 5-4 which indicates that the approximation is very good in air region and at normal incidence in earth region. The approximation may be improved by including the effects of the lateral waves. This is illustrated by the solid curve in Figure 5-4. For a lossy earth however, the radiated energy into the earth region is attenuated. A typical case is shown in Figure 5-5 for $\sigma_2=3\text{ms/m}$.

Using Equations (5.17) and (5.18) some near zone patterns were obtained for a magnetic line source (harmonic at 100 MHz) located on interface. Figure 5-6 shows the radiation patterns for a magnetic line source on the interface, in homogeneous earth, and in homogeneous air. The far zone magnetic field for the magnetic line source is proportional to $\epsilon_r^{3/4}$. For the case where the interface is introduced the approximate

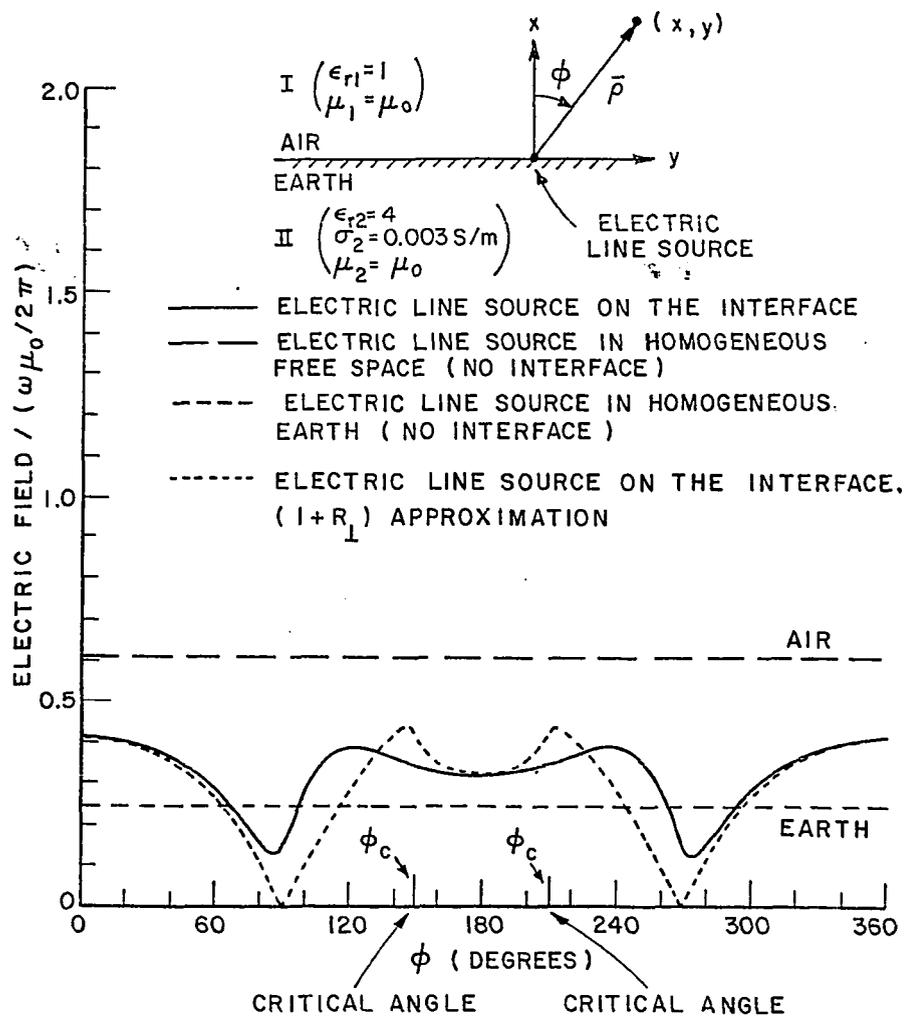


Figure 5-5. The same as Figure 5-4, except the earth is lossy ($\sigma_2=0.003\text{ S/m}$).

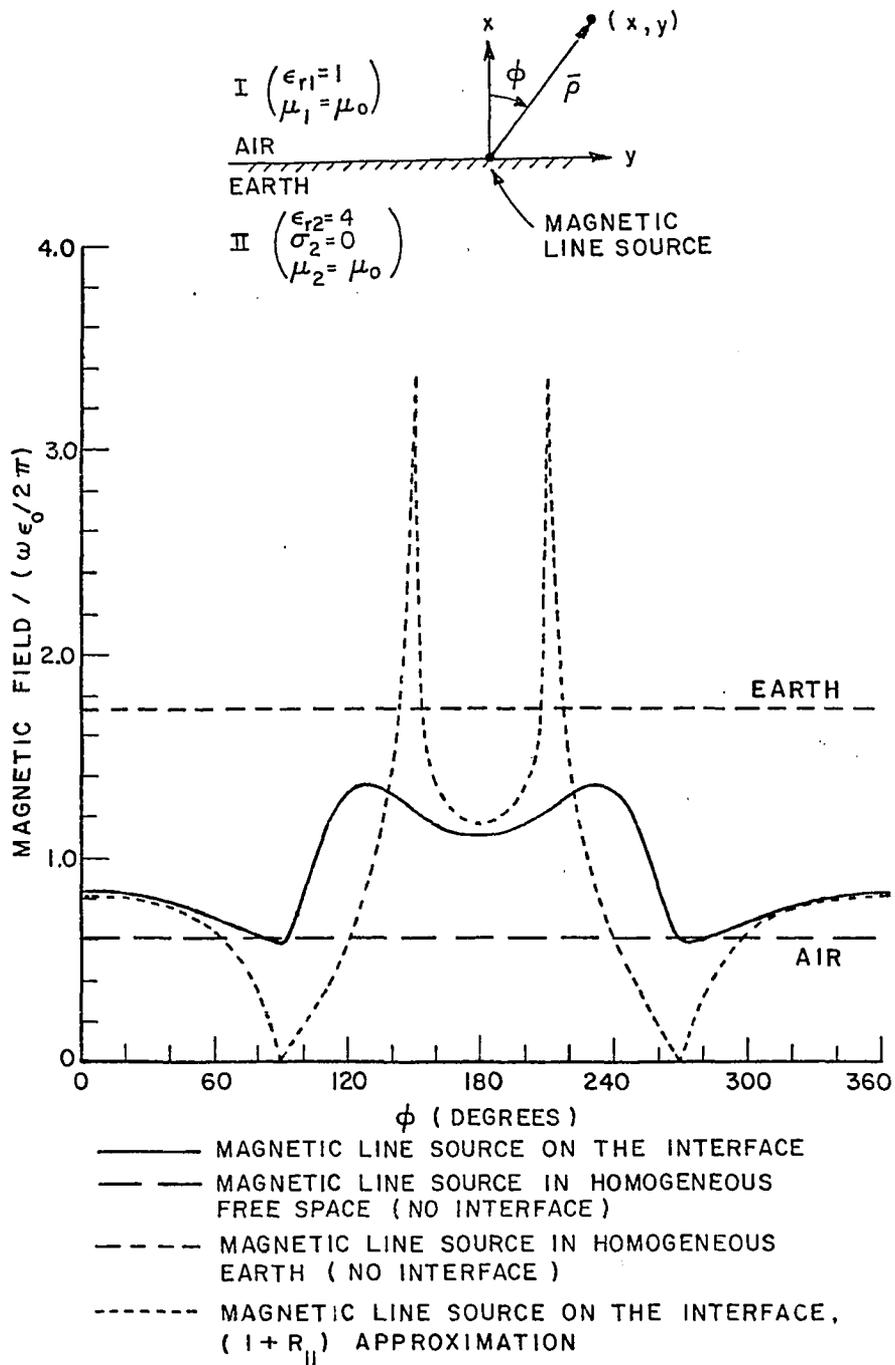


Figure 5-6. Near zone radiation pattern of a magnetic line source placed on the air-earth interface field is observed at a radial distance $\rho=2m$, and the frequency is 100 MHz.

solution is obtained by introducing a factor given by $(1+R_{\parallel})$ which is also plotted in Figure 5-6. As shown, this approximation is not as good as the electric line source case. This suggests that the effects of the lateral waves are more important in this case. For a lossy earth, the energy radiated into the earth is attenuated. A typical case is shown Figure 5-7 for $\sigma_2=3\text{sm/m}$.

D. LIMITING CASE

The limit is examined here as the line source approaches the interface. Let us consider Figure 5-8a where an electric line source is placed at (x',y') above the interface in the free space region. The field observed at (x,y) above the interface is

$$E_z(x,y) = -\frac{j\omega\mu_0}{2\pi} \left[\int_0^{\infty} \frac{e^{-f_0|x-x'|} \cos[g(y-y')]}{f_0} dg + \int_0^{\infty} \frac{R_{\perp}' e^{-f_0|x+x'|} \cos[g(y-y')]}{f_0} dg \right] \quad (5.19)$$

the line source is then moved towards the interface until it is directly placed on it, i.e., $x'=0$

$$\lim_{x' \rightarrow 0} (E_z(x,y)) = -\frac{j\omega\mu_0}{2\pi} \int_0^{\infty} \frac{(1+R_{\perp}') e^{-f_0|x|} \cos[g(y-y')]}{f_0} dg \quad (5.20)$$

where $R_{\perp}' = -R_{\perp}$, and R_{\perp} is given by Equation (5.12b). Using this in Equation (5.20) and further simplifying gives

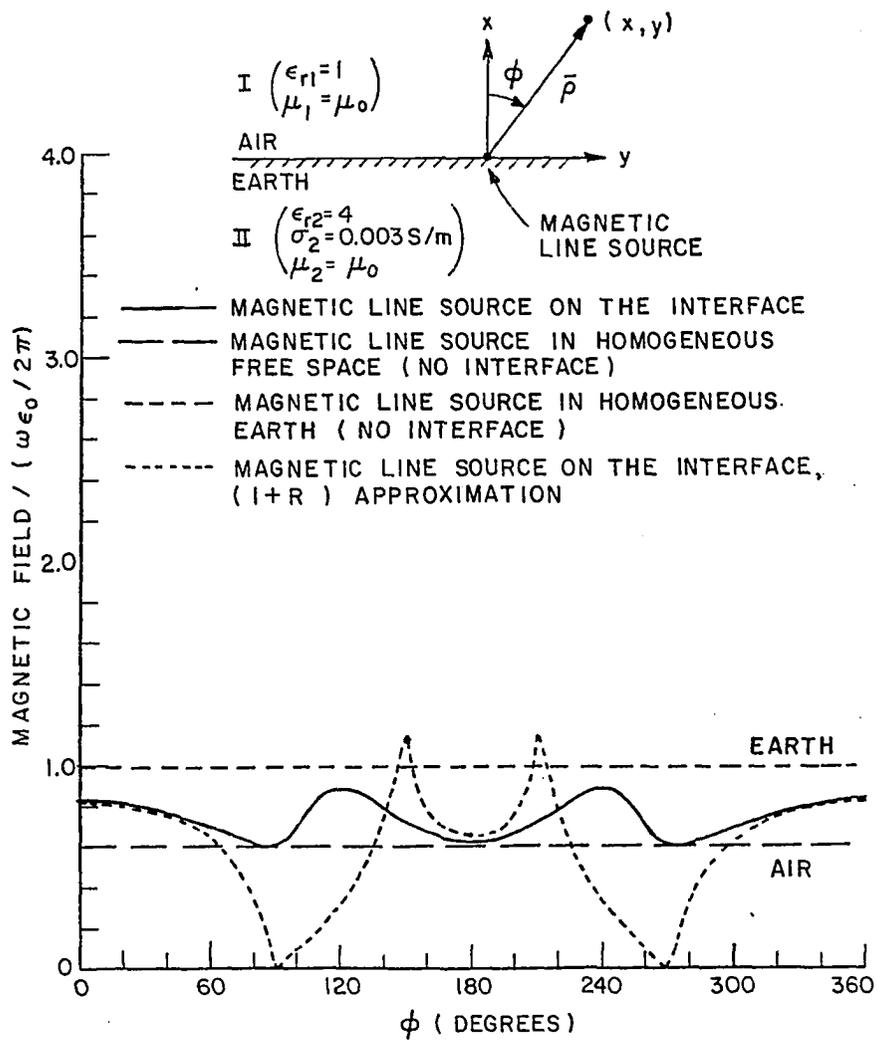


Figure 5-7. The same as Figure 5-6, except the earth lossy ($\sigma_2=0.003\text{ s/m}$).

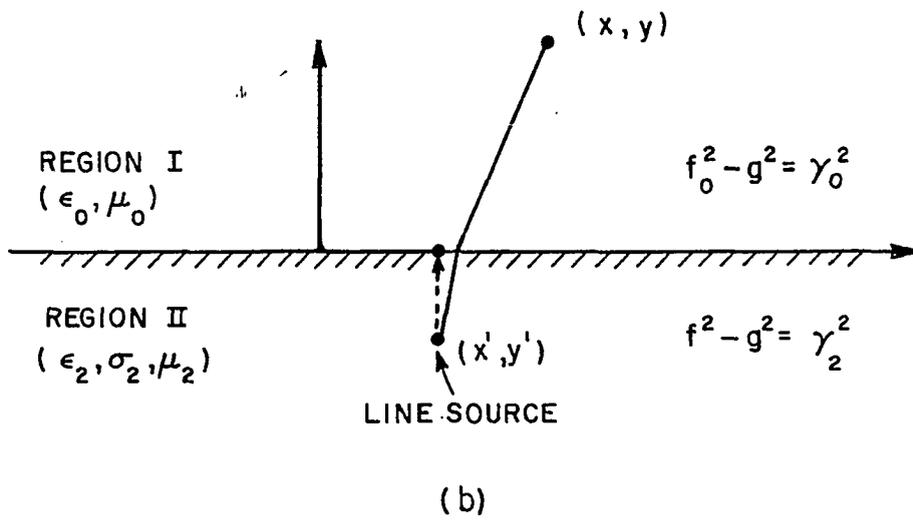
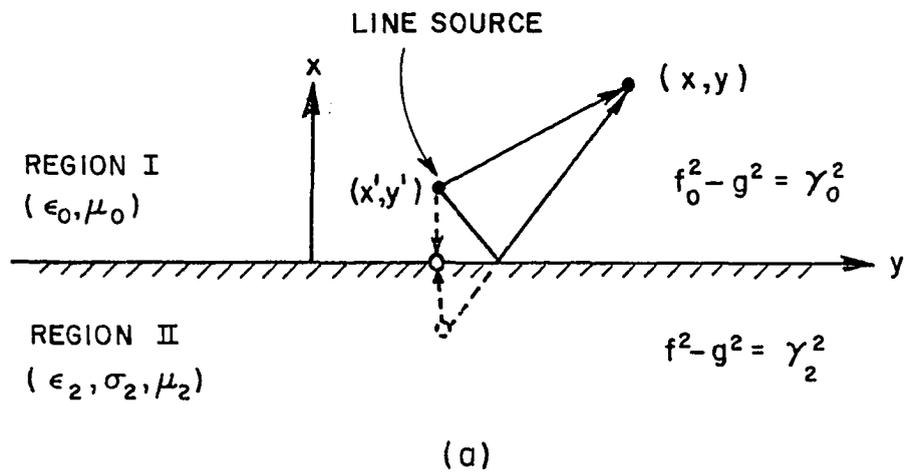


Figure 5-8. (a) An electric line source placed at (x', y') above the interface and moved towards the interface. (b) The same electric line source placed at (x', y') below the interface and moved towards the interface. In each case, the field is observed at (x, y) .

$$E_z(x,y) = \frac{-j\omega\mu_0\mu_2}{\pi} \int_0^{\infty} \frac{e^{-f_0x} \cos[g(y-y')]}{\mu_0f + \mu_2f_0} dy \quad ; x > 0 \quad . \quad (5.21)$$

Now, let us consider Figure 5-8b where the same electric line source is placed below the interface. The field observed at (x,y) above the interface can be expressed as

$$E_z(x,y) = \frac{-j\omega\mu_2}{2\pi} \int_0^{\infty} \frac{T_{\perp} e^{fx' - f_0x} \cos[g(y-y')]}{f_0} dg \quad ; x' < 0 \quad . \quad (5.22)$$

moving the line source towards the interface implies

$$\lim_{x' \rightarrow 0} (E_z(x,y)) = \frac{-j\omega\mu_2}{2\pi} \int_0^{\infty} \frac{T_{\perp} e^{-f_0x} \cos[g(y-y')]}{f} dg \quad . \quad (5.23)$$

substituting for T_{\perp} from Equation (5.12a) and simplifying give

$$E_z(x,y) = \frac{-j\omega\mu_0\mu_2}{\pi} \int_0^{\infty} \frac{e^{-f_0x} \cos[g(y-y')]}{\mu_0f + \mu_2f_0} dy \quad ; x > 0 \quad . \quad (5.24)$$

which is exactly the same as Equation (5.21). This can also be proved by using reciprocity theorem which is not included here.

The procedure is the same for a magnetic line source.

E. SOME REMARKS ON THE EVALUATION OF THE SOMMERFELD INTEGRAL

The Sommerfeld type integrals encountered in this dissertation are in general of the form

$$I = \int_0^{\infty} \frac{F(f,g)}{f} dg ; f^2 = \gamma_2^2 + g^2 . \quad (5.25)$$

The integrand may be singular depending on f , which can be expressed as

$$f^2 = -\omega^2 \mu_0 \epsilon'_2 + j\omega \mu_0 \sigma + g^2 . \quad (5.26)$$

where ϵ'_2 is the real part of the $\hat{\epsilon}_2$.

It can be seen from Equation (5.26) that for a lossy case, the above integrand does not have any singularities, thus, it can easily be evaluated numerically. For a lossless case, however, the integrand is singular when

$$g = g_c = \omega \sqrt{\mu_0 \epsilon'_2} . \quad (5.27)$$

To get around this problem, the integration path can be chosen as follows

$$I = \underbrace{\int_0^{g_1} \frac{F}{f} dg}_{I_1} + \underbrace{\int_{g_1}^{g_c} \frac{F}{f} dg}_{I_2} + \underbrace{\int_{g_c}^{\infty} \frac{F}{f} dg}_{I_3} \quad (5.28)$$

where

$$g_1 = g_c / \sqrt{2} .$$

I_1 is easy to evaluate. I_2 is evaluated by introducing the following transformation.

$$\beta^2 = g_c^2 - g^2 = -f^2 ; \quad \sigma = 0 . \quad (5.29a)$$

$$dg = -\frac{\beta}{g} d\beta \quad . \quad (5.29b)$$

$$I_2 = -j \int_0^{g_1} \frac{F}{g} d\beta \quad . \quad (5.30)$$

To evaluate I_3 the transformation

$$\alpha^2 = g^2 - g_c^2 = f^2 \quad ; \quad \sigma = 0. \quad (5.31a)$$

$$d_g = \frac{\alpha d\alpha}{g} \quad . \quad (5.31b)$$

$$I_3 = \int_0^{\infty} \frac{F}{g} d\alpha \quad . \quad (5.32)$$

May be used, thus the integral of Equation (5.25) takes the form

$$I = \int_0^{g_1} \frac{F}{f} dg + \begin{cases} \int_0^{g_1} \frac{F\beta d\beta}{fg} + \int_0^{\infty} \frac{F\alpha d\alpha}{fg} \quad ; \quad \sigma \neq 0 \\ -j \int_0^{g_1} \frac{F}{g} d\beta + \int_0^{\infty} \frac{F d\alpha}{g} \quad ; \quad \sigma = 0 \quad . \end{cases} \quad (5.33)$$

The $\int_0^{\infty} d\alpha$ may be approximated by $\int_0^{\alpha_1} d\alpha$, and a sufficiently large α_1 may be chosen for a good approximation. The value of α_1 is dependent on how fast or how slow the integrand is decaying. For the integrands encountered in this work $\alpha_1 = 10x[\text{maximum}(|\sigma_2|, |K_0|, g_c)]$ proved to be sufficient.

The above integrals have been programmed using Simpson's integration method and the program is included in Appendix E. F can be any nonsingular function of g .

F. SUMMARY

In this chapter the reflection coefficients for parallel and perpendicular polarizations were presented, some pattern were given for radiation by line sources on an air-earth interface. Finally, some remarks were made about the integration of Sommerfeld integral. In the next chapter, moment method formulation of E_z and H_z scattering by buried cylindrical geometries is presented.

CHAPTER VI

MOMENT METHOD FORMULATION FOR SCATTERING BY BURIED, LOSSY DIELECTRIC CYLINDERS OF INFINITE LENGTH

A. INTRODUCTION

In this chapter an electromagnetic scattering model for buried cylindrical geometries is introduced. The integral equations for E-Wave and H-wave scatterings are presented, and the moment method is used to solve these integral equations. Two sets of simultaneous linear equations obtained here are a modification of the system of linear equations obtained in Chapter II. This modification is introduced to incorporate the reflection at the air-earth interface into the solution.

Figure 6-1 shows a plane cut of the electromagnetic scattering model. The z-axis is parallel to the axis of the cylinder, and x=d plane constitutes the air-earth interface. The region inside the scatterer is designated by I ($\epsilon_1, \mu_1, \sigma_1$), and earth region external to the scatterer is designated by II ($\epsilon_2, \mu_2, \sigma_2$). The source of excitation is a line source at (x_s, y_s) or (ρ_s, ϕ_s) . For this model $x_s \leq d$

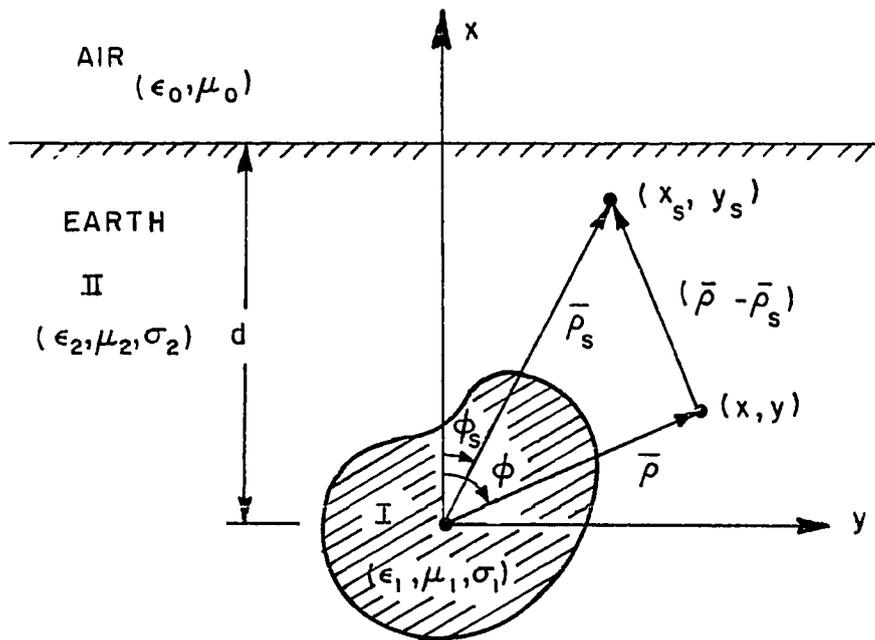


Figure 6-1. Electromagnetic scattering model for a lossy dielectric cylinder of infinite length buried in earth.

is considered without loss of generality. Thus the line source can be placed either on the interface or within the earth medium.

B. E-WAVE SCATTERING BY BURIED, LOSSY DIELECTRIC CYLINDERS OF INFINITE LENGTH

A uniform time harmonic, infinite electric line source is placed at (x_s, y_s) as shown in Figure 6-1. In homogeneous Medium II, this line source radiates a field given by Equation (2.1). For the model of Figure 6-1, the total field incident on the scatterer is the sum of the direct incident wave and the wave reflected at the interface and then incident toward the scatterer.

$$E_Z^i = E_Z^{id} + E_Z^{ir} \quad . \quad (6.1a)$$

where from Equation (5.15) one may obtain

$$E_Z^{id} = - \frac{j\omega\mu_0}{2\pi} \int_0^\infty \frac{e^{-f|x-x_s|} \cos[g(y-y_s)]}{f} dg \quad , \quad (6.1b)$$

and

$$E_Z^{ir} = - \frac{j\omega\mu_0}{2\pi} \int_0^\infty \frac{R_\perp e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \quad , \quad (6.1c)$$

where $I_0=1$ is assumed and R_\perp is the reflection coefficient given by Equation (5.12b).

In the presence of the scatterer and the interface the field at any point is given by

$$E_Z(x,y) = E_Z^{id} + E_Z^{ir} + E_Z^{sd} + E_Z^{sr} \quad . \quad (6.2)$$

where E_Z^{id} and E_Z^{ir} are direct and reflected incident fields due to the line source given by Equation (6.1). E_Z^{sd} and E_Z^{sr} are direct and reflected scattered fields. A typical ray geometry demonstrating these quantities are shown in Figure 6-2 for an elemental scatterer. Note that multiple reflections between the interface and the scatterer are implicitly contained in this solution. E_Z^{sd} and E_Z^{sr} are expressed

$$E_Z^{sd} = - \frac{j\omega\mu_0}{2\pi} \iint_{cs} J_{eq}(x',y') \left[\int_0^\infty \frac{e^{-f|x-x'|} \cos[g(y-y')]}{f} dg \right] ds' \quad , \quad (6.3a)$$

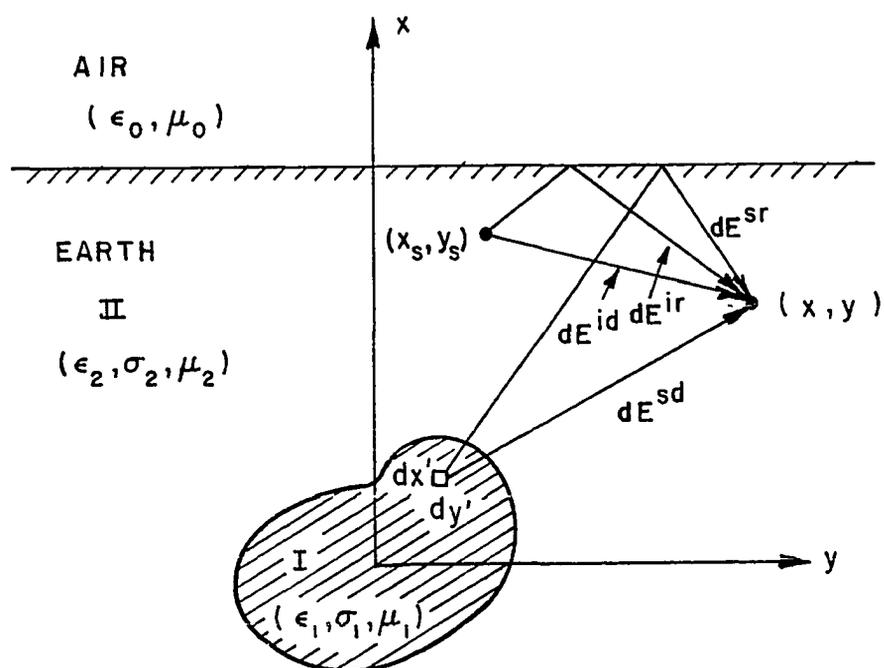


Figure 6-2. Illustration of typical direct incident and reflected incident fields, and direct scattered and reflected scattered fields for an element of the scatterer.

and

$$E_z^{sr} = -\frac{j\omega\mu_0}{2\pi} \iint_{cs} J_{eq}(x', y') \left[\int_0^\infty \frac{R_{\perp} e^{-f(2d-x-x')} \cos[g(y-y')]}{f} dg \right] ds' \quad (6.3b)$$

where J_{eq} is the equivalent volume polarization current placed at the position of the scatterer given by Equation (2.5). Using Equation (2.5) in Equation (6.3) yields

$$E_z^{sd} = \frac{\omega^2\mu_0(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{cs} E_z^I(x', y') \left[\int_0^\infty \frac{e^{-f|x-x'|} \cos[g(y-y')]}{f} dg \right] ds' \quad (6.4a)$$

and

$$E_Z^{sr} = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{CS} E_Z^I(x', y') \left[\int_0^\infty \frac{R_{\perp} e^{-f(2d-x-x')} \cos[g(y-y')]}{f} dg \right] ds'. \quad (6.4b)$$

$E_Z^I(x, y)$ is the field inside the scatterer to be obtained by evaluating Equation (6.2) in Region I. After rearranging Equation (6.2) and using Equations (6.4a) and (6.4b), the following integral equation is obtained.

$$E_Z^{id}(x, y) + E_Z^{ir}(x, y) = E_Z^I(x, y) - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{CS} E_Z^I(x', y') \left[\int_0^\infty \frac{e^{-f|x-x'|} \cos[g(y-y')]}{f} dg + \int_0^\infty \frac{R_{\perp} e^{-f(2d-x-x')} \cos[g(y-y')]}{f} dg \right] ds'. \quad (6.5)$$

The unknown function in the above integral equation is the field in Region I (E_Z^I). This unknown appears both in the integral and out of the integral, thus, it is a Fredholm integral equation of the second kind. The above integral equation is a modified form of integral equation given by Equation (2.7). The two additional terms are E^{ir} and E^{sr} due to the reflection at the interface. The present integral equation is solved in the same way as Equation (2.7) was solved. To avoid repetition, the attention is directed to the two new terms. The unknown function $E_Z^I(x, y)$ is expanded in terms of some known functions with unknown coefficients as in Equation (2.8), then substituted in the integral Equation (6.5). After the Galerkin testing is carried out

(discussed in Chapter II), the following system of linear equations is obtained

$$(V_m + \Delta V_m) = \sum_{n=1}^N C_n (Z_{mn} + \Delta Z_{mn}) \quad m=1,2,3,\dots, N \quad (6.6)$$

where V_m and Z_{mn} are given by Equations (2.12) and (2.13) respectively. ΔV_m and ΔZ_{mn} are given by

$$\Delta V_m = - \frac{j\omega\mu_0}{2\pi} \iint_{CS} F_m(x,y) \left[\int_0^{\infty} \frac{R_1 e^{-f(2d-x-x_s)} \cos g(y-y_s)}{f} dg \right] ds \quad (6.7)$$

and

$$\Delta Z_{mn} = - \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{CS} \iint_{CS} F_n(x',y') F_m(x,y) \left[\int_0^{\infty} \frac{R_1 e^{-f(2d-x-x')} \cos[g(y-y')] dg}{f} \right] ds' ds \quad (6.8)$$

After solving the system of linear Equation (6.6), the scattered field is obtained as

$$E_Z^S(x,y) = E_Z^{Sd}(x,y) + E_Z^{Sr}(x,y) \quad (6.9)$$

where $E_Z^{Sd}(x,y)$ is given by Equations (2.16) or (2.17), From Equations (6.4b) and (2.8), $E_Z^{Sr}(x,y)$ is obtained.

$$E_Z^{Sr}(x,y) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \sum_{m=1}^N C_m \iint_{CS} F_m(x',y') \left[\int_0^{\infty} \frac{R_1 e^{-f(2d-x-x')} \cos[g(y-y')] dg}{f} \right] ds' \quad (6.10)$$

For the backscattered case where $(x,y) = (x_s,y_s)$, $E_z^{sr}(x,y)$ can also be obtained by

$$E_z^{sr}(x_s,y_s) = j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) \sum_{m=1}^N C_m \Delta V_m \quad (6.11)$$

ΔV_m is given by Equation (6.7).

C. H-WAVE SCATTERING BY BURIED, LOSSY DIELECTRIC CYLINDERS OF INFINITE LENGTH

The electromagnetic scattering model of Figure 6-1 is used with the electric line source replaced by a magnetic line source. In homogeneous medium II, the magnetic field radiated by this magnetic line source is given by Equation (2.26). In the presence of the interface, the total field incident on the scatterer due to the line source is the sum of direct incident and reflected incident fields

$$H_z^i = H_z^{id} + H_z^{ir} \quad (6.12)$$

Substituting from Equation (3.6) into Equation (2.26) yields

$$H_z^{id} = -\frac{j\omega\hat{\epsilon}_2}{2\pi} \int_0^\infty \frac{e^{-f|x-x_s|} \cos[g(y-y_s)]}{f} dg \quad (6.13a)$$

and the reflected incident field is

$$H_z^{ir} = -\frac{j\omega\hat{\epsilon}_2}{2\pi} \int_0^\infty \frac{R_{||} e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \quad (6.13b)$$

where R_{\parallel} is the plane wave reflection coefficient given by Equation (5.11b). The scattered magnetic field at any point is the sum of direct scattered fields and scattered reflected fields

$$\bar{H}^s = \bar{H}^{sd} + \bar{H}^{sr} \quad , \quad (6.14)$$

where

$$\bar{H}^{sd} = \frac{1}{\mu_0} \nabla \times \bar{A}^{sd} \quad . \quad (6.15)$$

\bar{A}^{sd} is the electric vector potential given by Equation (2.29). From Equations (3.6), (2.29), and (6.15) the direct scattered field is obtained as

$$\bar{H}^{sd} = \frac{1}{2\pi} \nabla \times \iint_{cs} \bar{J}_{eq}(x',y') \left[\int_0^{\infty} e^{-f|x-x'|} \frac{\cos[g(y-y')]}{f} dg \right] ds' \quad . \quad (6.16)$$

Interchanging the order of differentiation and integration and using a well known vector identity yields

$$\begin{aligned} H_z^{sd} = & -\frac{1}{2\pi} \iint_{cs} \bar{J}_{eq}(x',y') \times \left[(\hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y}) \right. \\ & \left. \int_0^{\infty} e^{-f|x-x'|} \frac{\cos[g(y-y')]}{f} dg \right] ds. \end{aligned} \quad (6.17)$$

\bar{J}_{eq} is the equivalent electric volume polarization current in the scatterer given by Equation (2.5).

Using the reflection coefficient R_{\parallel} as given by Equation (5.11b) in above equation, the scattered reflected magnetic field is obtained as

$$\vec{H}^{sr} = -\frac{1}{2\pi} \iint_{cs} \vec{J}_{eq}(x', y') \times \left[\hat{x} \int_0^{\infty} \frac{f R_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dy \right. \\ \left. - \hat{y} \int_0^{\infty} \frac{g R_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right] ds' \quad (6.18a)$$

Thus

$$H_z^{sr} = \frac{1}{2\pi} \iint_{cs} \left[J_x(x', y') \int_0^{\infty} \frac{g R_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dy \right. \\ \left. + J_y(x', y') \int_0^{\infty} \frac{f R_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right] ds' \quad (6.18b)$$

where J_x and J_y are the x and y components of the equivalent electric volume polarization current.

The total magnetic field at any point is the sum of the direct incident and the reflected incident fields due to the magnetic line source and direct scattered and scattered reflected fields due to the scatterer. A typical ray geometry describing this situation for an elemental section of the scatterer is shown in Figure 6-2, where the E-field may be replaced by H field for the case under consideration.

Thus

$$\bar{H} = \bar{H}^{id} + \bar{H}^{ir} + \bar{H}^{sd} + \bar{H}^{sr} \quad (6.19)$$

As it was discussed in Chapter II, it is preferred to obtain an integral equation involving the electric field as the unknown function. This choice improved the convergence of the solution significantly (see Chapter II). To obtain an integral equation involving \bar{E}^I , Maxwell's equation is used to find \bar{E}^{id} , \bar{E}^{ir} , \bar{E}^{sd} , and \bar{E}^{sr} in Region II from \bar{H}^{id} , \bar{H}^{ir} , \bar{H}^{sd} , and \bar{H}^{sr} respectively. Then the resulting equation is evaluated in Region I.

Thus, one may write

$$\bar{E}^{id} + \bar{E}^{ir} = \bar{E}^I - \bar{E}^{sd} - \bar{E}^{sr} \quad ; \text{in Region I, where } \bar{E}^{id} \text{ is given by Equation (2.27a), and from Equation (6.13b)} \quad (6.20)$$

$$\begin{aligned} \frac{-ir}{E} &= \frac{1}{j\omega\hat{\epsilon}_2} \nabla \times \bar{H}^{ir} \\ &= \frac{1}{2\pi} \left[\hat{x} \int_0^\infty \frac{gR_{\parallel} e^{-f(2d-x-x_s)} \sin[g(y-y_s)]}{f} dg \right. \\ &\quad \left. + \hat{y} \int_0^\infty \frac{fR_{\parallel} e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \right] . \end{aligned} \quad (6.21)$$

\bar{E}^{sd} is given by Equation (2.37), which is found by using Maxwell's equation in Equation (6.15) and using Lorentz condition. \bar{E}^{sr} is found from Equation (6.18a) as follows

$$\begin{aligned}
\frac{\underline{s}r}{E} &= \frac{1}{j\omega\hat{\epsilon}_2} \nabla \times \underline{s}r \\
&= \frac{-1}{2\pi j\omega\hat{\epsilon}_2} \iint_{CS} \nabla \times \left\{ \bar{J}_{eq}(x',y') \times \left[\hat{x} \int_0^{\infty} \frac{fR_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right. \right. \\
&\quad \left. \left. - \hat{y} \int_0^{\infty} \frac{gR_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right] \right\} ds. \tag{6.22}
\end{aligned}$$

Using the above quantities in Equation (6.20) and substituting for \bar{J}_{eq} from Equation (2.5) yields the following integral equation.

$$\begin{aligned}
\frac{\underline{i}d}{E(x,y)} + \frac{\underline{i}r}{E(x,y)} &= \frac{\underline{I}}{E(x,y)} - \frac{\omega^2\mu_0(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} \iint_{CS} \bar{E}(x,y) K_0(\gamma_2|\bar{\rho} - \bar{\rho}'|) ds' \\
&\quad - \frac{\gamma_2(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi\hat{\epsilon}_2} \int_{\ell} \left[\bar{E}(x',y') \cdot \hat{n}(\ell') \right] K_1(\gamma_2|\bar{\rho} - \bar{\rho}'|) \hat{\rho} d\ell' \\
&\quad + \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi\hat{\epsilon}_2} \iint_{CS} \nabla \times \left\{ \bar{E}(x',y') \times \left[\hat{x} \int_0^{\infty} \frac{fR_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right. \right. \\
&\quad \left. \left. - \hat{y} \int_0^{\infty} \frac{gR_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right] \right\} ds'. \tag{6.23}
\end{aligned}$$

The unknown function in the above integral equation is $\bar{E}(x,y)$ which appears inside and outside of the integrals, thus, this may be viewed as a Fredholm integral equation of the second kind. \bar{E}^d and \bar{E}^r have been defined previously. The above integral equation is basically

the same as the integral equation in Equation (2.38b) except here two additional terms due to the reflection at the interface are added. This integral equation is solved in the same way as Equation (2.38b) was solved. To avoid repetition, the attention is focused on the reflected terms. After expansion and testing (see Chapter II) the new system of linear equations is as follows

$$(V_m + \Delta V_m) = \sum_{n=1}^N C_n (Z_{mn} + \Delta Z_{mn}) \quad (6.24a)$$

where V_m and Z_{mn} are given by Equations (2.42) and (2.43) respectively and,

$$\Delta V_m = \iint_{CS} \bar{F}_m(x,y) \cdot \bar{E}(x,y) \, ds \quad m=1,2,\dots,N \quad (6.24b)$$

Substituting from Equations (2.40b) and (6.21) in Equation (6.24b) yields

$$\Delta V_m = \frac{1}{2\pi} \iint_{CS} \left[\frac{\partial F_m(x,y)}{\partial y} \int_0^{\infty} \frac{g R_{\parallel} e^{-f(2d-x-x_s)} \sin[g(y-y_s)]}{f} dg - \frac{\partial F_m(x,y)}{\partial x} \int_0^{\infty} \frac{f R_{\parallel} e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \right] ds \quad (6.24c)$$

Testing the last term in the integral equation (6.23)

$$\Delta Z_{mn} = - \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2)P}{2\pi\hat{\epsilon}_2} \iint_{CS} \iint_{CS} \bar{F}_m(x,y) \cdot \left\{ \nabla_x \left[\bar{F}_n(x',y') \times \left(\hat{x} \int_0^\infty \frac{f R_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right. \right. \right. \\ \left. \left. \left. - \hat{y} \int_0^\infty \frac{g R_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right) \right] \right\} ds' ds . \quad (6.25)$$

where $\bar{F}_m(x,y)$ and P are given by Equations (2.40b) and (2.40c) respectively.

A further simplified form of ΔZ_{mn} is given by

$$\Delta Z_{mn} = - \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2)P}{2\pi\hat{\epsilon}_2} \iint_{CS} \iint_{CS} \left[\frac{\partial F_m(x,y)}{\partial y} \frac{\partial F_n(x',y')}{\partial y'} \right. \\ \left. \int_0^\infty \frac{g^2 R_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg + \left(\frac{F_m(x,y)}{\partial y} \frac{\partial F_n(x',y')}{\partial x'} \right. \right. \\ \left. \left. + \frac{\partial F_m(x,y)}{\partial x} \frac{\partial F_n(x',y')}{\partial y'} \right) \int_0^\infty \frac{f g R_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right. \\ \left. - \frac{\partial F_m(x,y)}{\partial x} \frac{\partial F_n(x',y')}{\partial x'} \int_0^\infty \frac{f^2 R_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right] ds' ds . \quad (6.26)$$

After solving the system of linear equations (6.24), the scattered field is obtained by

$$H_Z^S(x,y) = H_Z^{sd}(x,y) + H_Z^{sr}(x,y) . \quad (6.27)$$

$H_z^{sd}(x,y)$ is given by Equation (2.46) or Equation (2.47). To calculate H_z^{sr} Equation (2.40) is substituted in Equation (2.5), from which J_x and J_y are determined. Substituting for J_x and J_y in Equation (6.18b) yields

$$H_z^{sr}(x,y) = + \frac{j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)P}{2\pi} \sum_{m=1}^N C_m \iint_{CS} \left[\frac{\partial F_m(x',y')}{\partial y'} \int_0^{\infty} \frac{gR_{||} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg \right. \\ \left. - \frac{\partial F_m(x',y')}{\partial x'} \int_0^{\infty} \frac{fR_{||} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right] ds' \quad (6.28)$$

P is given by Equation (2.40c).

The above equation in general may be used to calculate the bistatic or backscattered fields. However, for backscattered case, i.e., $(x,y) = (x_s,y_s)$, a comparison of Equation (6.28) with Equation (6.24) reveals that the following can be written

$$H_z^{B.sr.}(x_s,y_s) = \frac{j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)P}{2\pi} \sum_{m=1}^N C_m \Delta V_m \quad (6.29)$$

where ΔV_m is given by Equation (6.24c).

D. SUMMARY

In this chapter, an electromagnetic scattering model for buried two-dimensional, cylindrical geometries was presented. Integral equations involving the unknown electric field inside the scatterer for

parallel and perpendicular polarization were derived. To solve these integral equations the moment method was used and corresponding linear equations were derived.

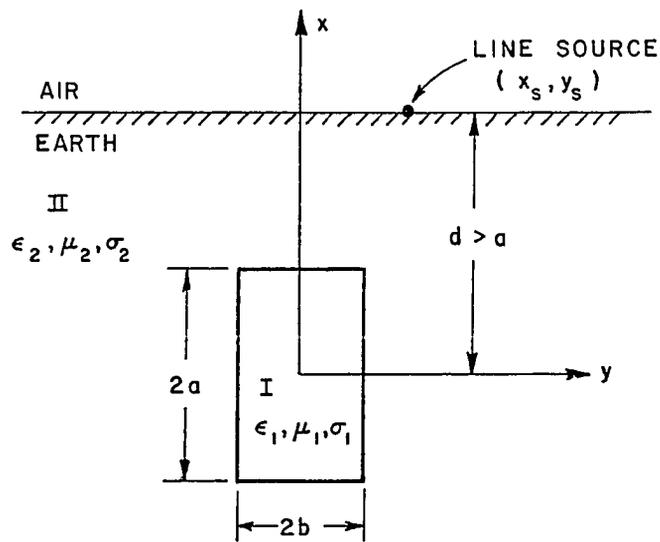
In the next chapter, the E-wave scattering model is specialized to buried rectangular cylinders and the moment method formulation presented here is applied by choosing a set of basis and testing functions.

CHAPTER VII
E-WAVE SCATTERING BY BURIED, LOSSY DIELECTRIC
RECTANGULAR CYLINDER OF INFINITE LENGTH

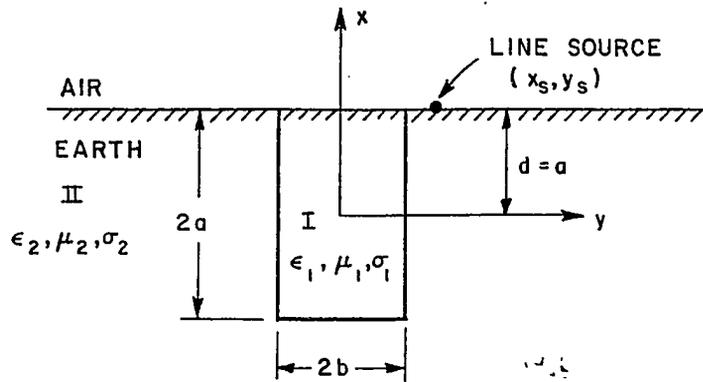
A. INTRODUCTION

An E-wave scattering model for lossy dielectric rectangular cylinders buried in earth is presented. This model may be used to simulate a tunnel or a trench geometry. The moment method formulations are presented. Then the number of plane waves in the expansion to obtain convergence is considered. Some numerical results are presented and discussed.

Figure 7-1 shows a plane cut of the electromagnetic scattering model. A $(2a)$ by $(2b)$ rectangular dielectric cylinder is buried in earth region designated by II $(\epsilon_2, \mu_2, \sigma_2)$. The z -axis is along the axis of the cylinder and $x=d$ plane constitutes the air-earth interface. For the sake of simplicity, $a \ll x_0 \ll d$ is assumed. If $d > a$, the tunnel geometry is modeled (Figure 7-1a), and if $d = a$, the trench geometries is modeled (Figure 7-1b). Most of the geometries considered in this chapter are for filled trenches and tunnels. This reflects the interest of one of the supporting agencies but does not restrict the applicability of the techniques.



(a) TUNNEL GEOMETRY



(b) TRENCH GEOMETRY

Figure 7-1. The electromagnetic scattering model for (a) a buried tunnel, and (b) a trench geometry.

B. PLANE WAVE EXPANSION

The system of linear Equation (6.6) has already been discussed for an infinite-length cylinder of arbitrary cross-section shape and for general basis functions. Here it suffices to choose the basis functions and evaluate the cross-sectional integrations in a closed form in the same manner as discussed in Chapter III. The set of simultaneous linear equations obtained are

$$(V_m + \Delta V_m) = \sum_{n=1}^N C_n (Z_{mn} + \Delta Z_{mn}) ; m = 1, 2, 3, \dots, N \quad (7.1)$$

V_m and Z_{mn} are now given by Equations (3.8) and (3.5) respectively, and from Equations (6.7) and (3.1).

$$\Delta V_m = \frac{-j\omega\mu_0}{2\pi} \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} \left[\int_0^\infty \frac{R_1 e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \right] dx dy \quad (7.2)$$

From Equations (6.8) and (3.1)

$$\Delta Z_{mn} = C_1 \int_{-a}^a \int_{-a}^b \int_{-a}^b \int_{-a}^b e^{-jf_n x'} e^{-jg_n y'} e^{-jf_m x} e^{-jg_m y} \left[\int_0^\infty \frac{R_1 e^{-f(2d-x-x')} \cos[g(y-y')] }{f} dg \right] dx' dy' dx dy \quad (7.3)$$

C_1 is given by Equation (3.5d).

Interchanging the order of the integrations in Equation (7.2) and rearranging terms, one obtains

$$\Delta V_m = -\frac{j\omega\mu_0}{2\pi} \int_0^\infty \frac{R_1 e^{-f(2d-x_s)}}{f} \left[\int_{-a}^a \int_{-b}^b \frac{e^{-j f_m x} e^{j f x}}{e^{-j g_m y} \cos[g(y-y_s)]} dx \int_{-b}^b e^{-j g_m y} \cos[g(y-y_s)] dy \right] dg ,$$

or

$$\Delta V_m = -\frac{j\omega\mu_0}{\pi} \int_0^\infty \frac{R_1 e^{-f(2d-x_s)}}{f} (F_m \cdot GE_m^V) dg , \quad (7.4a)$$

where

$$F_m = \frac{\sin[(f_m + j f) a]}{(f_m + j f)} . \quad (7.4b)$$

GE_m^V is given by Equation (3.8c).

Changing the order of integration and rearranging terms in Equation (7.3) yields

$$\Delta Z_{mn} = C_1 \int_0^\infty \frac{R_1 e^{-2fd}}{f} \left[\int_{-a}^a \int_{-a}^a \frac{e^{-j f_n x'} e^{j f x'}}{e^{-j f_m x} e^{j f x}} dx' \int_{-a}^a \int_{-b-b}^b \frac{e^{-j g_n y'} e^{-g_m y}}{e^{-j g_m y} \cos[g(y-y')] } dy' dy \right] ,$$

or

$$= 8C_1 \int_0^\infty \frac{R_1 e^{-2fd}}{f} (F_n \cdot F_m \cdot GE_{mn}) dg . \quad (7.5)$$

F_m and F_n are given by Equation (7.4b), and GE_{mn} is given by Equation (3.10c).

After solving the system of linear equations (7.1) for C_n 's, the scattered field is calculated by

$$E_Z^S(x,y) = E_Z^{sd} + E_Z^{Sr} \quad , \quad (7.6)$$

where E_Z^{sd} is given by Equations (3.11) or (3.12), and E_Z^{Sr} is found from Equations (6.10) and (3.1) as

$$E_Z^{Sr}(x,y) = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{\pi} \sum_{m=1}^N C_m \int_0^{\infty} \frac{R_{\perp} e^{-f(2d-x)}}{f} (F_m \cdot GE_m^V) dg \quad . \quad (7.7)$$

F_m is given by Equation (7.4b) and GE_m^V is given by Equation (3.8c) with y_s replaced by y . An additional way to obtain the backscattered field $((x,y) = (x_s, y_s))$ is by comparing Equations (7.7) and (7.4) which yields

$$E_Z^{Sr}(x_s, y_s) = -j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2) \sum_{m=1}^N C_m \Delta V_m \quad . \quad (7.8)$$

ΔV_m is given by Equation (7.4).

C. CONVERGENCE

Two computer programs were developed to model the air-earth interface and buried scatterers. These programs are called RTUNLE and RCYLEGP. The former uses the closed form evaluation for the cross-sectional integrals, whereas, the latter uses numerical integration for

the cross-sectional integrals. These computer programs are included and fully discussed in the Appendices B and F.

To test the convergence of the solution, a typical convergence test is made. The scattered field is calculated for increasing number of plane waves in the expansion (N). For this purpose, a 1 m square tunnel with $\epsilon_{r1}=2$ and $\sigma_1=.0012$ s/m buried 1 m below the interface in an earth with $\epsilon_{r2}=4$ and $\sigma_2=.003$ s/m, is considered. The source of excitation is an electric line source located on the interface directly above the tunnel. Figure 7-2 shows the resulting backscattered field versus increasing number of plane waves spanning the field inside the tunnel. The solution is converged for $N \geq 6$. After convergence the solution seems to be very stable and the curve is smooth for the range shown. Using Equation (3.14), a value for $\Delta\phi$ is included for all values of N and is included in Figure 7-2.

An approximate model can be developed that can be used to explain much of the details of structure of the scattering patterns to be computed using the above more precise numerical analysis.

First, the fields radiated into the "earth" medium by an electric line source at the interface are given by

$$\bar{E}_{em} = \bar{E}_{homo} (1 + R_{\perp}) \quad .$$

where \bar{E}_{homo} are the fields radiated into a homogeneous earth medium and

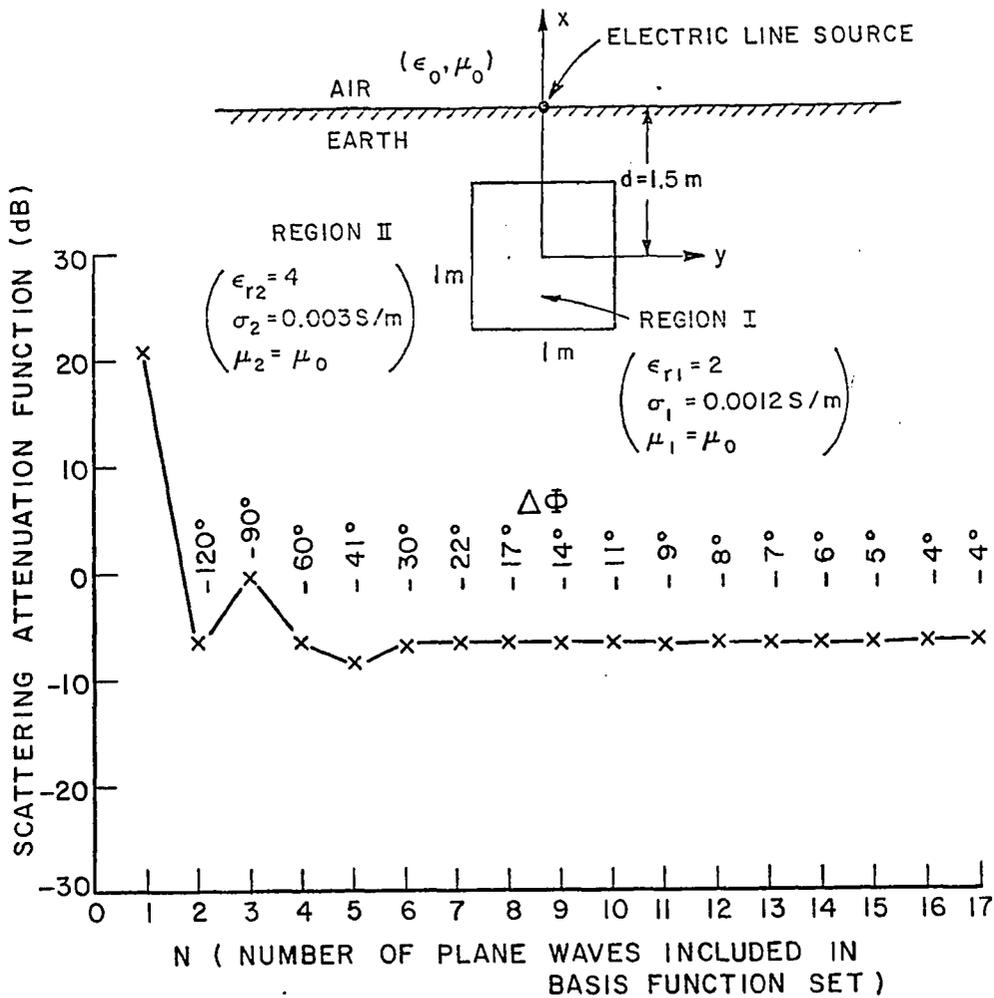


Figure 7-2. The convergence curve for computer program RTUNLE for a buried tunnel. Scattering Attenuation Function is calculated for increasing values of N , the number of plane waves in the expansion. The frequency used is 100 MHz.

R_{\perp} is the plane wave reflection coefficient for incidence on the interface from the "earth" medium.

This approximation was confirmed in Chapter V.

Second, the fields scattered by the target are also incident on the interface. This requires that a second $(1+R_{\perp})$ factor be introduced. Thus the SAF_I for the case for the interface could be approximated by

$$SAF_I = (SAF)_{\text{homo}} (1+R_{\perp})^2$$

where $(SAF)_{\text{homo}}$ is the scattering attenuation function when the target and source are contained in a homogeneous medium. Note that the normalization used in this dissertation did not include the interface, i.e., the normalization factor was the fields of a line source at the image position in a homogeneous medium. If the interface had been included in the normalization procedure, the SAF would to a first approximation be dependent only on the target.

Another factor that appears in the appropriate forms are the scattering patterns of the "tunnels". Referring to Figure 3-4, it is seen that only a small lobe appears at $\phi=180^\circ$. This is the region for which we will be observing these targets. Thus if one considers the factors discussed above, the scattering pattern of the tunnel in a homogeneous medium and the scattering pattern of the line source on the interface, then the computed results to be shown are those that would be anticipated.

D. SCATTERING PATTERNS

Some examples of bistatic and backscattered patterns are given for a filled trench and some tunnel geometries. A family of curves is presented for increasing values of "d", the depth of the center of the tunnel. The trench or tunnel (see Figure 7-1) is modeled by a 1 m by .5 m rectangular cylinder of infinite length with $\epsilon_{r1}=2$, $\sigma_2=.0012$ s/m, and $\mu_1=\mu_0$. The earth is modeled by a medium with $\epsilon_{r2}=4$, $\sigma_2=.003$ s/m, and $\mu_2=\mu_0$. The frequency used is 100 MHz. The electromagnetic scattering model is shown in Figure 7-3. An electric line source is placed on the interface parallel to z-axis at $(x_s=d, y_s)$.

1. Backscattered Patterns

Figure 7-3 shows various backscattered patterns. When $d=a=.5$ m, a trench geometry is modeled. The backscattered pattern for this trench geometry is shown in Figure 7-3, which indicates a strong backscattered field in regions directly above the trench. After a minimum at $|y|\approx.5$ m region, the backscattered field increases slightly and then falls rapidly as $|y|$ is increased.

For values of $d>a$ tunnel geometries are modeled. Some backscattered patterns are included in Figure 7-3 for tunnels buried at $d=.75$ m, 1m, 1.25m, and 1.5m. These patterns, in general, follow the same shape as that of the trench, except that, the pattern is widened and reduced in magnitude for most regions close to the scatterer. This is caused by the scattering pattern of the tunnel and is not an

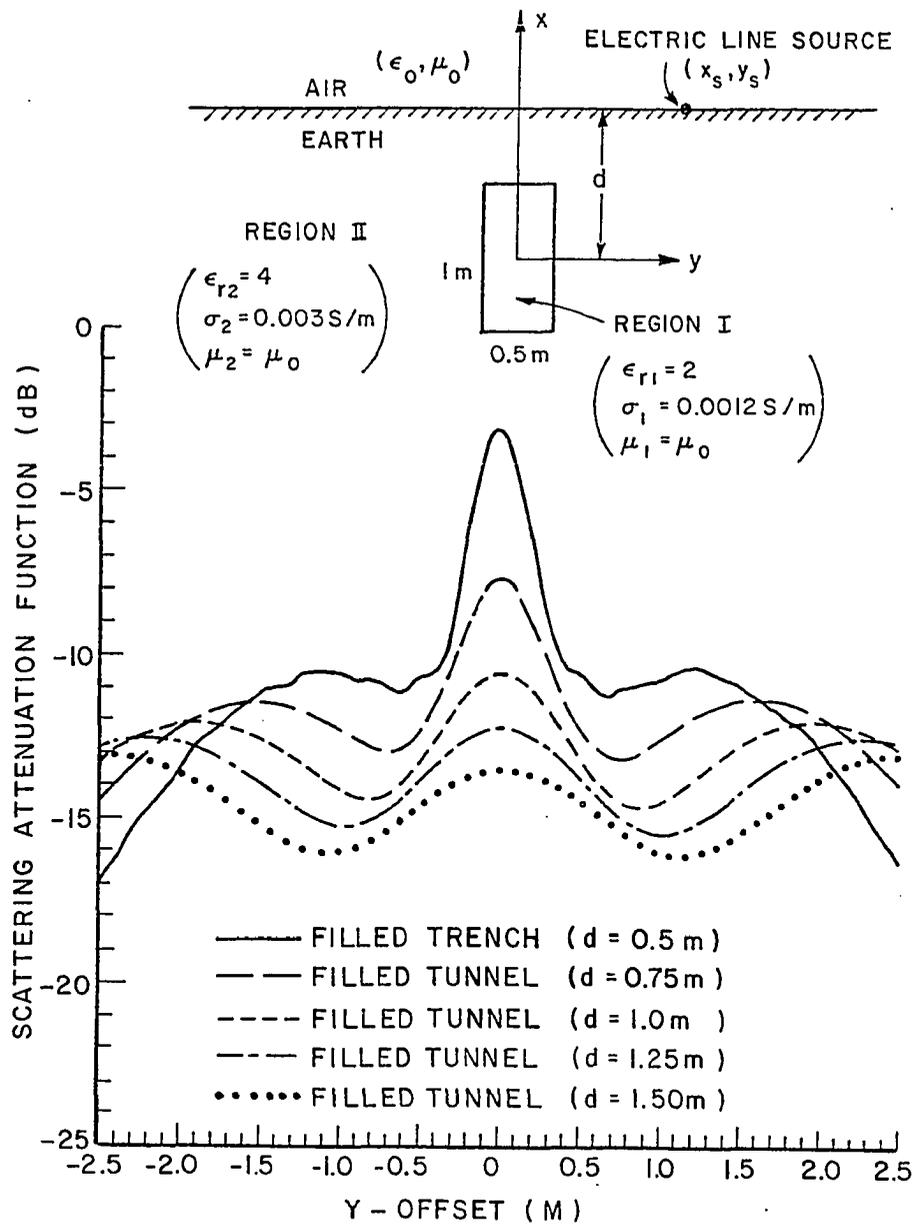


Figure 7-3. The backscattering patterns for trench and tunnel geometries. The electric line source is placed on the interface, parallel to z-axis, and moved from $y = -2.5 \text{ m}$ to $y = 2.5 \text{ m}$ incrementally. The frequency is 100 MHz.

interface phenomena. Figure 7-3 suggests that (for the case under consideration) for deeply buried tunnels, there is not a distinct maximum above the tunnel, while for shallowly buried tunnel for this case, there is a definite maximum directly above the tunnel.

To investigate the effect of the air-earth interface on the backscattering patterns of a trench and a tunnel, Figures 7-4 and 7-5 are presented. Figure 7-4 shows the backscattered pattern for the trench geometry discussed in Figure 7-3. In addition, an analogous backscattered pattern is given for a case where the air-earth interface is removed (i.e., air region is replaced with Region II). This pattern shows that the air-earth interface changes the backscattered pattern considerably. For the case shown, Figure 7-4 suggests that the interface enhances the backscattered field in the vicinity of the trench. This is because the source and observation point are in the immediate vicinity of the top of the tunnel. Note that the increase in the Scattering Attenuation Function (SAF) level at when the source is at the top of the trench may be obtained by multiplying the SAF with no interface by $(1+R_{\perp})^2$ where R_{\perp} is the plane wave reflection coefficient for a wave in the tunnel normally incident on the interface. The decay in the pattern as y increases is caused by the directional pattern of the line source on the interface as shown in Chapter V. For the case of the tunnel (Figure 7-5), the line source pattern is not significant. We also note that the presence of the interface is approximately accounted for by the $(1+R_{\perp})^2$ factor. In this case, the interface for which R_{\perp} is computed is that between medium II and free space.

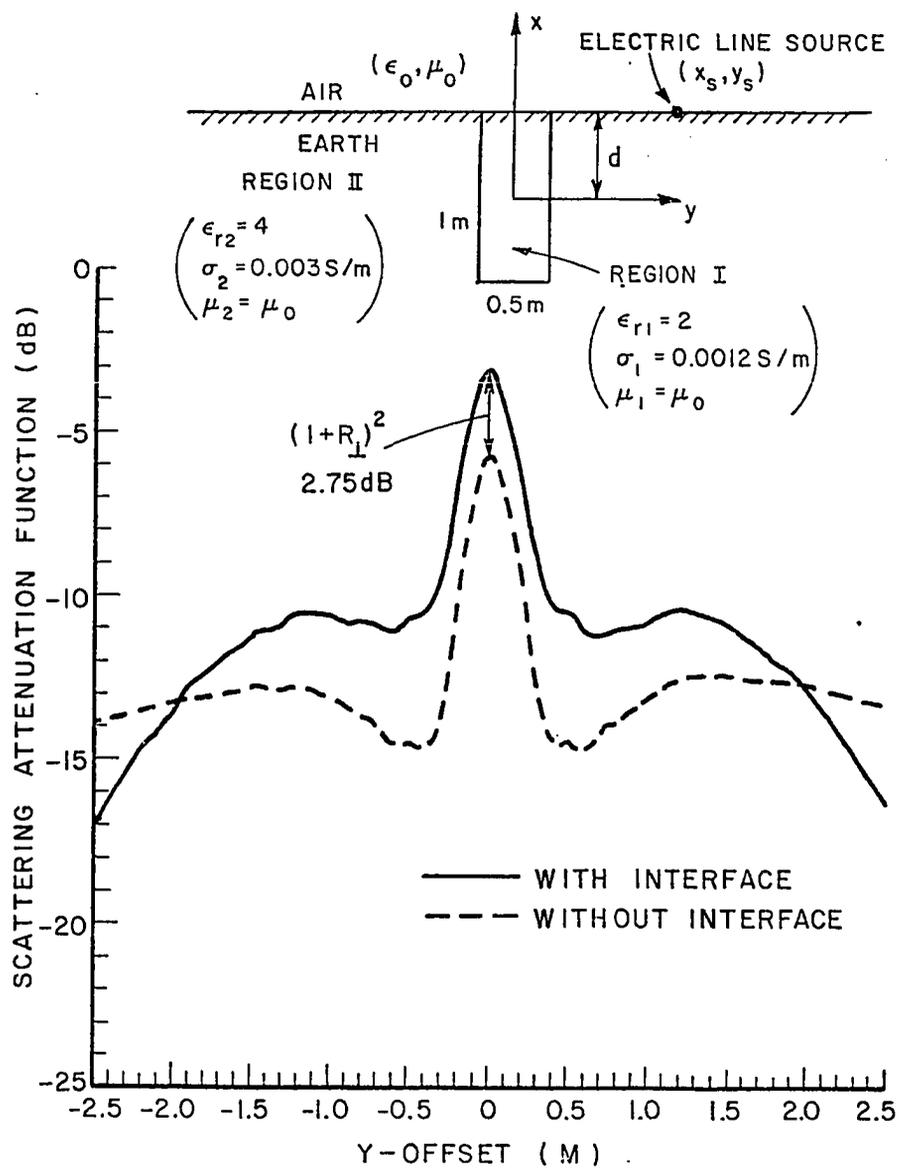


Figure 7-4. Comparison of backscattered field patterns of a trench geometry, with and without the air-earth interface. Frequency is 100 MHz.

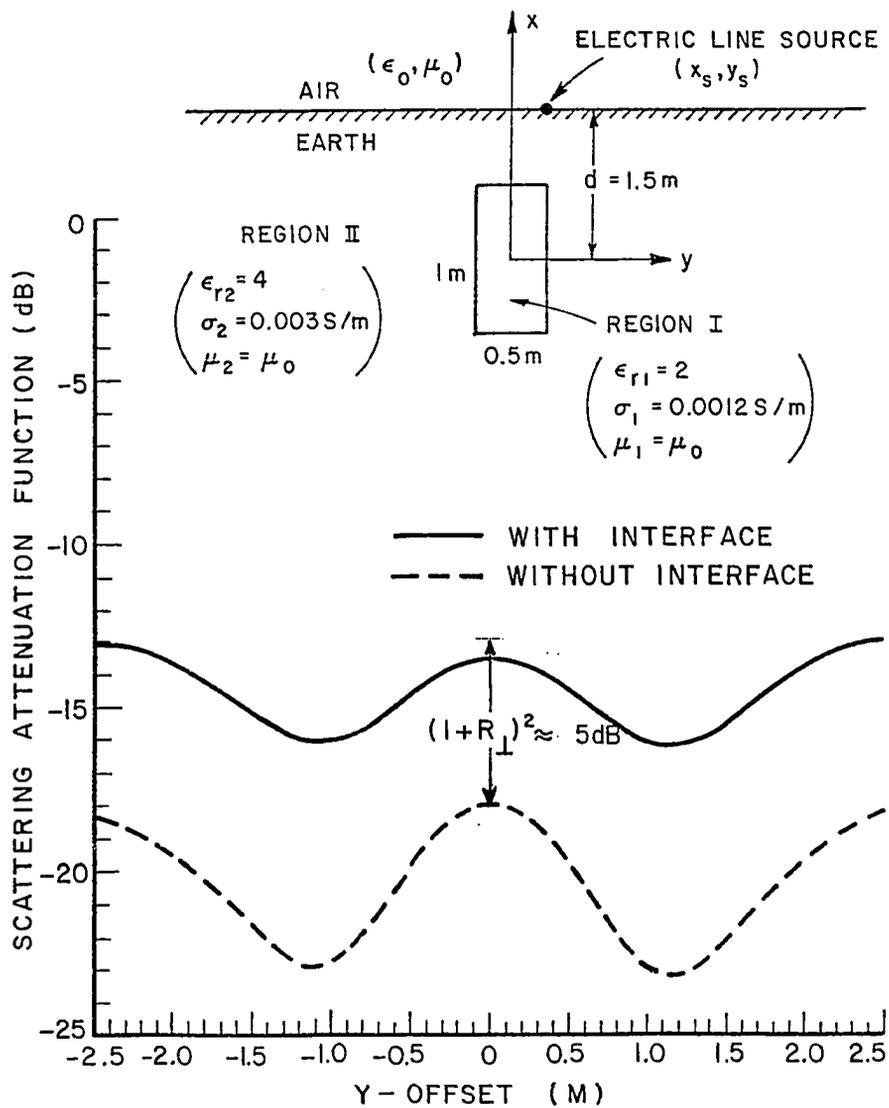


Figure 7-5. Comparison of backscattered field patterns of a tunnel geometry, with and without the air-earth interface. Frequency is 100 MHz.

This $(1+R_{\perp})^2$ factor is that suggested by Burrell and Peters [47]. The fields radiated by the line source into the medium are increased by $(1+R_{\perp})$ as was discussed in Chapter V. The total scattered fields are also increased by $(1+R_{\perp})$ on reflection at the interface.

2. Bistatic Scattering Patterns

As a first example of bistatic scattering pattern, an electric line source is placed on the interface at $(x_s, y_s) = (d, 0)$ and the scattered field is observed on the interface at $y = -2.5\text{m}$ to $y = 2.5\text{m}$ incrementally. This model is shown in Figure 7-6. Some bistatic scattering patterns are included in Figure 7-6 for a trench geometry and some tunnels buried at $d = .75\text{m}$, 1m , 1.25m , and 1.5m . For the trench case ($d = a = .5\text{m}$), the bistatic pattern is maximum directly above the trench and it falls rapidly as $|y|$ is increased. For tunnel geometries ($d > a$) the general shape of the bistatic pattern is similar to that of the trench and is reduced in amplitude and widened as d is increased. It is also noted that the bistatic pattern falls with a slower rate for deeper tunnels. This is primarily caused by the scattering angles becoming more restrictive as the depth increases.

To investigate the effect of the air-earth interface on the bistatic patterns of a trench and a tunnel, Figures 7-7 and 7-8 are presented. Figure 7-7 shows the bistatic scattering pattern for the trench geometry discussed in Figure 7-6. In addition, a similar bistatic scattering pattern is given for a case where the air-earth interface is removed (i.e., air region is replaced by Region II).

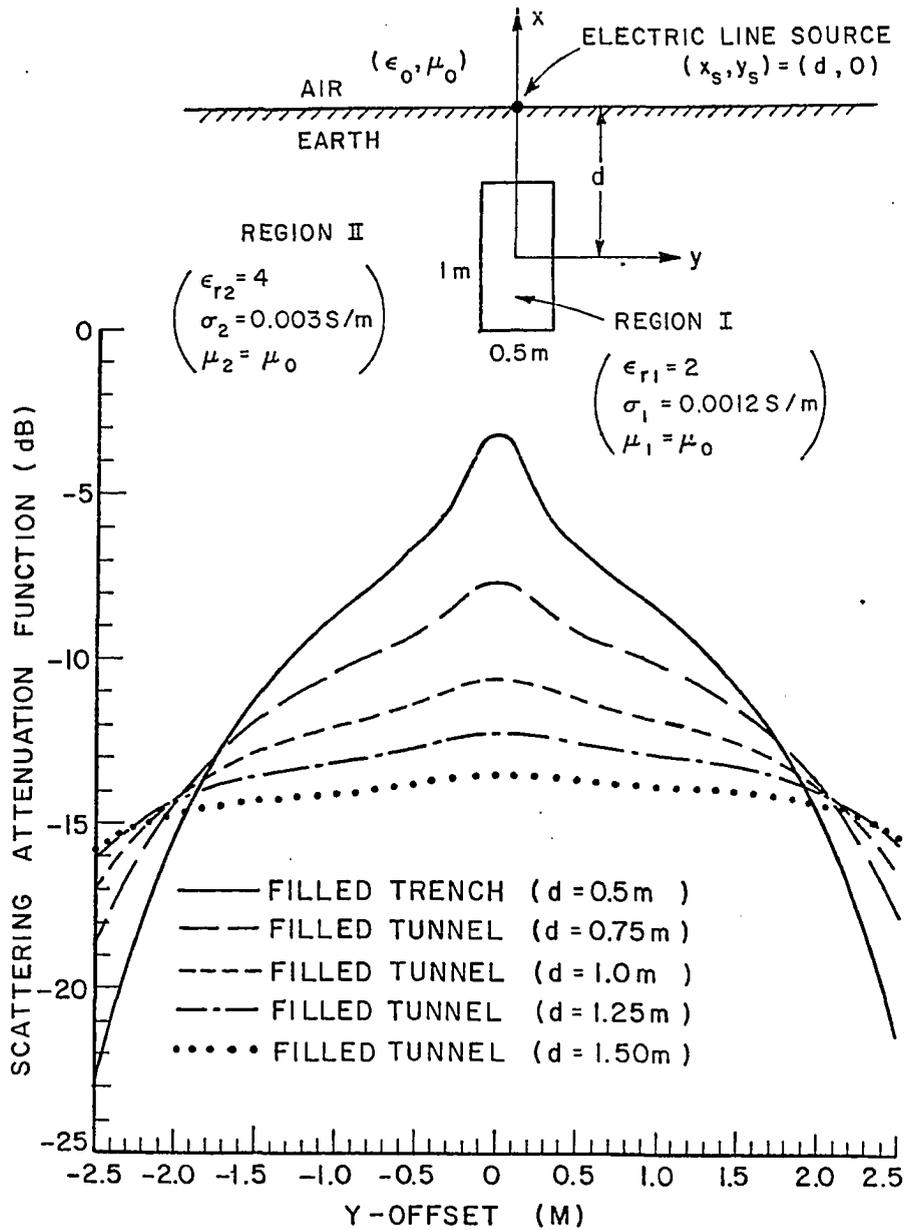


Figure 7-6. Bistatic scattering patterns for some trench and tunnel geometries. An electric line source is placed on the interface at $(x_s, y_s) = (d, 0)$ parallel to z-axis, and the scattered field is observed at points on the interface along y-axis (from $y = -2.5\text{m}$ to $y = 2.5\text{m}$). The frequency is 100 MHz.

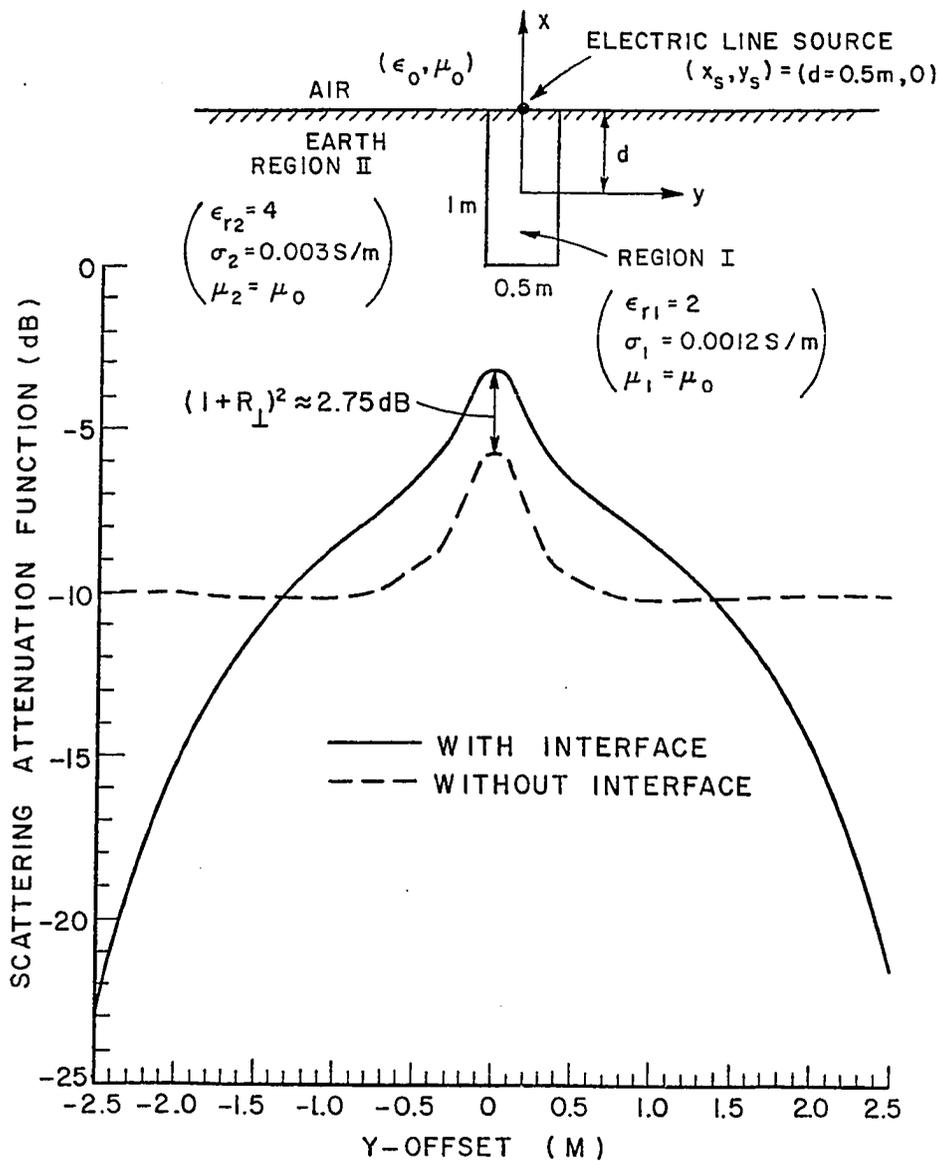


Figure 7-7. Comparison of the bistatic scattering patterns for a trench geometry, with and without the air-earth interface. Frequency is 100 MHz. $(1+R_{\perp})^2$

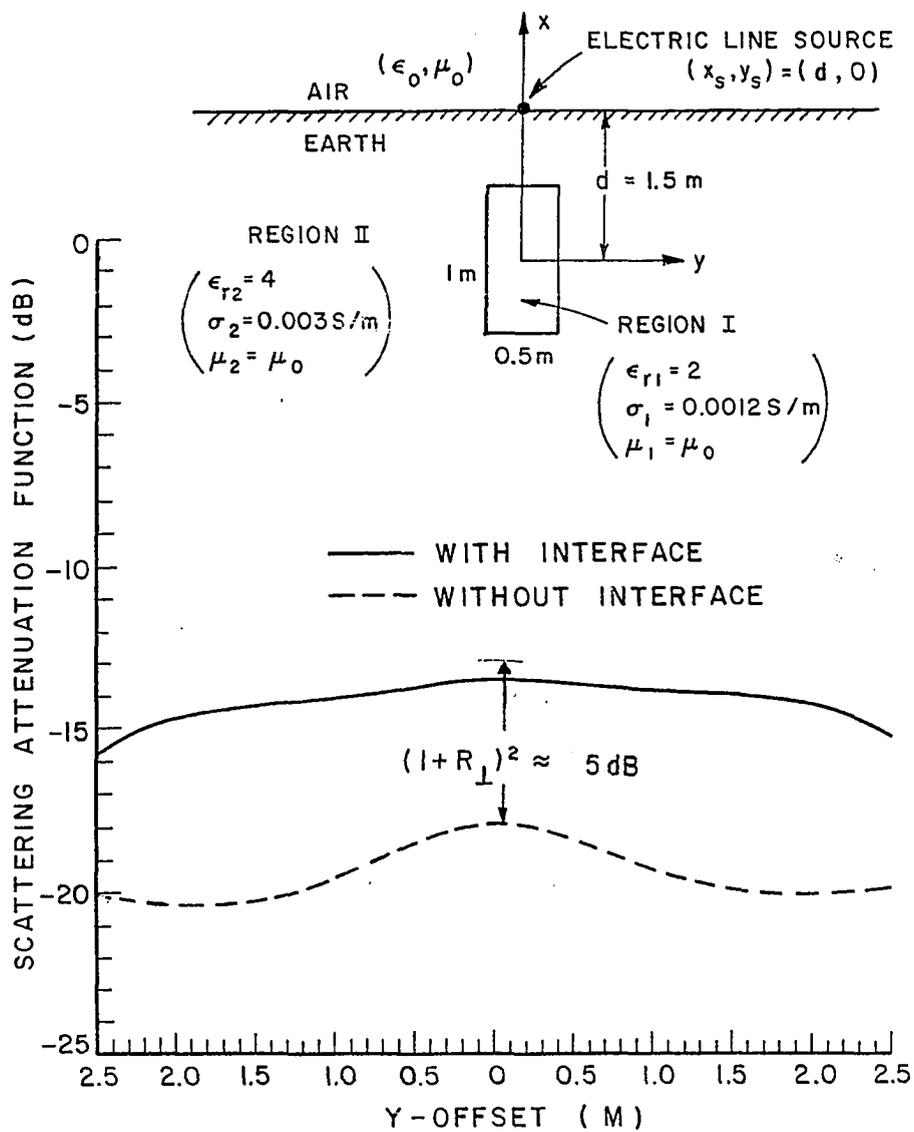


Figure 7-8. Comparison of the bistatic scattering patterns for a tunnel geometry, with and without the air-earth interface. Frequency is 100 MHz.

Figure 7-7 suggests that the bistatic pattern is enhanced by interface in the vicinity of the trench (i.e., $|y| < 1.5\text{m}$) by a factor of $(1+R_{\perp})^2$, where R_{\perp} is the plane wave reflection coefficient between region I and air. As $|y|$ is increased, the pattern falls rapidly, partially because of the effect of the radiation pattern of the line source on the interface as discussed in Chapter V. The pattern for the no-interface case remains unchanged for large values of $|y|$ for the range shown. Figure 7-8 shows an analogous set of patterns for a tunnel buried at $d=1.5\text{m}$. It is apparent that the interface produces only minor changes in the bistatic scattering pattern. For this case R_{\perp} in the $(1+R_{\perp})^2$ factor is between regions II and air.

As a second example of bistatic scattering pattern, an electric line source is placed on the interface at $(x_S, y_S) = (d, 1.5\text{m})$ and the scattered field is calculated on the interface from $y = -2.5\text{m}$ to $y = 2.5\text{m}$. The bistatic scattering patterns are shown in Figure 7-9 for a trench geometry and for a tunnel buried at $d = .75\text{m}$, 1m , 1.25m , and 1.5m . It is noted that because of the none symmetrical physical situation, the patterns do not have any symmetry. It is apparent that the general shape of the pattern is basically the same for all cases, except that as the tunnel is buried deeper, the pattern widens and is reduced in magnitude as is expected.

E. BACKSCATTERING VERSUS FREQUENCY

In this section two sets of frequency curves are presented, one for a trench geometry, and the other for a tunnel geometry. In each case a

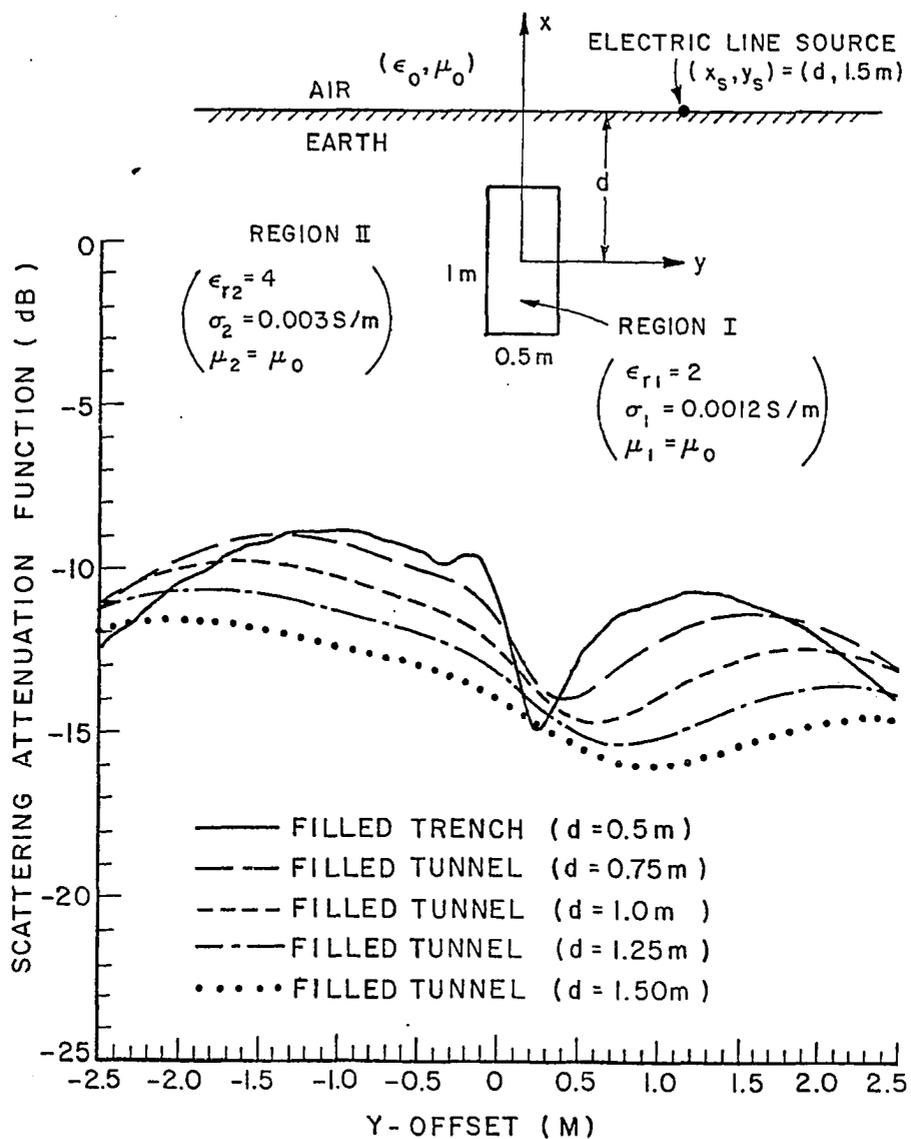


Figure 7-9. Bistatic scattering patterns for some trench and tunnel geometries. An electric line source is placed on the interface at $(x_s, y_s) = (d, 1.5\text{m})$ parallel to z-axis, and the scattered field is observed at points on the interface along y-axis (from $y = -2.5\text{m}$ to $y = 2.5\text{m}$). The frequency is 100 MHz.

curve for the no interface case is included for comparison. In addition, a set of frequency curves for an equivalent cross-section area circular cylinder is provided for testing the validity of the moment method solution.

The scattering model for a trench geometry is shown in Figure 7-10, where a 1 m by .5 m lossy rectangular trench is buried in an earth medium, is considered. For this model, a backscattered field versus frequency curve (solid line) is shown in Figure 7-10 which shows increases in relative scattering with frequency.

The dashed curve in Figure 7-10 is the relative scattering curve for the case where the interface is removed and the same source location is maintained. The two curves are related as has already been discussed. Similar results are shown in Figure 7-11 except that R_{12} is used in lieu of R_{11} where R_{11} is the reflection coefficient between region I and air, and R_{12} is the reflection coefficient between region II and air. It is again noted that the presence of the interface can be accounted for in a simple way and yet reasonably accurate results can be obtained.

Also included in Figure 7-11 are two analogous backscattered versus frequency curves, for an equivalent cross-section area circular cylinder. The circular cylinder is composed of the same medium (Region II). Comparing the corresponding curves for the rectangular and the circular cylinders, it is apparent that at low frequency regions (i.e., <50 MHz) the scattering curves that are the same for each corresponding case. As the frequency increases the corresponding scattering curves

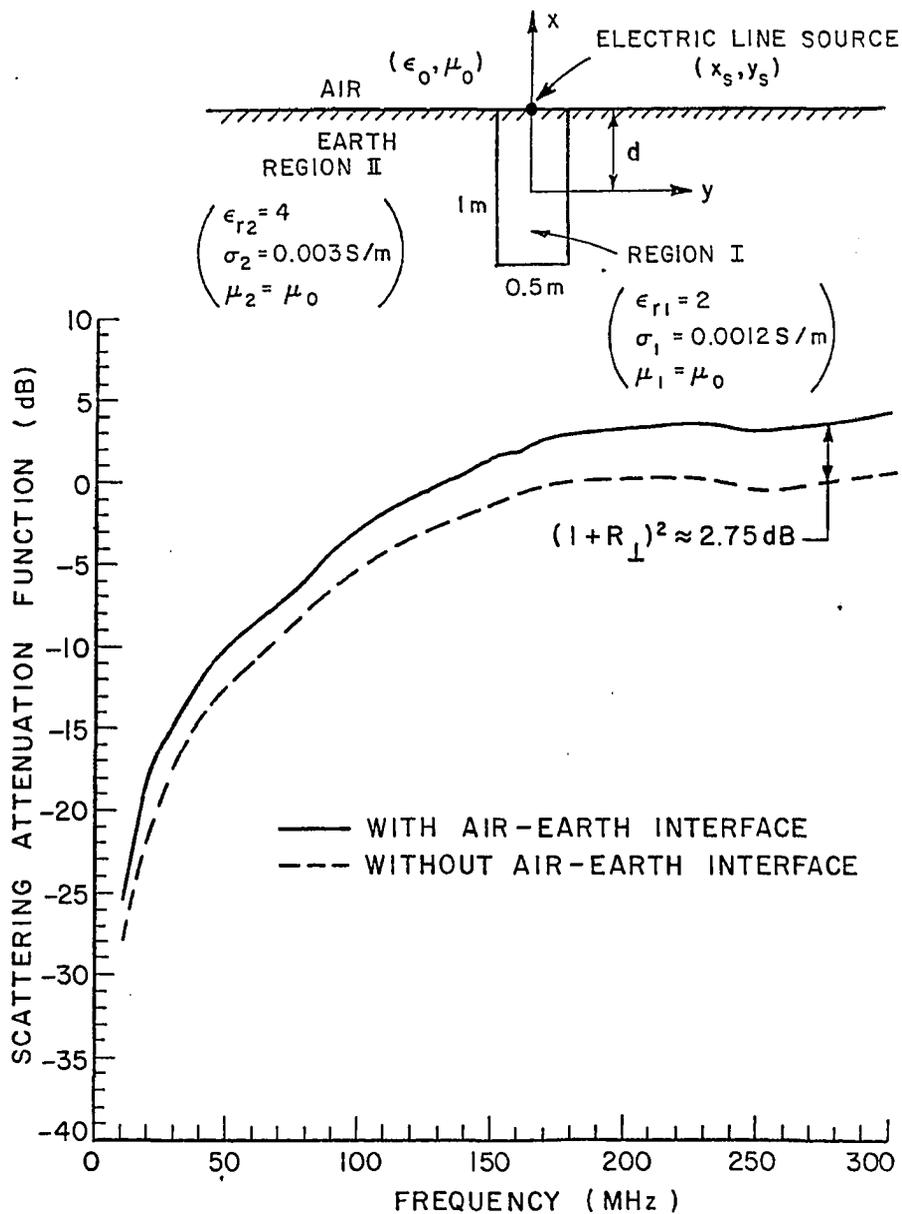


Figure 7-10. The backscattering versus frequency curve for a trench geometry, with and without the air-earth interface. An electric line source is placed at $(x_s, y_s) = (d, 0)$.

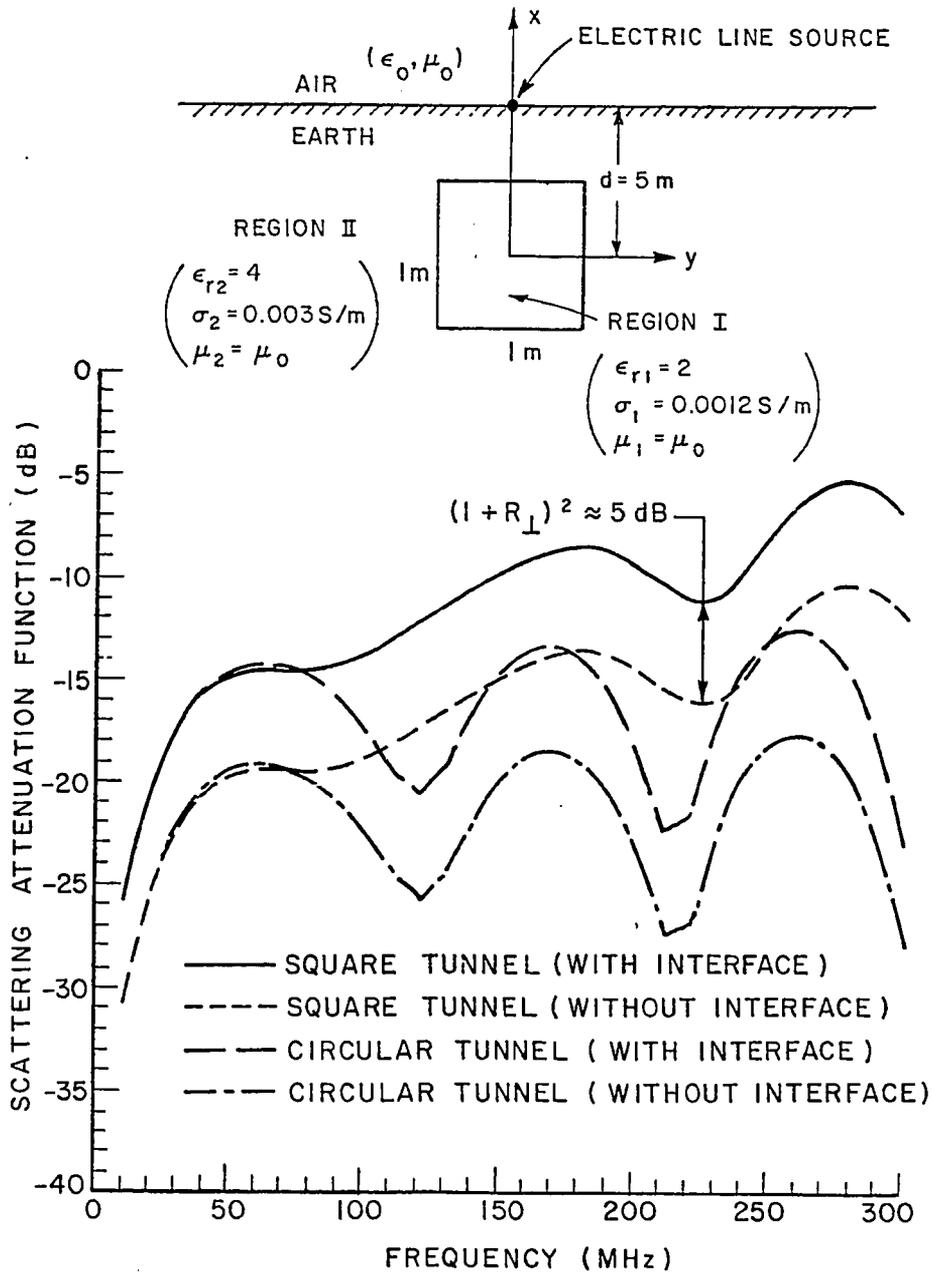


Figure 7-11. Backscattering versus frequency curves for a square tunnel with and without the air-earth interface and for an equivalent cross-section area circular cylinder tunnel, with and without the interface. The electric line source is placed at $(x_s, y_s) = (d, 0)$.

diverge. These curves are a good test for the solution of moment method at low frequencies.

F. SUMMARY

In this chapter, the E-wave scattering by buried lossy dielectric rectangular cylinders was considered. Moment method formulations were presented and a convergence curve was included which showed excellent convergence. Some numerical results were also presented and discussed. It is again noted that the presence of the interface can be accounted for in a simple way and yet reasonably accurate results can be obtained. In the next chapter H-wave scattering by buried lossy dielectric rectangular cylinders is presented.

CHAPTER VIII

H-WAVE SCATTERING BY LOSSY DIELECTRIC RECTANGULAR CYLINDERS OF INFINITE LENGTH

A. INTRODUCTION

The electromagnetic scattering model developed in Chapter VI is specialized to a rectangular scatterer. Again a plane wave expansion is used in the moment method formulation as a set of basis functions. A convergence test similar to that used in Chapters VI and VII is applied and which gives comparable results for the moment method. Some numerical results are presented and discussed. The results can be explained in a manner similar to the interpretations of Chapter VII. The major difference is that the $(1+R_{\perp})^2$ factor is replaced by $(1+R_{\parallel})^2$ factor.

The H-wave electromagnetic scattering model is the same as that for E-wave as shown in Figure 7-1, except that the electric line source is replaced by a uniform time harmonic magnetic line source. Using this model, the moment method formulations are derived.

B. PLANE WAVE EXPANSION

The system of linear equation

$$(V_m + \Delta V_m) = \sum_{n=1}^N C_n (Z_{mn} + \Delta Z_{mn}) \quad (8.1)$$

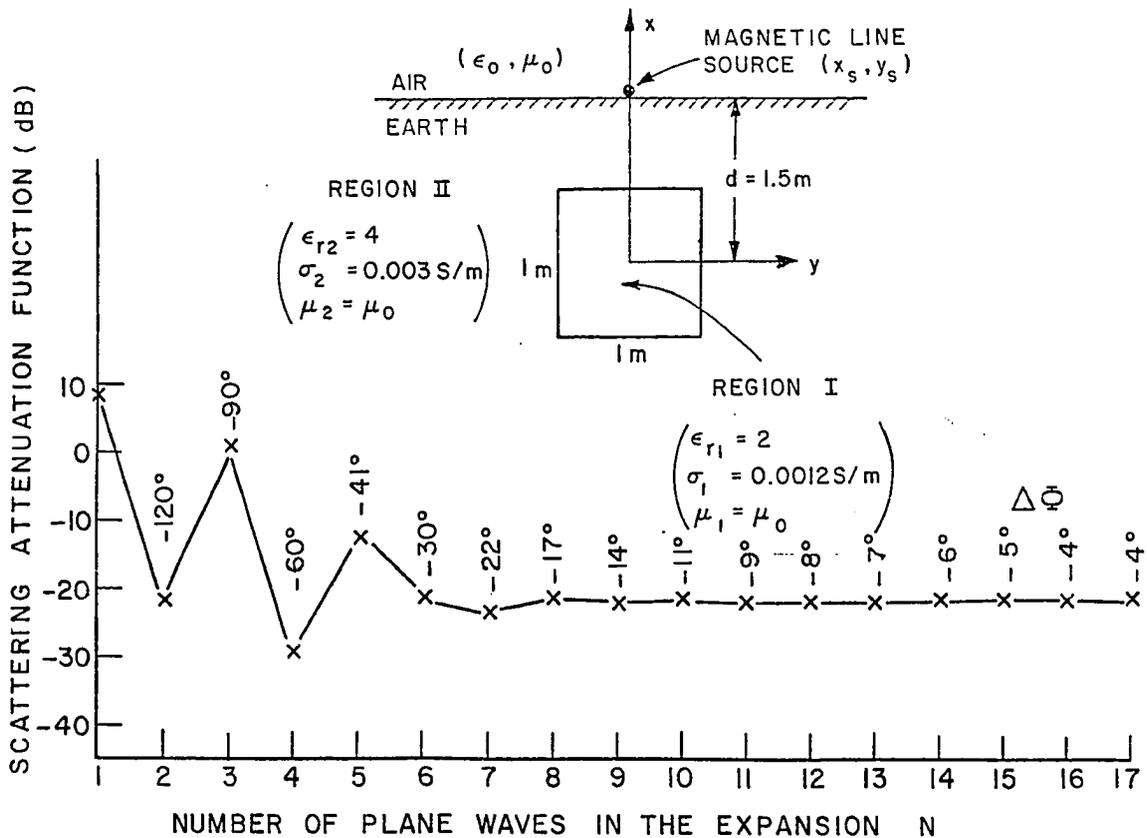


Figure 8-1. The convergence curve for computer program RTUNLH for a buried tunnel. Scattering Attenuation Function is calculated for increasing values of N, the number of plane waves in the expansion. The frequency used is 100 MHz.

was obtained by applying moment method to Integral Equation (6.23), where V_m and Z_{mn} are given by Equations (4.9) and (4.5) respectively, and ΔV_m and ΔZ_m are given by Equations (6.24c) and (6.26) respectively.

Using Equation (3.1) in Equation (6.24c) yields

$$\Delta V_m = -\frac{jk_1}{2\pi} \int_{-a}^a \int_{-b}^b e^{-jf_m x} e^{-jg_m y} \left[\int_0^\infty \frac{g R_{\parallel} e^{-f(2d-x-x_s)} \sin[g(y-y_s)]}{f} dg \sin \phi_m - \int_0^\infty \frac{f R_{\parallel} e^{-f(2d-x-x_s)} \cos[g(y-y_s)]}{f} dg \cos \phi_m \right] dx dy, \quad (8.2)$$

where Equation (3.2b) and (3.2c) has been used.

Substituting Equation (3.1) in Equation (6.26) yields

$$\Delta Z_{mn} = \frac{jk_1}{2\pi\epsilon_2} \frac{\hat{\epsilon}_1 - \hat{\epsilon}_2}{\hat{\epsilon}_2} \int_{-a}^a \int_{-a}^a \int_{-b}^b \int_{-b}^b e^{-jf_n x'} e^{-jg_n y'} e^{-f_m x} e^{-jg_m y} \left\{ \begin{aligned} & \sin \phi_m \sin \phi_n \int_0^\infty \frac{g^2 R_{\parallel} e^{-f(2d-x-x')} \cos[g(y-y')]}{f} dg \\ & + (\sin \phi_m \cos \phi_n + \cos \phi_m \sin \phi_n) \int_0^\infty \frac{f g R_{\parallel} e^{-f(2d-x-x')} \sin[g(y-y')]}{f} dg \\ & - \cos \phi_m \cos \phi_n \int_0^\infty \frac{f^2 R_{\parallel} e^{-f(2d-x-x')} \cos[g(y-y')]}{f} dg \end{aligned} \right\} dx' dy' dx dy \quad (8.3)$$

where Equations (2.40c), (3.2b), and (3.2c) have been used to simplify the constant term. Interchanging the order of integration and rearranging terms in Equation (8.2) yields

$$\Delta V_m = \frac{-1}{2\pi\eta_1} \int_0^\infty \frac{R_{||} e^{-f(2d-x_s)}}{f} \left\{ \left[\sin\phi_m g \int_{-b}^b e^{-jg_m y} \sin[g(y-y_s)] dy \right. \right. \\ \left. \left. - \cos\phi_m f \int_{-b}^b e^{-jg_m y} \cos[g(y-y_s)] dy \right] \int_{-a}^a e^{-j f_m x} e^{fx} dx \right\} dg \quad , \quad (8.4)$$

Or,

$$\Delta V_m = \frac{-1}{\pi\eta_1} \int_0^\infty \frac{R_{||} e^{-f(2d-x_s)}}{f} [F_m (\sin\phi_m g G_0^V - \cos\phi_m f G E_m^V)] dg \quad . \quad (8.5)$$

F_m is given by Equation (7.4b). $G E_m^V$ is given by Equation (3.8c) and G_0^V is given by Equation (4.9b).

In a similar manner, Equation (8.3) is reduced to

$$\Delta Z_{mn} = \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi\epsilon_2} \int_0^\infty \frac{R_{||} e^{-2df}}{f} \left\{ \left[(\sin\phi_m \sin\phi_n g^2 - \cos\phi_m \cos\phi_n f^2) \right. \right.$$

$$\left. \left. \int_{-b}^b \int_{-b}^b e^{-jg_n y} e^{-jg_m y} \cos[g(y-y')] dy' dy \right] \right\}$$

$$+ (\cos\phi_m \sin\phi_n + \sin\phi_m \cos\phi_n) fg \int_{-b}^b \int_{-b}^b e^{-jg_n y'} e^{-jg_m y} \sin[g(y-y')] dy' dy \left. \int_{-a}^a e^{-jf_n x'} e^{fx'} dx' \int_{-a}^a e^{-jf_m x} e^{fx} dx \right\} dg, \quad (8.6)$$

Or,

$$\Delta Z_{mn} = - \frac{4(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{\pi \hat{\epsilon}_2} \int_0^\infty \frac{R_{||} e^{-2df}}{f} \left\{ \begin{aligned} & [(\sin\phi_m \sin\phi_n g^2 - \cos\phi_m \cos\phi_n f^2) GE_{mn} \\ & + (\cos\phi_m \sin\phi_n + \sin\phi_m \cos\phi_n) fg GO_{mn}] \\ & F_n \cdot F_m \end{aligned} \right\} dg. \quad (8.7)$$

GE_{mn} is given by Equation (3.10c), GO_{mn} is given by Equation (4.19), and F_n and F_m are given by Equation (7.4b). In order to make ΔV_m and ΔZ_{mn} compatible with V_m and Z_{mn} derived in Chapter IV, ΔV_m and ΔZ_{mn} have been normalized to $-jk_1 \eta_1$.

After solving Equation (8.1) for C_n 's, the scattered field may be obtained by Equation (6.28) as

$$H_z^{Sr}(x,y) = \frac{(\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi \hat{\epsilon}_1} \sum_{m=1}^N C_m \int_{-a}^a \int_{-b}^b \left[\frac{\partial F_m(x',y')}{\partial y'} \int_0^\infty \frac{g R_{||} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dg - \frac{\partial F_m(x',y')}{\partial x'} \int_0^\infty \frac{f R_{||} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right] dx' dy'. \quad (8.8)$$

Substituting for $F_m(x,y)$ from Equation (3.1), and simplifying, the scattered field is reduced to

$$H_z^{sr}(x,y) = \frac{-j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)\eta_1}{2\pi} \sum_{m=1}^N C_m \int_{-a}^a \int_{-b}^b \left[\begin{aligned} & e^{-j\phi_m x'} e^{-jg_m y'} \left(\sin\phi_m \int_0^\infty \frac{gR_{\parallel} e^{-f(2d-x-x')}}{f} \sin[g(y-y')] dy \right. \right. \\ & \left. \left. - \cos\phi_m \int_0^\infty \frac{fR_{\parallel} e^{-f(2d-x-x')}}{f} \cos[g(y-y')] dg \right) \right] dx' dy' \quad (8.9) \end{aligned}$$

Interchanging the order of integration and rearranging the terms and evaluating the cross-sectional integrals yields

$$H_z^{sr}(x,y) = \frac{-j\omega(\hat{\epsilon}_1 - \hat{\epsilon}_2)\eta_1}{\pi} \sum_{m=1}^N C_m \int_0^\infty \frac{R_{\parallel} e^{-f(2d-x)}}{f} \left[F_m(\sin\phi_m g G_0^V - \cos\phi_m f G E_m^V) \right] dg ,$$

where F_m is given by Equation (7.4b). GE_m^V and G_0^V are given by Equations (3.8c) and (4.9b) respectively, with y_s replaced by y .

For backscattered field, some computational time may be saved by using the elements of the voltage column. This may be verified by replacing (x,y) by (x_s, y_s) in Equation (8.9), and comparing the result with Equation (8.4).

$$H_z^{B.sr}(x_s, y_s) = j\omega\eta_1^2 (\hat{\epsilon}_1 - \hat{\epsilon}_2) \sum_{m=1}^N C_m \Delta V_m \quad (8.11)$$

ΔV_m is given by Equation (8.5).

C. CONVERGENCE

A computer program was developed to model the air-earth interface and a buried scatterer. This program is called RTUNLH and it is included in the Appendix C. To check the convergence characteristic of this program, the program is used to calculate the relative scattering for increasing values of "N" the number of plane waves in the expansion. A typical curve is shown in Figure 8-1.

The scattering model used to obtain this curve is shown at top of Figure 8-1. This model is a 1m square filled cylindrical tunnel with $\epsilon_{r1}=2.$, and $\sigma_1=.0012$ s/m buried at $d=1.5$ m in earth with $\epsilon_{r2}=4$ and $\sigma_2=.003$ s/m. The interface is the $x=1.5$ m plane and the frequency is 100 MHz. As shown in Figure 8-1, the excitation line source is located at $(x_s, y_s)=(1.5, 0)$. As depicted in Figure 8-1, the solution seems to have converged for $N>6$. This convergence curve has the same behavior as the convergence curves presented in earlier chapters thus to avoid repetition, it is not discussed further. The $\Delta\phi$ corresponding to every value of N is calculated from Equation (3.14), and is included in Figure 8-1.

D. SCATTERING PATTERNS

Some examples of bistatic and backscattered patterns are given for a filled trench and some filled tunnel geometries. A family of curves is presented for increasing values of "d", the depth of the center of the tunnel. The trench or tunnel (see Figure 7-1) is modeled by a 1m by .5m rectangular cylinder of infinite length with $\epsilon_{r1}=2$, $\sigma_2=.0012$ s/m, and $\mu_1=\mu_0$. The earth is modeled by a medium with $\epsilon_{r2}=4$, $\sigma_2=.003$ s/m, and $\mu_2=\mu_0$. The frequency used is 100 MHz. The electromagnetic scattering model is shown in Figure 8-2. A magnetic line source is placed on the interface parallel to z-axis at (x_s, y_s) , and it can be moved in $\pm y$ -direction to obtain various excitation cases.

1. Backscattering Patterns

Figure 8-2 shows various backscattering patterns for some trench and tunnel geometries. When $d=.5$ m, a trench geometry is modeled. The backscattering pattern for this trench shows a strong relative backscattered field in regions directly above the trench. The relative scattered field decreases as the $|y|$ -offset is increased until $|y|\approx 2.2$ m, where an apparent null is obtained, beyond this point the field again increases for the range shown.

For values of $d>.5$ m tunnel geometries are modeled. Some backscattering patterns are included in Figure 8-2 for tunnels buried at $d=.75$ m, 1m, 1.25m, and 1.5m. Patterns for shallowly buried tunnels, i.e., $d=.75$ m, 1.m, have the same general shape as that of the trench, but

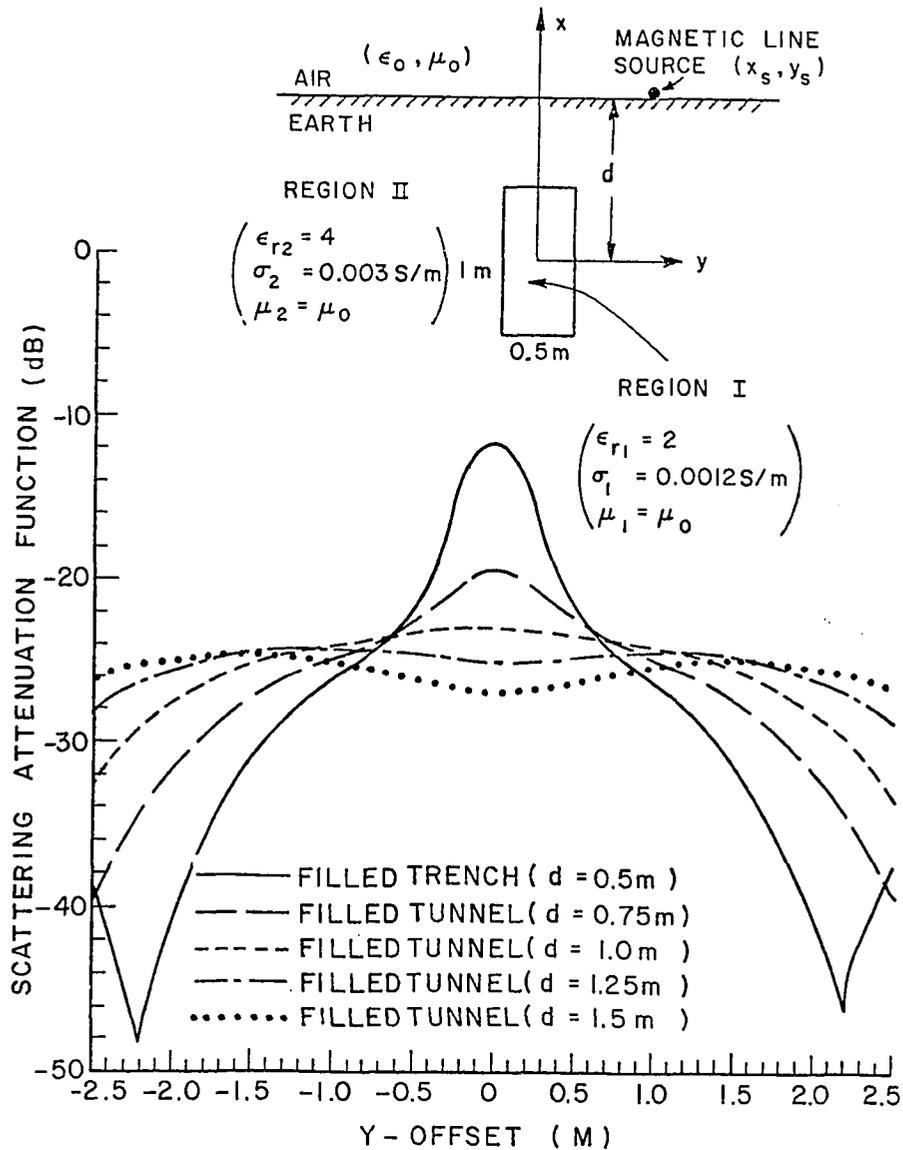


Figure 8-2. The backscattering patterns for trench and tunnel geometries. The magnetic line source is placed on the interface, parallel to z-axis, and moved from $y = -2.5 \text{ m}$ to $y = 2.5 \text{ m}$ incrementally. The frequency is 100 MHz.

are widened and reduced in magnitude. As the tunnels are buried deeper, the backscattered field is no longer maximum directly above the tunnel, this case is shown in Figure 8-2 for tunnels buried at $d=1.25\text{m}$, and 1.5m .

To illustrate the effect of the air-earth interface on the backscattering patterns of a trench and a tunnel, Figures 8-3 and 8-4 are presented. Figure 8-3 shows the backscattered pattern for the trench geometry discussed in Figure 8-2. In addition, an analogous backscattered pattern is given for a case where the air-earth geometry is removed (i.e., air region is replaced with region II). This pattern shows the significant effect of air-earth interface on the backscattered fields at various points. However, the approximate model discussed in Chapter VII does not seem to fit as well for this polarization. As suggested by Figure 8-3, the air-earth interface not only changes the backscattering pattern of a trench more dramatically, but it also reduces the magnitude of the backscattered field as would be predicted. However the approximate solution is not as accurate as was the case for the electric line source. An analogous set of curves is shown in Figure 8-4 for a tunnel buried at $d=1.5\text{m}$. For this curve, the approximate model seems to work better than the trench case of Figure 8-3.

2. Bistatic Patterns

As a first example of bistatic scattering pattern, a magnetic line source is placed on the interface at $(x_s, y_s) = (d, 0)$ and the scattered field is observed on the interface at $y = -2.5\text{m}$ to $y = 2.5\text{m}$ incrementally. This model is shown in Figure 8-5, where bistatic scattering patterns are

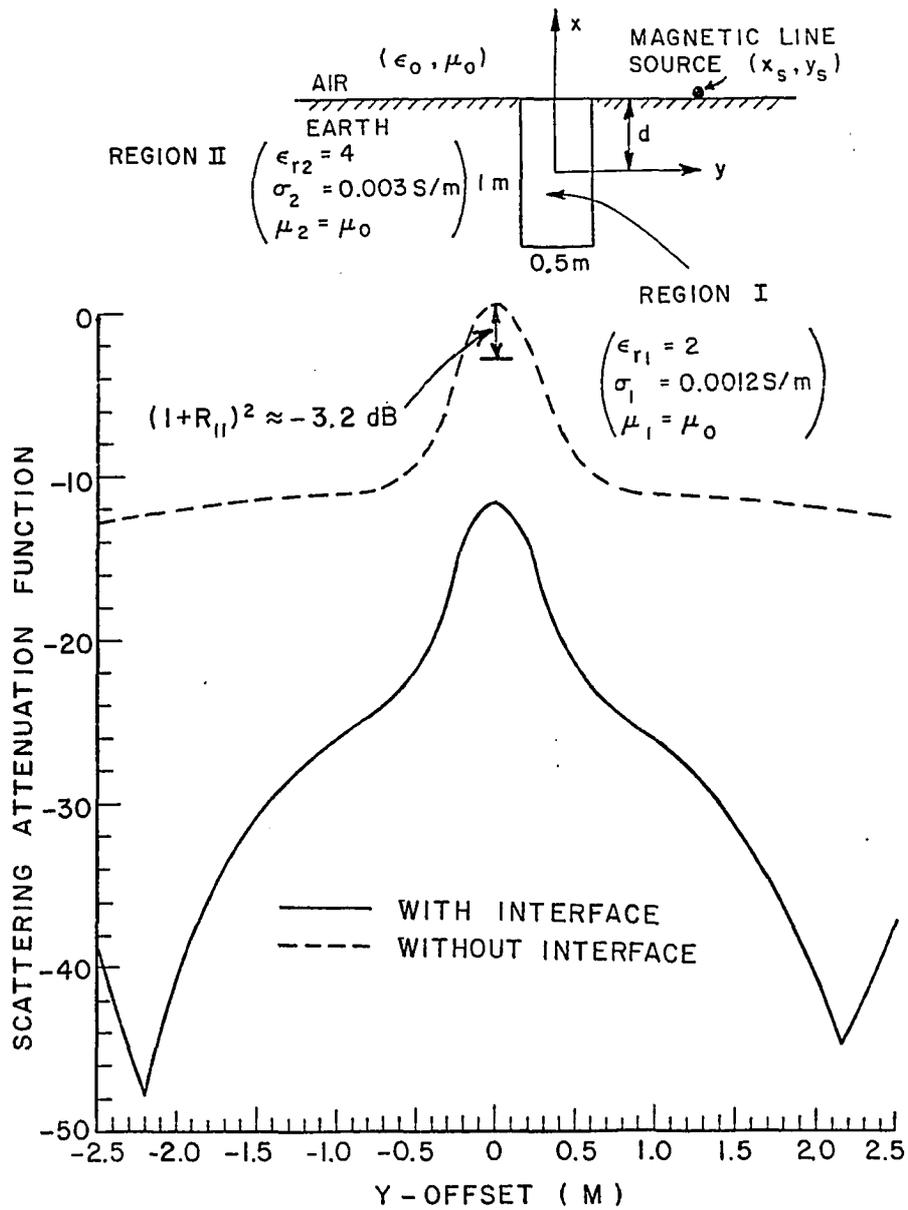


Figure 8-3. Comparison of backscattered field patterns of a trench geometry, with and without the air-earth interface. Frequency is 100 MHz.

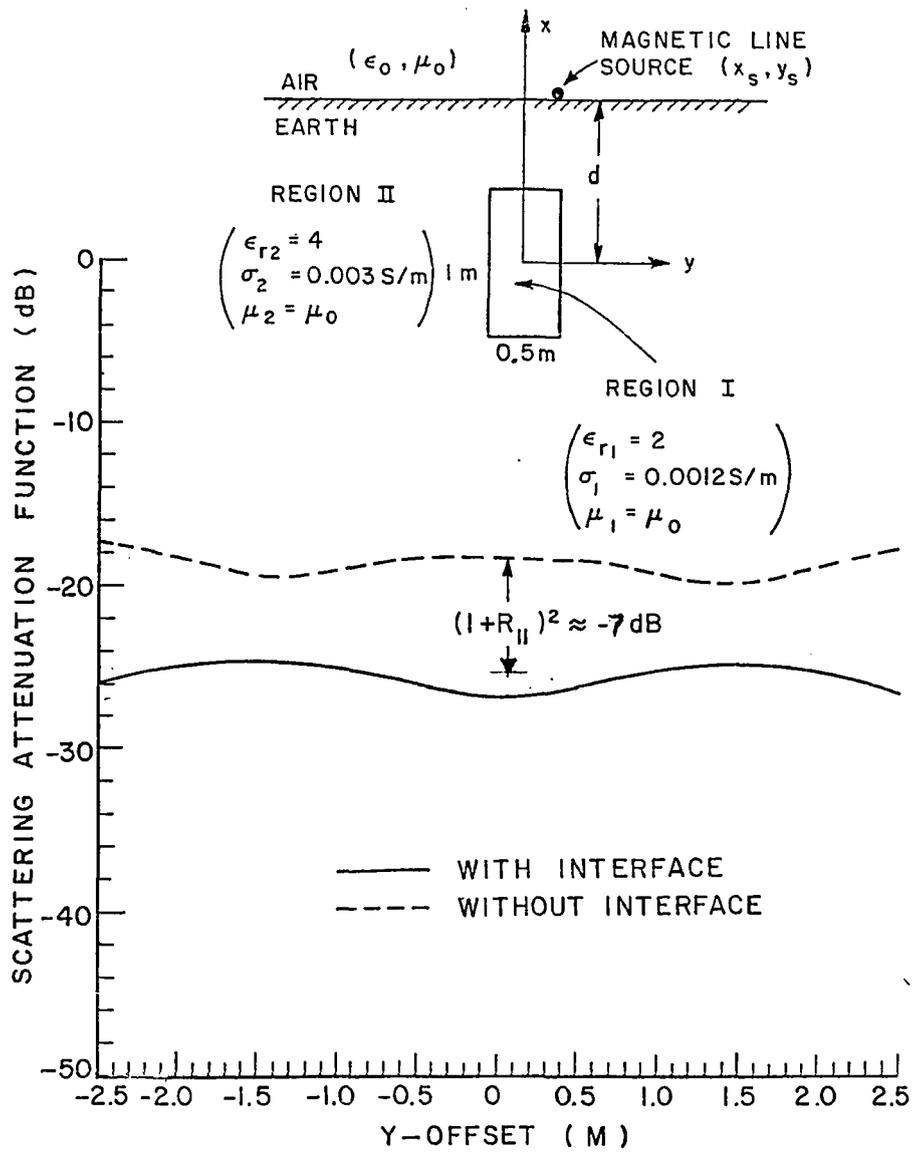


Figure 8-4. Comparison of backscattered field patterns of a tunnel geometry, with and without the air-earth interface. Frequency is 100 MHz.

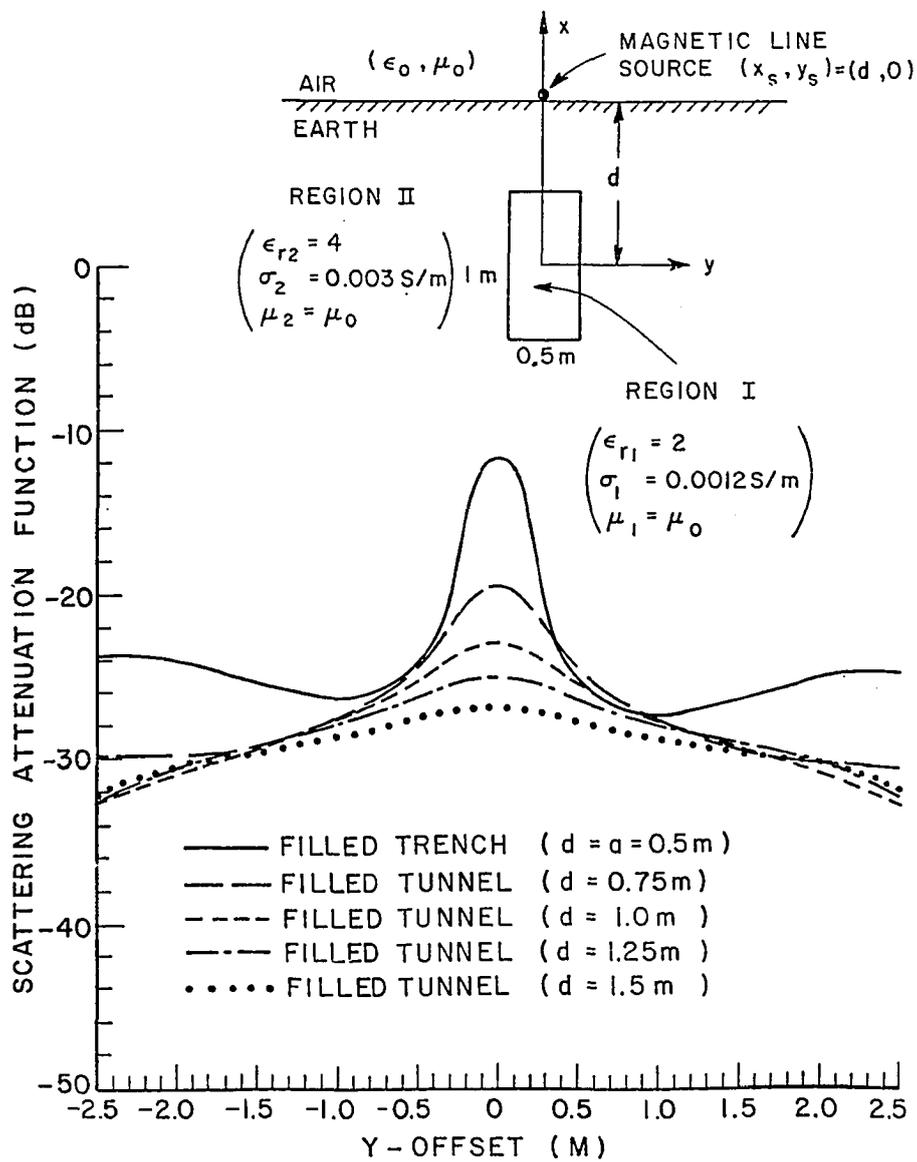


Figure 8-5. Bistatic scattering patterns for some trench and tunnel geometries. A magnetic line source is placed on the interface at $(x_s, y_s) = (d, 0)$ parallel to z-axis, and the scattered field is observed at points on the interface along y-axis (from $y = -2.5 \text{ m}$ to $y = 2.5 \text{ m}$). The frequency is 100 MHz.

included for a trench and some tunnels buried at $d=.75\text{m}$, 1m , 1.25m , and 1.5m . For the trench model where $d=.5\text{m}$, a maximum is obtained directly above the trench. The scattered field is reduced for increased $|y|$ -offsets up to $|y|\approx 1$, after which it smoothly increases for larger $|y|$ -offsets. For tunnel geometries ($d>.5\text{m}$), the patterns shown in Figure 8-5 depicts maxima directly above the tunnel and smoothly decreasing scattered field for increasing $|y|$ -offsets.

Figure 8-6 shows a comparison between the scattering pattern of a trench geometry and that of an analogous case with the air-earth interface removed (i.e., air region is replaced with region II), and Figure 8-7 shows an analogous sets of patterns for a tunnel geometry buried at $d=1.5\text{m}$.

A second example of bistatic scattering pattern is presented in Figure 8-8, where the scattering model of Figure 8-5 is used with the exception that the excitation line source is moved to $(x_s, y_s)=(d, 1.5\text{m})$. The patterns presented in Figure 8-8 are for a filled trench and some tunnels buried at $d=.75\text{m}$, 1m , 1.25m , and 1.5m . It is apparent that as the depth of burial of tunnel (d) is increased, the pattern is reduced and widened, and that the null directly above the tunnel remains very much in place, while the one to the left of tunnel gradually moves further away and becomes shallower.

E. BACKSCATTERING VERSUS FREQUENCY

In this section two sets of frequency curves are presented; one for a trench geometry and the other for a tunnel geometry. In each case an

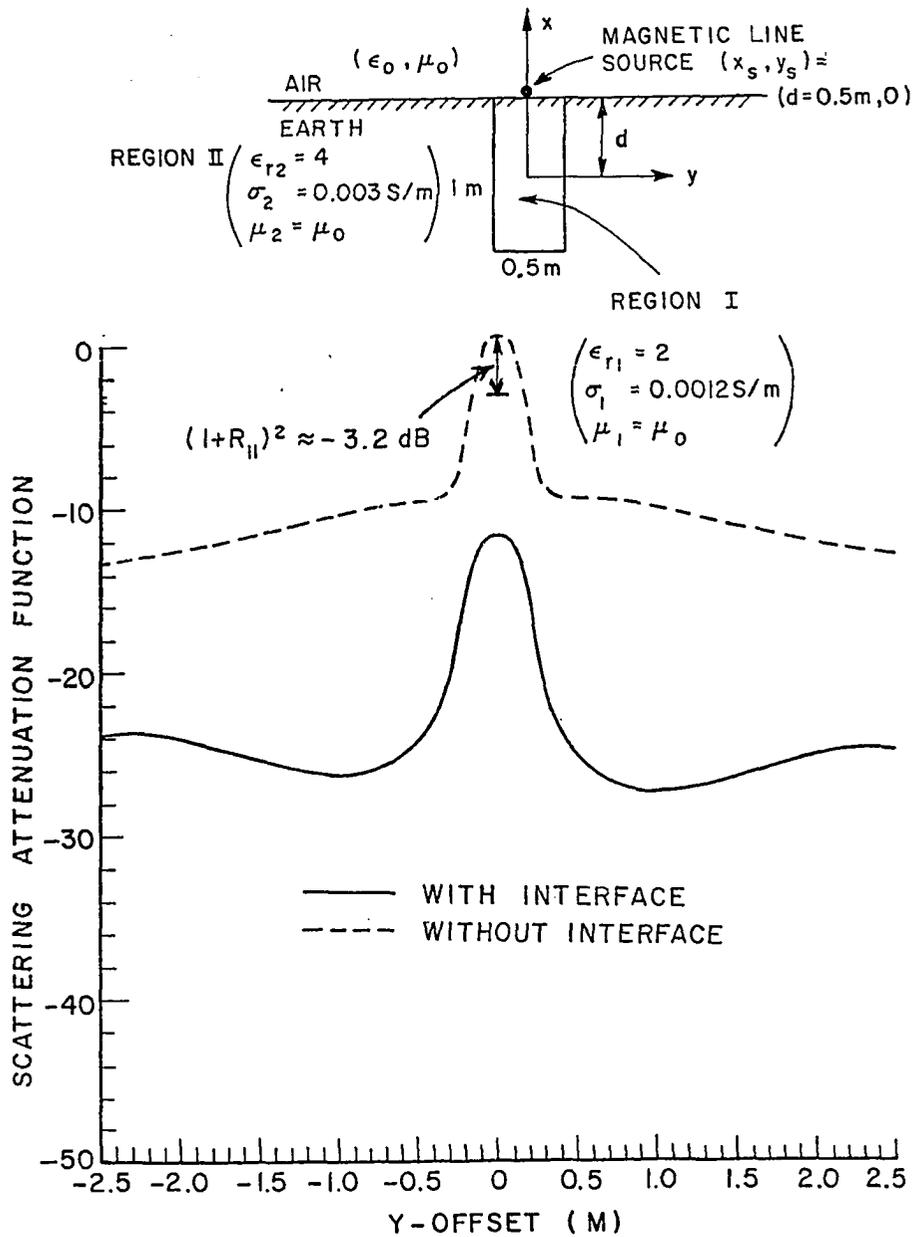


Figure 8-6. Comparison of the bistatic scattering patterns for a trench geometry, with and without the air-earth interface. Frequency is 100 MHz.

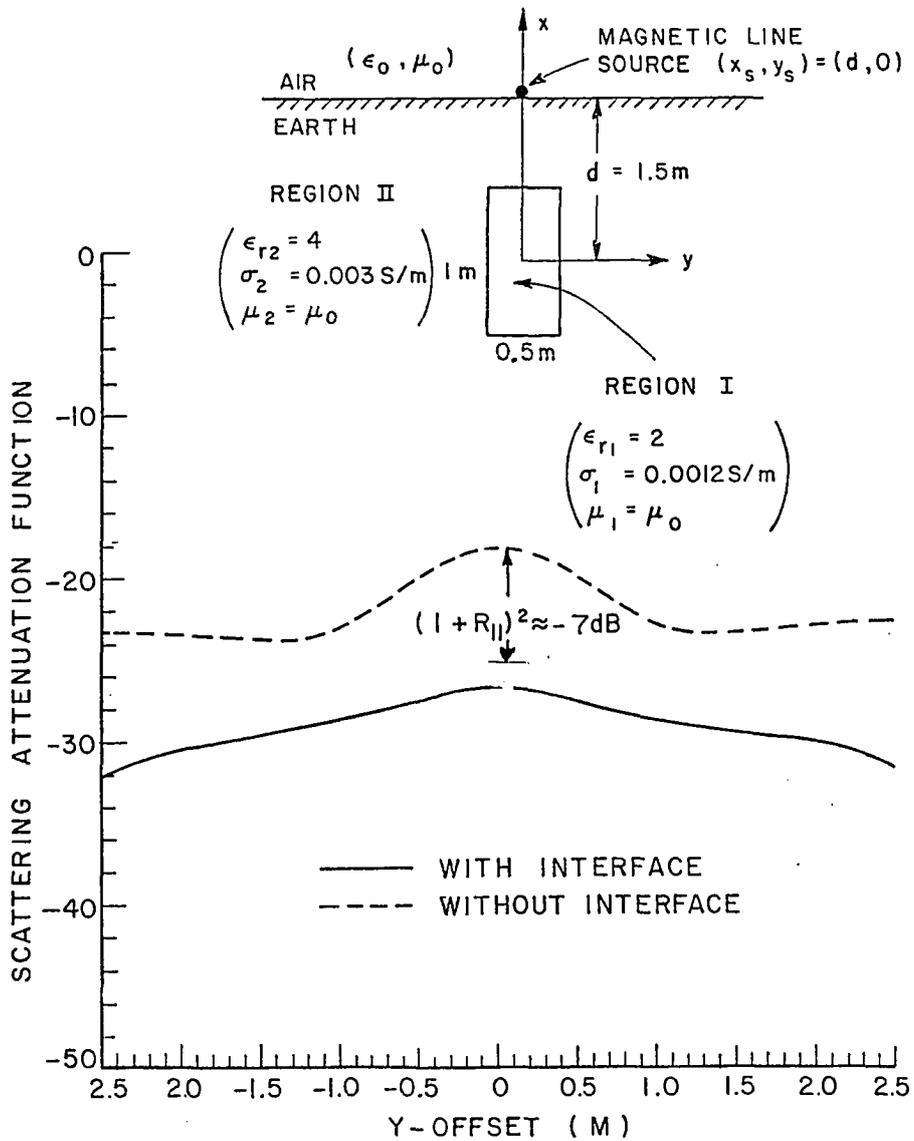


Figure 8-7. Comparison of bistatic scattering patterns for a tunnel geometry, with and without the air-earth interface. Frequency is 100 MHz.

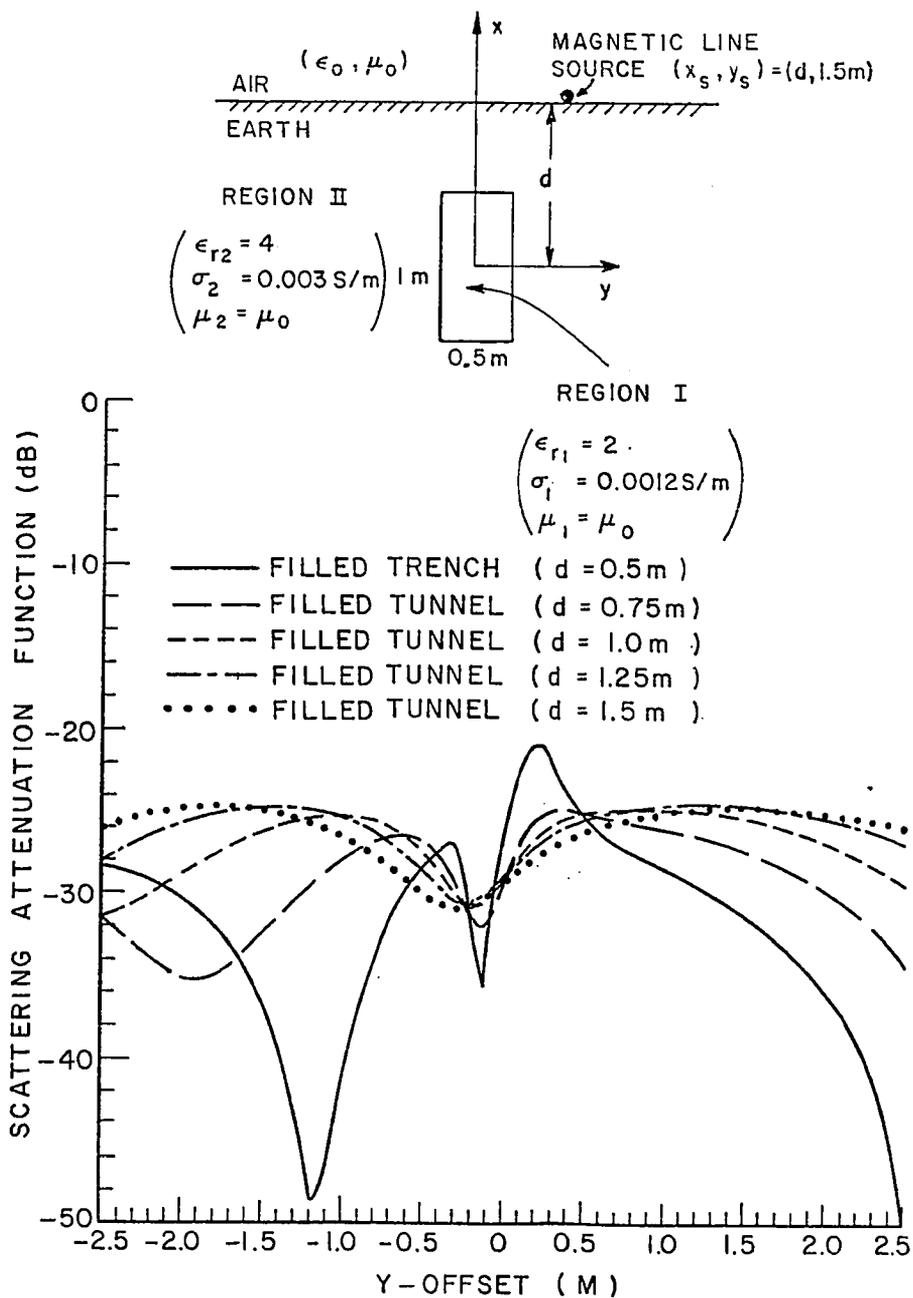


Figure 8-8. Bistatic scattering patterns for some trench and tunnel geometries. A magnetic line source is placed on the interface at $(x_s, y_s) = (d, 1.5\text{m})$ parallel to z -axis, and the scattered field is observed at points on the interface along y -axis (from $y = -2.5\text{m}$ to $y = 2.5\text{m}$). The frequency is 100 MHz.

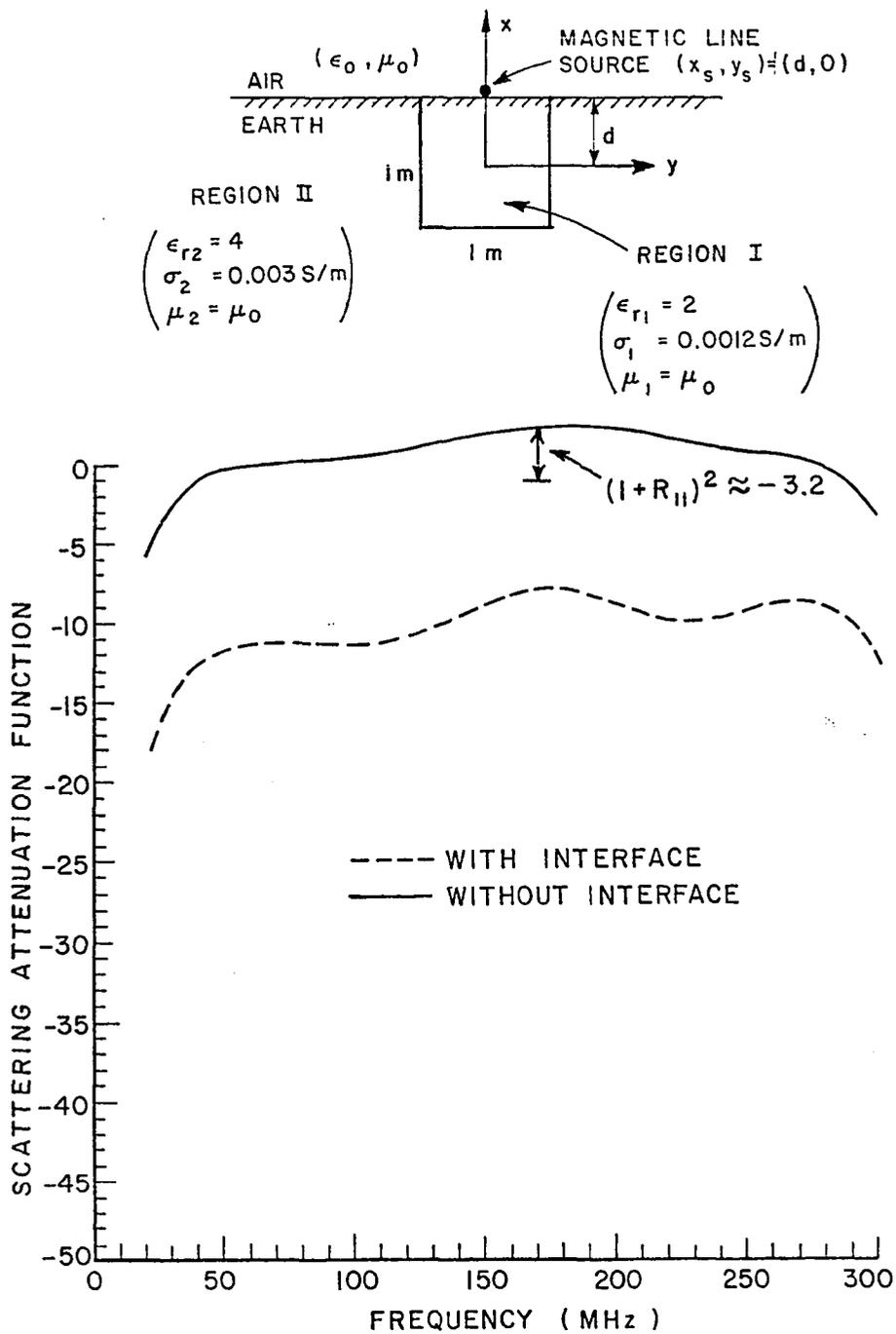


Figure 8-9. The backscattering versus frequency curves for a trench geometry, with and without the air-earth interface. The magnetic line source is placed at $(x_s, y_s) = (d, 0)$.

analogous curve for no the interface case is included for comparison. A 1m square trench with $\epsilon_{r1}=2$, and $\sigma_1=.0012$ s/m in a earth medium with $\epsilon_{r2}=4$ and $\sigma_2=.003$ s/m for a magnetic line source placed on the interface at $(x_s, y_s)=(d, 0)$ is shown in Figure 8-9. This geometry represents the electromagnetic scattering model of a filled trench.

The corresponding backscattering curves are shown in Figure 8-9. The dashed curve is the frequency curve for a trench, whereas, the solid curve is the frequency curve for the case where the air-earth interface is removed (i.e., air region is replaced by region II) and the same source geometry is retained. Comparing these two curves, it is apparent that the interface reduces the scattering as would be predicted and this reduction appears to be relatively nonuniform for various frequencies in contrast to the electric line source cases. The shape of the two curves appears to be almost the same for frequency range shown. Figure 8-10 shows a set of curves analogous to Figure 8-9 for a rectangular tunnel geometry. The electromagnetic scattering model is also shown. Comparing the curve for buried rectangular tunnel (dashed line) and the curve for the rectangular tunnel in the absence of air-earth interface (solid line), it is apparent that the two have the same shape for frequency range shown and that the interface effect, seems to be uniform at various frequencies. In fact, it seems like the interface shifted the solid curve by a -7.5 dB approximately. From a simplistic point of view, this factor may be approximated reasonably by a $(1+R_{\parallel})^2$ factor as discussed in Chapter VII, where R_{\parallel} is the plane wave reflection coefficient at the interface. The first $(1+R_{\parallel})$ factor is due to the total incidence field

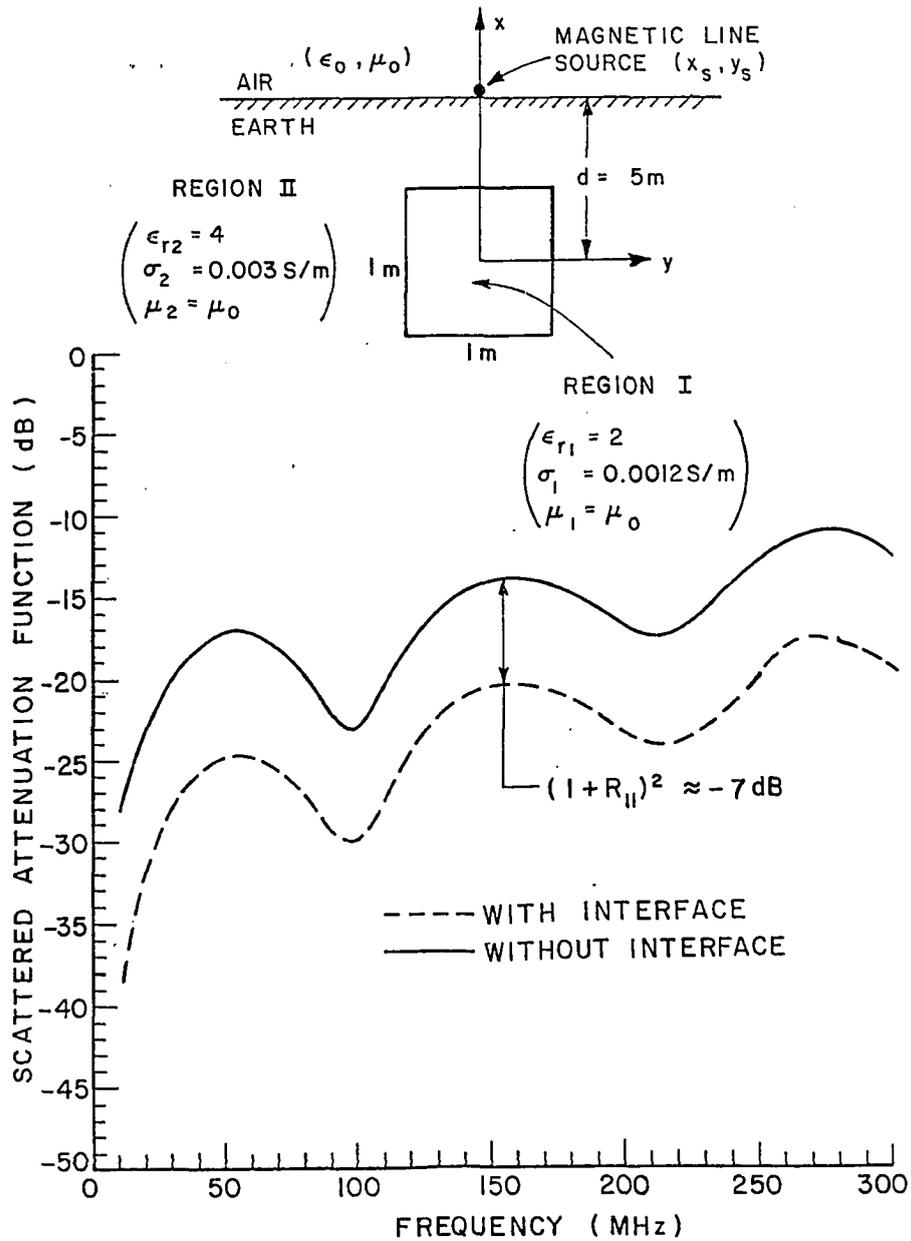


Figure 8-10. Backscattering versus frequency curves for a square tunnel with and without the air-earth interface. The magnetic line source is placed at $(x_s, y_s) = (d, 0)$.

on the scatterer, and a second $(1+R_{\parallel})$ factor is due to the scattered field, due to the induced currents in the scatterer. For the model shown in Figure 8-10, $R_{\parallel} \approx -\frac{1}{3}$ (neglecting the effect of loss as suggested by curves of Figure (8-10) and $(1+R_{\parallel})^2 = (1 - \frac{1}{3})^2$ which implies approximately a -7 dB shift of the solid curve to obtain the dashed curve in Figure 8-10. This approach fails for the target at the surface. This simplistic approximation is sufficiently accurate for the case under consideration, thus the costly evaluation of the Sommerfeld integrals may not be necessary in this case. It is hypothesized that the approximate model gives better results as the scatterer is buried deeper.

F. SUMMARY

In this chapter, a moment method formulation for H-wave scattering by buried lossy dielectric rectangular cylinders was given. A convergence curve was presented, and various numerical results were included and discussed.

CHAPTER IX
CPU-TIME CONSIDERATIONS

One advantage offered by using the plane wave expansion is that the number of linear equations required to solve a given problem is considerably less than the number of linear equations required to solve the same problem via a pulse basis method. This is very critical in terms of the CPU-time required to solve a set of simultaneous linear equations, usually, a matrix inversion or a gauss elimination routine is required to solve such a system. Thus, the efficiency of the operation is highly dependent on the efficiency of the matrix inversion routine. For this reason, it is convenient to choose a matrix reduction technique such as triangulation or gauss's elimination. This usually requires a $\frac{1}{3} N^3$ operations (one operation usually consists of an addition and a multiplication) to triangulate the matrix where N is the number of linearly independent equations to be solved, and $\frac{1}{2} N^2$ operations are required to solve the matrix. It is possible to use a compact scheme for gaussian elimination [48] such as Crout's method to solve the system of the N linearly independent equations. The CPU-time required for solving N simultaneous linear equations by Crout's method is proportional to N^2 . A subroutine implementing the Crout's method is included in the appendix (courtesy of Professor Richmond).

It is possible to subdivide a moment method computer program into four major parts in terms of the types of the operations involved, such as:

- 1) setting up the generalized impedance matrix
- 2) setting up the generalized voltage column
- 3) solving the matrix
- 4) calculating the final results, i.e., SAF or echowidth

Parts 2 and 4 are not very critical in terms of the amount of the required CPU-time, whereas, parts 1 and 3 usually represent the time consuming operations.

Depending on how a moment method solution is formulated and the type of expansion and testing used, the four operational categories are weighted differently in terms of the required CPU-time. For example: RCYLPWE program presented in Appendix A uses four fold symmetry and standing plane wave expansion and Galerkin testing, while, RTUNLE computer program presented in Appendix B uses traveling plane wave expansion and Galerkin testing. Thus, the former may require more time to set up the generalized impedance matrix than the latter, but the former is much faster in solving the matrix than the latter. In contrast, a simple pulse basis point matching requires a short set-up time, but it uses much longer time to invert the matrix. In fact, the time required for solving the matrix becomes so great for larger N's, that it becomes economically infeasible for larger geometries.

This is illustrated in Figure 9-1, where a comparison between the Pulse Basis Point Matching (PBPM) and a Plane Wave Expansion Galerkin

(PWEG) is given in form of the CPU-time and the number of required linear equations N as a function of frequency. The CPU-time values are the required time to obtain a convergent solution for the particular scatterer shown. These times are typical of the VAX-11/780 Computer in the ElectroScience Laboratory computing facilities, and may vary considerably on other computers. However, regardless of the computer speed, the relative speed of the PBPM and PWEG methods would be very similar to that of Figure 9-1.

For the PBPM computer program, the CPU-time increases very slowly for frequencies smaller than 80 MHz (see Figure 9-1), in fact, in this region, the PBPM program is faster than the PWEG program. The additional time required by PWEG program in this region is partially due to the time required to set up the generalized impedance matrix. As the frequency is increased beyond 80 MHz, the solution time for PBPM program increases rapidly as more equations are needed to obtain a convergent solution. In contrast to this, a much faster solution is obtained by PWEG program from fewer linear equations. The small rate of increase of the required CPU-time and the fewer needed linear equations makes the PWEG method very attractive for higher frequencies or larger geometries, while at low frequencies PBPM is more suitable. It is hypothesized that for larger values of N , the CPU-time becomes a function of N^2 .

The excitation source used in the scattering model of Figure 9-1 is a uniform time harmonic electric line source. An analogous set of curves is given in Figure 9-2 for a magnetic line source excitation. The moment method formulation for this case is more involved and the

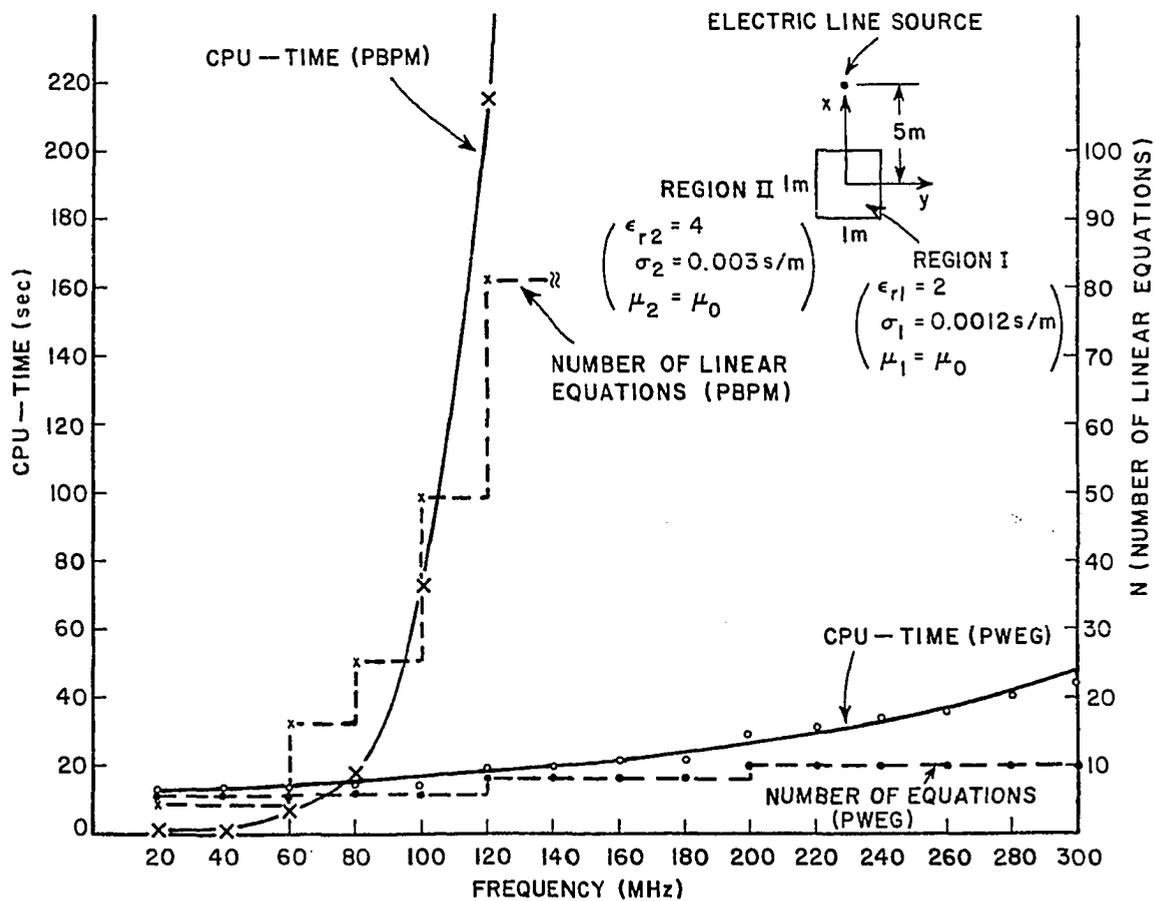


Figure 9-1. Comparison between the Pulse Basis Point Matching (PBPM) and a Plane Wave Expansion Galerkin (PWEG) methods. The CPU-time and the number of linear equations "N" needed to obtain a convergent solution is plotted for various frequencies. The excitation is due to a uniform electric line source and the computer programs used are RECTPPE and RTUNLE for PBPM and PWEG respectively.

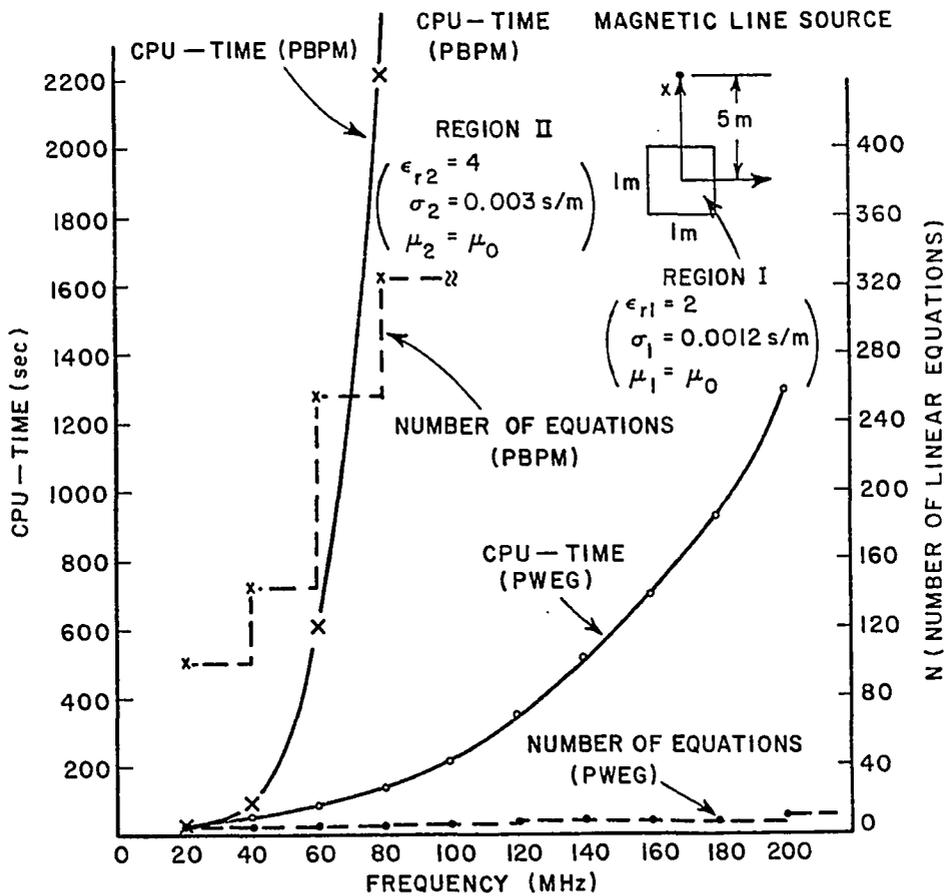


Figure 9-2. Comparison between the Pulse Basis Point Matching (PBPM) and a Plane Wave Expansion Galerkin (PWEG) methods. The CPU-time and the number of linear equations "N" needed to obtain a convergent solution is plotted for various frequencies. The excitation is due to a uniform magnetic line source and the computer programs used are SQCYLH and RTUNLH for PBPM and PWEG respectively.

execution time for the computer programs are longer than the electric line source case. Figure 9-2 basically shows the same relative CPU-time behavior for PBPM and PWEГ as that of Figure 9-1, and similar conclusions may be drawn.

The maximum frequency or the size of the scatterer to be modeled by the PWEГ technique may be limited by the economic considerations of CPU-execution time. Modern high density core memories in conjunction with added virtual memories may soon eliminate most of the limitations imposed by memory size. The VAX-11/780 computer can accommodate approximately a 1000 by 1000 matrix of complex elements in its addressable memory of about 2 Gbytes [50].

CHAPTER X

CONCLUSIONS

The object of this research has been to obtain an efficient computational model for the study of EM-scattering by buried, penetrable non-circular cylinder of infinite length. This model can be used to model two-dimensional scatterers in either a lossy half space or in a lossy homogeneous medium.

The Plane Wave Expansion Galerkin method presented here offers several advantages over the Pulse Basis Point Matching. It gives a stable convergence for a fewer number of linear equations, it provides reduced integration time for a rectangular based cylinder, where the cross-sectional integrals are evaluated in closed form. Additionally, the various optimizations provided by PWEg, enables modeling of larger scatterers that was not possible previously.

In Chapter III and IV, some numerical results were included for E-wave and H-wave scattering by a rectangular cylinder immersed in a homogeneous ambient medium. The scattering pattern obtained in Chapter III and IV were then used to develop an approximate model to explain much of the details of the structure of the scattering patterns obtained by the more exact solutions obtained by evaluating the Sommerfeld

integrals. In Chapter V the radiation patterns of a line sources placed on the air-interface were obtained. It was illustrated that these patterns may be approximated by $(1+R_{\perp})$ factor for an electric line source and $(1+R_{\parallel})$ factor for a magnetic line source. It is apparent that the simple approximation does not include the lateral type waves. Exclusion of the effect of lateral waves is more drastic for the case of the magnetic line source, because the lateral wave is more significant for this particular polarization because of its association with the Brewster angle [51]. It is also shown that the far field of a magnetic line source in a homogeneous lossless medium is proportional to $\epsilon_r^{-1/4}$ and far field of a magnetic line source in that medium is proportional to $\epsilon_r^{3/4}$.

In Chapter VII, E-wave, and in Chapter VIII, H-wave, scattering by buried lossy dielectric rectangular cylinders of infinite length were considered and some scattering patterns were presented. It was illustrated that a simple model may be used to obtain the effect of the air-earth interface. This approximate model suggests that SAF for a buried scatterer may be obtained by multiplying the SAF of scatterer immersed in homogeneous earth medium by $(1+R)^2$, where R is equal to R_{\perp} for an electric line source excitation, and R_{\parallel} for a magnetic line source excitation. The first $(1+R)$ factor is introduced to account for the presence of the interface on the field radiated by the line source. The second $(1+R)$ accounts for the reflection of the scattered fields by the interface. Thus the total of $(1+R)^2$ factor is required to approximate the effect of the interface on the scattered fields. This

approximation seems to work better for the electric line source excitation.

A. SUGGESTIONS

The EM-scattering models presented in this dissertation may be extended so that finite sources may be modeled. This would involve utilizing a Fourier transform and solving the above problem numerous times for various values of the transform argument. This however may be avoided by utilizing the method of Steepest descent for cases where the scatterer is located far enough so that the asymptotic evaluation of the pertinent integrals is possible.

A problem of interest in underground radar is the crossed dipole transmitter-receiver antenna pairs. This enables considerable isolation between the transmitter signal and the received signal. The EM-scattering results of the two different polarizations, the parallel and the perpendicular polarization may be combined to obtain a solution for such an antenna system [52].

Finally, the scattering models should be tested for various material case, i.e., good conductors and poor conductors. This would determine some of the limitations that the method may have.

APPENDICES

APPENDIX A

Computer program RCYLPWE uses Plane Wave Expansion Galerkin with four fold symmetry. The field inside the scatterer is expanded as

$$E^I(x,y) = \sum_{n=1}^N [a_n F_n^{ee}(x,y) + b_n F_n^{oe}(x,y) + c_n F_n^{eo}(x,y) + d_n F_n^{oo}(x,y)] , \quad (\text{A.1a})$$

where

$$F_n^{ee}(x,y) = \cos(f_n x) \cos(g_n y) , \quad (\text{A.1b})$$

$$F_n^{oe}(x,y) = \sin(f_n x) \cos(g_n y) , \quad (\text{A.1c})$$

$$F_n^{eo}(x,y) = \cos(f_n x) \sin(g_n y) , \quad (\text{A.1d})$$

and

$$F_n^{oo}(x,y) = \sin(f_n x) \sin(g_n y) . \quad (\text{A.1e})$$

The superscripts correspond to evenness or oddness w.r.t x and y.

From the wave equation it is shown that

$$f_n^2 + g_n^2 = k_1^2 , \quad (\text{A.2a})$$

where

$$f_n = k_1 \cos \phi_n \quad , \quad (A.2b)$$

$$g_n = k_1 \sin \phi_n \quad , \quad (A.2c)$$

$$\phi_n = \frac{(n-1) \pi}{(N-1) 2} \quad , \quad (A.2d)$$

and

$$k_1 = \omega \sqrt{\mu_0 \epsilon_1} \quad . \quad (A.2e)$$

Following the same derivation procedure as discussed in Chapter II, for the electric line source excitation we obtain an integral equation of the form of Equation (2.7) which can be reduced to four sets of decoupled systems of simultaneous linear equations. These system of equations are:

$$\sum_{n=1}^N a_n A_{mn} = V_m^{ee} \quad m = 1, 2, 3, \dots, N, \quad (A.3a)$$

$$\sum_{n=1}^N b_n B_{mn} = V_m^{oe} \quad m = 1, 2, 3, \dots, N, \quad (A.3b)$$

$$\sum_{n=1}^N c_n C_{mn} = V_m^{eo} \quad m = 1, 2, 3, \dots, N, \quad (A.3c)$$

and

$$\sum_{n=1}^N d_n D_{mn} = V_m^{oo} \quad m = 1, 2, 3, \dots, N, \quad (A.3d)$$

where $E_z^i(x,y)$ has been expressed as a sum of odd and even symmetrical functions of x and y

$$E_z^i(x,y) = E^{ee}(x,y) + E^{oe}(x,y) + E^{eo}(x,y) + E^{oo}(x,y) \quad , \quad (A.4)$$

for an electric line source excitation it was shown in Chapter II that

$$E_z^i(x,y) = I K_0(\gamma_2 \rho_1) \quad , \quad (A.5a)$$

ρ_1 is shown in Figure A-1, and

$$I = \frac{-j\omega\mu_0}{2\pi} \quad . \quad (A.5b)$$

thus from Equations (A.4) and (A.5) one can obtain the following:

$$E^{ee}(x,y) = \frac{I}{4} (K_0(\gamma_2 \rho_1) + K_0(\gamma_2 \rho_2) + K_0(\gamma_2 \rho_3) + K_0(\gamma_2 \rho_4)) \quad , \quad (A.6a)$$

$$E^{oe}(x,y) = \frac{I}{4} (K_0(\gamma_2 \rho_1) - K_0(\gamma_2 \rho_2) - K_0(\gamma_2 \rho_3) + K_0(\gamma_2 \rho_4)) \quad , \quad (A.6b)$$

$$E^{eo}(x,y) = \frac{I}{4} (K_0(\gamma_2 \rho_1) + K_0(\gamma_2 \rho_2) - K_0(\gamma_2 \rho_3) - K_0(\gamma_2 \rho_4)) \quad , \quad (A.6c)$$

$$E^{oo}(x,y) = \frac{I}{4} (K_0(\gamma_2 \rho_1) - K_0(\gamma_2 \rho_2) + K_0(\gamma_2 \rho_3) - K_0(\gamma_2 \rho_4)) \quad . \quad (A.6d)$$

For a uniform line source of unit current excitation placed at (x_1, y_1) , Equations (A.4), (A.5), and (A.6) can be achieved by replacing the

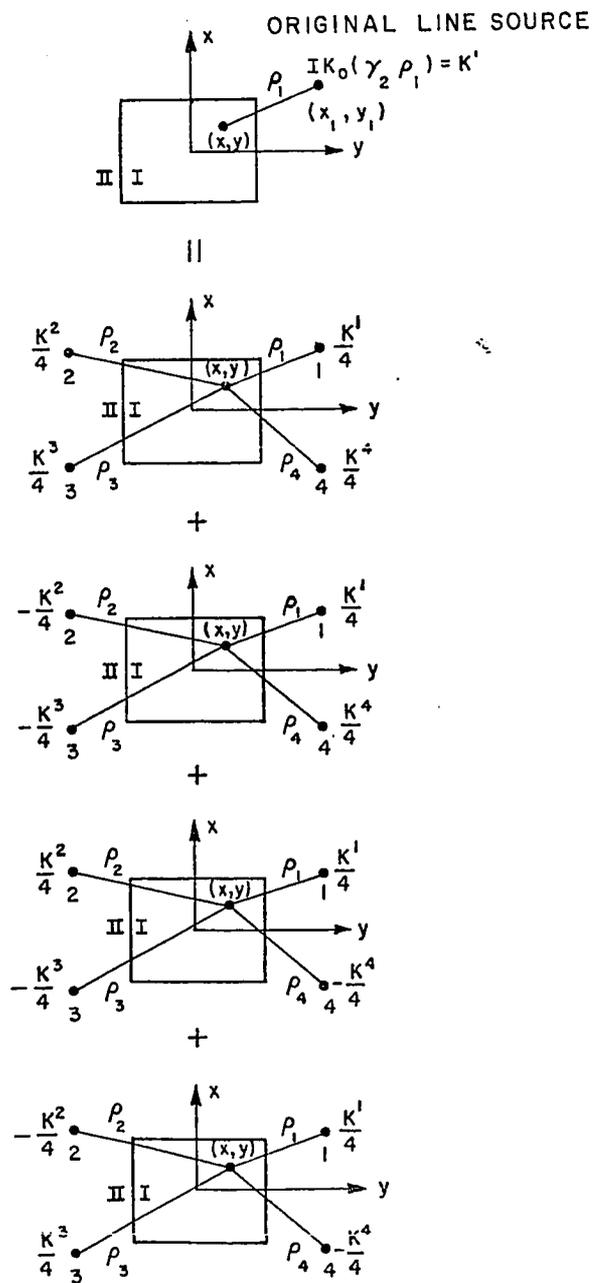


Figure A-1. Pictorial illustration of four fold symmetry where a line source is replaced by four line sources with desired symmetry.

this line source with four line sources of $\frac{1}{4}$ current strength at (x_1, y_1) , (x_2, y_2) , (x_3, y_3) , and (x_4, y_4) respectively as illustrated in Figure A-1. The polarity of the currents is chosen so that the desired symmetries w.r.t x and y are obtained. This is illustrated pictorially in Figure A-1. To simplify this figure the points (x_1, y_1) , (x_2, y_2) , (x_3, y_3) , and (x_4, y_4) are only designated by 1, 2, 3, and 4. Also the line source excitations are simplified as

$$I K_0(\gamma_2 \rho_i) = K^i \quad i = 1, 2, 3, 4.$$

The V_m 's of the Equations (A.3) involve a cross-sectional integration which can be evaluated easily, because there is no singularity involved.

These are given by

$$V_m^{ee} = \iint_{CS} F_m^{ee}(x, y) E^{ee}(x, y) ds \quad , \quad (A.7a)$$

$$V_m^{oe} = \iint_{CS} F_m^{oe}(x, y) E^{oe}(x, y) ds \quad , \quad (A.7b)$$

$$V_m^{eo} = \iint_{CS} F_m^{eo}(x, y) E^{eo}(x, y) ds \quad , \quad (A.7c)$$

$$V_m^{oo} = \iint_{CS} F_m^{oo}(x, y) E^{oo}(x, y) ds \quad , \quad (A.7d)$$

where F_m 's are defined in Equation (A.1), and E 's are defined in Equation (A.6).

The A_{mn} , B_{mn} , C_{mn} , and D_{mn} are given by

$$A_{mn} = \iint_{CS} F_m^{ee}(x,y) F_n^{ee}(x,y) ds + Q \iiint_{CSCS} F_m^{ee}(x,y) F_n^{ee}(x',y') K_0(\gamma_2 \rho) ds' ds , \quad (A.8a)$$

$$B_{mn} = \iint_{CS} F_m^{oe}(x,y) F_n^{oe}(x,y) ds + Q \iiint_{CSCS} F_m^{oe}(x,y) F_n^{oe}(x',y') K_0(\gamma_2 \rho) ds' ds , \quad (A.8b)$$

$$C_{mn} = \iint_{CS} F_m^{eo}(x,y) F_n^{eo}(x,y) ds + Q \iiint_{CSCS} F_m^{eo}(x,y) F_n^{eo}(x',y') K_0(\gamma_2 \rho) ds' ds , \quad (A.8c)$$

$$D_{mn} = \iint_{CS} F_m^{oo}(x,y) F_n^{oo}(x,y) ds + Q \iiint_{CSCS} F_m^{oo}(x,y) F_n^{oo}(x',y') K_0(\gamma_2 \rho) ds' ds , \quad (A.8d)$$

where

$$Q = \frac{\omega^2 \mu_0 (\hat{\epsilon}_1 - \hat{\epsilon}_2)}{2\pi} . \quad (A.8e)$$

and

$$\rho = \sqrt{(x-x')^2 + (y-y')^2} .$$

in the Equations (A.8a)-(A.8d), the integrals of the first terms are evaluated in a closed form with no difficulty, but, the integrals of the second terms are difficult to evaluate because of the singularity point at which $\rho=0$. A method that has been introduced by Richmond [2] for the point matching is applied here to evaluate these integrals. The method involves dividing the cross-section over which the integration is to be carried out into many square cells, and approximating the integration

over the cross-section by a sum of the integration over the cross-section of each cell. A further approximation can be made if the sizes of the cells are chosen small enough so that F_n 's of Equation (A.1) can be assumed to vary very slowly over the cross-section of a cell. These approximations reduce the integrations of the second terms of the equation (A.8a)-(A.8d)

$$\begin{aligned} & \iiint_{\text{CSCS}} F_m(x,y) F_n(x',y') K_0(\gamma_2 \rho) ds' ds \\ & \approx \sum_{i=1}^{NC} \sum_{j=1}^{NC} F_m(x_i, y_i) F_n(x_j, y_j) \iint_{\text{cell}_i} \iint_{\text{cell}_j} K_0(\gamma_2 r_{ij}) ds_i ds_j . \end{aligned} \quad (\text{A.9})$$

Approximate superscripts for F_m and F_n may be used as if applies to each Equation (A.8), and NC is the number of cell in the cross-section. Referring to Figure A-2, r_{ij} is defined as

$$r_{ij} = \sqrt{(x_i - x_j)^2 + (y_i - y_j)^2} \quad , \quad (\text{A.10})$$

where (x_i, y_i) defines a point in cell i and (x_j, y_j) defines a point in cell j . The square cells may be replaced by a circular cell which has the same cross-section area and is centered at the center of the corresponding cell [2]. Without including the details the final form is given as follows

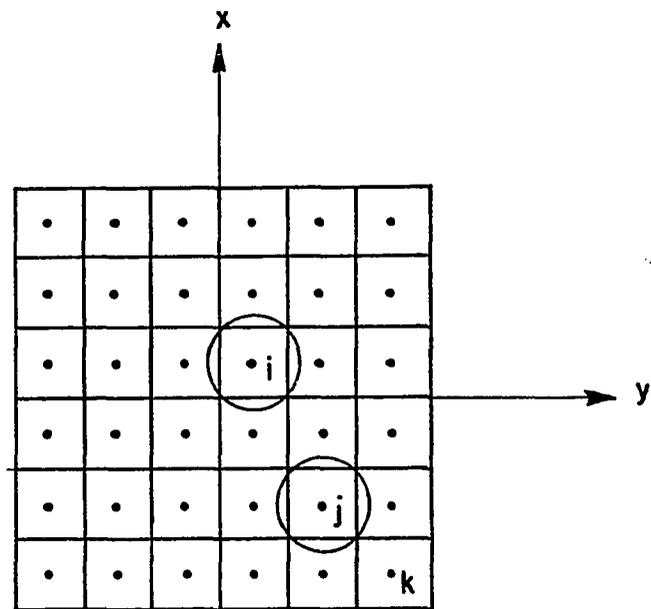


Figure A-2. Pictorial illustration for evaluating the cross sectional integrals.

$$\iint_{\text{cell}_i} \iint_{\text{cell}_j} K_0(\gamma_2 r_{ij}) ds_i ds_j = \begin{cases} \frac{(2\pi)^2 C}{\gamma_2^3} (1 - \gamma_2 C K_1(\gamma_2 C) I_1(\gamma_2 C)) ; i=j \\ \left[\frac{2\pi C}{\gamma_2} I_1(\gamma_2 C) \right]^2 K_0(\gamma_2 R_{ij}) ; i \neq j \end{cases} \quad (\text{A.11a})$$

C is the radius of the equivalent area circular cylinder and

$$R_{ij} = \sqrt{(X_i - X_j)^2 + (Y_i - Y_j)^2} \quad , \quad (\text{A.11b})$$

where

(X_i, Y_i) and (X_j, Y_j) are the centers of cell_i and cell_j respectively. I_1 is the modified Bessel function of the first kind of order one, K_1 and K_0 are the modified Bessel functions of the second kind and orders one and zero respectively.

RCYLPWE program is set up so that various outputs may be obtained selectively. It can be set ^{so} that to give single outputs or an array of numbers. Three major loops to be discussed are shown in Figure A-3. These are: frequency loop, backscattering loop, and bistatic scattering loop. The statement number of the start of the loop is also included in Figure A-3 for easy reference to the program listing in subsequent pages.

To obtain a frequency plot from 10 to 300 MHz. FCMX is set equal to 300, and IFMC is set to desired number of points to be calculated. To obtain a backscattered patterns IBS is set equal to the number of

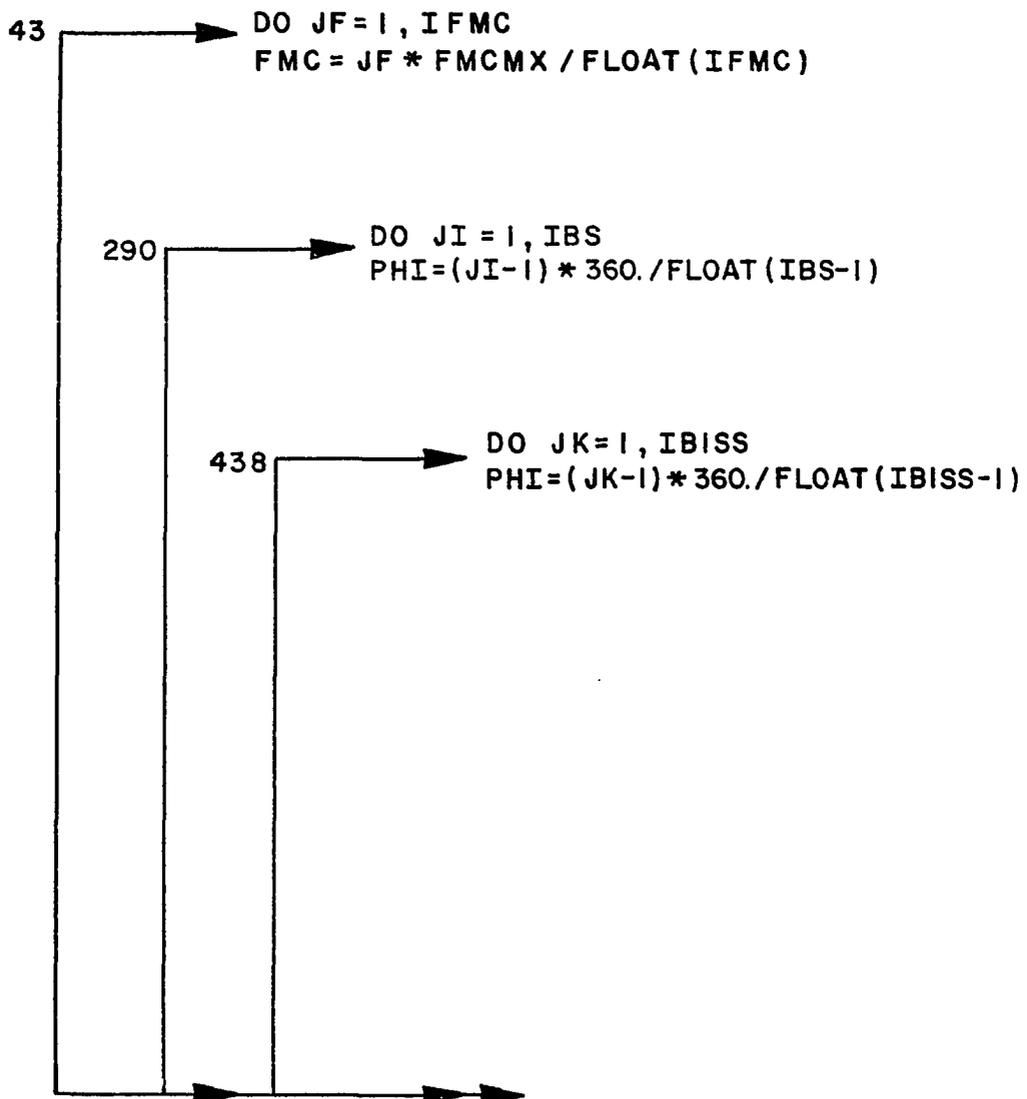


Figure A-3. Three major loops used in the computer program RCYLPWE.

points needed between 0° to 360°: for getting a Bistatic Scattering pattern IBISS is used similarly. It must be kept in mind that only one of the three inputs: IFMC, IBS, IBISS, may be used at a time. Other inputs may be used in combination to obtain desired outputs.

The RCYLPWE program can model an electric line source excitation or a plane wave excitation. If IPW=1, the plane wave excitation is used, and the output is the echowidth/ λ_2 , and if IPW=0, electric line source excitation is used and the output is the Scattering Attenuation Function (SAF).

The following is a list of the inputs for RCYLPWE program in the order they appear in line 29 of the listing:

- ER1: Relative dielectric constant of region I.
- SIG1: Conductivity of region I in s/m.
- ER2: Relative dielectric constant of region I.
- SIG2: Conductivity of region I in s/m.
- FMCMX: Maximum frequency in MHz for the frequency plot.
- AWM: The length (in meters) of the cross-section of the rectangular cylinders (see Figure 2-1b).
- BWM: Width (in meters) of the rectangular cylinder (see Figure 2-1b).
- PHI: The polar angle at which the line source is located or a plane wave is incident (Figure 2-1).
- IWR: If 1, all the generalized impedance matrix element and the voltage column element are written in a file FOR010.DAT. In addition, to above, the solutions of the plane wave

coefficients are also written in the above file. IWR=0 otherwise.

- IFILD: If 1, the field inside the scatterer is written in FOR010.DAT for various points in the first quadrant. Must be set to zero otherwise.
- IWRC: If set to 1, the various elements in CROUT subroutine is printed on the screen for debugging purposes. Set to zero otherwise.
- IPW: If set to 1, the plane wave excitation is used and the output is echowidth/ λ_2 , if set to zero, the line source excitation is used, and the output is (SAF).
- IBS: If > 1 , the backscattering pattern is calculated for IBS points, with angles divided equally. Otherwise it MUST BE SET TO 1.
- IBISS: The same as above, except for Bistatic Scattering Patterns. If not needed, it MUST BE SET TO 1.
- IFMC: Number of frequency points to be calculated for a frequency plot. If not used it MUST BE SET TO 1.
- IEQ: If set to 1, the program automatically calculates NEQ the number of plane waves needed in the expansion to obtain a convergent solution, and NY the number of cells in y-direction for the integration routines. If set to zero, the program asks for the values of NEQ and NY to be input by the user.

RLS: Radial position of the line source (in meters).

RCYLPWE program uses various optimization techniques, one of which is the use of Gaussian interpolation technique. This is done by subroutine INTERP in line 216. Instead of calculating a value of a Bessel function many times, a table of required numbers is calculated only at a few points and is kept. The needed values as they are needed are then extrapolated from this table. Another optimization is made in reducing the values of the Bessel function needed to a minimum by not calculating any values for redundant cases, i.e., cases where the same argument for Bessel functions occur over and over again.

```

0001 C LINK WITH CROUT & MBEZ10
0002 C
0003 C THIS PROGRAM (RCYLPWE.FOR) USES PLANE WAVE EXPANSION AND
0004 C GALERKIN METHOD TO CALCULATE THE SCATTERED FIELD BY
0005 C A LOSSY DIELECTRIC INFINITE RECTANGULAR CYLINDER
0006 C FOR AN ELECTRIC LINE SOURCE PARALLEL TO AXIS OF THE CYLINDER.
0007 C THE CYLINDER IS LOCATED IN A LOSSY HOMOGENEOUS MEDIUM.
0008 C THE PROGRAM USES FOUR FOLD SYMMETRY
0009 C
0010 C WRITTEN BY JAMAL IZADIAN NOVEMBER 1981.
0011 C
0012 C COMPLEX BKK(25,25),FNEE(25),FNOE(25),FNEO(25),FNCO(25)
0013 C COMPLEX FNEE(25),FMOE(25),FNOE(25),FMOO(25),FK(75)
0014 C COMPLEX CMN(25,25),DMN(25,25),EMN(25,25),FMN(25,25)
0015 C COMPLEX A(25),B(25),C(25),D(25),FA(25),GA(25)
0016 C COMPLEX GC,VEE,VOE,VED,VCO,CXP,CYP,SXP,SYL,CXL,CYL,SXL,SYL
0017 C COMPLEX EGXP,EGYP,EGXL,EGYL,EGX1,EGX2,EGX3,EGX4,FN,FM,GN,GM
0018 C COMPLEX EZ1,FMF,FPF,GMG,GPG,S1,S2,S3,S4,SS1,SS2,SS3,SS4
0019 C COMPLEX SFPP,SFMP,SGMG,SGPG,FMXP,GMYP,FMXL,GNYL
0020 C COMPLEX C11,C1K,CV1,EP1,EP2,ETA2,CST,CSS,EZ1,EZS,SEE,SOE,SEO,SOO
0021 C COMPLEX GAM1,GAM2,BI,BK,BI1,BK1,GR,K1,K2,SF,SG,REE,ROE,REO,ROO
0022 C DIMENSION XM(450),YM(450)
0023 C INTEGER P
0024 C DATA FP,TD2/12.5663706144,0./
0025 C DATA ETA,PI,TP/376.730366239,3.14159265359,6.28318530718/
0026 C DATA ICC,NX,ISIZE,NJ,ITBL/25,30,10,0,0/
0027 C DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0028 C call getcp(itl)
0029 C READ(7,*)ER1,SIG1,ER2,SIG2,FMCMX,AWM,BWM,PHI,IWR,IFILD,IWRC
0030 C &,IPW,IBS,IBISS,IFMC,IEQ,RLS
0031 C IFRSCT=IBISS
0032 C IBISS=IABS(IBISS)
0033 C WRITE(10,*)IBS,IBISS,IFMC
0034 C IC=(IBS-1)*(IBISS-1)+(IBS-1)*(IFMC-1)+(IBISS-1)*(IFMC-1)
0035 C IF(IC.NE.0) GO TO 600
0036 C WPH=PHI
0037 C IF(IEQ.EQ.0)TYPE*, 'GIVE NEQ & NY ='
0038 C IF(IEQ.EQ.0)ACCEPT*,NEQ,NY
0039 C IF(IFMC.GT.1) GO TO 41
0040 C 20 TYPE*, 'GIVE FMC='
0041 C ACCEPT*,FMC
0042 C IF(FMC.LT.0) GO TO 600
0043 C 41 DO 500 JF=1,IFMC
0044 C IF(IFMC.GT.1)FMC=JF*FMCMX/FLOAT(IFMC)
0045 C I12=1
0046 C AM=AWM/2.
0047 C BM=BWM/2.
0048 C OMEGA=IP*FMC*1.E6
0049 C BTS1=OMEGA*OMEGA*U0*ER1*E0
0050 C BET1=SQRT(BTS1)
0051 C EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0052 C EP2=ER2*E0*(1.,.0)
0053 C IF(TD2.GT.1.E-10)EP2=ER2*E0*CMPLX(1.,-TD2)
0054 C IF(SIG2.GT.1.E-10)EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0055 C ETA2=CSQRT(U0/EP2)
0056 C GAM2=OMEGA*CSQRT(-U0*EP2)
0057 C GAM1=OMEGA*CSQRT(-U0*EP1)
0058 C K1=(0.,-1.)*GAM1
0059 C K2=(0.,-1.)*GAM2
0060 C BET2=AIMAG(GAM2)
0061 C BTS2=BET2*BET2
0062 C WAV1=TP/BET1
0063 C WAV2=TP/BET2

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0064      CPH=1.-PI/(14.*BET1*AM)
0065      IF (ABS(CPH).GT.1) GO TO 25
0066      DPH=ACOS(CPH)
0067      IF (IEQ.EQ.1) NEQ=1.+PI/(2.*DPH)
0068 25     IF (NEQ.LT.2) NEQ=2
0069      IF (NEQ.GT.ICC) GO TO 600
0070      IF (IEQ.EQ.1) NY=15.*BET1*BWM/PI
0071      IF (NY.LT.6.AND. IEQ.EQ.1) NY=6
0072      IF (NY.GT.NYX) NY=NYX
0073      NY=2*(NY/2)
0074      NX=INT(AM/EM)*NY
0075      NX=(NX/2)*2
0076      NY2=NY/2
0077      NX2=NX/2
0078      K4=NX2*NY2
0079      DPH=.5*PI/(NEQ-1)
0080      DO 90 J=1,NEQ
0081      PH=(J-1)*DPH
0082      FA(J)=K1*COS(PH)
0083      GA(J)=K1*SIN(PH)
0084 90     CONTINUE
0085      IX=NX/2
0086      IY=NY/2
0087      DX=AWM/NX
0088      DY=BWM/NY
0089      DX2=DX/2.
0090      DY2=DY/2.
0091  C     FIND THE RADII OF EQUIVALENT CIRCULAR CELL
0092      CM=SQRT(DX*DY/PI)
0093      GC=GAM2*CM
0094      CALL MBEZ10(GAM2*CM,BI,BK,BI1,BK1,1,-1)
0095      CSS=(1.-GC*BK1)*(EP1-EP2)/EP2
0096      CST=GC*BI1*(EP1-EP2)/EP2
0097      CIK=CSS*2.*FP*CM*BI1/GAM2
0098      CII=CST*2.*FP*CM*BI1/GAM2
0099      CV1=-ETA2*CM*BI1
0100      RAB=SQRT(AWM*AWM+BWM*BWM)
0101 21     DELTR=(RAB-DX)/ISIZE
0102      IF (DX.GT.DELTR) GO TO 23
0103      ISIZE=ISIZE+5
0104      GO TO 21
0105 23     DO 22 I=1,ISIZE
0106      RR=I*DELTR
0107      CALL MBK0Z(GAM2*RR,BK,-1)
0108      FK(I)=BK*CII
0109 22     CONTINUE
0110      TYPE*, 'ISIZE=', ISIZE
0111      M=0
0112      Y=DY2
0113  C     SET UP THE COORDINATES OF CENTERS OF CELL M
0114      DO 40 J=1,NY2
0115      X=DX2
0116      DO 30 I=1,NX2
0117      M=M+1
0118      XM(M)=X
0119      YM(M)=Y
0120 30     X=X+DX
0121 40     Y=Y+DY
0122      DO 42 J=1,25
0123      DO 42 I=1,25
0124 42     EKK(I,J)=(0.,0.)
0125  C     SET UP IMPEDANCE MATRIX
0126      DO 200 M=1,NEQ

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0127      FM=FA(M)
0128      GM=GA(M)
0129      DO 160 N=M,NEQ
0130      FN=FA(N)
0131      GN=GA(N)
0132      FNF=FN-FM
0133      FPF=FN+FM
0134      GNG=GN-GM
0135      GPG=GN+GM
0136      IF (M.NE.N) GO TO 31
0137      SF=CSIN(2.*FN*AM)
0138      SG=CSIN(2.*GN*BM)
0139      S1=AM*BM
0140      IF (M.EQ.1) THEN
0141      S3=.5*BM*SF/FN
0142      REE=2.*(S1+S3)
0143      ROE=2.*(S1-S3)
0144      REO=(0.,0.)
0145      ROO=(0.,0.)
0146      GO TO 33
0147      END IF
0148      IF (M.EQ.NEQ) THEN
0149      S2=.5*AM*SG/GN
0150      REE=2.*(S1+S2)
0151      ROE=(0.,0.)
0152      REO=2.*(S1-S2)
0153      ROO=(0.,0.)
0154      GO TO 33
0155      END IF
0156      S2=.5*AM*SG/GN
0157      S3=.5*BM*SF/FN
0158      S4=.25*SF*SG/FN/GN
0159      REE=S1+S2+S3+S4
0160      ROE=S1+S2-S3-S4
0161      REO=S1-S2+S3-S4
0162      ROO=S1-S2-S3+S4
0163      GO TO 33
0164      31 SFMF=CSIN(FMF*AM)
0165      SFPF=CSIN(FPF*AM)
0166      SGNG=CSIN(GNG*BM)
0167      SGPG=CSIN(GPG*BM)
0168      SS1=SFMF*SGNG/FMF/GNG
0169      SS2=SFMF*SGPG/FMF/GPG
0170      SS3=SFPF*SGNG/FPF/GNG
0171      SS4=SFPF*SGPG/FPF/GPG
0172      REF=SS1+SS2+SS3+SS4
0173      ROE=SS1+SS2-SS3-SS4
0174      REO=SS1-SS2+SS3-SS4
0175      ROO=SS1-SS2-SS3+SS4
0176      33 CONTINUE
0177      CMN(M,N)=REE
0178      DMN(M,N)=ROE
0179      M1=M-1
0180      N1=N-1
0181      IF (M.GT.1) EMN(M1,N1)=REO
0182      IF (M.GT.1) FMN(M1,N1)=ROO
0183      180 CONTINUE
0184      200 CONTINUE
0185      DO 160 P=1,K4
0186      XP=XM(P)
0187      YP=YM(P)
0188      JPP=(P-1)/IX+1
0189      IPP=P-(JPP-1)*IX

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0190 JP=JPP+IX
0191 IP=IPP+IX
0192 DO 140 I=1,K4
0193 XL=XM(L)
0194 YI=YM(L)
0195 JLP=(L-1)/IX+1
0196 ILP=L-(JLP-1)*IX
0197 XN=XL
0198 YN=YL
0199 IN=ILP
0200 JN=JLP
0201 SIGX=1.
0202 SIGY=1.
0203 DO 120 I1=1,2
0204 YY=YP-YL
0205 YS=YY*YY
0206 JI=IY+JLP+(I1-1)
0207 DO 100 I2=1,2
0208 XX=XP-XL
0209 XS=XX*XX
0210 IL=IX+ILP+(I2-1)
0211 II=I+IABS(IP-II)
0212 JJ=1+IABS(JP-JI)
0213 ROH=SQRT(XS+YS)
0214 IF (ROH.LT.IX2) GO TO 79
0215 IF (BKK (II, JJ), BQ, (0, 0,)) THEN
0216 CALL INTERP(ROH, BKK (II, JJ), DELTA, FK, ISIZE)
0217 BKK (JJ, II)=BKK (II, JJ)
0218 NJ=NJ+1
0219 END IF
0220 DO 80 M=1,NEQ
0221 IF (L.GT.1) GO TO 77
0222 FM=FA(M)
0223 GM=GA(M)
0224 FMXP=FM*XP*(0,1,.)
0225 GMXP=GM*YP*(0,1,.)
0226 BEXP=CEXP (FMXP)
0227 BEXP=CEXP (GMXP)
0228 CXP=.5*(BEXP+1./BEXP)
0229 CYP=.5*(BEXP+1./BEXP)
0230 SKP=(0,.-.5)*(BEXP-1./BEXP)
0231 SYP=(0,.-.5)*(BEXP-1./BEXP)
0232 FHEE(M)=CXP*CYP
0233 FHOE(M)=SKP*CYP
0234 FHOO(M)=CXP*SYP
0235 FHOO(M)=SKP*SYP
0236 DO 80 N=M,NEQ
0237 IF (L1.GT.1.OR.L2.GT.1) GO TO 75
0238 FN=FA(N)
0239 GN=GA(N)
0240 FNXL=FN*XL*(0,1,.)
0241 GNXL=GN*YL*(0,1,.)
0242 BXYL=CEXP (FNXL)
0243 BXYL=CEXP (GNXL)
0244 CXL=.5*(BXYL+1./BXYL)
0245 SYL=.5*(BXYL+1./BXYL)
0246 SYL=(0,.-.5)*(BXYL-1./BXYL)
0247 FNEE(N)=CXL*CYL
0248 FHOE(N)=SKL*CYL
0249 FNBO(N)=CXL*SYL
0250 FNDO(N)=SKL*SYL
0251 IF (ROH.GT.IX2) GO TO 35
0252
75

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0253      CMN(M,N)=CMN(M,N)+FMEE(M)*FNEE(N)*CIK
0254      DMN(M,N)=DMN(M,N)+FMOE(M)*FNOE(N)*CIK*SIGX
0255      M1=M-1
0256      N1=N-1
0257      IF(M.GT.1)EMN(M1,N1)=EMN(M1,N1)+FMEO(M)*FNEO(N)*CIK*SIGY
0258      IF(M.GT.1)FMN(M1,N1)=FMN(M1,N1)+FMOO(M)*FNOO(N)*CIK*SIGX*SIGY
0259      GO TO 80
0260 35    BK=BKK(II,JJ)
0261      CMN(M,N)=CMN(M,N)+FMEE(M)*FNEE(N)*BK
0262      DMN(M,N)=DMN(M,N)+FMOE(M)*FNOE(N)*BK*SIGX
0263      M1=M-1
0264      N1=N-1
0265      IF(M.GT.1)EMN(M1,N1)=EMN(M1,N1)+FMEO(M)*FNEO(N)*BK*SIGY
0266      IF(M.GT.1)FMN(M1,N1)=FMN(M1,N1)+FMOO(M)*FNOO(N)*BK*SIGX*SIGY
0267 80    CONTINUE
0268      SIGX=-1.
0269      ILP=-IN
0270 100   XL=-XN
0271      SIGX=1.
0272      SIGY=-1.
0273      XL=XN
0274      ILP=IN
0275      JLP=-JN
0276 120   YL=-YN
0277 140   CONTINUE
0278 160   CONTINUE
0279      TYPE*, 'NJ=' ,NJ
0280      NJ=0
0281      IF(IWR.EQ.1) THEN
0282      WRITE(10,2)
0283      DO 210 M=1,NEQ
0284      DO 210 N=M,NEQ
0285      WRITE(10,3)M,N,CMN(M,N),DMN(M,N),EMN(M,N),FMN(M,N)
0286 210    CONTINUE
0287      END IF
0288      IF(IWR.EQ.1)WRITE(10,9)
0289      IF(IWR.EQ.1)WRITE(10,4)
0290      DO 500 JI=1,IBS
0291      IF(IBS.GT.1)PHI=(JI-1)*360./FLOAT(IBS-1)
0292      PH1=.0174533*PHI
0293      PH2=PI-PH1
0294      PH3=PI+PH1
0295      PH4=-PH1
0296      CS1=CCS(PH1)
0297      SN1=SIN(PH1)
0298      CS2=CCS(PH2)
0299      SN2=SIN(PH2)
0300      CS3=CCS(PH3)
0301      SN3=SIN(PH3)
0302      CS4=CCS(PH4)
0303      SN4=SIN(PH4)
0304      XLS1=RLS*CS1
0305      YLS1=RLS*SN1
0306      XLS2=RLS*CS2
0307      YLS2=RLS*SN2
0308      XLS3=RLS*CS3
0309      YLS3=RLS*SN3
0310      XLS4=RLS*CS4
0311      YLS4=RLS*SN4
0312  C     SET UP THE VOLTAGE MATRIX
0313      DO 240 M=1,NEQ
0314      FM=FA(M)
0315      GM=GA(M)

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0316      SEE=(0.,0.)
0317      SOE=(0.,0.)
0318      SEO=(0.,0.)
0319      SOO=(0.,0.)
0320      DO 220 P=1,K4
0321      X=XM(P)
0322      Y=YM(P)
0323      FMXP=FM*X*(0.,1.)
0324      GMYP=GM*Y*(0.,1.)
0325      EGXP=CEXP(FMXP)
0326      EGYP=CEXP(GMYP)
0327      CXP=.5*(EGXP+1./EGXP)
0328      CYP=.5*(EGYP+1./EGYP)
0329      SXP=(0.,-.5)*(EGXP-1./EGXP)
0330      SYP=(0.,-.5)*(EGYP-1./EGYP)
0331      FMEE(M)=CXP*CYP
0332      FMOE(M)=SXP*CYP
0333      FMEO(M)=CXP*SYP
0334      FMOO(M)=SXP*SYP
0335      IF(IPW.EQ.1) THEN
0336      PSI1=X*CS1+Y*SN1
0337      PSI2=X*CS2+Y*SN2
0338      PSI3=X*CS3+Y*SN3
0339      PSI4=X*CS4+Y*SN4
0340      EGX1=CEXP(GAM2*PSI1)
0341      EGX2=CEXP(GAM2*PSI2)
0342      EGX3=CEXP(GAM2*PSI3)
0343      EGX4=CEXP(GAM2*PSI4)
0344      CV1=(1.,0.)*DX*DY
0345      GO TO 219
0346      END IF
0347      X1=XLS1-X
0348      Y1=YLS1-Y
0349      X2=XLS2-X
0350      Y2=YLS2-Y
0351      X3=XLS3-X
0352      Y3=YLS3-Y
0353      X4=XLS4-X
0354      Y4=YLS4-Y
0355      RH1=SQRT(X1*X1+Y1*Y1)
0356      RH2=SQRT(X2*X2+Y2*Y2)
0357      RH3=SQRT(X3*X3+Y3*Y3)
0358      RH4=SQRT(X4*X4+Y4*Y4)
0359      CALL NEK0Z(GAM2*RH1,EGX1,-1)
0360      CALL NEK0Z(GAM2*RH2,EGX2,-1)
0361      CALL NEK0Z(GAM2*RH3,EGX3,-1)
0362      CALL NEK0Z(GAM2*RH4,EGX4,-1)
0363      219 VEE=EGX1+EGX2+EGX3+EGX4
0364      VOE=EGX1-EGX2-EGX3+EGX4
0365      VEO=EGX1+EGX2-EGX3-EGX4
0366      VOO=EGX1-EGX2+EGX3-EGX4
0367      SEE=SEE+FMEE(M)*VEE
0368      SOE=SOE+FMOE(M)*VOE
0369      SEO=SEO+FMEO(M)*VEO
0370      SOO=SOO+FMOO(M)*VOO
0371      220 CONTINUE
0372      A(M)=SEE*CV1
0373      B(M)=SOE*CV1
0374      M1=M-1
0375      IF(M.GT.1)C(M1)=SEO*CV1
0376      IF(M.GT.1)D(M1)=SOO*CV1
0377      240 CONTINUE
0378      IF(IWR.EQ.1) THEN

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0379          DO 202 M=1,NEQ
0380          202 WRITE (10,5) M,A(M) ,B(M) ,C(M) ,D(M)
0381             WRITE (10,9)
0382             END IF
0383             NN1=NEQ-1
0384             NN2=NEQ-2
0385             ISYM=0
0386             CALL CROUT(CMN,A,ICC,ISYM,IWRC,I12,NEQ)
0387             CALL CROUT(EMN,B,ICC,ISYM,IWRC,I12,NN1)
0388             CALL CROUT(FMN,C,ICC,ISYM,IWRC,I12,NN1)
0389             CALL CROUT(FMN,D,ICC,ISYM,IWRC,I12,NN2)
0390             IF (IWR.EQ.1) THEN
0391             WRITE (10,6)
0392             DO 244 M=1,NEQ
0393             244 WRITE (10,5) M,A(M) ,B(M) ,C(M) ,D(M)
0394                CONTINUE
0395                WRITE (10,9)
0396                END IF
0397                DO 242 J=1,NEQ-1
0398                I=NEQ-J
0399                C(I+1)=C(I)
0400                242 D(I+1)=D(I)
0401                C(1)=(0.,0.)
0402                D(1)=(0.,0.)
0403                D(NEQ)=(0.,0.)
0404                C FIND THE FIELD IN CELLS OF FIRST QUADRANT
0405                IF (FILD.NE.1) GO TO 45
0406                WRITE (10,8)
0407                DO 248 L=1,K4
0408                EZ1=(0.,0.)
0409                XL=XM(L)
0410                YL=YM(L)
0411                DO 246 N=1,NEQ
0412                FN=FA(N)
0413                GN=GA(N)
0414                FNXL=FN*XL*(0.,1.)
0415                GNXL=GN*XL*(0.,1.)
0416                EGXL=CEXP(FNXL)
0417                EGYL=CEXP(GNXL)
0418                CXL=.5*(EGXL+1./EGXL)
0419                CYL=.5*(EGYL+1./EGYL)
0420                SXL=(0.,-.5)*(EGXL-1./EGXL)
0421                SYL=(0.,-.5)*(EGYL-1./EGYL)
0422                FNEE(N)=CXL*CYL
0423                FNOE(N)=SXL*CYL
0424                FNEO(N)=CXL*SYL
0425                FNOO(N)=SXL*SYL
0426                EZ1=EZ1+(A(N)*FNEE(N)+B(N)*FNOE(N)+C(N)*FNEO(N)+D(N)*FNOO(N))
0427                246 CONTINUE
0428                CX=.0174533
0429                RE=REAL(EZ1)
0430                AIE=AIMAG(EZ1)
0431                AMP=CAES(EZ1)
0432                PHASE=ATAN2(AIE,RE)/CX
0433                WRITE (10,11) XL,YL,AMP,PHASE
0434                248 CONTINUE
0435                45 IF (IWR.EQ.1) WRITE (10,9)
0436                PHS=PH1
0437                IF (IFRST.EQ.-1) PHS=PHS+PI
0438                DO 500 JK=1,IBISS
0439                IF (IBISS.GT.1) THEN
0440                PHI=(JK-1)*360./FLOAT(IBISS-1)
0441                PHS=.0174533*PHI

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0442      END IF
0443      XLS=RLS*COS(PHS)
0444      YLS=RLS*SIN(PHS)
0445      C    FIND THE BACKSCATTERED FIELD
0446      EZS=(.0,.0)
0447      DO 290 L=1,K4
0448      XL=XN(L)
0449      YL=YM(L)
0450      XN=XL
0451      YN=YL
0452      SIGX=1.
0453      SIGY=1.
0454      DO 280 L1=1,2
0455      YY=YLS-YL
0456      YS=YY*YY
0457      DO 270 L2=1,2
0458      XX=XLS-XL
0459      XS=XX*XX
0460      IF (IPW.EQ.1) THEN
0461      PST=XL*COS(PHS)+YL*SIN(PHS)
0462      BK=CEXP(GAM2*PSI)
0463      GO TO 47
0464      END IF
0465      ROH=SQRT(XS+YS)
0466      CALL MBK0Z(GAM2*ROH,BK,-1)
0467      47    EZ1=(0.,0.)
0468      DO 260 N=1,NEQ
0469      IF (L1.GT.1.OR.L2.GT.1) GO TO 269
0470      FN=FA(N)
0471      GN=GA(N)
0472      FNXL=FN*XL*(0.,1.)
0473      GNXL=GN*YL*(0.,1.)
0474      EGXL=CEXP(FNXL)
0475      EGYL=CEXP(GNXL)
0476      CXL=.5*(EGXL+1./EGXL)
0477      CYL=.5*(EGYL+1./EGYL)
0478      SXL=(0.,-.5)*(EGXL-1./EGXL)
0479      SYL=(0.,-.5)*(EGYL-1./EGYL)
0480      FNEE(N)=CXL*CYL
0481      FNOE(N)=SXL*CYL
0482      FNEO(N)=CXL*SYL
0483      FNOO(N)=SXL*SYL
0484      269    EZ1=EZ1+(A(N)*FNEE(N)+B(N)*FNOE(N)*SIGX+C(N)*FNEO(N)*SIGY
0485      &+D(N)*FNOO(N)*SIGX*SIGY)
0486      260    CONTINUE
0487      EZS=EZS+EZ1*BK
0488      SIGX=-1.
0489      270    XL=-XN
0490      SIGX=1.
0491      SIGY=-1.
0492      XL=XN
0493      280    YL=-YN
0494      290    CONTINUE
0495      EZS=-CST*EZS
0496      IF (IPW.EQ.1) EZS=EZS*CSQRT(.5*PI/GAM2)
0497      AZS=CABS(EZS)
0498      IF (IWR.EQ.1) WRITE(10,*) 'AZS=',AZS
0499      EWL=IP*AZS*AZS/WAV2
0500      DB=.0
0501      C    FIND THE NORMALIZED SCATTERING ATTENUATION FUNCTION
0502      IF (IPW.EQ.0) THEN
0503      GR=2.*GAM2*RLS
0504      CALL MBK0Z(GR,BK,-1)

```

```

0505      EZI=(.0,-1.)*OMEGA*U0*BK/TP
0506      AZI=CABS(EZI)
0507      IF(IWR.EQ.1)WRITE(10,*)'AZI=',AZI
0508      AZN=AZS/AZI
0509      DB=20.*ALOG10(AZN)
0510      TYPE1,NEQ,NX,NY,FMC,DB,PHI
0511      WRITE(10,1)NEQ,NX,NY,FMC,DB,PHI
0512      GO TO 599
0513      END IF
0514      TYPE1,NEQ,NX,NY,FMC,EVL,PHI
0515      WRITE(10,1)NEQ,NX,NY,FMC,EVL,PHI
0516 599    IF(IFS.EQ.1.AND.IBISS.EQ.1.AND.IFNC.EQ.1)GO TO 20
0517      I12=2
0518 500    CONTINUE
0519 600    CONTINUE
0520      IF(IPW.EQ.1)WRITE(10,14)
0521      IF(IPW.EQ.0)WRITE(10,13)
0522      WRITE(10,9)
0523      WRITE(10,*)' ER1 & SIG1 =' ,ER1,SIG1
0524      WRITE(10,*)' ER2 & SIG2 =' ,ER2,SIG2
0525      WRITE(10,*)' AWM & BWM =' ,AWM,BWM
0526      WRITE(10,*)' RLS=' ,RLS,'PHI=' ,WPH
0527      call getcp(it2)
0528      time=(it2-it1)/100.
0529      WRITE(10,*)' CPU TIME (SEC) =' ,TIME
0530      TYPE*,' CPU TIME (SEC) = ',TIME
0531      WRITE(10,*)'RCYCLEW.FOR'
0532 1      FORMAT(1X,3I5,6F12.6)
0533 2      FORMAT(5X,'M',4X,'N',13X,'GMN',21X,'DMN',21X,'EMN',21X,'FMN')
0534 3      FORMAT(1X,2I5,8F12.6)
0535 4      FORMAT(5X,'M',18X,'VEE',21X,'VOE',21X,'VEO',21X,'VCO')
0536 5      FORMAT(1X,I5,5X,8F12.6)
0537 6      FORMAT(5X,'M',18X,' A ',21X,' B ',21X,' C ',21X,' D ')
0538 8      FORMAT(5X,'X',9X,'Y',11X,'AMPLITUDE',3X,'PHASE')
0539 9      FORMAT(1H0)
0540 11     FORMAT(1X,2F10.5,5X,2F12.6)
0541 13     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF',9X,'PHI')
0542 14     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'EVL',9X,'PHI')
0543      CALL EXIT
0544      END

```

APPENDIX B

The computer program RTUNLE uses the formulation of Chapter III and Chapter VII. It is capable of treating a rectangular scatterer in a homogeneous ambient medium or in a lossy half space. To include the effects of the half space IGROND is set to one otherwise, it must be set to zero. All the inputs necessary to execute the program is shown in line 16 and 17 in the listing. This program has the same type of internal DO loops as described in Figure A-3 for RCYLPWE program. Here, only the new inputs are described.

- NEQ: Number of plane waves to be included in the plane wave expansion, restricted to condition in line 53. This will be used by the program when line 24-25 and 48-52 are not to be executed.
- DM: The x-coordinate of the air-earth interface plane parallel to yz-plane as shown in Figure 7-1. DM is in meters.
- XLS: X-coordinate of the electric line source location (in meters) as shown in Figure 7-1. In this program the restriction $\frac{AWM}{2} \leq XLS \leq DM$ is made.
- YLS: Y-coordinate of the electric line source (in meters) as shown in Figure 7-1.

IGROND: If set to one, the air-earth interface will be included in the model as shown in Figure 7-1. If set to zero only the homogeneous ambient medium is considered.

IZMN: If set to one, the elements of the generalized impedance matrix is stored in file FOR $\phi\phi$ 8.DAT for cases where these elements are needed again. If set to zero, the program does not calculate the elements of generalized impedance matrix, instead it reads them from file FOR $\phi\phi$ 8.DAT.

```

0001 C This is program (KTUNLE.FOR) Rectangular TUNnel Ez-polarization.
0002 C It uses Plane Wave Expansion Galerkin.
0003 C
0004 C WRITTEN BY JAMAL IZADIAN DECEMBER 1981.
0005 C
0006 COMPLEX A(25),V(25),DV(25),VT(25),Z(25,25),DZ(25,25),ZT(25,25)
0007 COMPLEX FA(25),GA(25),B(25),EZ1,EZI,EZS
0008 COMPLEX SUM1,SUM2,SUMT,RMN,SMN,FM,FM,GN,GM,S1,S2,FNFM,GNGM
0009 COMPLEX C2,CST,C1,CJ,EP1,EP2,GAM1,GAM2,GAM2S,K1,K2,EXF,EXG,BK
0010 DIMENSION XM(100),YM(100)
0011 COMMON /JI/ GAM2S,GAM2,OMEGA,ER2,SIG2
0012 COMMON FN,FM,GN,GM,AM,BM,DM,XLS,YLS
0013 DATA PI,TP/3.14159265359,6.28318530718/
0014 DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0015 DATA IWRC,ICC,I12,ISYM/0,25,1,0/
0016 READ(7,*)ER1,SIG1,ER2,SIG2,FMCIX,NEQ,AWM,BWM,DM,XLS,YLS,IWR
0017 &,IFILD,IBS,IBISS,IFMC,IGRAND,IZMN
0018 call getcp(itl)
0019 IF((AWM/2.).GT.DM.OR.XLS.GT.DM) GO TO 500
0020 WRITE(10,*)MAX(ABS,IBISS,IFMC)
0021 CJ=(0.,1.)
0022 CX=.0174533
0023 NY=1
0024 21 TYPE*, 'GIVE FMC,NEQ,NY='
0025 ACCEPT*,FMC,NEQ,NY
0026 IF(FMC.LT.0) GO TO 500
0027 NX=(AWM/BWM)*NY
0028 AM=AWM/2.
0029 BM=BWM/2.
0030 DO 500 JF=1,IFMC
0031 IF(IFMC.GT.1)FMC=JF*FMCIX/FLOAT(IFMC)
0032 OMEGA=TP*FMC*1.E6
0033 EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0034 EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0035 GAM1=OMEGA*CSQRT(-U0*EP1)
0036 GAM2=OMEGA*CSQRT(-U0*EP2)
0037 BET1=AIFAG(GAM1)
0038 GAM2S=GAM2*GAM2
0039 K1=CJ*GAM1
0040 K2=CJ*GAM2
0041 CST=-OMEGA*OMEGA*U0*(EP1-EP2)/TP
0042 C1=CJ*OMEGA*U0/TP
0043 C2=CJ*OMEGA*(EP1-EP2)
0044 DX=AWM/NX
0045 DY=BWM/NY
0046 DX2=DX/2.
0047 DY2=DY/2.
0048 CPH=1.-PI/(14.*BET1*AM)
0049 IF(ABS(CPH).GT.1) GO TO 19
0050 DPH=ACOS(CPH)
0051 NEQ=1.+PI/(2.*DPH)
0052 NEQ=2*NEQ
0053 19 IF(NEQ.LT.6) NEQ=6
0054 M=0
0055 Y=-BM+DY2
0056 DO 20 J=1,NY
0057 X=-AM+DX2
0058 DO 22 I=1,NX
0059 M=M+1
0060 XM(M)=X
0061 YM(M)=Y
0062 22 X=X+DX
0063 20 Y=Y+DY

```

```

0064 KK=M
0065 DPH=JP/NEQ
0066 DO 90 J=1,NEQ
0067 A(J)=(C,0.)
0068 B(J)=(0.,0.)
0069 PH=(J-1)*DPH
0070 FA(J)=K1*COS(PH)
0071 GA(J)=K1*SIN(PH)
0072 IF (IWR.EQ.1)WRITE(10,1)
0073 IF (IZRR.EQ.0) THEN
0074 DO 92 N=1,NEQ
0075 DO 92 N=N,NEQ
0076 READ(6,2)I,J,Z(N,N),DZ(N,N),ZT(N,N)
0077 GO TO 404
0078 END IF
0079 DO 100 M=1,NEQ
0080 FM=FA(M)
0081 GM=GA(M)
0082 DO 200 N=M,NEQ
0083 FN=FA(N)
0084 GN=GA(N)
0085 FNM=FN+FM
0086 GNM=GN+GM
0087 SI=AM
0088 S2=BM
0089 IF (CABS(FNM).GT.1.E-6)SI=CSIN(FNM*AM)/FNM
0090 IF (CABS(GNM).GT.1.E-6)S2=CSIN(GNM*BM)/GNM
0091 RNM=4.*SI*S2
0092 CALL SPCIRM(SUMT,2,IGROUND)
0093 SMN=4.*CST*SUMT
0094 Z(M,N)=RNM+SMN
0095 IF (IGROUND.EQ.1)CALL SPCIRM(SUMT,3,IGROUND)
0096 IF (IGROUND.EQ.1)DZ(M,N)=8.*CST*SUMT
0097 IF (IGROUND.EQ.1)ZT(M,N)=Z(M,N)+DZ(M,N)
0098 IF (IWR.EQ.1)WRITE(10,2)M,N,Z(M,N),DZ(M,N),ZT(M,N)
0099 WRITE(8,2)M,N,Z(M,N),DZ(M,N),ZT(M,N)
0100 CONTINUE
0101 CONTINUE
0102 CONTINUE
0103 IF (IGROUND.EQ.1) THEN
0104 DO 106 N=1,NEQ
0105 DO 106 N=N,NEQ
0106 Z(M,N)=ZT(M,N)
0107 END IF
0108 IF (IWR.EQ.1)WRITE(10,3)
0109 IF (IWR.EQ.1)WRITE(10,4)
0110 DO 500 JI=1,IBS
0111 IF (IBS.GT.1)YLS=(IBS-1)/(2+1-JI)*.0625
0112 YLSS=YLS
0113 SET UP THE VOLTAGE COLUMN
0114 DO 120 M=1,NEQ
0115 FM=FA(M)
0116 GM=GA(M)
0117 CALL SPCIRM(SUMT,0,IGROUND)
0118 A(M)=SUMT
0119 V(M)=2.*C1*SUMT
0120 IF (IGROUND.EQ.1) THEN
0121 CALL SPCIRM(SUMT,1,IGROUND)
0122 B(M)=SUMT
0123 DV(M)=2.*C1*SUMT
0124 VT(M)=V(M)+DV(M)
0125 END IF
0126 IF (IWR.EQ.1)WRITE(10,5)M,V(M),DV(M),VT(M)

```

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404

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C

120

```

0127 IF (IMR.EQ.1) WRITE (10,3)
0128 IF (IGROND.EQ.1) THEN
0129 DO 104 N=1,NRQ
0130 V(M)=VT(M)
0131 END IF
0132 CALL CROUT(Z,V,ICC,ISM,IMRC,I12,NRQ)
0133 IF (IFLD.EQ.0) GO TO 45
0134 FIND FIELD INSIDE THE TUNNEL
0135 WRITE (10,3)
0136 DO 300 I=1,KK
0137 EZ1=(0.,0.)
0138 X=XM(I)
0139 Y=YM(I)
0140 IF (X.IT.0.OR.Y.IT.0) GO TO 300
0141 DO 400 N=1,NRQ
0142 FN=FA(N)
0143 GN=GA(N)
0144 EXE=CEXP(-CJ*FN*X)
0145 EXG=CEXP(-CJ*GN*Y)
0146 EZ1=EZ1+EXE*EXG*V(N)
0147 RB=REAL(EZ1)
0148 AIE=AIMAG(EZ1)
0149 PHASE=ATAN2(AIE,RE)/CX
0150 AMP=CABS(EZ1)
0151 WRITE (10,7) X,Y,AMP,PHASE
0152 CONTINUE
0153 WRITE (10,3)
0154 FIND SCATTERED FIELD
0155 DO 500 JK=1,IBISS
0156 IF (IBISS.GT.1) YLS=((IBISS-1)/2+1-JK)*.0625
0157 EZS=(0.,0.)
0158 DO 600 M=1,NRQ
0159 IF (IBISS.GT.1) THEN
0160 FM=FA(M)
0161 GM=GA(M)
0162 CALL SPCTRM(SUMT,0,IGROND)
0163 A(M)=SUMT
0164 IF (IGROND.EQ.1) CALL SPCTRM(SUMT,1,IGROND)
0165 IF (IGROND.EQ.1) B(M)=SUMT
0166 END IF
0167 EZS=EZS+V(M)*(A(M)+B(M))
0168 EZS=-CST*2.*EZS
0169 AZS=CABS(EZS)
0170 IF (IGROND.EQ.0) THEN
0171 RLSQ=SQRT(XLS*XLS+YLS*YLS)
0172 RLSQ=SQRT(XLS*XLS+YLS*YLS)
0173 CALL MK0Z(GMZ*(RLSQ+RLSS),BK,-1)
0174 EZI=BK*CI
0175 AZI=CABS(EZI)
0176 AZN=AZS/AZI
0177 DB=20.*ALOG10(AZN)
0178 TYPE8,NRQ,NX,NY,FM,C,DB,YLS
0179 WRITE (10,8) NRQ,NX,NY,FM,C,DB,YLS
0180 GO TO 499
0181 END IF
0182 TYPE8,NRQ,NX,NY,FM,C,AZS,YLS
0183 WRITE (10,8) NRQ,NX,NY,FM,C,AZS,YLS
0184 IF (IBS.GT.1) I12=2
0185 IF (IBS.EQ.1.AND.IBISS.EQ.1.AND.IMFC.EQ.1) GO TO 21
0186 CONTINUE
0187 IF (IGROND.EQ.1) WRITE (10,9)
0188 IF (IGROND.EQ.0) WRITE (10,10)
0189

```

```

0190 1   FORMAT(5X,'M',4X,'N',13X,'ZMN',20X,'DZMN',20X,'ZIMN'25X)
0191 2   FORMAT(1X,2I5,8F12.6)
0192 3   FORMAT(1H0)
0193 4   FORMAT(5X,'M',12X,' VM ',21X,'DVM',21X,'VIM',21X)
0194 5   FORMAT(1X,I5,8F12.6)
0195 6   FORMAT(5X,'X',9X,'Y',13X,'AMPLITUDE',3X,'PHASE')
0196 7   FORMAT(1X,2F10.5,5X,2F12.6)
0197 8   FORMAT(1X,3I5,6F12.6)
0198 9   FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF')
0199 10  FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF')
0200    call getcp(it2)
0201    time=(it2-it1)/100.
0202    WRITE(10,*)'ER1 & SIG1=',ER1,SIG1
0203    WRITE(10,*)'ER2 & SIG2=',ER2,SIG2
0204    WRITE(10,*)'AWM,EWM,DM,XLS,YLS=',AWM,EWM,DM,XLS,YLS
0205    write(10,*)'cpu time=',time,'sec'
0206    WRITE(10,*)'RUNTIME.FOR'
0207    write(10,*)ER1,SIG1,ER2,SIG2,FMC,NEQ,AWM,EWM,DM,XLS,YLS,IWR
0208    &,IFILD,IBS,IBISS
0209    STOP
0210    END

```

FUNCTIONS AND SUBROUTINES REFERENCED

```

0001  C
0002    SUBROUTINE SPCIRM(SUM1,I0123,IGROND)
0003    COMPLEX GAM2S,GAM2,GAM0S,FQ,RC,F,F0,FF,SUM1,SUM2,SUM3,SUMT
0004    COMPLEX FN,FM,GN,GM,AN,BM,DM,XLS,YLS
0005    REAL KO
0006    COMMON /JI/GAM2S,GAM2,OMEGA,ER2,SIG2
0007    COMMON FN,FM,GN,GM,AN,BM,DM,XLS,YLS
0008    DATA PI,TP/3.14159265359,6.28318530718/
0009    DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0010    CJ=(0.,1.)
0011    KO=OMEGA*SQRT(E0*U0)
0012    GAM0S=-KO*KO*(1.,0.)
0013    GC=OMEGA*SQRT(U0*ER2*E0)
0014    GCS=GC*GC
0015    G1=GC/SQRT(2.)
0016  C
0017    SET UP FOR SUM1 & SUM2
0018    IF(I0123.LT.3)DEL=PI/10./(AM+PM)
0019    IF(I0123.EQ.3)DEL=PI/10./(AM+DM+EM)
0020    NS=G1/DEL
0021    IF(NS.LT.20) NS=20
0022    NP=2*(NS/2)
0023    DEL=G1/NP
0024    NP=NP+1
0025    DEL3=DEL/3.
0026    SUM1=(0.,0.)
0027    SUM2=(0.,0.)
0028    DO 100 I=1,2
0029    SIGN=1.
0030    DO 100 J=1,NP
0031    W=(3.-SIGN)*DEL3
0032    IF(J.EQ.1.OR.J.EQ.NP) W=DEL3
0033    IF(I.EQ.2)GO TO 31
0034    G=(J-1)*DEL
0035    GO TO 33
0036 31  B=(J-1)*DEL
    BS=B*B

```

```

0037      G=SQRT(GCS-BS)
0038 33     GS=G*G
0039      F=CSQRT(GAM2S+GS)
0040      F0=CSQRT(GAM0S+GS)
0041      IF(IGROND.EQ.1) RC=(F-F0)/(F+F0)
0042      IF(I0123.EQ.0) FF=FF1(G,F)*CEXP(-F*XLS)
0043      IF(I0123.EQ.1) FF=FF1(G,F)*RC*CEXP(F*(-2.*DM+XLS))
0044      IF(I0123.EQ.2) FF=FF2(G,F)
0045      IF(I0123.EQ.3) FF=FF3(G,F)*RC*CEXP(-2.*F*DM)
0046      IF(SIG2.NE.0.AND.I.EQ.2) FQ=B/F
0047      IF(SIG2.EQ.0.AND.I.EQ.2) FQ=(0.,-1.)
0048      IF(I.EQ.1) SUM1=SUM1+W*FF/F
0049      IF(I.EQ.2) SUM2=SUM2+W*FF*FQ/G
0050 100    SIGN=-SIGN
0051 C     type*, 'np1=', np
0052      ALPHA=10.*AMAX1(K0,CC,CABS(GAM2))
0053 C     SET UP FOR SUM3 & SUM4
0054      DELAL=DEL
0055      NS=ALPH1/DELAL
0056      IF(NS.LT.20) NS=20
0057      NP=2*(NS/2)
0058      DELAL=ALPH1/NP
0059      NPT=NP/4
0060      NP=NP+1
0061      SUM3=(0.,0.)
0062      SIGN=1.
0063      DELA3=DELAL/3.
0064      IABORT=0
0065      DO 200 I=1,NP
0066      W1=3.-SIGN
0067      W=W1*DELA3
0068      IF(I.EQ.1.OR.I.EQ.NP) W=DELA3
0069 34     ALPHA=(I-1)*DELAL
0070      ALPHS=ALPHA*ALPHA
0071      G=SQRT(ALPHS+GCS)
0072      GS=G*G
0073      F=CSQRT(GAM2S+GS)
0074      F0=CSQRT(GAM0S+GS)
0075      IF(IGROND.EQ.1) RC=(F-F0)/(F+F0)
0076      IF(I0123.EQ.0) FF=FF1(G,F)*CEXP(-F*XLS)
0077      IF(I0123.EQ.1) FF=FF1(G,F)*RC*CEXP(F*(-2.*DM+XLS))
0078      IF(I0123.EQ.2) FF=FF2(G,F)
0079      IF(I0123.EQ.3) FF=FF3(G,F)*RC*CEXP(-2.*F*DM)
0080      IF(SIG2.NE.0) FQ=ALPHA/F
0081      IF(SIG2.EQ.0) FQ=(1.,0.)
0082      DSUM=W*FF*FQ/G
0083      SUM3=SUM3+DSUM
0084      IF(IABORT.EQ.1) GO TO 300
0085      IF(CABS(DSUM).LT.(CABS(SUM3)/1000.).AND.I.GT.NPT.AND.
0086 &W1.EQ.4.) THEN
0087      IABORT=1
0088      W=DELA3
0089      GO TO 34
0090      END IF
0091 200    SIGN=-SIGN
0092 C     type*, 'np2=', np
0093 300    SUMT=SUM1+SUM2+SUM3
0094      RETURN
0095      END

```

```
0001 C
```

```

0002      COMPLEX FUNCTION FF1(G,F)
0003      COMPLEX FN,FM,GN,GM,F,CJ,T1,T2,T3,FMPF,GMG,GMPG,S1,S2
0004      COMMON FN,FM,GN,GM,AM,BN,DM,XLS,YLS
0005      CJ=(0.,1.)
0006      C      TYPE*, 'FF1,AM,BN,DM,XLS,YLS=',AM,BN,DM,XLS,YLS
0007      FMPF=FM+CJ*F
0008      GMG=GM-G
0009      GMPG=GM+G
0010      S1=BM
0011      IF (CABS(GMG) .GT. 1.E-6) S1=CSIN(GMG*BM)/GMG
0012      S2=BM
0013      IF (CABS(GMPG) .GT. 1.E-6) S2=CSIN(GMPG*BM)/GMPG
0014      T1=CSIN(FMPF*AM)/FMPF
0015      T2=CEXP(-CJ*G*YLS)*S1
0016      T3=CEXP(CJ*G*YLS)*S2
0017      FF1=T1*(T2+T3)
0018      RETURN
0019      END

0001      C
0002      COMPLEX FUNCTION FF2(G,F)
0003      COMPLEX FN,FM,GN,GM,F,SNK1,SNK2,SNK3,SNK4,SNK5,SNK6,SNK7,SNK8
0004      COMPLEX EX1,EX2,T1,T2,T3,T4,T5,T6,CJ
0005      COMPLEX GMPG,GNMG,GMPG,GMG,FMFN,FNPF,FMMF,FMPF,FNMF
0006      COMMON FN,FM,GN,GM,AM,BN,DM,XLS,YLS
0007      C      TYPE*, 'FF2,AM,BN,DM,XLS,YLS=',AM,BN,DM,XLS,YLS
0008      CJ=(0.,1.)
0009      GMPG=GN+G
0010      GNMG=GN-G
0011      GMPG=GM+G
0012      GMG=GM-G
0013      FMFN=FM+FN
0014      FNPF=FM+CJ*F
0015      FMMF=FM-CJ*F
0016      FMPF=FM+CJ*F
0017      FNMF=FM-CJ*F
0018      SNK1=BM
0019      IF (CABS(GMPG) .GT. 1.E-6) SNK1=CSIN(GMPG*BM)/GMPG
0020      SNK2=BM
0021      IF (CABS(GMG) .GT. 1.E-6) SNK2=CSIN(GMG*BM)/GMG
0022      SNK3=BM
0023      IF (CABS(GNMG) .GT. 1.E-6) SNK3=CSIN(GNMG*BM)/GNMG
0024      SNK4=BM
0025      IF (CABS(GMPG) .GT. 1.E-6) SNK4=CSIN(GMPG*BM)/GMPG
0026      SNK5=AM
0027      IF (CABS(FMFN) .GT. 1.E-6) SNK5=CSIN(FMFN*AM)/FMFN
0028      SNK6=AM
0029      IF (CABS(FMMF) .GT. 1.E-6) SNK6=CSIN(FMMF*AM)/FMMF
0030      SNK7=AM
0031      IF (CABS(FMPF) .GT. 1.E-6) SNK7=CSIN(FMPF*AM)/FMPF
0032      SNK8=SNK5
0033      EX1=AM
0034      IF (CABS(FNPF) .GT. 1.E-6) EX1=CEXP(CJ*FNPF*AM)/FNPF
0035      EX2=-AM
0036      IF (CABS(FNMF) .GT. 1.E-6) EX2=CEXP(-CJ*FNMF*AM)/FNMF
0037      T1=SNK1*SNK2
0038      T2=SNK3*SNK4
0039      T3=-SNK5/FNPF
0040      T4=EX1*SNK6
0041      T5=-EX2*SNK7

```

```

0042          T6=SNK8/FNMF
0043          FF2=-CJ*(T1+T2)*(T3+T4+T5+T6)
.0044          RETURN
0045          END

```

```

0001      C
0002          COMPLEX FUNCTION FF3(G,F)
0003          COMPLEX FN,FM,GN,GH,CJ,F
0004          COMPLEX SNK1,SNK2,SNK3,SNK4,SNK5,SNK6,T1,T2,T3
0005          COMPLEX FNPF,FMPF,GNPG,GMG,GNMG,GMFG
0006          COMMON FN,FM,GN,GH,AM,BM,DM,XLS,YLS
0007      C          TYPE*, 'FF3,AM,BM,DM,XLS,YLS=',AM,BM,DM,XLS,YLS
0008          CJ=(0.,1.)
0009          FNPF=FN+CJ*F
0010          FMPF=FM+CJ*F
0011          GNPG=GN+G
0012          GMG=GM-G
0013          GNMG=GN-G
0014          GMFG=GM+G
0015      C          TYPE*, 'G,F=',G,F
0016      C          TYPE*, 'FNPF,FMPF',FNPF,FMPF
0017          SNK1=AM
0018          IF (CABS(FNPF) .GT.1.E-6) SNK1=CSIN(FNPF*AM)/FNPF
0019          SNK2=AM
0020          IF (CABS(FMPF) .GT.1.E-6) SNK2=CSIN(FMPF*AM)/FMPF
0021          SNK3=BM
0022          IF (CABS(GNPG) .GT.1.E-6) SNK3=CSIN(GNPG*BM)/GNPG
0023          SNK4=BM
0024          IF (CABS(GMG) .GT.1.E-6) SNK4=CSIN(GMG*BM)/GMG
0025          SNK5=BM
0026          IF (CABS(GNMG) .GT.1.E-6) SNK5=CSIN(GNMG*BM)/GNMG
0027          SNK6=BM
0028          IF (CABS(GMFG) .GT.1.E-6) SNK6=CSIN(GMFG*BM)/GMFG
0029          T1=SNK1*SNK2
0030          T2=SNK3*SNK4
0031          T3=SNK5*SNK6
0032          FF3=T1*(T2+T3)
0033          RETURN
0034          END

```

APPENDIX C

The program RTUNLH is based on the formulation given in Chapters IV and VIII. All other descriptions are analogous to RTUNLE.

```

0001 C This is program (KTUNLH.FOR) Rectangular TUNnel using
0002 C Hz-polarization with electric field formulation.
0003 C It uses Plane Wave Expansion Galerkin.
0004 C
0005 C WRITTEN BY JAMAL S. IZADIAN MARCH 1982.
0006 C
0007 COMPLEX A(25),V(25),DV(25),VT(25),Z(25,25)
0008 COMPLEX FA(25),GA(25),B(25),HZ1,HZI,HZS,GR
0009 COMPLEX SUMT,RMN,SMN,FM,GN,GM,S1,S2,FNFM,CNGM
0010 COMPLEX CST2,CST1,CV1,CJ,EP1,EP2,GAM1,GAM2,GAM2S
0011 COMPLEX C1,K1,K2,EXF,EXG,BK,BK1,ETA1,ETA2
0012 DIMENSION PHY(25),XM(500),YM(500)
0013 COMMON /JI/ GAM2S,GAM2,OMEGA,ER2,SIG2,EP2
0014 COMMON /JERK/ CST1,CST2,CSMN
0015 COMMON FN,FM,GN,GM,AM,EM,DM,XLS,YLS,CSN,SNN,CSM,SNM
0016 DATA PI,TP/3.14159265359,6.28318530718/
0017 DATA EO,U0/8.85418533677E-12,1.25663706144E-6/
0018 DATA IWRG,ICC,I12,ISYM/0,25,1,0/
0019 READ(7,*)ER1,SIG1,ER2,SIG2,FMCMX,NEQ,AWM,BWM,DM,XLS,YLS,IWR
0020 &,IFILD,IBS,IBISS,IFMC,IGRND,IZMN
0021 call getcp(itl)
0022 IF((AWM/2.).GT.DM.OR.XLS.GT.DM) GO TO 500
0023 WRITE(10,*)MAX(IBS,IBISS,IFMC)
0024 CJ=(0.,1.)
0025 CX=.0174533
0026 NY=1
0027 201 IF(IFMC.EQ.1)TYPE*, 'GIVE FMC,NEQ,NY='
0028 IF(IFMC.EQ.1)ACCEPT*, FMC,NEQ,NY
0029 IF(FMC.LT.0)GO TO 500
0030 DO 500 JF=1,IFMC
0031 IF(IFMC.GT.1)FMC=JF*FMCMX/FLOAT(IFMC)
0032 NX=(AWM/BWM)*NY
0033 AM=AWM/2.
0034 BM=BWM/2.
0035 OMEGA=TP*FMC*1.E6
0036 EP1=CMPLX(ER1*EO,-SIG1/OMEGA)
0037 EP2=CMPLX(ER2*EO,-SIG2/OMEGA)
0038 ETA1=CSQRT(U0/EP1)
0039 ETA2=CSQRT(U0/EP2)
0040 GAM1=OMEGA*CSQRT(-U0*EP1)
0041 BET1=AIMAG(GAM1)
0042 GAM2=OMEGA*CSQRT(-U0*EP2)
0043 GAM2S=GAM2*GAM2
0044 K1=-CJ*GAM1
0045 K2=-CJ*GAM2
0046 CST1=-OMEGA*OMEGA*U0*(EP1-EP2)/TP
0047 CST2=-(EP1-EP2)/(TP*EP2)
0048 CV1=-1./(ETA1*PI)
0049 C1=CJ*OMEGA*(EP1-EP2)*ETA1/PI
0050 DX=AWM/NX
0051 DY=BWM/NY
0052 DX2=DX/2.
0053 DY2=DY/2.
0054 C CPH=1.-PI/(14.*BET1*AM)
0055 C IF(ABS(CPH).GT.1)GO TO 19
0056 C DPH=ACOS(CPH)
0057 C NEQ=1.+PI/(2.*DPH)
0058 C NEQ=NEQ*2
0059 C19 IF(NEQ.LT.6)NEQ=6
0060 M=0
0061 Y=-EM+DY2
0062 DO 20 J=1,NY
0063 X=-AM+DX2

```

```

0064 DO 22 I=1,NX
0065 M=N+1
0066 XM(M)=X
0067 YN(M)=Y
0068 X=X+DX
0069 Y=Y+DY
0070 KK=N
0071 DPH=TP/NEQ
0072 DO 90 J=1,NEQ
0073 A(J)=(0.,0.)
0074 B(J)=(0.,0.)
0075 PH=(J-1)*DPH
0076 PHZ(J)=PH
0077 FA(J)=KI*COS(PH)
0078 GA(J)=KI*SIN(PH)
0079 IF(IWR.EQ.1)WRITE(10,1)
0080 IF(IZMN.EQ.0)THEN
0081 DO 92 M=1,NEQ
0082 N=M,NEQ
0083 READ(8,2)I,J,Z(M,N)
0084 GO TO 404
0085 END IF
0086 DO 100 M=1,NEQ
0087 PHN=PHY(M)
0088 CSN=COS(PHN)
0089 SNN=SIN(PHN)
0090 FN=FA(M)
0091 GM=GA(M)
0092 DO 200 N=M,NEQ
0093 PHN=PHY(N)
0094 CSN=COS(PHN)
0095 SNN=SIN(PHN)
0096 CSNN=COS(PHN-PHN)
0097 FN=FA(N)
0098 GN=GA(N)
0099 FNFN=FN*FN
0100 GNGN=GN*GN
0101 S1=AN
0102 S2=BM
0103 IF(CABS(FNFN).GT.1.E-6)S1=CSIN(FNFN*AN)/FNFN
0104 IF(CABS(GNGN).GT.1.E-6)S2=CSIN(GNGN*BN)/GNGN
0105 RAN=4.*S1*S2*CSNN
0106 CALL SPECIRN(SNN,2,IGROND)
0107 Z(M,N)=RAN+SNN
0108 IF(IWR.EQ.1)WRITE(10,2)M,N,Z(M,N)
0109 IF(IZMN.EQ.1)WRITE(8,2)M,N,Z(M,N)
0110 CONTINUE
0111 CONTINUE
0112 CONTINUE
0113 IF(IWR.EQ.1)WRITE(10,3)
0114 IF(IWR.EQ.1)WRITE(10,4)
0115 DO 500 JI=1,IBS
0116 IF(ABS(GT.1)YLS=((IBS-1)/2+1-JI)*.0625
0117 YLSS=YLS
0118 SET UP THE VOLTAGE COLUMN
0119 DO 120 M=1,NEQ
0120 PH=PHY(M)
0121 CSN=COS(PH)
0122 SNN=SIN(PH)
0123 FN=FA(M)
0124 GM=GA(M)
0125 CALL SPECIRN(SUM1,1,IGROND)
0126 A(M)=SUMT

```

200

100

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C

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0127          V(M)=CV1*SUMT
0128      120  IF (IWR.EQ.1)WRITE(10,5)M,V(M),DV(M),VT(M)
0129          IF (IWR.EQ.1)WRITE(10,3)
0130          CALL CROOT(Z,V,ICC,ISYM,IWRC,I12,NEQ)
0131          IF (IWR.EQ.1) THEN
0132              WRITE(10,3)
0133              WRITE(10,10)
0134              DO 108 M=1,NEQ
0135      108  WRITE(10,5)M,V(M)
0136              WRITE(10,3)
0137              END IF
0138          IF (IFILD.EQ.0) GO TO 45
0139      C      FIND FIELD INSIDE THE TUNNEL
0140          WRITE(10,3)
0141          WRITE(10,6)
0142          DO 300 L=1,KK
0143              HZ1=(0.,0.)
0144              X=XM(L)
0145              Y=YM(L)
0146              IF (X.LT.0.OR.Y.LT.0) GO TO 300
0147              DO 400 N=1,NEQ
0148                  FN=FA(N)
0149                  GN=GA(N)
0150                  EXF=CEXP(-CJ*FN*X)
0151                  EXG=CEXP(-CJ*GN*Y)
0152      400  HZ1=HZ1+EXF*EXG*V(N)
0153                  RE=REAL(HZ1)
0154                  AIE=AIMAG(HZ1)
0155                  PHASE=ATAN2(AIE,RE)/CX
0156                  AMP=CABS(HZ1)
0157                  WRITE(10,7)X,Y,AMP,PHASE
0158      300  CONTINUE
0159                  WRITE(10,3)
0160      C      FIND SCATTERED FIELD
0161      45  DO 500 JK=1,IBISS
0162          IF (IBISS.GT.1) YLS=((IBISS-1)/2+1-JK)*.0625
0163          HZS=(0.,0.)
0164          DO 600 M=1,NEQ
0165              IF (IBISS.GT.1) THEN
0166                  PH=PHY(M)
0167                  CSN=COS(PH)
0168                  SNM=SIN(PH)
0169                  FM=FA(M)
0170                  GM=GA(M)
0171                  CALL SPCIRH(SUMT,1,IGRND)
0172                  A(M)=SUMT
0173              END IF
0174      600  HZS=HZS+V(M)*A(M)
0175              HZS=C1*HZS
0176              AZS=CABS(HZS)
0177              RLSS=SQRT(XLS*YLS+YLS*YLS)
0178              RLSS=SQRT(XLS*XLS+YLS*YLS)
0179              GR=(RLSS+RLSS)*CAM2
0180              IF (CABS(GR).GT.80.) THEN
0181                  BK=CSQRT(.5*PI/GR)*CEXP(-GR)
0182                  GO TO 47
0183              END IF
0184              CALL BK0Z(GR,BK,-1)
0185      47  HZI=BK*(-GAM2/ETA2/TP)
0186              AZI=CABS(HZI)
0187              AZN=AZS/AZI
0188              IF (IWR.EQ.1)WRITE(10,*)'AZS=',AZS
0189              IF (IWR.EQ.1)WRITE(10,*)'AZI=',AZI

```

```

0190          DB=20.*ALOG10(AZN)
0191          IF(ABS.GT.1) I12=2
0192          TYPE8,NEQ,NX,NY,FMC,DB, YLS
0193          WRITE(10,8) NEQ,NX,NY,FMC,DB, YLS
0194          IF(IFMC.EQ.1.AND.IBS.EQ.1.AND.IBISS.EQ.1) GO TO 201
0195          500 CONTINUE
0196          WRITE(10,9)
0197          1  FORMAT(5X,'M',4X,'N',13X,'ZMN',24X,'DZMN',26X,'ZTMN'25X)
0198          2  FORMAT(1X,2I5,8(2X,G12.6))
0199          3  FORMAT(1H0)
0200          4  FORMAT(5X,'M',13X,' VM ',25X,'DVM',23X,'VIM',21X)
0201          5  FORMAT(1X,I5,6(2X,G12.6))
0202          6  FORMAT(9X,'X',9X,'Y',13X,'AMPLITUDE',3X,'PHASE')
0203          7  FORMAT(1X,2(2X,G10.5),5X,2(2X,G12.6))
0204          8  FORMAT(1X,3I5,6F12.6)
0205          9  FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF')
0206          10 FORMAT(5X,'M',18X,' A ')
0207          call getcp(it2)
0208          time=(it2-it1)/100.
0209          WRITE(10,*) 'ER1 & SIG1=' ,ER1,SIG1
0210          WRITE(10,*) 'ER2 & SIG2=' ,ER2,SIG2
0211          WRITE(10,*) 'AWM,BWM,DM,XLS, YLS=' ,AWM,BWM,DM,XLS, YLS
0212          write(10,*) ' cpu time=' ,time,'sec'
0213          WRITE(10,*) 'RTUNLH.FOR'
0214          write(10,*) ER1,SIG1,ER2,SIG2,FMC,NEQ,AWM,BWM,DM,XLS, YLS,IWR
0215          &,IFILD,IBS,IBISS
0216          STOP
0217          END

```

FUNCTIONS AND SUBROUTINES REFERENCED

```

0001  C
0002          SUBROUTINE SPCTRM(SUMT,I12,IGROND)
0003          COMPLEX GAM2S,GAM2,GAMOS,FQ,RC,F,F0,FF,SUM1,SUM2,SUM3,SUMT
0004          COMPLEX FN,FM,GN,GH,CJ,FF1,FF2,FF3,EP2,DSUM
0005          REAL KO
0006          COMMON /JI/GAM2S,GAM2,OMEGA,ER2,SIG2,EP2
0007          COMMON FN,FM,GN,GH,AM,EM,DM,XLS, YLS,CSN,SNN,CSM,SNM
0008          DATA PI,TP/3.14159265359,6.28318530718/
0009          DATA EO,UO/8.85418533677E-12,1.25663706144E-6/
0010          CJ=(0.,1.)
0011          KO=OMEGA*SQRT(EO*UO)
0012          GAMOS=-KO*KO*(1.,0.)
0013          GC=OMEGA*SQRT(UO*ER2*EO)
0014          GCS=GC*CC
0015          G1=GC/SQRT(2.)
0016  C          SET UP FOR SUM1 & SUM2
0017  C          IF(I12.LT.3) DEL=PI/10./ (AM+EM)
0018          DEL=PI/10./ (AM+EM+EN)
0019          NS=G1/DEL
0020          IF(NS.LT.30) NS=30
0021          NP=2*(NS/2)
0022          DEL=G1/NP
0023          NP=NP+1
0024          DEL3=DEL/3.
0025          SUM1=(0.,0.)
0026          SUM2=(0.,0.)
0027          DO 100 I=1,2
0028             SIGN=1.
0029             DO 100 J=1,NP
0030                W=(3.-SIGN)*DEL3

```

```

0031      IF (J.EQ.1.OR.J.EQ.NP) W=DEL3
0032      IF (I.EQ.2) GO TO 31
0033      G=(J-1)*DEL
0034      GO TO 33
0035  31    B=(J-1)*DEL
0036      BS=B*B
0037      G=SQRT(GCS-BS)
0038  33    GS=G*G
0039      F=CSQRT(GAM2S+GS)
0040      F0=CSQRT(GAM0S+GS)
0041      RC=(E0*F-EP2*F0)/(E0*F+EP2*F0)
0042      IF (I12.EQ.1) FF=FF1(G,F)*(CEXP(-F*XLS)+IGROND*RC
0043      &*CEXP(F*(-2.*DM+XLS)))
0044      IF (I12.EQ.2.AND.IGROND.EQ.1) FF=FF3(G,F)*RC*CEXP(-2.*F*DM)
0045      IF (I12.EQ.2) FF=FF2(G,F)+IGROND*FF
0046      IF (SIG2.NE.0.AND.I.EQ.2) FQ=E/F
0047      IF (SIG2.EQ.0.AND.I.EQ.2) FQ=(0.,-1.)
0048      IF (I.EQ.1) SUM1=SUM1+W*FF/F
0049      IF (I.EQ.2) SUM2=SUM2+W*FF*FQ/G
0050  100   SIGN=-SIGN
0051  C     type*, 'np1=', np
0052      ALPH1=10.*AMAX1(K0,GC,CABS(GAM2))
0053  C     SET UP FOR SUM3 & SUM4
0054      DELAL=DEL
0055      NS=ALPH1/DELAL
0056      IF (NS.LT.30) NS=30
0057      NP=2*(NS/2)
0058      DELAL=ALPH1/NP
0059      NP=NP+1
0060      SUM3=(0.,0.)
0061      SIGN=1.
0062      DELA3=DELAL/3.
0063      DO 200 I=1,NP
0064      W=(3.-SIGN)*DELA3
0065      IF (I.EQ.1.OR.I.EQ.NP) W=DELA3
0066      ALPHA=(I-1)*DELAL
0067      ALPHS=ALPHA*ALPHA
0068      G=SQRT(ALPHS+GCS)
0069      GS=G*G
0070      F=CSQRT(GAM2S+GS)
0071      F0=CSQRT(GAM0S+GS)
0072      RC=(E0*F-EP2*F0)/(E0*F+EP2*F0)
0073      IF (I12.EQ.1) FF=FF1(G,F)*(CEXP(-F*XLS)+IGROND*RC
0074      &*CEXP(F*(-2.*DM+XLS)))
0075      IF (I12.EQ.2.AND.IGROND.EQ.1) FF=FF3(G,F)*RC*CEXP(-2.*F*DM)
0076      IF (I12.EQ.2) FF=FF2(G,F)+IGROND*FF
0077      IF (SIG2.NE.0) FQ=ALPHA/F
0078      IF (SIG2.EQ.0) FQ=(1.,0.)
0079      DSUM=W*FF*FQ/G
0080      SUM3=SUM3+DSUM
0081  C     IF (CABS(DSUM) .LT. (CABS(SUM3)/1000.)) GO TO 300
0082  200   SIGN=-SIGN
0083  C     type*, 'np2=', np
0084  300   SUMT=SUM1+SUM2+SUM3
0085      RETURN
0086      END

0001  C
0002      COMPLEX FUNCTION FF1(G,F)
0003      COMPLEX FN,FM,GN,GH,GA,F,CJ,T1,T2,T3,FMPF,GMMG,GMPG,S1,S2

```

```

0004 COMPLEX CSY,SNY
0005 COMMON FN,FM,GN,GM,AM,EM,DM,XLS,YLS,CSN,SNN,CSM,SNM
0006 CJ=(0.,1.)
0007 FMFF=FM+CJ*F
0008 GMG=GM-G
0009 GMFG=GM+G
0010 S1=EM
0011 IF (CABS(GMG) .GT. 1.E-6) S1=CSIN(GMG*EM)/GMG
0012 S2=EM
0013 IF (CABS(GMFG) .GT. 1.E-6) S2=CSIN(GMFG*EM)/GMFG
0014 T1=CSIN(FMFF*AM)/FMFF
0015 T2=CEXP(-CJ*G*YLS)*S1
0016 T3=CEXP(CJ*G*YLS)*S2
0017 CSY=T2+T3
0018 SNY=-CJ*(T2-T3)
0019 FF1=T1*(SNM*G*SNY-CSM*F*CSY)
0020 RETURN
0021 END

```

```

0001 C
0002 COMPLEX FUNCTION FF2(G,F)
0003 COMPLEX FN,FM,GN,GM,F,SNK1,SNK2,SNK3,SNK4,SNK5,SNK6,SNK7,SNK8
0004 COMPLEX EX1,EX2,T1,T2,T3,T4,T5,T6,CJ,FXE,FXO,SNY,CSY,PEX,EXM
0005 COMPLEX EXBM,EXBP,SYBM,SYBP,CBPM,CSBP,S1,S2,S3,S4,S5,S6,S7,S8
0006 COMPLEX EXBMN,EXBPN,CST1,CST2,F1,F2
0007 COMPLEX GMPG,GNMG,GMFG,GMG,FMFN,FNPF,FMMF,FMPF,FNMF
0008 COMMON FN,FM,GN,GM,AM,EM,DM,XLS,YLS,CSN,SNN,CSM,SNM
0009 COMMON /JERK/ CST1,CST2,CSMN
0010 CJ=(0.,1.)
0011 GMPG=GN+G
0012 GNMG=GN-G
0013 GMFG=GM+G
0014 GMG=GM-G
0015 FMFN=FM+FN
0016 FNPF=FM+CJ*F
0017 FMMF=FM-CJ*F
0018 FMPF=FM+CJ*F
0019 FNMF=FM-CJ*F
0020 SNK1=EM
0021 IF (CABS(GMPG) .GT. 1.E-6) SNK1=CSIN(GMPG*EM)/GMPG
0022 SNK2=EM
0023 IF (CABS(GMG) .GT. 1.E-6) SNK2=CSIN(GMG*EM)/GMG
0024 SNK3=EM
0025 IF (CABS(GNMG) .GT. 1.E-6) SNK3=CSIN(GNMG*EM)/GNMG
0026 SNK4=EM
0027 IF (CABS(GMFG) .GT. 1.E-6) SNK4=CSIN(GMFG*EM)/GMFG
0028 SNK5=AM
0029 IF (CABS(FMFN) .GT. 1.E-6) SNK5=CSIN(FMFN*AM)/FMFN
0030 SNK6=AM
0031 IF (CABS(FMMF) .GT. 1.E-6) SNK6=CSIN(FMMF*AM)/FMMF
0032 SNK7=AM
0033 IF (CABS(FMPF) .GT. 1.E-6) SNK7=CSIN(FMPF*AM)/FMPF
0034 SNK8=SNK5
0035 EX1=CEXP(CJ*FNPF*AM)/FNPF
0036 EX2=CEXP(-CJ*FNMF*AM)/FNMF
0037 T1=SNK1*SNK2
0038 T2=SNK3*SNK4
0039 T3=SNK5/FNPF
0040 T4=EX1*SNK6
0041 T5=EX2*SNK7

```

```

0042      T6=SNK8/FNMF
0043      FXE=CJ*(T3-T4+T5-T6)
0044      FXO=CJ*(T3-T4-T5+T6)
0045      CSY=T1+T2
0046      SNY=-CJ*(T1-T2)
0047      F1=FXE*CSY*CST1*CSMN*4.
0048      EXBMN=CEXP(-CJ*GN*BM)
0049      EXBPN=CEXP(CJ*GN*BM)
0050      EXEM=CEXP(-CJ*G*BM)
0051      EXBP=CEXP(CJ*G*BM)
0052      SYBM=-CJ*(EXEM*SNK2-EXBP*SNK4)
0053      SYBP=-CJ*(EXBP*SNK2-EXEM*SNK4)
0054      CSEM=EXBM*SNK2+EXBP*SNK4
0055      CSBP=EXBP*SNK2+EXEM*SNK4
0056      EXM=CEXP(-CJ*FNMF*AM)
0057      PEX=CEXP(CJ*FNMF*AM)
0058      S1=4.*EXM*SNK7*SNY
0059      S2=-4.*EXM*SNK7*CSY
0060      S3=2.*EXBMN*FXE*SYBM
0061      S4=2.*EXBMN*FXO*CSEM
0062      S5=4.*PEX*SNK6*SNY
0063      S6=4.*PEX*SNK6*CSY
0064      S7=2.*EXBPN*FXE*SYBP
0065      S8=2.*EXBPN*FXO*CSBP
0066      C  WRITE(8,*)'F,G,SNY=',F,G,SNY
0067      C  WRITE(8,*)'CSN,SNN,CSM,SNM=',CSN,SNN,CSM,SNM
0068      C  WRITE(8,*)'S1,S5=',S1,S5
0069      C  WRITE(8,*)'S2,S6=',S2,S6
0070      C  WRITE(8,*)'S3,S7=',S3,S7
0071      C  WRITE(8,*)'S4,S8=',S4,S8
0072      F2=-SNN*CSM*C*(S1-S5)+SNN*SNM*F*(S2-S6)+CSN*CSM*G*(S3-S7)
0073      &-CSN*SNM*F*(S4-S8)
0074      F2=F2*CST2
0075      FF2=F1+F2
0076      C  WRITE(8,*)'FF2=',FF2
0077      RETURN
0078      END

```

```

0001      C
0002      COMPLEX FUNCTION FF3(G,F)
0003      COMPLEX FN,FM,GN,GM,CJ,F,CST1,CST2
0004      COMPLEX SNK1,SNK2,SNK3,SNK4,SNK5,SNK6,T1,T2,T3
0005      COMPLEX FNPF,FMPF,GNPG,GMG,GNMG,GMFG,SNY,CSY
0006      COMMON FN,FM,GN,GM,AM,EM,DM,XLS,YLS,CSN,SNN,CSM,SNM
0007      COMMON /JERK/ CST1,CST2,CSMN
0008      CJ=(0.,1.)
0009      FNPF=FN+CJ*F
0010      FMPF=FM+CJ*F
0011      GNPG=GN+G
0012      GMG=GM-G
0013      GNMG=GN-G
0014      GMFG=GM+G
0015      SNK1=AM
0016      IF(CABS(FNPF).GT.1.E-6) SNK1=CSIN(FNPF*AM)/FNPF
0017      SNK2=AM
0018      IF(CABS(FMPF).GT.1.E-6) SNK2=CSIN(FMPF*AM)/FMPF
0019      SNK3=EM
0020      IF(CABS(GNPG).GT.1.E-6) SNK3=CSIN(GNPG*BM)/GNPG
0021      SNK4=EM

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0022      IF (CABS(GMVG) .GT. 1.E-6) SNK4=CSIN(GMVG*EM)/GMVG
0023      SNK5=EM
0024      IF (CABS(GMVG) .GT. 1.E-6) SNK5=CSIN(GMVG*EM)/GMVG
0025      SNK6=EM
0026      IF (CABS(GMVG) .GT. 1.E-6) SNK6=CSIN(GMVG*EM)/GMVG
0027      T1=SNK1*SNK2
0028      T2=SNK3*SNK4
0029      T3=SNK5*SNK6
0030      CSY=T2+T3
0031      SNY=-CJ*(T2-T3)
0032      FF3=(SNN*SNN*G*G+CSN*CSM*F*F)*CSY
0033      FF3=FF3+(SNN*CSM-CSN*SNN)*F*G*SNY
0034      FF3=T1*FF3*CST2*8.
0035      RETURN
0036      END

```

APPENDIX D

Program RCYLHGP is the same as RTUNLH, except it does not include the air-earth interface, and it can model plane wave incidence.

```

0001 C LINK WITH CROUT & MBEZ10
0002 C
0003 C THIS PROGRAM (RCYLHGP.FOR) USES TRAVELING PLANE WAVE EXPANSION AND
0004 C GALERKIN METHOD TO CALCULATE THE SCATTERING ATTENUATION
0005 C FUNCTION OF A LOSSY DIELECTRIC INFINITE RECTANGULAR CYLINDER,
0006 C FOR A MAGNETIC LINE SOURCE PARALLEL TO AXIS OF THE CYLINDER.
0007 C THE CYLINDER IS LOCATED IN A LOSSY HOMOGENEOUS MEDIUM.
0008 C
0009 C WRITTEN BY JAMAL IZADIAN MARCH. 1982.
0010 C
0011 C COMPLEX C(25),A(25),FA(25),GA(25),FNEE(25),Z(25,25),V(25)
0012 C COMPLEX FNEE(25),FNXP,GNYP,EGXP,EGYP,sumc,sums
0013 C COMPLEX GC,VEE,EGYL,EGXL,EGX1,FNXL,GNYL,SEE,HZ1,HZS
0014 C COMPLEX SUMT,RNN,SNM,FM,GN,GM,S1,S2,FNFM,GNGM,HZI
0015 C COMPLEX CST2,CST1,CV1,CJ,EP1,EP2,GAM1,GAM2,GAM2S,GR
0016 C COMPLEX C1,C1,K1,K2,B1,B11,BK,BK1,ETA1,ETA2,DET
0017 C DIMENSION PHY(25),XM(1000),YM(1000),LL(25),MM(25)
0018 C INTEGER P
0019 C COMMON /JI/ GAM2S,GAM2,OMEGA,ER2,SIG2,EP2
0020 C COMMON /JERK/ CST1,CST2,CSMN
0021 C COMMON FN,FM,GN,GM,AM,EM,DM,XLS,YLS,CSN,SNM,CSM,SNM
0022 C DATA PI,TP/3.14159265359,6.28316530718/
0023 C DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0024 C DATA IWRC,ICC,I12,ISYM/0,25,1,0/
0025 C call getcp(itl)
0026 C CJ=(0.,1.)
0027 C READ(7,*)ER1,SIG1,ER2,SIG2,FNMX,AWM,BWM,DM,XLS,YLS,IWR,IFILD,IWRC
0028 C &,IPW,IBS,IBISS,IFMC,IEQ,IGRND,IZMN
0029 C PHI=ATAN2(YLS,XLS)/.0174533
0030 C RLS=SQRT(XLS*XLS+YLS*YLS)
0031 C WPH=PHI
0032 C WRITE(10,*)MAX(ABS,IBISS,IFMC)
0033 C CX=.0174533
0034 201 IF (IEQ.EQ.0) TYPE*, 'GIVE NEQ & NY='
0035 C IF (IEQ.EQ.0) ACCEPT*,NEQ,NY
0036 C IF (IFMC.EQ.1) TYPE*, 'GIVE FMC='
0037 C IF (IFMC.EQ.1) ACCEPT*,FMC
0038 C IF (FMC.LT.0) GO TO 500
0039 C DO 500 JF=1,IFMC
0040 C IF (IFMC.GT.1) FMC=JF*FNMX/FLOAT(IFMC)
0041 C AM=AWM/2.
0042 C EM=EM/2.
0043 C OMEGA=TP*FMC*1.E6
0044 C EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0045 C EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0046 C ETA1=CSQRT(U0/EP1)
0047 C ETA2=CSQRT(U0/EP2)
0048 C GAM1=OMEGA*CSQRT(-U0*EP1)
0049 C BET1=AIMAG(GAM1)
0050 C GAM2=OMEGA*CSQRT(-U0*EP2)
0051 C GAM2S=GAM2*GAM2
0052 C WAV2=300./(SQRT(ER2)*FMC)
0053 C WAV1=300./(SQRT(ER1)*FMC)
0054 C K1=-CJ*GAM1
0055 C K2=-CJ*GAM2
0056 C CST1=-OMEGA*OMEGA*U0*(EP1-EP2)/TP
0057 C CST2=-OMEGA*(EP1-EP2)/(TP*EP2)
0058 C CV1=-GAM2/(ETA1*TP)
0059 C C1=CJ*OMEGA*(EP1-EP2)*GAM2*ETA1/TP
0060 C C1=-CJ*OMEGA*EP2/TP
0061 C TYPE*, 'AOL=', (AWM/WAV1)
0062 C IF (IEQ.EQ.1) THEN
0063 C NY=15.*BET1*AM/PI

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0064      IF (NY.LT.8.AND.IEQ.EQ.1) NY=8
0065      CPH=1.-PI/(14.*BET1*AM)
0066      TYPE*, 'CPH=',CPH
0067      IF (ABS(CPH).GT.1) GO TO 19
0068      DPH=ACOS(CPH)
0069      NEQ=1.+PI/(2.*DPH)
0070      19  IF (NEQ.LT.6) NEQ=6
0071          NEQ=NEQ*2+2
0072          END IF
0073          NY=2*(NY/2)
0074          NY=NY
0075          NX=INT(AM/EM)*NY
0076          NX=(NX/2)*2
0077          DX=AM/NX
0078          DY=EM/NY
0079          DX2=DX/2.
0080          DY2=DY/2.
0081          DXY=DX*DY
0082          M=0
0083          Y=-EM+DY2
0084          DO 20 J=1,NY
0085              X=-AM+DX2
0086              DO 22 I=1,NX
0087                  M=M+1
0088                  XM(M)=X
0089                  YM(M)=Y
0090      22  X=X+DX
0091      20  Y=Y+DY
0092          KK=M
0093          IF (KK.GT.1000) GO TO 500
0094          DPH=TP/NEQ
0095          DO 90 J=1,NEQ
0096              PH=(J-1)*DPH
0097              PHY(J)=PH
0098              FA(J)=K1*COS(PH)
0099      90  GA(J)=K1*SIN(PH)
0100          IF (IZMN.EQ.0) THEN
0101              DO 92 M=1,NEQ
0102              DO 92 N=M,NEQ
0103      92  READ(8,2) I,J,Z(I,J)
0104              GO TO 404
0105              END IF
0106          IF (IWR.EQ.1) WRITE(10,1)
0107          DO 100 M=1,NEQ
0108              PHM=PHY(M)
0109              CSM=COS(PHM)
0110              SNM=SIN(PHM)
0111              FM=FA(M)
0112              GM=GA(M)
0113              DO 200 N=M,NEQ
0114              PHN=PHY(N)
0115              CSN=COS(PHN)
0116              SNN=SIN(PHN)
0117              CSNM=COS(PHM-PHN)
0118              FN=FA(N)
0119              GN=GA(N)
0120              FNFM=FN+FM
0121              GNGM=GN+GM
0122              S1=AM
0123              S2=EM
0124              IF (CABS(FNFM).GT.1.E-6) S1=CSIN(FNFM*AM)/FNFM
0125              IF (CABS(GNGM).GT.1.E-6) S2=CSIN(GNGM*EM)/GNGM
0126              RM=4.*S1*S2*CSNM

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```

0127 CALL SPCIRN(SNN,2)
0128 Z(M,N)=RWN+SMN
0129 IF (IWR.EQ.1) WRITE(10,2)M,N,Z(M,N)
0130 WRITE(8,2)M,N,Z(M,N)
0131 CONTINUE
0132 CONTINUE
0133 IF (IWR.EQ.1) WRITE(10,3)
0134 IF (IWR.EQ.1) WRITE(10,4)
0135 DO 500 JI=1,IBS
0136 SET UP THE VOLTAGE COLUMN
0137 RLS=SQRT(XLS*XLS+YLS*YLS)
0138 IF (IBS.GT.1) PHI=(JI-1)*360./FLOAT(IBS-1)
0139 PHI=CX*PHI
0140 CSL=COS(PHI)
0141 SNI=SIN(PHI)
0142 XLS1=RLS*CSL
0143 YLS1=RLS*SNI
0144 DO 240 N=1,NEQ
0145 FM=FA(M)
0146 GM=GA(M)
0147 PHM=PHY(M)
0148 SEE=(0.,0.)
0149 DO 220 P=1,KK
0150 X=XM(P)
0151 Y=YM(P)
0152 FMXP=CJ*FM*X
0153 GMXP=CJ*GM*Y
0154 EGXP=CEXP(FMXP)
0155 EGYP=CEXP(GMXP)
0156 FMEF(M)=EGXP*EGYP
0157 IF (IPW.EQ.1) THEN
0158 PSI1=X*CS1+Y*SNI
0159 EGX1=CEXP(GM2*PSI1)
0160 CV1=-ETAZ/ETAL
0161 PH=PHI
0162 GO TO 219
0163 END IF
0164 X1=X-XLS1
0165 Y1=Y-YLS1
0166 PH=ATAN2(Y1,X1)
0167 PHI=SQRT(X1*X1+Y1*Y1)
0168 CALL NBEZ10(GM2*RH1,BL,BK,BL1,EGX1,1,-1)
0169 SEE=SEE+FMEF(M)*EGX1*COS(PHI-PH)
0170 CONTINUE
0171 A(M)=SEE
0172 V(M)=A(M)*CV1*DX
0173 CONTINUE
0174 IF (IWR.EQ.1) THEN
0175 DO 202 N=1,NEQ
0176 WRITE(10,5)E,V(M)
0177 WRITE(10,3)
0178 END IF
0179 CALL CROUT(Z,V,ICC,ISM,IWRC,I12,NEQ)
0180 CALL CMINV(A,V,Z,ICC,IWRC,I12,LL,WM,NEQ,DET)
0181 DO 242 N=1,NEQ
0182 V(M)=A(M)
0183 IF (IWR.EQ.1) THEN
0184 WRITE(10,6)
0185 DO 244 N=1,NEQ
0186 WRITE(10,5)M,V(M)
0187 CONTINUE
0188 WRITE(10,3)
0189 END IF

```

200

100

404

C

219

220

240

202

C

C

C242

244

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C
0190 FIND THE FIELD IN CELLS OF FIRST QUADRANT
0191 IF (IFILD.NE.1) GO TO 45
0192 WRITE(10,8)
0193 DO 248 I=1, KK
0194 HZ1=(0.,0.)
0195 XL=XM(L)
0196 YL=YM(L)
0197 DO 246 N=1, NEQ
0198 FN=FA(N)
0199 GN=GA(N)
0200 FNXL=CJ*FN*XL
0201 GNXL=CJ*GN*YL
0202 EGXL=CEXP(FNXL)
0203 EGYL=CEXP(GNXL)
0204 FNEE(N)=EGXL*EGYL
0205 HZ1=HZ1+V(N)*FNEE(N)
0206 CONTINUE
0207 IF (XL.GT.0.AND.YL.GT.0) THEN
0208 RE=REAL(HZ1)
0209 AIE=ALVAG(HZ1)
0210 ANP=CABS(HZ1)
0211 PHASE=ATAN2(AIE,RE)/CX
0212 WRITE(10,11)XL,YL,ANP,PHASE
0213 END IF
0214 CONTINUE
0215 IF (IWR.EQ.1) WRITE(10,3)
0216 PHS=PHI
0217 DO 500 JK=1,IBISS
0218 IF (IBISS.GT.1) THEN
0219 PHI=(JK-1)*360./FLOMT(IBISS-1)
0220 PHS=CX*PHI
0221 END IF
0222 XLS=RLS*COS(PHS)
0223 YLS=RLS*SIN(PHS)
C
0224 FIND THE BACKSCATTERED FIELD
0225 HZS=(0.,0)
0226 DO 292 N=1,NEQ
0227 IF (IBISS.GT.1) THEN
0228 FN=FA(N)
0229 GN=GA(N)
0230 PHN=PHI(N)
0231 A(N)=(0.,0.)
0232 DO 290 I=1, KK
0233 XL=XM(L)
0234 YL=YM(L)
0235 IF (IPW.EQ.1) THEN
0236 PSI=XL*COS(PHS)+YL*SIN(PHS)
0237 BK1=CEXP(GNIZ*PSI)
0238 PH=PHS
0239 GO TO 47
0240 END IF
0241 YY=VLS-YL
0242 YS=YY*YY
0243 XX=XLS-XL
0244 XS=XX*XX
0245 PH=ATAN2(YY,XX)
0246 ROH=SQRT(XS+YS)
0247 FNXL=CJ*FN*XL
0248 GNXL=CJ*GN*YL
0249 EGXL=CEXP(FNXL)
0250 EGYL=CEXP(GNXL)
0251 FNEE(N)=EGXL*EGYL
0252
0247
47

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```

0253 290 A(N)=A(N)+BK1*FNEE(N)*CGS(PHN-PH)
0254      END IF
0255 292 HZS=HZS+V(N)*A(N)
0256      HZS=C1*HZS*DXY
0257      IF(IPW.EQ.1)HZS=HZS*CSQRT(.5*PI/GAM2)
0258      AZS=CABS(HZS)
0259      IF(IWR.EQ.1)WRITE(10,*)'AZS=',AZS
0260      EWL=TP*AZS*AZS/WAV2
0261      DB=.0
0262 C      FIND THE NORMALIZED SCATTERING ATTENUATION FUNCTION
0263      IF(IPW.EQ.0)THEN
0264          GR=2.*GAM2*RLS
0265          IF(CABS(GR).GT.80) THEN
0266              BK=CSQRT(.5*PI/GR)*CEXP(-GR)
0267              GO TO 555
0268          END IF
0269          CALL MBEZ10(GR,BI,BK,BI1,BK1,0,-1)
0270 555    HZI=CI*BK
0271          TYPE*,'HZI=',HZI
0272          AZI=CABS(HZI)
0273          IF(IWR.EQ.1)WRITE(10,*)'AZI=',AZI
0274          AZN=AZS/AZI
0275          IF(AZN.NE.0.)DB=20.*ALOG10(AZN)
0276          TYPE9,NEQ,NX,NY,FMC,DB,PHI
0277          WRITE(10,9)NEQ,NX,NY,FMC,DB,PHI
0278          GO TO 599
0279          END IF
0280          TYPE9,NEQ,NX,NY,FMC,EWL,PHI
0281          WRITE(10,9)NEQ,NX,NY,FMC,EWL,PHI
0282 599    IF(IFS.EQ.1.AND.IBISS.EQ.1.AND.IFMC.EQ.1)GO TO 201
0283          IF(IFS.GT.1)I12=2
0284 500    CONTINUE
0285 600    CONTINUE
0286          IF(IPW.EQ.1)WRITE(10,14)
0287          IF(IPW.EQ.0)WRITE(10,13)
0288          WRITE(10,3)
0289          WRITE(10,*)'ER1 & SIG1 =' ,ER1,SIG1
0290          WRITE(10,*)'ER2 & SIG2 =' ,ER2,SIG2
0291          WRITE(10,*)'AWM & BWM =' ,AWM,BWM
0292          WRITE(10,*)'RLS=' ,RLS,'PHI=' ,WPH
0293          call getcp(it2)
0294          time=(it2-it1)/100.
0295          WRITE(10,*)'CPU TIME (SEC) =' ,TIME
0296          TYPE*,'CPU TIME (SEC) =' ,TIME
0297          WRITE(10,*)'RCYLHGP.FOR'
0298 1      FORMAT(5X,'M',4X,'N',13X,'ZMN',24X,'DZMN',26X,'ZTMN'25X)
0299 2      FORMAT(1X,2I5,8(2X,G12.6))
0300 3      FORMAT(1H0)
0301 4      FORMAT(5X,'M',13X,'VM ',25X,'DVM',23X,'VM',21X)
0302 5      FORMAT(1X,I5,6(2X,G12.6))
0303 6      FORMAT(5X,'M',18X,'A ')
0304 8      FORMAT(5X,'X'.9X,'Y',13X,'AMPLITUDE',3X,'PHASE')
0305 9      FORMAT(1X,3I5,6F12.6)
0306 11     FORMAT(1X,2(2X,G10.5),5X,2(2X,G12.6))
0307 13     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF',9X,'PHI')
0308 14     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'EWL',9X,'PHI')
0309      CALL EXIT
0310      STOP
0311      END

0001 C

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```

0002      SUBROUTINE SPCTRM(SUMT,I0123)
0003      COMPLEX GAM2S,GAM2,GAM0S,FQ,RC,F,F0,FF,SUM1,SUM2,SUM3,SUMT
0004      COMPLEX FN,FM,GN,GM,CJ,FF1,FF2,FF3,EP2,DSUM
0005      REAL KO
0006      COMMON /JI/GAM2S,GAM2,OMEGA,ER2,SIG2,EP2
0007      COMMON FN,FM,GN,GM,AM,BM,DM,XLS,YLS,CSN,SNN,CSM,SNM
0008      DATA PI,TP/3.14159265359,6.28318530718/
0009      DATA EQ,U0/8.85418533677E-12,1.25663706144E-6/
0010      CJ=(0.,1.)
0011      KO=OMEGA*SQRT(E0*U0)
0012      GAM0S=-KO*KO*(1.,0.)
0013      GC=OMEGA*SQRT(U0*ER2*E0)
0014      GCS=CC*GC
0015      G1=GC/SQRT(2.)
0016      C      SET UP FOR SUM1 & SUM2
0017      IF(I0123.LT.3)DEL=PI/10./(AM+EM)
0018      IF(I0123.EQ.3)DEL=PI/10./(AM+EM+EM)
0019      NS=G1/DEL
0020      IF(NS.LT.20) NS=20
0021      NP=2*(NS/2)
0022      DEL=G1/NP
0023      NP=NP+1
0024      DEL3=DEL/3.
0025      SUM1=(0.,0.)
0026      SUM2=(0.,0.)
0027      DO 100 I=1,2
0028      SIGN=1.
0029      DO 100 J=1,NP
0030      W=(3.-SIGN)*DEL3
0031      IF(J.EQ.1.OR.J.EQ.NP) W=DEL3
0032      IF(I.EQ.2) GO TO 31
0033      G=(J-1)*DEL
0034      GO TO 33
0035      31      B=(J-1)*DEL
0036      BS=B*B
0037      G=SQRT(GCS-BS)
0038      33      GS=G*G
0039      F=CSQRT(GAM2S+GS)
0040      F0=CSQRT(GAM0S+GS)
0041      IF(I0123.EQ.2) FF=FF2(G,F)
0042      IF(SIG2.NE.0.AND.I.EQ.2) FQ=B/F
0043      IF(SIG2.EQ.0.AND.I.EQ.2) FQ=(0.,-1.)
0044      IF(I.EQ.1) SUM1=SUM1+W*FF/F
0045      IF(I.EQ.2) SUM2=SUM2+W*FF*FQ/G
0046      100     SIGN=-SIGN
0047      C      type*, 'np1=',np
0048      FACT=5.
0049      ALPH1=FACT*ANAX1(KO,GC,CABS(GAM2))
0050      C      SET UP FOR SUM3 & SUM4
0051      DELAL=DEL
0052      NS=ALPH1/DELAL
0053      IF(NS.LT.20) NS=20
0054      NP=2*(NS/2)
0055      DELAL=ALPH1/NP
0056      NPT=NP/4
0057      NP=NP+1
0058      C      type*, 'np & npt =',np,npt
0059      SUM3=(0.,0.)
0060      SIGN=1.
0061      C      IABORT=0
0062      DELA3=DELAL/3.
0063      DO 200 I=1,NP
0064      W1=3.-SIGN

```

```

0065          W=W1*DELA3
0066          IF (I.EQ.1.OR.J.EQ.NP) W=DELA3
0067      34    ALPHA=(I-1)*DELAL
0068      C     type*, 'i & w =' , i, w
0069          ALPHS=ALPHA*ALPHA
0070          G=SQRT (ALPHS+GCS)
0071          GS=G*G
0072          F=CSQRT (GM12S+GS)
0073          F0=CSQRT (GM0S+GS)
0074          IF (I0123.EQ.2) FF=FF2(G,F)
0075          IF (SIG2.NE.0) FQ=ALPHA/F
0076          IF (SIG2.EQ.0) FQ=(1.,0.)
0077          DSUM=W*FF*FQ/G
0078          SUM3=SUM3+DSUM
0079      C     IF (IABORT.EQ.1) GO TO 300
0080      C     IF (CABS(DSUM) .LT. (CABS(SUM3)/1000.) .AND. I. GT. NPT. AND. W1.EQ.4.
0081      C     &) THEN
0082      C     IABORT=1
0083      C     W=DELA3
0084      C     GO TO 34
0085      C     END IF
0086      200    SIGN=-SIGN
0087      C     type*, 'np2=' , np
0088      300    SUMT=SUM1+SUM2+SUM3
0089          RETURN
0090          END

```

FUNCTIONS AND SUBROUTINES REFERENCED

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0001      C
0002      C
0003          COMPLEX FUNCTION FF2(G,F)
0004          COMPLEX FN,FM,GN,GM,F,SNK1,SNK2,SNK3,SNK4,SNK5,SNK6,SNK7,SNK8
0005          COMPLEX EX1,EX2,T1,T2,T3,T4,T5,T6,CJ,FXE,FXO,SNV,CSY,PEX,EXM
0006          COMPLEX EXBM,EXBP,SYEM,SYBP,CSEB,CSEB,S1,S2,S3,S4,S5,S6,S7,S8
0007          COMPLEX EXEMN,EXBPN,CST1,CST2,F1,F2
0008          COMPLEX GNPG,GNMG,GMFG,GMNG,FMFN,FNPF,FMMF,FMPF,FNMF
0009          COMMON FN,FM,GN,GM,AM,EM,DM,XLS, YLS,CSN,SNN,CSM,SNM
0010          COMMON /JERK/ CST1,CST2,CSMN
0011          CJ=(0.,1.)
0012          GNPG=GN+G
0013          GNMG=GN-G
0014          GMFG=GM+G
0015          GMNG=GM-G
0016          FMFN=FM+FN
0017          FNPF=FN+CJ*F
0018          FMMF=FM-CJ*F
0019          FMPF=FM+CJ*F
0020          FNMF=FN-CJ*F
0021          SNK1=EM
0022          IF (CABS(GNPG) .GT. 1.E-6) SNK1=CSIN(GNPG*EM)/GNPG
0023          SNK2=EM
0024          IF (CABS(GMFG) .GT. 1.E-6) SNK2=CSIN(GMFG*EM)/GMFG
0025          SNK3=EM
0026          IF (CABS(GNMG) .GT. 1.E-6) SNK3=CSIN(GNMG*EM)/GNMG
0027          SNK4=EM
0028          IF (CABS(GMNG) .GT. 1.E-6) SNK4=CSIN(GMNG*EM)/GMNG
0029          SNK5=AM
0030          IF (CABS(FMFN) .GT. 1.E-6) SNK5=CSIN(FMFN*AM)/FMFN
0031          SNK6=AM
0032          IF (CABS(FMMF) .GT. 1.E-6) SNK6=CSIN(FMMF*AM)/FMMF

```

```

0033      SNK7=AM
0034      IF (CABS(FNEFF).GT.1.E-6) SNK7=CSIN(FNEFF*AM)/FNEFF
0035      SNK8=SNK5
0036      EX1=CEXP(CJ*FNEFF*AM)/FNEFF
0037      EX2=CEXP(-CJ*FNEFF*AM)/FNEFF
0038      T1=SNK1*SNK2
0039      T2=SNK3*SNK4
0040      T3=SNK5/FNEFF
0041      T4=EX1*SNK6
0042      T5=EX2*SNK7
0043      T6=SNK8/FNEFF
0044      FXE=CJ*(T3-T4+T5-T6)
0045      FXO=CJ*(T3-T4-T5+T6)
0046      CSY=T1+T2
0047      SNY=-CJ*(T1-T2)
0048      F1=4.*FXE*CSY*CSII*CSNN
0049      EXBAM=CEXP(-CJ*GM*EM)
0050      EXBPN=CEXP(CJ*GN*EM)
0051      EXBM=CEXP(-CJ*G*BM)
0052      EXBP=CEXP(CJ*G*BM)
0053      SYBM=-CJ*(EXBM*SNK2-EXBP*SNK4)
0054      SYBP=-CJ*(EXBP*SNK2-EXBM*SNK4)
0055      CSRM=EXBM*SNK2+EXBP*SNK4
0056      CSBP=EXBP*SNK2+EXBM*SNK4
0057      EXM=CEXP(-CJ*FNEFF*AM)
0058      PEX=CEXP(CJ*FNEFF*AM)
0059      S1=4.*EXM*SNK7*SNY
0060      S2=-4.*EXM*SNK7*CSY
0061      S3=2.*EXBM*FXE*SYBM
0062      S4=2.*EXBM*FXO*CSRM
0063      S5=4.*PEX*SNK6*SNY
0064      S6=4.*PEX*SNK6*CSY
0065      S7=2.*EXBPN*FXE*SYBP
0066      S8=2.*EXBPN*FXO*CSBP
0067      T1=SNM*SNM*F*(S1-S5)
0068      T2=SNM*SNM*F*(S2-S6)
0069      T3=CSN*CSN*F*(S3-S7)
0070      T4=CSN*SNM*F*(S4-S8)
0071      WRITE(8,*)'F,G,SNY=',F,G,SNY
0072      WRITE(8,*)'CSN,SNN,CSN,SNM=',CSN,SNN,CSN,SNM
0073      WRITE(8,*)'T1,T2=',T1,T2
0074      WRITE(8,*)'T3,T4=',T3,T4
0075      WRITE(8,*)'S3,S7=',S3,S7
0076      WRITE(8,*)'S4,S8=',S4,S8
0077      F2=-SNM*CSM*G*(S1-S5)+SNM*SNM*F*(S2-S6)+CSN*CSN*G*(S3-S7)
0078      &-CSM*SNM*F*(S4-S8)
0079      F2=F2*CSII
0080      FF2=F1+F2
0081      WRITE(8,*)'FF2=',FF2
0082      RETURN
0083      END

```

APPENDIX E

Subroutine SMRFLD2 is based on the formulation of Section E in Chapter V. The program uses Figure 5-3 as its model. The evaluated integral is output as SUMT. The rest of the inputs are self explanatory.

```

0001      SUBROUTINE SMRFLD2(X,Y,XP,YP,D,ER2,SIG2,FMC,I01,SUMT)
0002      C
0003      C      THIS IS PROGRAM (SMRFLD2.FOR) WHICH USES SIMPSON'S
0004      C      RULE TO INTEGRATE A SUMMERFELD INTEGRAL FROM ZERO TO INFINITY.
0005      C      IT CAN BE USED TO TEST A MODIFIED BESSEL FUNCTION K0(Z)
0006      C      IF I01= 1 RC IS THE ELECTRIC REF. COEF.
0007      C      IF I01=-1 RC IS THE MAGNETIC REF. COEF.
0008      C      IF I01= 0 RC IS = 1.
0009      C      IF I01> 1 RC IS =-1.
0010      C
0011      C      PROGRAM WRITTEN BY JANAL S. IZADIAN NOV.-81
0012      C
0013      C      COMPLEX GAM2S,GAM2,F,FF,SUM1,SUM2,SUM3,SUM4,SUMT,EP2
0014      C      COMPLEX S1,S2,S3,GAM,GAM0S,FQ,CL,F0,RC,EF,C2,AA,EXAA,Z
0015      C      REAL K0
0016      C      DATA PI,TP/3.14159265359,6.28318530718/
0017      C      DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0018      C      IF (IABS(I01).GE.1) ARG=2.*D-X-XP
0019      C      IF (IABS(I01).EQ.0) ARG=ABS(X-XP)
0020      C      OMEGA=TP*FMC*1.E6
0021      C      K0=OMEGA*SQRT(E0*U0)
0022      C      GAM0S=-K0*K0*(1.,0.)
0023      C      EP2=CNPLX(ER2*E0,-SIG2/OMEGA)
0024      C      GAM2S=-OMEGA*OMEGA*U0*EP2
0025      C      GAM2=CSQRT(GAM2S)
0026      C      C1=(0.,-1.)*OMEGA*U0/TP
0027      C      GC=OMEGA*SQRT(U0*ER2*E0)
0028      C      GCS=GC*GC
0029      C      C2=((0.,1.)*OMEGA*U0*SIG2+GAM0S-GCS)/8.
0030      C      G1=GC/SQRT(2.)
0031      C      SET UP FOR SUM1 & SUM2
0032      C      DEL=PI/10./(ARG+Y-YP)
0033      C      NS=G1/DEL
0034      C      IF (NS.LT.40) NS=40
0035      C      NP=2*(NS/2)
0036      C      DEL=G1/NP
0037      C      NP=NP+1
0038      C      DEL3=DEL/3.
0039      C      SUM1=(0.,0.)
0040      C      SUM2=(0.,0.)
0041      C      DO 100 I=1,2
0042      C      SIGN=1.
0043      C      DO 100 J=1,NP
0044      C      W=(3.-SIGN)*DEL3
0045      C      IF (J.EQ.1.OR.J.EQ.NP) W=DEL3
0046      C      IF (I.EQ.2) GO TO 31
0047      C      G=(J-1)*DEL
0048      C      GO TO 33
0049      31      B=(J-1)*DEL
0050      C      BS=B*B
0051      C      G=SQRT(GCS-BS)
0052      33      GS=G*G
0053      C      F=CSQRT(GAM2S+GS)
0054      C      F0=CSQRT(GAM0S+GS)
0055      C      IF (I01.EQ.1) RC=(F-F0)/(F+F0)
0056      C      IF (I01.EQ.-1) RC=(E0*F-EP2*F0)/(E0*F+EP2*F0)
0057      C      IF (IABS(I01).EQ.0) RC=(1.,0.)
0058      C      IF (IABS(I01).GT.1) RC=(-1.,0.)
0059      C      EF=CEXP(-F*ARG)
0060      C      CS=CCS(G*(Y-YP))
0061      C      FF=RC*EF*CS
0062      C      IF (SIG2.NE.0.AND.I.EQ.2) FQ=B/F
0063      C      IF (SIG2.EQ.0.AND.I.EQ.2) FQ=(0.,-1.)

```

```

0064 IF (I.EQ.1) SUM1=SUM1+W*FF/F
0065 IF (I.EQ.2) SUM2=SUM2+W*FF*FQ/G
0066 SIGN=-SIGN
0067 CONTINUE
100 ALPHA=15./ARG
C SET UP FOR SUM3 & SUM4
0069 DELAL=DEL
0070 NS=ALPH1/DELAL
0071 IF (NS.LT.40) NS=40
0072 NP=2*(NS/2)
0073 DELAL=ALPH1/NP
0074 NP=NP+1
0075 SUM3=(0.,0.)
0076 SIGN=1.
0077 DELA3=DELAL/3.
0078 DO 200 I=1,NP
0079 W=(3.-SIGN)*DELA3
0080 IF (I.EQ.1.OR.I.EQ.NP) W=DELA3
0081 ALPHA=(I-1)*DELAL
0082 ALPHS=ALPHA*ALPHA
0083 G=SQRT(ALPHS+GCS)
0084 GS=G*G
0085 F=CSQRT(GAM2S+GS)
0086 F0=CSQRT(GAM0S+GS)
0087 IF (I01.EQ.1) RC=(F-F0)/(F+F0)
0088 IF (I01.EQ.-1) RC=(E0*F-EP2*F0)/(E0*F+EP2*F0)
0089 IF (IABS(I01).EQ.0) RC=(1.,0.)
0090 IF (IABS(I01).GT.1) RC=(-1.,0.)
0091 EF=CEXP(-F*ARG)
0092 CS=COS(G*(Y-YP))
0093 FF=RC*EF*CS
0094 IF (SIG2.NE.0) FQ=ALPHA/F
0095 IF (SIG2.EQ.0) FQ=(1.,0.)
0096 SUM3=SUM3+W*FF*FQ/G
0097 SIGN=-SIGN
200 CONTINUE
SUM4=(0.,0.)
SIGN=1.
DO 300 J=1,2
GAM=-ARG+(0.,1.)*SIGN*(Y-YP)
AA=GAM*ALPH1
Z=-AA
EXAA=CEXP(AA)
S1=-.5*EXAA/ALPH1/ALPH1
S2=-.5*GAM*EXAA/ALPH1
EI=.711093/(Z+.415775)
EI=EI+.278518/(Z+.2.29428)
EI=EI+.010389/(Z+.6.29)
EI=EI*CEXP(-Z)
S3=GAM*GAM*.5*EI
SUM4=SUM4+S1+S2+S3
SIGN=-1.
300 SUM4=SUM4*C2
SUMT=SUM1+SUM2+SUM3+SUM4
RETURN
END

```

APPENDIX F

Computer program RCYLEGP is the same as RTUNLE except, this has used Trapezoidal rule to integrate all the integrations over the cross section. The treatment is similar to RCYLPWE of Appendix A. In addition this program models the air-earth interface. When the interface is not modeled, the plane wave incidence excitation may also be used.

```

0001 C LINK WITH CROUT & MBEZ10
0002 C
0003 C THIS PROGRAM (RCYLEGP.FOR) USES TRAVELING PLANE WAVE EXPANSION
0004 C AND GALERKIN METHOD TO CALCULATE THE SCATTERED FIELD BY
0005 C A LOSSY DIELECTRIC INFINITE RECTANGULAR CYLINDER, AND
0006 C FOR AN ELECTRIC LINE SOURCE PARALLEL TO AXIS OF THE CYLINDER.
0007 C THE CYLINDER MAY BE IMMersed IN A LOSSY HOMOGENEOUS MEDIUM,
0008 C OR IT MAY BE BURIED IN A LOSSY HOMOGENEOUS EARTH.
0009 C
0010 C WRITTEN BY JAMAL IZADIAN JAN. 1982.
0011 C
0012 C COMPLEX BKK(25,25),FNEE(25),FMEE(25),FK(75),CMN(25,25),B(25)
0013 C COMPLEX A(25),FA(25),GA(25),DCMN(25,25),CTMN(25,25)
0014 C COMPLEX EZSR,C1,GC,VEE,SUMT,SDD
0015 C COMPLEX EGXP,EGYP,EGXL,EGYL,EGX1,FM,FM,GN,GM
0016 C COMPLEX EZI,PPF,GPG,SSL,SS2
0017 C COMPLEX SFPF,SGFG,FMXP,GMYP,FMXL,GMXL
0018 C COMPLEX CSP,CII,CIK,CV1,EP1,EP2,ETA2,CST,CSS,EZ1,EZS,SEE
0019 C COMPLEX GAM1,GAM2,BI,BK,BI1,BK1,GR,K1,K2,REE
0020 C DIMENSION XM(450),YM(450)
0021 C INTEGER P
0022 C DATA FP,TD2,CX/12.5663706144,0.,.0174533/
0023 C DATA ETA,PI,TP/376.730366239,3.14159265359,6.28318530718/
0024 C DATA ICC,NX,ISIZE,NJ,ITBL/25,30,10,0,0/
0025 C DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0026 C call getcp(itl)
0027 C READ(7,*)ER1,SIG1,ER2,SIG2,FMCX,AWM,BWM,DM,XLS,YLS,IWR,
0028 C &IFILD,IWRC,IPW,IBS,IBISS,IFMC,IEQ,IGROND
0029 C PHI=ATAN2(YLS,XLS)/.0174533
0030 C RLS=SQRT(XLS*XLS+YLS*YLS)
0031 C WPH=PHI
0032 C IF(IEQ.EQ.0)TYPE*, 'GIVE NEQ & NY ='
0033 C IF(IEQ.EQ.0)ACCEPT*,NEQ,NY
0034 C IF(IFMC.GT.1) GO TO 41
0035 C 20 TYPE*, 'GIVE FMC='
0036 C ACCEPT*,FMC
0037 C IF(FMC.LT.0) GO TO 600
0038 C 41 DO 500 JF=1,IFMC
0039 C IF(IFMC.GT.1)FMC=JF*FMCX/FLOAT(IFMC)
0040 C I12=1
0041 C AM=AWM/2.
0042 C BM=BWM/2.
0043 C OMEGA=TP*FMC*1.E6
0044 C B1S1=OMEGA*OMEGA*U0*ER1*E0
0045 C BET1=SQRT(B1S1)
0046 C EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0047 C EP2=ER2*E0*(1.,.0)
0048 C IF(TD2.GT.1.E-10)EP2=ER2*E0*CMPLX(1.,-TD2)
0049 C IF(SIG2.GT.1.E-10)EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0050 C ETA2=CSQRT(U0/EP2)
0051 C GAM2=OMEGA*CSQRT(-U0*EP2)
0052 C GAM1=OMEGA*CSQRT(-U0*EP1)
0053 C K1=(0.,-1.)*GAM1
0054 C K2=(0.,-1.)*GAM2
0055 C BET2=AIMAG(GAM2)
0056 C B1S2=BET2*BET2
0057 C WAV1=TP/BET1
0058 C WAV2=TP/BET2
0059 C CPH=1.-PI/(14.*BET1*AM)
0060 C DPH=ACOS(CPH)
0061 C IF(IEQ.EQ.1)NEQ=(1.+PI/(2.*DPH))*2
0062 C IF(NEQ.LT.4) NEQ=4

```

```

0063      IF (NEQ.GT.ICC) GO TO 600
0064      IF (IEQ.EQ.1) NY=15.*BET1*BKM/PI
0065      IF (NY.LT.6.AND.IEQ.EQ.1) NY=6
0066      IF (NY.GT.NYX) NY=NYX
0067      NY=2*(NY/2)
0068      NX=INT(AM/EM)*NY
0069      NX=(NX/2)*2
0070      NY2=NY/2
0071      NX2=NX/2
0072      KK=NX*NY
0073      DPH=TP/NEQ
0074      DO 90 J=1,NEQ
0075      PH=(J-1)*DPH
0076      FA(J)=K1*COS(PH)
0077      GA(J)=K1*SIN(PH)
0078      90  CONTINUE
0079      DX=AM/NX
0080      DY=EM/NY
0081      DXY=DX*DY
0082      DX2=DX/2.
0083      DY2=DY/2.
0084      C  FIND THE RADII OF EQUIVALENT CIRCULAR CELL
0085      CM=SQRT(DX*DY/PI)
0086      GC=GAM2*CM
0087      CALL MBEZ10(GAM2*CM,BI,BK,BI1,BK1,1,-1)
0088      CSF=-OMEGA*OMEGA*U0*(EP1-EP2)*DXY*DXY/TP
0089      CSS=(1.-GC*BK1)*(EP1-EP2)/EP2
0090      CST=GC*BI1*(EP1-EP2)/EP2
0091      CIK=CSS*2.*PI*CM*BI1/GAM2
0092      CII=CST*2.*PI*CM*BI1/GAM2
0093      CV1=-ETA2*CM*BI1
0094      C1=(0.,-1.)*OMEGA*U0/TP
0095      RAB=SQRT(AM*AM+EM*EM)
0096      21  DELTR=(RAB-DX)/ISIZE
0097      IF (DX.GT.DELTR) GO TO 23
0098      ISIZE=ISIZE+5
0099      GO TO 21
0100      23  DO 22 I=1,ISIZE
0101      RR=I*DELTR
0102      CALL MBK0Z(GAM2*RR,BK,-1)
0103      FK(I)=BK*CII
0104      22  CONTINUE
0105      TYPE*, 'ISIZE=', ISIZE
0106      M=0
0107      Y=-EM+DY2
0108      C  SET UP THE COORDINATES OF CENTERS OF CELL M
0109      DO 40 J=1,NY
0110      X=-AM+DX2
0111      DO 30 I=1,NX
0112      M=M+1
0113      XM(M)=X
0114      YM(M)=Y
0115      30  X=X+DX
0116      40  Y=Y+DY
0117      DO 42 J=1,25
0118      DO 42 I=1,25
0119      42  BK(I,J)=(0.,0.)
0120      C  SET UP IMPEDANCE MATRIX
0121      DO 200 M=1,NEQ
0122      FM=FA(M)
0123      GM=GA(M)
0124      DO 160 N=M,NEQ
0125      FN=FA(N)

```

```

0126      GN=GA(N)
0127      FPF=FN+FM
0128      GPG=GN+GM
0129      SFPP=CSIN(FPF*AM)
0130      SGPG=CSIN(GPG*EM)
0131      SS1=AM
0132      IF(CABS(FPF).GT.J.E-6) SS1=SFPP/FPF
0133      SS2=EM
0134      IF(CABS(GPG).GT.I.E-6) SS2=SGPG/GPG
0135      REE=4.*SS1*SS2
0136      DCMN(M,N)=(0.,0.)
0137      CMN(M,N)=REE
0138      180 CONTINUE
0139      200 CONTINUE
0140      DO 160 P=1, KK
0141      XP=XM(P)
0142      YP=YM(P)
0143      JP=(P-1)/NX+1
0144      IP=P-(JP-1)*NX
0145      DO 140 L=1, KK
0146      XL=XM(L)
0147      YL=YM(L)
0148      JL=(L-1)/NX+1
0149      IL=L-(JL-1)*NX
0150      YY=YP-YL
0151      YS=YY*YY
0152      XX=XP-XL
0153      XS=XX*XX
0154      II=1+IABS(IP-IL)
0155      JJ=1+IABS(JP-JL)
0156      ROH=SQRT(XS+YS)
0157      IF(ROH.LT.DX2) GO TO 79
0158      IF(EKK(II, JJ).EQ.(0.,0.)) THEN
0159      CALL INTERP(ROH, BKK(II, JJ), DELTA, EK, ISIZE)
0160      BKK(JJ, II)=BKK(II, JJ)
0161      NJ=NJ+1
0162      END IF
0163      79 DO 80 M=1, NEQ
0164      FM=FA(M)
0165      GM=GA(M)
0166      FMXP=FM*XP*(0.,-1.)
0167      GMYP=GM*YP*(0.,-1.)
0168      EGXP=CEXP(FMXP)
0169      EGYM=CEXP(GMYP)
0170      FMEM(M)=EGXP*EGYM
0171      DO 80 N=M, NEQ
0172      FN=FA(N)
0173      GN=GA(N)
0174      FNXL=FN*XL*(0.,-1.)
0175      GNYL=GN*YL*(0.,-1.)
0176      EGXL=CEXP(FNXL)
0177      EGYL=CEXP(GNYL)
0178      FNEN(N)=EGXL*EGYL
0179      IF(IGROND.EQ.1) CALL SMRFLD2(XP, YP, XL, YL, DM, ER2, SIG2, FMC, I, SUMT)
0180      IF(IGROND.EQ.1) NI=NI+1
0181      IF(IGROND.EQ.1) DCMN(M, N)=DCMN(M, N)+FMEM(M)*FNEN(N)*SUMT*CSF
0182      IF(ROH.GT.DX2) GO TO 35
0183      CMN(M, N)=CMN(M, N)+FMEM(M)*FNEN(N)*CIK
0184      GO TO 75
0185      35 BK=EKK(II, JJ)
0186      CMN(M, N)=CMN(M, N)+FMEM(M)*FNEN(N)*BK
0187      75 IF(IGROND.EQ.1) CIMN(M, N)=CMN(M, N)+DCMN(M, N)
0188      80 CONTINUE

```

```

0189      140      CONTINUE
0190      160      CONTINUE
0191      TYPE*, 'NJ=', NJ, 'NI=', NI
0192      NI=0
0193      NJ=0
0194      IF (IMR.EQ.1) THEN
0195          WRITE(10,2)
0196      DO 210 N=1,NBQ
0197          WRITE(10,3) M, N, GAM(M, N), DGM(M, N), CTM(M, N)
0198      CONTINUE
0199      210
0200      END IF
0201      IF (IMR.EQ.1) WRITE(10,9)
0202      IF (IMR.EQ.1) WRITE(10,4)
0203      DO 500 JI=1, IBS
0204          IF (IBS.GT.1) PH1=(JI-1)*360./FLOAT( IBS-1)
0205              PH1=CX*PH1
0206              CSI=COS( PH1)
0207              SNI=SIN( PH1)
0208              XI.S1=RS*CSI
0209              YI.S1=RS*SNI
0210      SET UP THE VOLTAGE MATRIX COLUMN
0211      DO 240 N=1,NBQ
0212          FM=FA(M)
0213          G1=GA(M)
0214          SDD=(0.,0.)
0215          SEB=(0.,0.)
0216      DO 220 P=1,KK
0217          X=XM(P)
0218          Y=YM(P)
0219          FMXP=FM*X*(0.,-1.)
0220          GMXP=GM*Y*(0.,-1.)
0221          EGXP=CEXP( FMXP)
0222          BGXP=CEXP( GMXP)
0223          PNEE(M)=EGXP+BGXP
0224      IF (IEM.EQ.1) THEN
0225          IF (IGRND.EQ.1) TYPE*, 'NO FORMULATION FOR P.W. REFLECTION YET!!!'
0226          PS11=X*CSI+Y*SNI
0227          EGX1=CEXP( GAM2*PS11)
0228          CV1=(1.,0.)*DX*DY
0229          GO TO 219
0230      END IF
0231          X1=XI.S1-X
0232          Y1=YI.S1-Y
0233          RH1=SQRT( X1*X1+Y1*Y1)
0234          CALL NEK02( GAM2*RH1, EGX1, -1)
0235          IF (IGRND.EQ.1) CALL SBR1D2( X, Y, XI.S1, YI.S1, DI, ER2, SIG2, FWC, J, SUMPT)
0236          VEB=BGX1
0237      IF (IGRND.EQ.1) SDD=SDD+PNEE(M)*SUMT
0238          SEB=SEB+VEE(M)*VEB
0239      CONTINUE
0240          A(M)=SEB*CV1
0241      IF (IGRND.EQ.1) B(M)=-SDD*CI+DXY
0242      CONTINUE
0243      IF (IMR.EQ.1) THEN
0244          DO 202 N=1,NBQ
0245              WRITE(10,5) M, A(M), B(M), (A(M)+B(M))
0246              WRITE(10,9)
0247          END IF
0248          IF (IGRND.EQ.1) THEN
0249              DO 204 N=1,NBQ
0250                  A(M)=A(M)+B(M)
0251              DO 204 N=N,NBQ

```

```

0252      204      CMN(M,N)=CIMP(M,N)
0253      END IF
0254      ISYM=0
0255      CALL CROUT(CMN,A,ICC,ISYM,IWRC,I12,NEQ)
0256      IF (IWR.EQ.1) THEN
0257          WRITE(10,6)
0258          DO 244 M=1,NEQ
0259              WRITE(10,5)M,A(M)
0260      244      CONTINUE
0261          WRITE(10,9)
0262          END IF
0263          WRITE(8,*)KK,NX
0264      C      FIND THE FIELD IN CELLS OF FIRST QUADRANT
0265          IF (IFILD.NE.1) GO TO 45
0266          WRITE(10,8)
0267          DO 248 L=1,KK
0268              EZ1=(0.,0.)
0269              XL=XM(L)
0270              YL=YM(L)
0271              DO 246 N=1,NEQ
0272                  FN=FA(N)
0273                  GN=GA(N)
0274                  FNXL=FN*XL*(0.,-1.)
0275                  GNYL=GN*YL*(0.,-1.)
0276                  EGXL=CEXP(FNXL)
0277                  EGYL=CEXP(GNYL)
0278                  FNEL(N)=EGXL*EGYL
0279                  EZ1=EZ1+A(N)*FNEL(N)
0280      246      CONTINUE
0281      C      IF (XL.GT.0.AND.YL.GT.0) THEN
0282          RE=REAL(EZ1)
0283          AIE=AIMAG(EZ1)
0284          AMP=CABS(EZ1)
0285          PHASE=ATAN2(AIE,RE)/CX
0286          WRITE(10,11)XL,YL,AMP,PHASE
0287          WRITE(8,*)L,AMP,PHASE
0288      C      END IF
0289      248      CONTINUE
0290      45      IF (IWR.EQ.1) WRITE(10,9)
0291          PHS=PH1
0292          DO 500 JK=1,IBISS
0293              IF (IBISS.GT.1) THEN
0294                  PHI=(JK-1)*360./FLOAT(IBISS-1)
0295                  PHS=CX*PHI
0296              END IF
0297                  XLS=RLS*COS(PHS)
0298                  YLS=RLS*SIN(PHS)
0299      C      FIND THE BACKSCATTERED FIELD
0300          EZSR=(0.,0.)
0301          EZSR=(0.,0.)
0302          DO 290 L=1,KK
0303              XL=XM(L)
0304              YL=YM(L)
0305              YY=YLS-YL
0306              YS=YY*YY
0307              XX=XLS-XL
0308              XS=XX*XX
0309              IF (IPW.EQ.1) THEN
0310                  PSI=XL*COS(PHS)+YL*SIN(PHS)
0311                  BK=CEXP(GAM2*PSI)
0312                  GO TO 47
0313              END IF
0314              ROH=SQRT(XS+YS)

```

```

0315      CALL NBRK02(GM2*RC01,BK,-1)
0316      IF (IGRND.EQ.1) CALL SRRFD2(XL,YL,XLS,YLS,DM,ER2,SIG2,FNC,1,SUMR)
0317      EZ1=(0.,0.)
0318      DO 260 N=1,NBQ
0319         FN=PA(N)
0320         GN=CA(N)
0321         FNYI=FN*XL*(0.,-1.)
0322         GNVI=GN*YL*(0.,-1.)
0323         BGYL=CEXP(FNXL)
0324         BGYI=CEXP(GNVI)
0325         FNEB(N)=BCKL*BGYL
0326         EZ1=EZ1+A(N)*FNEB(N)
0327         CONTINUE
0328      EZS=EZS+EZ1*BK
0329      IF (IGRND.EQ.1) EZSR=EZSR+EZ1*SUMR
0330      CONTINUE
0331      EZS=CST*EZS
0332      EZSR=EZSR*C1*(0.,1.)*(BP1-EP2)*OMEGA*DX1
0333      EZS=EZS+EZSR
0334      IF (IPW.EQ.1) EZS=EZS+CQSQR(.5*PI/GM2)
0335      AZS=CABS(EZS)
0336      IF (IWR.EQ.1) WRITE(10,*) 'AZS=',AZS
0337      EWI=TP*AZS*NZS/WNV2
0338      DB=.0
0339      C
0340      FIND THE NORMALIZED SCATTERING ATTENUATION FUNCTION
0341      IF (IPW.EQ.0) THEN
0342         GR=2.*GM2*RLS
0343         CALL NBRK02(GR,BK,-1)
0344         EZI=C1*BK
0345         IF (IWR.EQ.1) WRITE(10,*) 'AZI=',AZI
0346         AZN=AZS/AZI
0347         DB=20.*ALOG10(AZN)
0348         TYPEL,NBQ,NX,NY,FNC,DB,PHI
0349         WRITE(10,1)NBQ,NX,NY,FNC,DB,PHI
0350         GO TO 599
0351      END IF
0352      TYPEL,NBQ,NX,NY,FNC,EWL,PHI
0353      WRITE(10,1)NBQ,NX,NY,FNC,EWL,PHI
0354      IF (IBS.EQ.1.AND.IBISS.EQ.1.AND.IFNC.EQ.1) GO TO 20
0355      I12=2
0356      CONTINUE
0357      CONTINUE
0358      IF (IPW.EQ.1) WRITE(10,14)
0359      IF (IPW.EQ.0) WRITE(10,13)
0360      WRITE(10,9)
0361      WRITE(10,*) ' ER1 & SIG1 =' ,ER1,SIG1
0362      WRITE(10,*) ' ER2 & SIG2 =' ,ER2,SIG2
0363      WRITE(10,*) ' AMM & EMM =' ,AMM,EMM
0364      WRITE(10,*) ' RLS=' ,RLS,' PHI=' ,PHI
0365      call getcp(i12)
0366      time=(i12-i11)/100.
0367      WRITE(10,*) ' CPU TIME (SEC) =' ,TIME
0368      TYPE*,' CPU TIME (SEC) = ',TIME
0369      WRITE(10,*) 'RCXLEP FOR'
0370      WRITE(10,*) ER1,SIG1,ER2,SIG2,FNCKX,AMM,EMM,DM,XLS,YLS,IWR,IFIID,IMRC
0371      &,IPW,IBS,IBISS,IFNC,IEQ,IGRND
0372      FORNW1(1X,3I5,6F12.6)
0373      FORNW1(5X,'N',4X,'N',13X,'ZMN',21X,'DMN',21X,'ZTN')
0374      FORNW1(1X,2I5,8F12.6)
0375      FORNW1(5X,'N',18X,'VM',21X,'DVM',21X,'VM')
0376      FORNW1(1X,I5,5X,8F12.6)
0377      FORNW1(5X,'N',18X,'A',)

```

```
0378 8      FORMAT(5X,'X',9X,'Y',13X,'AMPLITUDE',3X,'PHASE')
0379 9      FORMAT(LH0)
0380 11     FORMAT(1X,2F10.5,5X,2F12.6)
0381 13     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'SAF',9X,'PHI')
0382 14     FORMAT(3X,'NEQ',3X,'NX',3X,'NY',6X,'FMC',9X,'EVL',9X,'PHI')
0383      CALL EXIT
0384      END
```

APPENDIX G

Program LS0IFP calculates near field patterns of electric or magnetic line sources on or off an interface between media I and II. The model for this program is Figure 5-3, except region I is not restricted to free space. The program always assumes the line source is in medium II, where in the limit it can be moved to be placed on the interface.

```

0001 C PROGRAM (LSOIFP.FOR) CALCULATES THE PATTERN OF A UNIFORM
0002 C ELECTRIC OR MAGNETIC LINE SOURCE ON OR OFF THE INTERFACE
0003 C BETWEEN MEDIUM I (ABOVE I.F.) AND MEDIUM II (BELOW I.F.).
0004 C
0005 C
0006 C 101 = 1 ELECTRIC REF. COEF.
0007 C -1 MAGNETIC REF. COEF.
0008 C 0 RC=1
0009 C >1 RC=-1
0010 C NANG = NUMBER OF POINTS IN THE PATTERN.
0011 C XP,YP= LOCATION OF THE LINE SOURCE.
0012 C D = X-LOCATIONS OF THE INTERFACE.
0013 C R = RADIAL DISTANCE OF THE OBSERVATION POINT W.R.T.
0014 C LINE SOURCE.
0015 C
0016 C WRITTEN BY JANAL S. IZADIAN MARCH 1982
0017 C
0018 C COMPLEX CJ,ET,SUM1,BK,BI,BK1,BI1,GAML,GAM2,EP1,EP2
0019 C COMPLEX CST1,CST2,BK1,BK11
0020 C DATA PI,TP/3.14159265359,6.28318530718/
0021 C DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0022 C CJ=(0.,1.)
0023 C READ(1,*)ER1,SIG1,ER2,SIG2,XP,YP,D,R,FMC,NANG,I01
0024 C WRITE(10,*)NANG
0025 C OMEGA=TP*FMC*1.E6
0026 C EP1=CNPLX(E0*ER1,-SIG1/OMEGA)
0027 C EP2=CNPLX(E0*ER2,-SIG2/OMEGA)
0028 C GAML=CJ*CSQRT(EP1*U0)*OMEGA
0029 C GAM2=CJ*CSQRT(EP2*U0)*OMEGA
0030 C IF (I01.EQ.1) CST2=(1.,0.)
0031 C IF (I01.EQ.-1) CST2=EP2/E0
0032 C IF (I01.EQ.1) CST1=(1.,0.)
0033 C IF (I01.EQ.-1) CST1=EP1/E0
0034 C PHI=0.
0035 C CALL MBEZ10(GAM2*R,BI,BK11,BI1,BK1,0,-1)
0036 C CALL MBEZ10(GAML*R,BI,BK1,BI1,BK1,0,-1)
0037 C DO 100 J=1,NANG
0038 C IF (NANG.GT.1) PHI=FLOAT(J-1)*(TP/(NANG-1))
0039 C XB=R*COS(PHI)
0040 C YB=R*SIN(PHI)
0041 C X=XP+XB
0042 C Y=YP+YB
0043 C IF (X.LT.D) THEN
0044 C CALL SMRFLD(X,Y,XP,YP,D,ER2,SIG2,ER1,SIG1,FMC,I01,SUMT)
0045 C ET=(BK11+SUMT)
0046 C GO TO 101
0047 C END IF
0048 C CALL SMRFLD(X,Y,XP,YP,D,ER2,SIG2,ER1,SIG1,FMC,I01,SUMT)
0049 C ET=SUMT
0050 C PHY=PHI/.0174533
0051 C WRITE(10,6)PHY,CABS(ET*CST2),CABS(BK1*CST1),CABS(BK11*CST2)
0052 C CONTINUE
0053 C 6
0054 C FORMAT(IX,6F12.6)
0055 C END

```



```

0001 C
0002 C SUBROUTINE SMRFLD(X,Y,XP,YP,D,ER2,SIG2,ER1,SIG1,FMC,I01,SUMT)
0003 C
0004 C PROGRAM WRITTEN BY JANAL S. IZADIAN NOV.-81
0005 C
0006 C COMPLEX GAM2S,GAM2,F,FF,SUM1,SUM2,SUM3,SUM4,SUMT,EP2

```

```

0007      COMPLEX EP1,GAM0S,FQ,F0,RC,EF,BI,BK,BI1,BK1
0008      DATA PI,TP/3.14159265359,6.28318530718/
0009      DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0010      C      TYPE*, 'ER1,SIG1,ER2,SIG2=' ,ER1,SIG1,ER2,SIG2
0011      D1=D-XP
0012      IF (X.GT.D) E=X-D
0013      ARG=2.*D-X-XP
0014      OMEGA=TP*FNC*1.E6
0015      EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0016      EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0017      GAM2S=-OMEGA*OMEGA*U0*EP2
0018      GAM2=CSQRT(GAM2S)
0019      GAM0S=-OMEGA*OMEGA*U0*EP1
0020      GC=OMEGA*SQRT(U0*ER2*E0)
0021      GCS=CC*GC
0022      G1=GC/SQRT(2.)
0023      C      SET UP FOR SUM1 & SUM2
0024      DEL=PI/10./(ARG+Y-YP)
0025      NS=G1/DEL
0026      IF(NS.LT.40) NS=40
0027      NP=2*(NS/2)
0028      DEL=G1/NP
0029      NP=NP+1
0030      DEL3=DEL/3.
0031      SUM1=(0.,0.)
0032      SUM2=(0.,0.)
0033      DO 100 I=1,2
0034      SIGN=1.
0035      DO 100 J=1,NP
0036      W=(3.-SIGN)*DEL3
0037      IF(J.EQ.1.OR.J.EQ.NP) W=DEL3
0038      IF(I.EQ.2)GO TO 31
0039      G=(J-1)*DEL
0040      GO TO 33
0041      31      B=(J-1)*DEL
0042      BS=B*B
0043      G=SQRT(GCS-BS)
0044      33      GS=G*G
0045      F=CSQRT(GAM2S+GS)
0046      F0=CSQRT(GAM0S+GS)
0047      IF(I01.EQ.1)RC=(F-F0)/(F+F0)
0048      IF(I01.EQ.-1)RC=(EP1*F-EP2*F0)/(EP1*F+EP2*F0)
0049      WRITE(8,*) 'G,F,F0,RC=' ,G,F,F0,RC
0050      IF(IABS(I01).EQ.0)RC=(1.,0.)
0051      IF(IABS(I01).GT.1)RC=(-1.,0.)
0052      IF(X.GT.D)RC=1.+RC
0053      IF(X.LE.D)EF=CEXP(-F*ARG)
0054      IF(X.GT.D)EF=CEXP(-F*D1-F0*H)
0055      CS=COS(G*(Y-YP))
0056      FF=RC*EF*CS
0057      IF(SIG2.NE.0.AND.I.EQ.2)FQ=B/F
0058      IF(SIG2.EQ.0.AND.I.EQ.2)FQ=(0.,-1.)
0059      IF(I.EQ.1)SUM1=SUM1+W*FF/F
0060      IF(I.EQ.2)SUM2=SUM2+W*FF*FQ/G
0061      SIGN=-SIGN
0062      100     CONTINUE
0063      C      ALPH1=5.*ANAX1(GC,CABS(GAM2),CABS(CSQRT(GAM0S)))
0064      SET UP FOR SUM3 & SUM4
0065      DELAL=DEL
0066      NS=ALPH1/DELAL
0067      IF(NS.LT.40)NS=40
0068      NP=2*(NS/2)
0069      DELAL=ALPH1/NP

```

```

0070      NP=NP+1
0071      SUM3=(0.,0.)
0072      SIGN=1.
0073      DELA3=DELAL/3.
0074      DO 200 I=1,NP
0075      W=(3.-SIGN)*DELA3
0076      IF (I.EQ.1.OR.I.EQ.NP)W=DELA3
0077      ALPHA=(I-1)*DELAL
0078      ALPHS=ALPHA*ALPHA
0079      G=SQRT(ALPHS+GCS)
0080      GS=G*G
0081      F=CSQRT(GAM2S+GS)
0082      FC=CSQRT(GAMOS+GS)
0083      IF (I01.EQ.1)RC=(F-F0)/(F+F0)
0084      IF (I01.EQ.-1)RC=(EP1*F-EP2*F0)/(EP1*F+EP2*F0)
0085      IF (IABS(I01).EQ.0)RC=(1.,0.)
0086      IF (IABS(I01).GT.1)RC=(-1.,0.)
0087      IF (X.GT.D)RC=1.+RC
0088      IF (X.LE.D)EF=CEXP(-F*ARG)
0089      IF (X.GT.D)EF=CEXP(-F*D1-F0*H)
0090      CS=COS(G*(Y-YP))
0091      FF=RC*EF*CS
0092      IF (SIG2.NE.0)FQ=ALPHA/F
0093      IF (SIG2.EQ.0)FQ=(1.,0.)
0094      SUM3=SUM3+W*FF*FQ/G
0095      SIGN=-SIGN
0096      200 CONTINUE
0097      SUMT=SUM1+SUM2+SUM3
0098      C      HH=2.*D1+(X-XP)
0099      C      RCH2=SQRT(HH*HH+(Y-YP)*(Y-YP))
0100      C      CALL MBEZ10(GAM2*RCH2,BI,BK,BIL,RK1,0,-1)
0101      C      TYPE*, 'BK,SUMT=',BK,SUMT
0102      RETURN
0103      END

```

APPENDIX H

Subroutine MBEZ1 ϕ (courtesy of Professor Richmond) is used to calculate the modified Bessel functions of order zero and one.

- SZ: is the complex argument of the Modified Bessel Function to be calculated.
- SBI: the calculated Modified Bessel Function of first kind of order zero.
- SBK: the calculated Modified Bessel Function of second kind of order zero.
- SBI1: the same as SBI except of order one.
- SBK1: the same as SBK except of order one.
- ID: if zero, only zero order functions are calculated. If one, only functions of order one are calculated. If > 1 , both orders of zeros and ones are calculated.

```

0001      SUBROUTINE NBEZ10(CZ,SBI,SRK,SB11,SRK1,JD,ISC)
0002      C DOUBLE PRECISION
0003      C MODIFIED BESSEL FUNCTIONS WITH COMPLEX ARGUMENT
0004      C ORDER ZERO AND ONE
0005      C SET ISC=-1 TO AVOID SCALING.
0006      C SET ISC=1 FOR SCALED FUNCTIONS.
0007      C IF ISC=1 AND REAL(Z).GE.0, I(Z) = BI*CEXP(Z).
0008      C IF ISC=1 AND REAL(Z).LT.0, I(Z) = BI/CEXP(Z).
0009      C IF ISC=-1, K(Z) = BK/CEXP(Z).
0010      REAL*8 ABR,AUG,AV,CI2,ST2,T1,X,Y,YP,AC2,AN,C,CY2,EMX2
0011      REAL*8 R2,STPR,XI,AC21,ARE,C2,DX,EPX2,R4,S,SY2,THETA
0012      REAL*8 XM,C57,PI,YI,AS2,PSI,RB,S2,T,TK,XP,YM
0013      REAL*8 IMIZ,IMKZ,R,REKZ,REI2,ZRE,ZIM,Y2,T2
0014      COMPLEX S2,SBI,SRK,SB11,SRK1
0015      COMPLEX*16 BI0,BK0,FI2,FKZ,Z,EZ
0016      COMPLEX*16 BI,BK,BI1,BK1
0017      COMPLEX*16 BIA,BIB,BIC,BKA,BKB,BKC,PA,EB,FA,AI
0018      DATA PI/3.1415926535897932/
0019      DATA FMV/1.E16/
0020      DATA C57/.5772156649015328/
0021      Z=SZ
0022      R=CDABS(Z)
0023      ZRE=DREAL(Z)
0024      ZIM=DIMG(Z)
0025      THETA=DATAN2(ZIM,ZRE)
0026      C=ZRE/R
0027      S=ZIM/R
0028      BI=(.0,.0)
0029      BK=(.0,.0)
0030      BI1=(.0,.0)
0031      BK1=(.0,.0)
0032      IF(R.GT.9.)GO TO 10
0033      IF(ISC.LE.0)GO TO 8
0034      EX=DEXP(ZRE)
0035      EZ=EX*DCMPLX(DCOS(ZIM),DSIN(ZIM))
0036      C2=2.*C+C-1.
0037      S2=2.*C*S
0038      R2=R/2.
0039      R4=R*R/4.
0040      GO TO 15
0041      R8=8.*R
0042      ARE=DABS(ZRE)
0043      EMX2=.0
0044      EPX2=.0
0045      IF(ARE.GT.40.)GO TO 11
0046      IF(ZRE.GE..0)EMX2=DEXP(-2.*ZRE)
0047      IF(ZRE.LT..0)EPX2=DEXP(2.*ZRE)
0048      IF(ISC.GT.0)GO TO 14
0049      IF(R.LT.80.)GO TO 12
0050      TYPE*, ' ARGUMENT MAGNITUDE EXCEEDED 80 !!!'
0051      GO TO 81
0052      C
0053      EX=DEXP(ZRE)
0054      EZ=EX*DCMPLX(DCOS(ZIM),DSIN(ZIM))
0055      C
0056      CY2=DCOS(Y2)
0057      SY2=DSIN(Y2)
0058      STPR=DSQRT(2.*PI*R)
0059      T2=THETA/2.
0060      CI2=DCOS(T2)
0061      SI2=DSIN(T2)
0062      TK=DSQRT(PI/(2.*R))
0063      NA=1

```

```

0064      NB=2
0065      IF (ID.EQ.0) NB=1
0066      IF (ID.EQ.1) NA=2
0067      DO 80 NP1=NA,NB
0068      N=NP1-1
0069      IF (R.GT.9.) GO TO 50
0070      AC2=C2
0071      AS2=S2
0072      T=1.
0073      X=1.
0074      Y=.0
0075      DO 20 J=1,1000
0076      T=T*R4/(J*(N+J))
0077      X=X+T*AC2
0078      Y=Y+T*AS2
0079      AY=DABS(Y)
0080      AM=DABS(X)
0081      IF (AY.GT.AM) AM=AY
0082      IF (T.LT.AM/FMX) GO TO 21
0083      AC21=AC2
0084      AC2=AC21*C2-AS2*S2
0085      20 AS2=AS2*C2+AC21*S2
0086      21 REIZ=X
0087      IMIZ=Y
0088      IF (N.EQ.0) GO TO 25
0089      REIZ=R2*(X*C-Y*S)
0090      IMIZ=R2*(X*S+Y*C)
0091      25 AC2=C2
0092      AS2=S2
0093      T=1.
0094      PSI=-ALG
0095      IF (N.EQ.1) PSI=.5-ALG
0096      X=PSI
0097      Y=-THETA
0098      DO 40 J=1,1000
0099      IF (N.EQ.1) GO TO 30
0100      PSI=PSI+1./J
0101      T=1*R4/(J*J)
0102      GO TO 35
0103      30 JP=(J+1)*J
0104      PSI=PSI+(J+.5)/JP
0105      T=T*R4/JP
0106      35 DX=T*(AC2*PSI+AS2*THETA)
0107      X=X+DX
0108      Y=Y+T*(AS2*PSI-AC2*THETA)
0109      AY=DABS(Y)
0110      AM=DABS(X)
0111      IF (AY.GT.AM) AM=AY
0112      IF (DABS(T*PSI).LT.AM/FMX) GO TO 41
0113      AC21=AC2
0114      AC2=AC21*C2-AS2*S2
0115      40 AS2=AS2*C2+AC21*S2
0116      41 REKZ=X
0117      IMKZ=Y
0118      IF (N.EQ.0) GO TO 70
0119      REKZ=C/R-(X*ZRE-Y*ZIM)/2.
0120      IMKZ=-S/R-(Y*ZRE+X*ZIM)/2.
0121      GO TO 70
0122      50 AC2=C
0123      AS2=S
0124      MU=4*N*N
0125      I=-1
0126      T=1.

```

```

0127      XM=1.
0128      YM=.0
0129      XP=1.
0130      YP=.0
0131      T1=1.
0132      DO 60 J=1,1000
0133      K=2*J-1
0134      T=(MU-K*K)*T/(J*R8)
0135      ABT=DABS(T)
0136      IF (ABT.LT.1.E-30) GO TO 61
0137      IF (ABT.GT.T1) GO TO 61
0138      T1=ABT
0139      XM=XM+I*T*AC2
0140      YM=YM-I*T*AS2
0141      XP=XP+T*AC2
0142      YP=YP-T*AS2
0143      AC21=AC2
0144      AC2=AC21*C-AS2*S
0145      AS2=AS2*C+AC21*S
0146      60 I=-I
0147      61 I=1
0148      IF (N.EQ.1) I=-1
0149      J=1
0150      IF (ZIM.LE.0) J=-1
0151      K=I*J
0152      IF (ZRE.GE..0) GO TO 66
0153      XI=-K*YP+(XM*CY2-YM*SY2)*EPX2
0154      YI= K*XP+(XM*SY2+YM*CY2)*EPX2
0155      GO TO 68
0156      66 XI=XM+K*(XP*SY2-YP*CY2)*EMX2
0157      YI=YM+K*(XP*CY2+YP*SY2)*EMX2
0158      68 REIZ=(XI*CT2+YI*ST2)/STPR
0159      IMIZ=(YI*CT2-XI*ST2)/STPR
0160      REKZ=IK*(XP*CT2+YP*ST2)
0161      IMKZ=IK*(YP*CT2-XP*ST2)
0162      70 FIZ=DCMLPX(REIZ,IMIZ)
0163      FKZ=DCMLPX(REKZ,IMKZ)
0164      IF (ISC.GT.0) GO TO 74
0165      IF (R.LE.9.) GO TO 78
0166      IF (ZRE.LT..0) FIZ=FIZ/EZ
0167      IF (ZRE.GE..0) FIZ=FIZ*EZ
0168      FKZ=FKZ/EZ
0169      GO TO 78
0170      74 IF (R.GT.9.) GO TO 78
0171      IF (ZRE.LT..0) FIZ=FIZ*EZ
0172      IF (ZRE.GE..0) FIZ=FIZ/EZ
0173      FKZ=FKZ*EZ
0174      78 IF (N.EQ.1) GO TO 79
0175      BI=FIZ
0176      BK=FKZ
0177      GO TO 80
0178      79 BI1=FIZ
0179      BK1=FKZ
0180      80 CONTINUE
0181      81 SBI=BI
0182      SBK=BK
0183      SB11=BI1
0184      SBK1=BK1
0185      RETURN
0186      END

```

APPENDIX I

Subroutine CROUT (courtesy of Professor Richmond) uses Crout's method to solve a system of simultaneous linear equations.

C: the NxN matrix to be solved.

S: the excitation column as input, and the solution as output.

ICC: maximum number of linear equations or unknowns.

ISYM: set to zero if C is symmetric, otherwise set to 1.

IWR: if one, the subroutine prints some numerical values for debugging purposes, otherwise set to zero.

I12: if 1, inverts and solves, if 2, it only solves.

N: number of unknowns or linear equations to be solved.

```

0001 SUBROUTINE CROUT(C,S,ICC,ISYM,IWR,IL2,N)
0002 COMPLEX C(ICC,ICC),S(1)
0003 COMPLEX F,P,SS,T
0004 FORMAT(15X,'LIST OF THE LOOP CURRENTS CJ(I)')
0005 FORMAT(5X,'I',3X,'MAGNITUDE',3X,'PHASE',5X,'REAL',
0006 2,5X,'IMAGINARY')
0007 FORMAT(1X,I5,F10.4,F10.1,2E12.4)
0008 FORMAT(1H0)
0009 IF(112.NE.1)GO TO 22
0010 IF(N.EQ.1)S(1)=S(1)/C(1,1)
0011 IF(N.EQ.1)GO TO 39
0012 IF(1SYM.NE.0)GO TO 8
0013 DO 6 I=1,N
0014 DO 6 J=1,N
0015 C(J,I)=C(I,J)
0016 F=C(1,1)
0017 DO 10 I=2,N
0018 C(1,I)=C(1,I)/F
0019 DO 20 I=2,N
0020 LLL=L-1
0021 DO 20 I=L,N
0022 F=C(I,L)
0023 DO 11 K=1,LLL
0024 F=F-C(I,K)*C(K,L)
0025 C(I,L)=F
0026 IF(L.EQ.1)GO TO 20
0027 P=C(L,L)
0028 IF(1SYM.EQ.0)GO TO 15
0029 F=C(L,I)
0030 DO 12 K=1,LLL
0031 F=F-C(L,K)*C(K,I)
0032 C(L,I)=F/P
0033 GO TO 20
0034 F=C(I,L)
0035 C(L,I)=F/P
0036 CONTINUE
0037 DO 30 I=1,N
0038 P=C(L,L)
0039 T=S(I)
0040 IF(L.EQ.1)GO TO 30
0041 LLL=L-1
0042 DO 25 K=1,LLL
0043 T=T-C(L,K)*S(K)
0044 S(L)=T/P
0045 DO 38 I=2,N
0046 I=N-I+1
0047 II=I+1
0048 T=S(I)
0049 DO 35 K=II,N
0050 T=T-C(I,K)*S(K)
0051 S(I)=T
0052 IF(IWR.LE.0) GO TO 100
0053 WRITE(6,5)
0054 WRITE(6,1)
0055 WRITE(6,2)
0056 CNOR=.0
0057 DO 40 I=1,N
0058 SA=CABS(S(I))
0059 IF(SA.GT.CNOR)CNOR=SA
0060 IF(CNOR.LE.0.)CNOR=1.
0061 DO 44 I=1,N
0062 SS=S(I)

```

```
0063      SA=CABS(SS)
0064      SNOR=SA/CNOR
0065      PH=.0
0066      IF(SA.GT.0.)PH=57.29578*ATAN2(AIMAG(SS),REAL(SS))
0067  44  WRITE(6,3) I,SNOR,PH,SS
0068      WRITE(6,5)
0069  100 RETURN
0070      END
```

APPENDIX J

Program RECT (courtesy of Professor Richmond) modified slightly to calculate some curves for checking the results of some of the programs. It calculates the scattered electric field from a rectangular cylindrical scatterer considered throughout the dissertation. Some of the outputs of this program are included in Chapter III. This program uses Pulse Basis Point Matching (PBPM).

```

0001 C LINK WITH CROUT & HANK
0002 C THIS IS PROGRAM RECT.FOR FOR EZ POLARIZATION
0003 C
0004 COMPLEX H0,H1,ECM,EP,EZ,CII,CST
0005 COMPLEX C(500,500),V(500)
0006 DIMENSION X(500),Y(500)
0007 DATA ETA,PI,TP,E0/376.727,3.14159,6.28318,8.85E-12/
0008 1 FORMAT(1X,8E15.4)
0009 2 FORMAT(1X,3I5,8F12.6)
0010 5 FORMAT(1H0)
0011 7 FORMAT(7F10.5)
0012 11 FORMAT(1H1)
0013 call getcp(it1)
0014 IDN=500
0015 TYPE*, 'GIVE IBS,IBISS,PHI='
0016 ACCEPT*,IBS,IBISS,PHI
0017 IFRSCT=IBISS
0018 IBISS=IABS(IBISS)
0019 WRITE(10,*) IBS,IBISS,IFMC
0020 201 TYPE*, 'GIVE FMC,NY'
0021 ACCEPT*,FMC,NY
0022 IF(FMC.LT.0) GO TO 300
0023 SIG=-.3E-3
0024 ER=4.
0025 OMEGA=TP*FMC*1.E6
0026 TD=SIG/(OMEGA*ER*E0)
0027 EP=ER*CMPLX(1.,-TD)
0028 ECM=EP-1.
0029 IFMC=1
0030 AM=1.
0031 EM=.5
0032 NK=(AM/EM)*NY
0033 WAV=300./FMC
0034 AL=AM/WAV
0035 TYPE*, 'AL=' ,AL
0036 BL=EM/WAV
0037 AK=TP*AL
0038 BK=TP*BL
0039 DX=AK/NK
0040 DY=BK/NY
0041 K=0
0042 YY=DY/2.
0043 DO 20 J=1,NY
0044 XX=DX/2.
0045 DO 18 I=1,NX
0046 K=K+1
0047 X(K)=XX
0048 Y(K)=YY
0049 18 XX=XX+DX
0050 20 YY=YY+DY
0051 N=NX*NY
0052 CK=SQRT(DX*DY/PI)
0053 CALL HANK(CK,H0,H1,1)
0054 CII=1.+ECM*(.0,.5)*(PI*CK*H1-(.0,2.))
0055 BL=REAL(H1)
0056 CST=-(.0,1.)*(1.,1.)*CK*BL*ECM/(2.*1.414214)
0057 DO 200 I=1,N
0058 XI=X(I)
0059 YI=Y(I)
0060 C(I,I)=CII
0061 DO 200 J=I,N
0062 IF(J.EQ.I)GO TO 200

```

```

0063      XJ=X(J)
0064      YJ=Y(J)
0065      R=SQRT((XJ-XI)**2+(YJ-YI)**2)
0066      CALL HANK(R,H0,H1,0)
0067      C(I,J)=.5*PI*CK*(.0,1.)*ECM*B1*H0
0068 200 CONTINUE
0069      I12=1
0070      DO 600 JI=1,IBS
0071      IF(IBS.GT.1)PHI=(JI-1)*360./FLOAT(IBS-1)
0072      PHR=.0174533*PHI
0073      CPH=COS(PHR)
0074      SPH=SIN(PHR)
0075      DO 202 I=1,N
0076      XI=X(I)
0077      YI=Y(I)
0078      PSI=XI*CPH+YI*SPH
0079      V(I)=CMPLX(COS(PSI),SIN(PSI))
0080 202 CONTINUE
0081      IWR=0
0082      ISYM=0
0083      CALL CROUT(C,V,IDM,ISYM,IWR,I12,N)
0084      I12=2
0085 C      DO 220 J=1,4
0086 C      NS=55+J*10
0087 C      DO 220 I=NS,NS+5
0088 C      FACT=WAV/TP
0089 C      WRITE(10,*)'X=',(X(I)*FACT),'Y=',(Y(I)*FACT)
0090 C      RE=REAL(V(I))
0091 C      AIE=AIMAG(V(I))
0092 C      AMP=CABS(V(I))
0093 C      PHAS=ATAN2(AIE,RE)/.0174533
0094 C      WRITE(10,*)'EZ1=',AMP,'PHASE=',PHAS
0095 C220 CONTINUE
0096      IF(IFRSCT.EQ.-1)PHR=PHR+PI
0097      DO 600 JK=1,IBISS
0098      IF(IBISS.GT.1)THEN
0099      PHI=(JK-1)*360./FLOAT(IBISS-1)
0100      PHR=.0174533*PHI
0101      END IF
0102      CPH=COS(PHR)
0103      SPH=SIN(PHR)
0104      EZ=(.0,.0)
0105      DO 250 I=1,N
0106      PSI=X(I)*CPH+Y(I)*SPH
0107 250 EZ=EZ+V(I)*CMPLX(COS(PSI),SIN(PSI))
0108      EZ=CST*EZ
0109      EZA=CABS(EZ)
0110      EWL=TP*EZA*EZA
0111      WRITE(10,2)N,NX,NY,FMC,EWL,PHI
0112      TYPE2,N,NX,NY,FMC,EWL,PHI
0113      IF(IBS.EQ.1.AND.IBISS.EQ.1)GO TO 201
0114 600 CONTINUE
0115      WRITE(10,*)'      FMC      EWL      NX      XY '
0116 300 call getcp(it2)
0117      WRITE(10,*)'PHI=',PHI
0118      WRITE(10,*)'AWM=',AM,'BWM=',BM
0119      time=(it2-it1)/100.
0120      type*,'cpu time secs=',time
0121      CALL EXIT
0122      END

```

APPENDIX K

Program SQCYLH (courtesy of Professor Richmond) modified slightly to calculate magnetic scattered field from a rectangular cylindrical geometry considered in this dissertation. Some of the outputs of this program is included in Chapter IV. It uses Pulse Basis Point Matching (PBPM).

```

0001 C LINK WITH CROUT & DMBEZ10
0002 COMPLEX CMN(500,500),A(500)
0003 COMPLEX EGR,GP,GR,HZI,HZS,CJX,CJY,EKK,BKX,BKY
0004 COMPLEX EP1,EP2,ETA2,GAM2,CST,BI,BK,BI1,BK1
0005 DIMENSION XM(500),YM(500)
0006 DATA FP/12.5663706144/
0007 DATA ETA,PI,TP/376.730366239,3.14159265359,6.28318530718/
0008 DATA E0,U0/8.85418533677E-12,1.25663706144E-6/
0009 1 FORMAT(1X,2I5,6F12.3)
0010 2 FORMAT(1X,F12.6,I5,6F12.6)
0011 5 FORMAT(1H0)
0012 9 FORMAT(1X,3I5,6F12.6)
0013 READ(7,*)ER1,SIG1,ER2,SIG2,FMCMX,AWM,BWM,DM,XLS, YLS,IWR,
0014 &IFILD,IWRC,IPW,IBS,IBISS,IFMC,ICMN
0015 WRITE(10,*)MAX(IBS,IBISS,IFMC)
0016 CALL GETCP(IT1)
0017 20 TYPE*, 'GIVE FMC,NYY'
0018 ACCEPT*,FMC,NYY
0019 I12=1
0020 ICC=500
0021 CX=.0174533
0022 PHI=ATAN2(YLS,XLS)/CX
0023 RLS=SQRT(XLS*XLS+YLS*YLS)
0024 PH=CX*PHI
0025 AM=AWM/2.
0026 BM=BWM/2.
0027 DO 500 JF=1,IFMC
0028 IF(IFMC.GT.1)FMC=JF*FMCMX/FLOAT(IFMC)
0029 OMEGA=TP*FMC*1.E6
0030 BET1=OMEGA*SQRT(U0*ER1*E0)
0031 EP1=CMPLX(ER1*E0,-SIG1/OMEGA)
0032 EP2=ER2*E0*(1.,.0)
0033 IF(SIG2.GT.1.E-10)EP2=CMPLX(ER2*E0,-SIG2/OMEGA)
0034 ETA2=CSQRT(U0/EP2)
0035 GAM2=OMEGA*CSQRT(-U0*EP2)
0036 WAV2=300./FMC/SQRT(ER2)
0037 C NY=5.*BET1*AWM/TP
0038 NY=NY
0039 NY2=NY/2
0040 NY=2*NY2
0041 IF(NY.LT.2)NY=2
0042 NX=INT(AM/BM)*NY
0043 NX2=NX/2
0044 NX=2*NX2
0045 NEQ=NX*NY
0046 IF(NEQ.GT.ICC)GO TO 600
0047 DX=AWM/NX
0048 DY=BWM/NY
0049 DX2=DX/2.
0050 DY2=DY/2.
0051 CM=DX/SQRT(PI)
0052 CALL MBEZ10(GAM2*CM,BI,BK,BI1,BK1,1,0)
0053 CST=-CM*(EP1-EP2)*BI1/(DX*EP1)
0054 M=0
0055 Y=-BM+DY2
0056 DO 40 J=1,NY
0057 X=-AM+DX2
0058 DO 30 I=1,NX
0059 M=M+1
0060 XM(M)=X
0061 YM(M)=Y
0062 30 X=X+DX
0063 40 Y=Y+DY

```

```

0064         IF (ICMN.EQ.0) GO TO 299
0065         DO 50 J=1,NEQ
0066         DO 45 I=1,NEQ
0067     45     CMN(I,J)=(.0,.0)
0068     50     CMN(J,J)=(1.,.0)
0069         DO 200 M=1,NEQ
0070         X=XM(M)
0071         Y=YM(M)
0072         DO 180 N=1,NEQ
0073         IF (N.EQ.N) GO TO 180
0074         XN=XM(N)
0075         YN=YM(N)
0076         XX=X-XN
0077         YY=Y-YN
0078         RH=SQRT(XX*XX+YY*YY)
0079         CALL MBEZ10(GAM2*RH,BI,BK,BI1,BK1,1,0)
0080         BK1=CST*BK1/RH
0081         J=1+(N-1)/NX
0082         I=N-(J-1)*NX
0083         NP=N
0084         IF (I.GT.NX2) NP=N-1
0085         NU=N
0086         IF (J.GT.NY2) NU=N-NX
0087         NV=NU+NX
0088         NQ=NP+1
0089         CMN(M,NP)=CMN(M,NP)-XX*BK1
0090         CMN(M,NQ)=CMN(M,NQ)+XX*BK1
0091         CMN(M,NU)=CMN(M,NU)-YY*BK1
0092         CMN(M,NV)=CMN(M,NV)+YY*BK1
0093     180     CONTINUE
0094     200     CONTINUE
0095     299     CONTINUE
0096         DO 500 JI=1,IBS
0097         IF (IBS.GT.1) PHI=(JI-1)*360./FLOAT(IBS-1)
0098         PH=CX*PHI
0099         CPH=COS(PH)
0100         SPH=SIN(PH)
0101         XLS=RLS*CPH
0102         YLS=RLS*SPH
0103         DO 240 M=1,NEQ
0104         X=XM(M)
0105         Y=YM(M)
0106         IF (IPW.EQ.0) GO TO 238
0107         PSI=X*CPH+Y*SPH
0108         GP=GAM2*PSI
0109         EGR=CEXP(GP)
0110         GO TO 240
0111     238     XX=XLS-X
0112         YY=YLS-Y
0113         YS=YY*YY
0114         RH=SQRT(XX*XX+YS)
0115         GR=GAM2*RH
0116         CALL MBEZ10(GR,BI,BK,BI1,BK1,0,0)
0117         EGR=EK
0118     240     A(M)=EGR
0119         IWRC=0
0120         ISYM=1
0121         IF (ICMN.EQ.0.AND.JI.EQ.1) THEN
0122         DO 298 M=1,NEQ
0123         DO 298 N=1,NEQ
0124     298     READ(8,*) CMN(M,N)
0125         I12=2
0126         END IF

```

```

0127 CALL CROUT(CHN,A,ICC,ISYM,IMRC,I12,NEQ)
0128 IF (ICNN.EQ.1.AND.JI.EQ.1) THEN
0129 DO 300 N=1,NEQ
0130 DO 300 M=1,NEQ
0131 WRITE(E,*)CMN(M,N)
0132 END IF
0133 DO 500 JK=1,IBISS
0134 IF (IBISS.GT.1) THEN
0135 PHI=(JK-1)*360./FLOAT(IBISS-1)
0136 PHS=CX*PHI
0137 CPH=COS(PHS)
0138 SPH=SIN(PHS)
0139 XLS=RLS*CPH
0140 YLS=RLS*SPH
0141 END IF
0142 HZS=(.0,.0)
0143 DO 280 N=1,NEQ
0144 X=XX(N)
0145 Y=YI(N)
0146 IF (IFILD.EQ.1) THEN
0147 RE=REAL(A(N))
0148 AIE=AINAG(A(N))
0149 PHASE=ATAN2(AIE,RE)/.0174533
0150 AMP=CABS(A(N))
0151 WRITE(10,*) 'X,Y,AMP,PHASE=',X,Y,AMP,PHASE
0152 END IF
0153 J=1+(N-1)/NX
0154 I=N-(J-1)*NX
0155 NP=N
0156 IF (I.GT.NX2) NP=N-1
0157 MQ=NP+1
0158 NU=N
0159 IF (J.GT.NY2) NU=N-NX
0160 NV=NU+NX
0161 CJX=A(NV)-A(NU)
0162 CJY=A(NO)-A(NP)
0163 IF (IPW.EQ.0) GO TO 270
0164 PSI=X*CPH+Y*SPH
0165 GP=CEXP(GAM2*PSI)
0166 HZS=HZS+GP*(CJX*SPH+CJY*CPH)
0167 GO TO 280
0168 XX=XLS-X
0169 YY=YLS-Y
0170 RR=SQRT(XX*XX+YY*YY)
0171 GR=GAM2*RH
0172 CALL MBEZ10(GR,BI,FK,BL,BK1,1,0)
0173 HZS=HZS+(YY*CJX+XX*CJY)*BK1/RH
0174 CONTINUE
0175 HZS=-CST*HZS
0176 IF (IPW.EQ.1) THEN
0177 HZS=HZS*CSQRT(.5*PI/GAM2)
0178 AZS=CABS(HZS)
0179 EWL=TP*AZS*AZS/WAV2
0180 TYPE9,NEQ,NX,NY,FNC,EWL,PHI
0181 WRITE(10,9)NEQ,NX,NY,FNC,EWL,PHI
0182 GO TO 400
0183 END IF
0184 GR=2.*GAM2*RLS
0185 CALL MBEZ10(GR,BI,FK,BL,BK1,0,0)
0186 AZS=CABS(HZS)
0187 HZI=BK
0188 AZI=CABS(HZI)
0189 AZN=AZS/AZI

```

```

0190          DB=20.*ALOG10(AZN)
0191          TYPE9,NEQ,NX,NY,FMC,DB,PHI
0192          WRITE(10,9)NEQ,NX,NY,FMC,DB,PHI
0193 C        IF(NY.LT.100)GO TO 20
0194 400      IF(ABS.GT.1)I12=2
0195 500      CONTINUE
0196          CALL GETCP(IT2)
0197          TIME=(IT2-IT1)/100.
0198          WRITE(10,*)'ER1 & SIG1=', ER1,SIG1
0199          WRITE(10,*)'ER2 & SIG2=',ER2,SIG2
0200          WRITE(10,*)'FMC ,XLS ,PHI =' ,FMC,XLS,PHI
0201          WRITE(10,*)'AM=',AM
0202          WRITE(10,*)'CPU TIME=',TIME,'SEC'
0203          WRITE(10,*)'SQCYLH.FOR'
0204 600 CALL EXIT
0205          END

```

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